

Real-Time Systems

Lecture 04: Duration Calculus II

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Contents & Goals

Last Lecture:

- Started DC Syntax and Semantics: Symbolic, State Assertions

This Lecture:

- Educational Objectives: Capabilities for following tasks/questions
- Read (and at best also write) Duration Calculus terms.

Content:

- Duration Calculus continued

Duration Calculus Cont'd

Duration Calculus: Overview

We will introduce three (or five) syntactical "levels":

$$I: \text{DC} \rightarrow (\text{Time} \rightarrow \mathcal{D})$$

$$X: \text{Time} \rightarrow \mathcal{D}(X)$$

(i) Symbols:

$$0, 1, 3^k, -d, g, \text{true}, \text{false}, =, <, >, \leq, \geq, X, Y, Z, X \cdot Y, Z, d$$

(ii) State Assertions:

$$P ::= \text{0} \mid \text{1} \mid \text{X} = \text{d} \mid \text{R}_1 \mid \text{P}_1 \wedge \text{P}_2$$

(iii) Terms:

$$\theta ::= x \mid \ell \mid f \mid P \mid f(\theta_1, \dots, \theta_n)$$

(iv) Formulas:

$$F ::= p(\theta_1, \dots, \theta_n) \mid \neg F_1 \mid F_1 \wedge F_2 \mid \forall x. \bullet F_1 \mid F_1 \mid F_2$$

(v) Abbreviations:

$$\lceil \cdot \rceil, \lceil P \rceil, \lceil P \rceil^c, \lceil P \rceil^S, \diamond F, \square F$$

Terms: Syntax

- Duration terms (DC terms or just terms) are defined by the following grammar:

$$\theta ::= x \mid \ell \mid f \mid P \mid f(\theta_1, \dots, \theta_n)$$

where x is a global variable, ℓ and f are special symbols, P is a state assertion, and f a function symbol (of arity n).

- f is called **length operator**, f is called **integral operator**

- Notation: we may write function symbols in **infix notation** as usual, i.e. write $\theta_1 + \theta_2$ instead of $+(\theta_1, \theta_2)$.

Definition 1. [rigid]
A term **without** length and integral symbols is called **rigid**.

$$\text{Example: } x + (y \cdot z) \text{ is rigid}$$

Terms: Semantics

- Closed intervals in the time domain

$$\text{Intv} := \{[b, e] \mid b, e \in \text{Time and } b \leq e\}$$

Point intervals: $[b, b]$

- Let GVar be the set of global variables.

A valuation of GVar is a function

$$V: \text{GVar} \rightarrow \mathbb{R}$$

We use V to denote the set of all valuations of GVar , i.e. $\text{Val} = (\text{GVar} \rightarrow \mathbb{R})$.

Terms: Semantics

- The semantics of a term is a function $\mathcal{I}[\theta]$: $\text{Val} \times \text{Intv} \rightarrow \mathbb{R}$
- i.e. $\mathcal{I}[\theta](\gamma, [b, e])$ is the real number that θ denotes under interpretation \mathcal{I} and valuation γ in the interval $[b, e]$.
- The value is defined **inductively** on the structure of θ .

$$\begin{aligned} \mathcal{I}[c](\gamma, [b, e]) &= c \\ \mathcal{I}[x](\gamma, [b, e]) &= \gamma(x) \\ \mathcal{I}[e_1 + e_2](\gamma, [b, e]) &= \int_b^e \mathcal{I}[e_1](\gamma, [b, e]) + \mathcal{I}[e_2](\gamma, [b, e]) \\ \mathcal{I}[e_1 * e_2](\gamma, [b, e]) &= \int_b^e \mathcal{I}[e_1](\gamma, [b, e]) * \mathcal{I}[e_2](\gamma, [b, e]) \end{aligned}$$

Terms: Semantics Well-defined?

- So, $\mathcal{I}[P](\gamma, [b, e]) = \int_b^e P_2(t) dt$ — but does the integral always exist?
- LOW: is there a P_2 which is not (Riemann-)integrable? Yes. For instance $P_2(t) = \begin{cases} 1, & \text{if } t \in \mathbb{Q} \\ 0, & \text{if } t \notin \mathbb{Q} \end{cases}$

To exclude such functions, DC considers only interpretations \mathcal{I} satisfying the following condition of **finite variability**.
 For each state variable X and each interval $[b, e]$, there is a finite partition of $[b, e]$ such that the interpretation $X_{\mathcal{I}}$ is constant on each part.
 Thus on each interval $[b, e]$, the function $X_{\mathcal{I}}$ has only **finitely many points of discontinuity**.

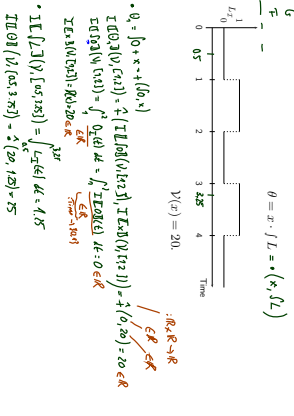
Terms: Remarks

Remark 2.5: The semantics $\mathcal{I}[\theta]$ of a term is insensitive against changes of the interpretation \mathcal{I} at individual time points.
 Let I_1, I_2 be interpretations such that $I_1(x)(t) = I_2(x)(t)$ for all x and all $t \in \mathbb{R}$ except for $t \in T$.
 Then, $\mathcal{I}_1[\mathcal{E}(\theta)](\gamma, [b, e]) = \mathcal{I}_2[\mathcal{E}(\theta)](\gamma, [b, e])$.
Remark 2.6: The semantics $\mathcal{I}[\theta](\gamma, [b, e])$ of a rigid term does not depend on the interval $[b, e]$.

Duration Calculus: Overview

- We will introduce three (or two) syntactical "levels":
- (i) **Symbols:** $0, 1, 3, 4, \# \in \mathbb{R}; f, \theta, \text{true}, \text{false}, =, <, >, \leq, \geq, x, y, z, X, Y, Z, d$
 - (ii) **State Assertions:** $P ::= 0 \mid 1 \mid X = d \mid \neg P_1 \mid P_1 \wedge P_2$
 - (iii) **Terms:** $\theta ::= x \mid t \mid f(P_1, \dots, P_n)$
 - (iv) **Formulae:** $F ::= \mathcal{I}[\mathcal{E}(\theta)](\gamma, [b, e]) \rightarrow \mathcal{I}[\mathcal{E}(\theta)](\gamma, [b, e])$
 - (v) **Abbreviations:** $\square, \square^+, [P], [P]^+, [P]^S, \diamond P, \square P$

Terms: Example



Formulae: Syntax

- The set of **DC formulae** is defined by the following grammar: $F ::= p(\theta_1, \dots, \theta_n) \mid \neg F_1 \mid F_1 \wedge F_2 \mid \forall x \bullet F_1 \mid F_1 ; F_2$ where p is a predicate symbol, θ_i a term, x a global variable.
- chop operator:** $;$
- atomic formulae:** $p(\theta_1, \dots, \theta_n)$
- rigid formulae:** all terms are rigid
- chop free:** $;$ doesn't occur
- usual notion of free and bound (global) variables**
- Note: quantification only over **(first-order) global variables**, not over **(second-order) state variables**.

Formulas: Priority Groups

- To avoid parentheses, we define the following five priority groups from highest to lowest priority:
 - ~
 - ! (negation)
 - ∧, ∨ (and/or)
 - ⇒, ⇔ (implication/equivalence)
 - ∃, ∀ (quantifiers)

Examples:

- ~F : F ∨ H
- ∃x • (F ∧ G)

Syntactic Substitution...

- ...of a term θ for a variable x in a formula F .
- We use $F[x := \theta]$ to denote the formula that results from performing the following steps:
 - transform F into F' by (consistently) renaming bound variables such that no free occurrence of x in F' appears within a quantified subformula $\exists z \bullet C$ or $\forall z \bullet C$ for some z occurring in θ
 - locally replace all free occurrences of x in F' by θ .

Examples: $F := (x \geq y \Rightarrow \exists z \bullet z \geq 0 \wedge x = y + z)$, $\theta_1 := t$, $\theta_2 := t + z$,

- $F[x := \theta_1] = (t \geq y \Rightarrow \exists z \bullet z \geq 0 \wedge t = y + z)$
- $F[x := \theta_2] = (t + z \geq y \Rightarrow \exists z \bullet z \geq 0 \wedge t + z = y + z)$

Formulas: Semantics

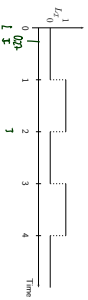
- The semantics of a formula is a function $\mathbb{I}F\mathbb{I} : \text{Val} \times \text{IntV} \rightarrow \{\text{tt}, \text{ff}\}$ i.e. $\mathbb{I}F\mathbb{I}(v, [b, e])$ is the truth value of F under interpretation \mathcal{I} and valuation \mathcal{V} in the interval $[b, e]$.

This value is defined inductively on the structure of F :

- $\mathbb{I}b\mathbb{I}(v, [b, e]) = \text{tt}$ iff $\mathbb{I}E\mathbb{I}(v, [b, e]) = \text{tt}$
- $\mathbb{I}F_1 \wedge F_2\mathbb{I}(v, [b, e]) = \text{tt}$ iff $\mathbb{I}F_1\mathbb{I}(v, [b, e]) = \text{tt}$ and $\mathbb{I}F_2\mathbb{I}(v, [b, e]) = \text{tt}$
- $\mathbb{I}F_1 \vee F_2\mathbb{I}(v, [b, e]) = \text{tt}$ iff $\mathbb{I}F_1\mathbb{I}(v, [b, e]) = \text{tt}$ or $\mathbb{I}F_2\mathbb{I}(v, [b, e]) = \text{tt}$
- $\mathbb{I}F_1 \Rightarrow F_2\mathbb{I}(v, [b, e]) = \text{tt}$ iff $\mathbb{I}F_1\mathbb{I}(v, [b, e]) = \text{ff}$ or $\mathbb{I}F_2\mathbb{I}(v, [b, e]) = \text{tt}$
- $\mathbb{I}\neg F\mathbb{I}(v, [b, e]) = \text{tt}$ iff $\mathbb{I}F\mathbb{I}(v, [b, e]) = \text{ff}$
- $\mathbb{I}\forall x \bullet F\mathbb{I}(v, [b, e]) = \text{tt}$ iff for all $a \in \mathbb{R}$, $\mathbb{I}F[x := a]\mathbb{I}(v, [b, e]) = \text{tt}$
- $\mathbb{I}\exists x \bullet F\mathbb{I}(v, [b, e]) = \text{tt}$ iff there is an $a \in \mathbb{R}$ such that $\mathbb{I}F[x := a]\mathbb{I}(v, [b, e]) = \text{tt}$

Formulas: Example

$$F := \mathbb{I}b\mathbb{I} = 0 \wedge \mathbb{I}e\mathbb{I} = 1$$



$$\mathbb{I}x \geq y\mathbb{I} = 1$$

- $\mathbb{I}F\mathbb{I}(v, [0, 2]) = \text{tt}$
- $\mathbb{I}F\mathbb{I}(v, [1, 2]) = \text{ff}$
- $\mathbb{I}F\mathbb{I}(v, [0, 1]) = \text{tt}$
- $\mathbb{I}F\mathbb{I}(v, [1, 1]) = \text{tt}$
- $\mathbb{I}F\mathbb{I}(v, [0, 0]) = \text{tt}$
- $\mathbb{I}F\mathbb{I}(v, [0, 1]) = \text{tt}$
- $\mathbb{I}F\mathbb{I}(v, [1, 1]) = \text{tt}$
- $\mathbb{I}F\mathbb{I}(v, [1, 2]) = \text{ff}$
- $\mathbb{I}F\mathbb{I}(v, [2, 2]) = \text{ff}$
- $\mathbb{I}F\mathbb{I}(v, [2, 3]) = \text{ff}$
- $\mathbb{I}F\mathbb{I}(v, [3, 3]) = \text{ff}$
- $\mathbb{I}F\mathbb{I}(v, [3, 4]) = \text{ff}$
- $\mathbb{I}F\mathbb{I}(v, [4, 4]) = \text{ff}$

References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automate Verification*. Cambridge University Press.