

# *Real-Time Systems*

## *Lecture 04: Duration Calculus II*

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### *Contents & Goals*

#### **Last Lecture:**

- Started DC Syntax and Semantics: Symbols, State Assertions

#### **This Lecture:**

- **Educational Objectives:** Capabilities for following tasks/questions.
  - Read (and at best also write) Duration Calculus terms.
- **Content:**
  - Duration Calculus continued

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## Duration Calculus Cont'd

### Duration Calculus: Overview

We will introduce three (or five) syntactical “levels”:

$$\begin{array}{l} I: Obs \rightarrow (Time \rightarrow \mathcal{D}) \\ \mid \\ X_I: Time \rightarrow \mathcal{D}(X) \end{array}$$

(i) **Symbols:**

$$0, 1, 3, 4, f, g, \quad true, false, =, <, >, \leq, \geq, \quad x, y, z, \quad X, Y, Z, \quad d$$

(ii) **State Assertions:**  $\vdash I \llbracket P \rrbracket : Time \rightarrow \{0, 1\}$

$$P ::= 0 \mid 1 \mid x = d \mid \neg P_1 \mid P_1 \wedge P_2$$

(iii) **Terms:**

$$\vdash I \llbracket \theta \rrbracket : Intv \times Val \rightarrow \mathbb{R}$$

$$\theta ::= x \mid \ell \mid \int P \mid f(\theta_1, \dots, \theta_n)$$

(iv) **Formulae:**

$$F ::= p(\theta_1, \dots, \theta_n) \mid \neg F_1 \mid F_1 \wedge F_2 \mid \forall x \bullet F_1 \mid F_1 ; F_2$$

(v) **Abbreviations:**

$$\lceil \cdot \rceil, \quad \lceil P \rceil, \quad \lceil P \rceil^t, \quad \lceil P \rceil^{\leq t}, \quad \diamond F, \quad \square F$$

## Terms: Syntax

- **Duration terms** (DC terms or just terms) are defined by the following grammar:

$$\theta ::= x \mid \ell \mid \int P \mid f(\theta_1, \dots, \theta_n)$$

where  $x$  is a global variable,  $\ell$  and  $f$  are special symbols,  $P$  is a state assertion, and  $f$  a function symbol (of arity  $n$ ).

- $\ell$  is called **length operator**,  $\int$  is called **integral operator**
- Notation: we may write function symbols in **infix notation** as usual, i.e. write  $\theta_1 + \theta_2$  instead of  $+(\theta_1, \theta_2)$ .

### Definition 1. [Rigid]

A term **without** length and integral symbols is called **rigid**.

Example:  $x + (y \cdot z) \cdot z$  is rigid

## Terms: Semantics

- Closed **intervals** in the time domain

$$\text{Intv} := \{[b, e] \mid b, e \in \text{Time and } b \leq e\}$$

**Point intervals:**  $[b, b]$

- Let  $GVar$  be the set of global variables.  
A valuation of  $GVar$  is a function

$$V: GVar \rightarrow \mathbb{R}$$

We use  $Val$  to denote the set of all valuations of  $GVar$ , i.e.  $Val = (GVar \rightarrow \mathbb{R})$ .

## Terms: Semantics

- The **semantics** of a **term** is a function

$$\mathcal{I}[\theta] : \text{Val} \times \text{Intv} \rightarrow \mathbb{R}$$

i.e.  $\mathcal{I}[\theta](\mathcal{V}, [b, e])$  is the real number that  $\theta$  denotes under interpretation  $\mathcal{I}$  and valuation  $\mathcal{V}$  in the interval  $[b, e]$ .

- The value is defined **inductively** on the structure of  $\theta$ :

$$\mathcal{I}[x](\mathcal{V}, [b, e]) = \mathcal{V}(x).$$

$$\mathcal{I}[\ell](\mathcal{V}, [b, e]) = e - b$$

$$\mathcal{I}[f P](\mathcal{V}, [b, e]) = \int_b^e P_{\mathcal{I}}(t) dt$$

$$\mathcal{I}[f(\theta_1, \dots, \theta_n)](\mathcal{V}, [b, e]) = \hat{f}(\mathcal{I}[\theta_1](\mathcal{V}, [b, e]), \dots, \mathcal{I}[\theta_n](\mathcal{V}, [b, e]))$$

## Terms: Semantics Well-defined?

- So,  $\mathcal{I}[f P](\mathcal{V}, [b, e])$  is  $\int_b^e P_{\mathcal{I}}(t) dt$  — but does the integral always exist?
- IOW: is there a  $P_{\mathcal{I}}$  which is not (Riemann-)integrable? Yes. For instance

$$P_{\mathcal{I}}(t) = \begin{cases} 1 & , \text{ if } t \in \mathbb{Q} = \left\{ \frac{p}{q} \mid p, q \in \mathbb{Z} \right\} \\ 0 & , \text{ if } t \notin \mathbb{Q} \end{cases}$$

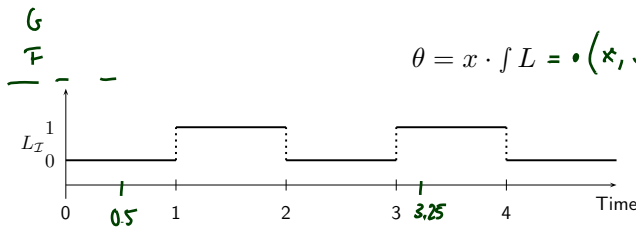
- To exclude such functions, DC considers only interpretations  $\mathcal{I}$  satisfying the following condition of **finite variability**:

For each state variable  $X$  and each interval  $[b, e]$  there is a **finite partition** of  $[b, e]$  such that the interpretation  $X_{\mathcal{I}}$  is **constant on each part**.

Thus on each interval  $[b, e]$  the function  $X_{\mathcal{I}}$  has only **finitely many points of discontinuity**.

Terms: Example

$$L = G \wedge \neg F$$



$$\theta = x \cdot \int L = \bullet(x, \int L)$$

$$V(x) = 20.$$

- $\theta_1 = \int 0 + x = +(\int 0, x)$
- $\mathcal{I}[\llbracket \theta \rrbracket](V, [1, 2]) = \hat{+}(\mathcal{I}[\llbracket \int 0 \rrbracket](V, [1, 2]), \mathcal{I}[x](V, [1, 2])) = \hat{+}(0, 20) = 20 \in \mathbb{R}$
- $\mathcal{I}[\llbracket \int 0 \rrbracket](V, [1, 2]) = \int_1^2 0_{\mathcal{I}}(t) dt = \int_1^2 \mathcal{I}[0](t) dt = 0 \in \mathbb{R}$
- $\mathcal{I}[x](V, [1, 2]) = V(x) = 20 \in \mathbb{R}$
- $\mathcal{I}[\llbracket \int L \rrbracket](V, [0.5, 3.25]) = \int_{0.5}^{3.25} L_I(t) dt = 1.25$
- $\mathcal{I}[\llbracket \theta \rrbracket](V, [0.5, 3.25]) = \hat{+}(20, 1.25) = 25$

*:  $\mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$   
 $\mathbb{R} \rightarrow \mathbb{R}$   
 $\mathbb{R} \rightarrow \mathbb{R}$*

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Terms: Remarks

*"finitely many points don't matter"*

**Remark 2.5.** The semantics  $\mathcal{I}[\llbracket \theta \rrbracket]$  of a term is insensitive against changes of the interpretation  $\mathcal{I}$  at individual time points.

*Let  $\mathcal{I}_1, \mathcal{I}_2$  be interpretations such that  $\mathcal{I}_1(x)(t) = \mathcal{I}_2(x)(t)$  for all  $x$  for all  $t \in \text{Time}$  except for  $t_0 \in \text{Time}$ .  
 Then  $\mathcal{I}_1[\llbracket \theta \rrbracket](V, [b, e]) = \mathcal{I}_2[\llbracket \theta \rrbracket](V, [b, e])$ .*

**Remark 2.6.** The semantics  $\mathcal{I}[\llbracket \theta \rrbracket](V, [b, e])$  of a rigid term does not depend on the interval  $[b, e]$ .

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## Duration Calculus: Overview

We will introduce three (or five) syntactical “levels”:

(i) **Symbols:**

$0, 1, 3, 14, a \in \mathbb{R}, f, g, \text{ true, false, } =, <, >, \leq, \geq, x, y, z, X, Y, Z, d$

(ii) **State Assertions:**

$$P ::= 0 \mid 1 \mid X = d \mid \neg P_1 \mid P_1 \wedge P_2$$

(iii) **Terms:**

$$\theta ::= x \mid \ell \mid \int P \mid f(\theta_1, \dots, \theta_n)$$

(iv) **Formulae:**  $\Gamma \vdash \{F\}; \text{ Val}(x \text{ lctv} \rightarrow \{t, f\})$

$$F ::= p(\theta_1, \dots, \theta_n) \mid \neg F_1 \mid F_1 \wedge F_2 \mid \forall x \bullet F_1 \mid F_1 ; F_2$$

(v) **Abbreviations:**

$$[\ ], [P], [P]^t, [P]^{\leq t}, \diamond F, \square F$$

## Formulae: Syntax

- The set of **DC formulae** is defined by the following grammar:

$$F ::= p(\theta_1, \dots, \theta_n) \mid \neg F_1 \mid F_1 \wedge F_2 \mid \forall x \bullet F_1 \mid F_1 ; F_2$$

where  $p$  is a predicate symbol,  $\theta_i$  a term,  $x$  a global variable.

- chop operator:** ‘;’
- atomic formula:**  $p(\theta_1, \dots, \theta_n)$
- rigid formula:** all terms are rigid
- chop free:** ‘;’ doesn’t occur
- usual notion of **free** and **bound** (global) variables
- Note: quantification only over (**first-order**) global variables, not over (**second-order**) state variables.

## Formulae: Priority Groups

- To avoid parentheses, we define the following five priority groups from highest to lowest priority:
  - $\neg$  (negation)
  - $;$  (chop)
  - $\wedge, \vee$  (and/or)
  - $\implies, \iff$  (implication/equivalence)
  - $\exists, \forall$  (quantifiers)

- Examples:
- $\neg F ; F \vee H$ 
    - $(\neg F ; F) \vee H$
    - $(\neg F) ; F \vee H$  ✓
    - $(\neg F) ; (F \vee H)$
  - $\forall x \bullet (F \wedge G)$

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## Syntactic Substitution...

...of a term  $\theta$  for a variable  $x$  in a formula  $F$ .

- We use

$$F[x := \theta]$$

to denote the formula that results from performing the following steps:

- transform  $F$  into  $\tilde{F}$  by (consistently) renaming bound variables such that no free occurrence of  $x$  in  $\tilde{F}$  appears within a quantified subformula  $\exists z \bullet G$  or  $\forall z \bullet G$  for some  $z$  occurring in  $\theta$ ,
- textually replace all free occurrences of  $x$  in  $\tilde{F}$  by  $\theta$ .

Examples:  $F := (x \geq y \implies \exists z \bullet z \geq 0 \wedge x = y + z)$ ,  $\theta_1 := \ell$ ,  $\theta_2 := \ell + z$ ,

- $F[x := \theta_1] = (\ell \geq y \implies \exists z \bullet z \geq 0 \wedge \ell = y + z)$
- $F[x := \theta_2] = (\ell + z \geq y \implies \exists \tilde{z} \bullet \tilde{z} \geq 0 \wedge \ell + z = y + \tilde{z})$

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## Formulae: Semantics

- The **semantics** of a **formula** is a function

$$\mathcal{I}[[F]] : \text{Val} \times \text{Intv} \rightarrow \{\text{tt}, \text{ff}\}$$

i.e.  $\mathcal{I}[[F]](\mathcal{V}, [b, e])$  is the truth value of  $F$  under interpretation  $\mathcal{I}$  and valuation  $\mathcal{V}$  in the interval  $[b, e]$ .

- This value is defined **inductively** on the structure of  $F$ :

$$\mathcal{I}[[p(\theta_1, \dots, \theta_n)]](\mathcal{V}, [b, e]) = \hat{p}(\mathcal{I}[[\theta_1]](\mathcal{V}, [b, e]), \dots, \mathcal{I}[[\theta_n]](\mathcal{V}, [b, e]))$$

$$\mathcal{I}[[\neg F_1]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff } \mathcal{I}[[F_1]](\mathcal{V}, [b, e]) = \text{ff}$$

$$\mathcal{I}[[F_1 \wedge F_2]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff } \mathcal{I}[[F_i]](\mathcal{V}, [b, e]) = \text{tt}, \quad i=1,2$$

$$\mathcal{I}[[\forall x \bullet F_1]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff for all } a \in \mathbb{R} \text{ the symbol!}$$

$$\mathcal{I}[[F_1[x:=a]]](\mathcal{V}, [b, e]) = \text{tt}$$

$$\mathcal{I}[[F_1 ; F_2]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff there is an } m \in [b, e] \text{ such that}$$

$$\mathcal{I}[[F_1]](\mathcal{V}, [b, m]) = \text{tt} \text{ and } \mathcal{I}[[F_2]](\mathcal{V}, [m, e]) = \text{tt}$$

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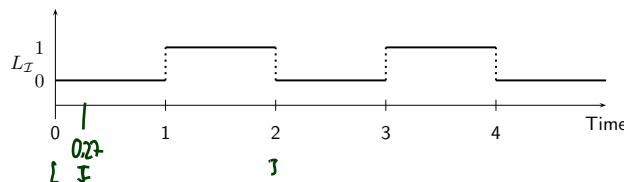
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## Formulae: Example

$$F := \int_{L=0}^{L=1} ; \int_{L=1}^{L=1}$$

$$\int (x = \text{open}) > 1$$

$$\int (L=1) > 2$$



- $\mathcal{I}[[F]](\mathcal{V}, [0, 2]) = \text{tt}$  (\*)

choose  $m=1.0$ :  $\mathcal{I}[[L=0]](\mathcal{V}, [0, 1]) = \text{tt}$  because  $\mathcal{I}[[L]]([0, 1]) = \int_0^1 L_I(t) dt = 0$

and  $\mathcal{I}[[L=1]]([0, 1]) = \int_0^1 (L_I(t) - 1) dt = -1$

$$\mathcal{I}[[L=1]](\mathcal{V}, [1, 2]) = \int_1^2 L_I(t) dt = 1$$

all math., not DC symbols

what about

$m = 0.27$ : witness for (\*)  $\rightarrow$  chop point not necessarily unique

$m = 1.75$ : no witness for (\*)

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## *References*

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## References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.