

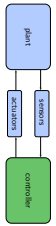
Real-Time Systems
Lecture 08: DC Implementables
 2012-06-12
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Contents & Goals

- Last Lectures:**
 - (Un)decidability results for fragments of DC in discrete and continuous time.
- This Lecture:**
 - Educational Objectives:** Capabilities for following tasks/ questions.
 - What does this standard forms mean? Give a satisfying interpretation.
 - What are implementables? What is a control automaton?
 - Please specify (and prove correct) a controller which satisfies this requirement.
 - Content:**
 - DC Standard Forms
 - Control Automata
 - DC Implementables
 - Example

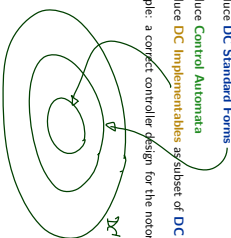
Requirements vs. Implementations

- Problem:** in general, a DC requirement doesn't tell **how** to achieve it, how to build a controller/write a program which ensures it.
- What a controller (clearly) can do is:
 - consider inputs now,
 - change (local) state, or
 - wait,
 - set outputs now.
 (But not, e.g., consider future inputs now.)
- So, if we have
 - a DC requirement "Req",
 - a description "Impl" in DC,
 - which uses **just these** operations,
 then
 - proving correctness amounts to proving $\models \text{Impl} \implies \text{Req}$ (in DC)
 - and we (more or less) know how to program (the correct) "Impl" in a PL/C language, or in C on a real-time OS, or or...



Approach: Control Automata and DC Implementables

- Plan:**
 - Introduce **DC Standard Forms**
 - Introduce **Control Automata**
 - Introduce **DC Implementables** as subset of **DC Standard Forms**
- Example: a correct controller design for the notorious Gas Burner



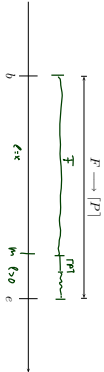
DC Implementables

DC Standard Forms: Followed-by

- In the following: F a DC formula, P a state assertion, θ a rigid term.
- Followed-by:**

$$F \rightarrow [P] \iff \neg \langle F \rangle ; [-P] \iff \Box \neg (F ; [-P])$$
- in other symbols

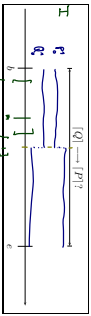
$$\forall x \bullet \Box ((F \wedge \ell = x) ; t > 0 \implies (F \wedge \ell = x) ; [P] ; ! \mu)$$



DC Implementables
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DC Standard Form: Followed-by Examples

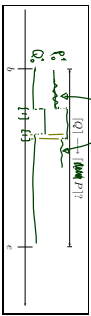
$$\forall x \bullet \Box((F \wedge \ell = x) : t > 0 \implies (F \wedge \ell = x) : [P] ; true)$$



↳ I on [b,e] does not satisfy [Q] → 9P7

DC Standard Form: Followed-by Examples

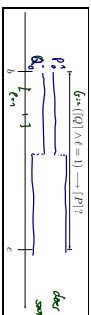
$$\forall x \bullet \Box((F \wedge \ell = x) : t > 0 \implies (F \wedge \ell = x) : [P] ; true)$$



[Q] → [Q ∨ 0]

DC Standard Form: Followed-by Examples

$$\forall x \bullet \Box((F \wedge \ell = x) : t > 0 \implies (F \wedge \ell = x) : [P] ; true)$$

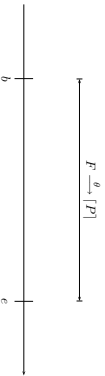


does not satisfy for any in-between of P

DC Standard Form: (Timed) leads-to

- (Timed) leads-to: $F \xrightarrow{\theta} P$

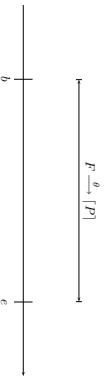
$$F \xrightarrow{\theta} [P] \iff (F \wedge \ell = \theta) \rightarrow [P]$$



DC Standard Form: (Timed) up-to

- (Timed) up-to: $F \xrightarrow{\leq \theta} P$

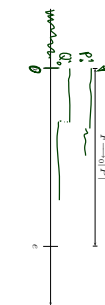
$$F \xrightarrow{\leq \theta} [P] \iff (F \wedge \ell \leq \theta) \rightarrow [P]$$



DC Standard Form: Initialisation

- Followed-by-Initially: $F \xrightarrow{-\theta} P$

$$F \xrightarrow{-\theta} [P] \iff \neg(F : \neg P)$$



- (Timed) up-to-Initially: $F \xrightarrow{\leq -\theta} P$
- Initialisation: $\Box \vee [P] ; true$

$$F \xrightarrow{\leq -\theta} [P] \iff (F \wedge \ell \leq \theta) \rightarrow \neg P$$

- Let X_1, \dots, X_k be k state variables ranging over finite domains $D(X_1), \dots, D(X_k)$.
- With a DC formula 'impl' ranging over X_1, \dots, X_k we have a system of k control automata.
- 'impl' is typically a conjunction of DC implementables.
- A state assertion of the form $X_i = d_i, d_i \in D(X_i)$, which constrains the values of X_i , is called **basic phase** of X_i .
- A phase of X_i is a Boolean combination of basic phases of X_i .

- Abbreviations:**
- Write X_i instead of $X_i = 1$, if X_i is Boolean.
- Write d_i instead of $X_i = d_i$, if $D(X_i)$ is disjoint from $D(X_j), i \neq j$.

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Model of Gas Burner controller as a system of four control automata:

- H Boolean, representing **heat request**, (input)
- F Boolean, representing **flame**, (input)
- C with $D(C) = \{\text{idle, purge, ignite, burn}\}$, representing the (status of the) controller, (local)
- G Boolean, representing **gas valve**, (output)

- Basic phase** of C : $C = \text{purge}$ (or only: purge)
- Phase** of C : $\text{purge} \vee \text{idle}$

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- DC Implementables are special patterns of DC Standard Forms (due to A.P. Ravn)
- Within one pattern, $\pi, \pi_1, \dots, \pi_n, n \geq 0$, denote **phases** of the same state variable X_i .
- φ denotes a state assertion not depending on X_i .
- θ denotes a **rigid** term.

- Initialization:** $\llbracket \vee [\pi] \rrbracket : true$
- Sequencing:** $[\pi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$
- Progress:** $[\pi] \xrightarrow{\theta} [\pi]$
- Synchronisation:** $[\pi \wedge \varphi] \xrightarrow{\theta} [\pi]$

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DC Implementables Cont'd

- Bounded Stability:** $[\neg \pi] \vdash [\pi \wedge \varphi] \xrightarrow{\leq \theta} [\pi \vee \pi_1 \vee \dots \vee \pi_n]$
- Unbounded Stability:** $[\neg \pi] : [\pi \wedge \varphi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$
- Bounded initial stability:** $[\pi \wedge \varphi] \xrightarrow{\leq \theta_0} [\pi \vee \pi_1 \vee \dots \vee \pi_n]$
- Unbounded initial stability:** $[\pi \wedge \varphi] \longrightarrow_{\theta_0} [\pi \vee \pi_1 \vee \dots \vee \pi_n]$

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Specification by DC Implementables

- Let 'impl' and X_1, \dots, X_k be a system of k control automata.
- Let 'impl' be a conjunction of DC implementables.
- Then 'impl' specifies all interpretations Z of X_1, \dots, X_k and all valuations γ such that $Z, \gamma \models_{\theta} \text{impl}$
- Hmm: And what does this have to do with controllers...?

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Example: Gas Burner

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Recall: Control Automata

Model of Gas Burner controller as a system of four control automata:

- H : Boolean, representing heat request;
- F : Boolean, representing flame;
- C with $D(C) = \{idle, purge, ignite, burn\}$, representing the controller;
- G : Boolean, representing gas valve.

(input) (input) (local) (output)

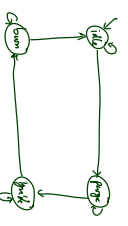
Gas Burner Controller Specification: Timed

$\square \vee [idle] : true, \square \vee [F] : true, \square \vee [G] : true$
 $[idle] \xrightarrow{0.5 \leq t \leq 1} [idle \vee purge]$
 $[purge] \xrightarrow{0.5 \leq t \leq 1} [ignite \vee burn]$
 $[burn] \xrightarrow{0.5 \leq t \leq 1} [burn \vee idle]$
 $[purge] \xrightarrow{0.5 \leq t \leq 1} [purge]$
 $[idle \wedge H] \xrightarrow{0.5 \leq t \leq 1} [idle]$
 $[burn \wedge (\neg H \vee \neg F)] \xrightarrow{0.5 \leq t \leq 1} [burn]$
 $[G \wedge (idle \vee purge)] \xrightarrow{0.5 \leq t \leq 1} [G]$
 $[idle \wedge \neg G] \xrightarrow{0.5 \leq t \leq 1} [idle]$
 $[purge] : [purge] \xrightarrow{0.5 \leq t \leq 1} [purge]$
 $[ignite] : [ignite] \xrightarrow{0.5 \leq t \leq 1} [ignite]$
 $[burn] : [burn \wedge H \wedge F] \xrightarrow{0.5 \leq t \leq 1} [burn]$
 $[F] : [F \wedge \neg G] \xrightarrow{0.5 \leq t \leq 1} [F]$
 $[G] : [G \wedge (idle \vee purge)] \xrightarrow{0.5 \leq t \leq 1} [G]$
 $[G] : [G \wedge (burn \vee idle)] \xrightarrow{0.5 \leq t \leq 1} [G]$

Gas Burner Controller Specification: Untimed

$\square \vee [idle] : true$
 $[idle] \xrightarrow{} [idle \vee purge]$
 $[purge] \xrightarrow{} [ignite \vee burn]$
 $[ignite] \xrightarrow{} [ignite \vee burn]$
 $[burn] \xrightarrow{} [burn \vee idle]$

(Init-1) (Seq-1) (Seq-2) (Seq-3) (Seq-4)



Gas Burner Controller Specification: Timing

$[purge] \xrightarrow{0.5 \leq t \leq 1} [purge]$
 $[ignite] \xrightarrow{0.5 \leq t \leq 1} [ignite]$
 $[burn] \xrightarrow{0.5 \leq t \leq 1} [burn]$
 $[idle \wedge H] \xrightarrow{0.5 \leq t \leq 1} [idle]$
 $[burn \wedge (\neg H \vee \neg F)] \xrightarrow{0.5 \leq t \leq 1} [burn]$
 $[G \wedge (idle \vee purge)] \xrightarrow{0.5 \leq t \leq 1} [G]$
 $[idle \wedge \neg G] \xrightarrow{0.5 \leq t \leq 1} [idle]$
 $[purge] : [purge] \xrightarrow{0.5 \leq t \leq 1} [purge]$
 $[ignite] : [ignite] \xrightarrow{0.5 \leq t \leq 1} [ignite]$

(Prog-1) (Prog-2) (Stab-2) (Stab-3)



Fig. 1: (Idle state) (Purge state)
 Fig. 2: (Stab-2: C/P) (Stab-3: H)
 (Stab-1: idle) (Stab-2: idle) (Stab-3: idle)

Gas Burner Controller Specification: Outputs

$[G \wedge (idle \vee purge)] \xrightarrow{0.5 \leq t \leq 1} [G]$
 $[G] : [G \wedge (ignite \vee burn)] \xrightarrow{0.5 \leq t \leq 1} [G]$
 $[G] : [G \wedge (idle \vee purge)] \xrightarrow{0.5 \leq t \leq 1} [G]$
 $[G] : [G \wedge (idle \vee purge)] \xrightarrow{0.5 \leq t \leq 1} [G]$
 $[G] : [G \wedge (burn \vee idle)] \xrightarrow{0.5 \leq t \leq 1} [G]$

(Syn-3) (Syn-4) (Stab-6) (Stab-7)



Gas Burner Controller Specification: Inputs

$[idle \wedge H] \xrightarrow{0.5 \leq t \leq 1} [idle]$
 $[burn \wedge (\neg H \vee \neg F)] \xrightarrow{0.5 \leq t \leq 1} [burn]$
 $[idle] : [idle \wedge \neg H] \xrightarrow{0.5 \leq t \leq 1} [idle]$
 $[idle \wedge \neg H] \xrightarrow{0.5 \leq t \leq 1} [idle]$
 $[burn] : [burn \wedge H \wedge F] \xrightarrow{0.5 \leq t \leq 1} [burn]$

(Syn-1) (Syn-2) (Stab-1) (Stab-1-imp) (Stab-4)

Gas Burner Controller Specification: Assumptions

- $\Box \vee \neg \text{init}1; \text{true}$ (Init-2)
- $\Box \vee \neg \text{init}2; \text{true}$ (Init-3)
- $\Box \vee \neg \text{init}3; \text{true}$ (Init-4)
- $[F1] : \neg F1 \wedge \neg \text{ignite} \rightarrow \neg F1$ (Stab-5)
- $\neg F1 \wedge \neg \text{ignite} \rightarrow \neg F1$ (Stab-5-Inv)

Goal p
 $\neg \text{Stab} \wedge \neg \text{ZS}$

Gas Burner Controller Correctness Proof

$$\text{GB-Ctrl} := \text{Init}1 \wedge \dots \wedge \text{Stab}7 \wedge \epsilon > 0$$

Recall:
 Req $\leftrightarrow \Box(\ell \geq 60 \Rightarrow 20 \cdot J.L \leq \ell)$
 and (cf [Olderog and Dierks, 2008])
 $\models \text{Req}1 \Rightarrow \text{Req}$

for the simplified

$$\text{Req}1 := \Box(\ell \leq 30 \Rightarrow J.L \leq 1)$$

Here we show

$$\models \text{GB-Ctrl} \wedge A(\epsilon) \Rightarrow \text{Req}1$$

Lemma 3.15

$$\models \text{GB-Ctrl} \Rightarrow \Box \left(\begin{array}{l} (\text{idle}) \Rightarrow J.G \leq \epsilon \\ \wedge (\text{purge}) \Rightarrow J.G \leq \epsilon \\ \wedge (\text{ignite}) \Rightarrow \ell \leq 0.5 + \epsilon \\ \wedge (\text{burn}) \Rightarrow J.F1 \leq 2\epsilon \end{array} \right)$$



Proof: Let \mathcal{I} be an interpretation, ν a valuation, and $[c, d]$ an interval with $\mathcal{I}, \nu, [c, d] \models \text{GB-Ctrl}$. Let $[k, d] \subseteq [c, d]$.

• Case 1: $\mathcal{I}, \nu, [k, d] \models \text{idle}$

$$[\mathcal{I} \wedge (\text{idle} \vee \text{purge})] \xrightarrow{c} \neg \text{C1} \quad (\text{Syn-3})$$

$$[\mathcal{I}] : \neg \text{C} \wedge (\text{idle} \vee \text{purge}) \rightarrow \neg \text{C1} \quad (\text{Stab-6})$$

Goal
 $\mathcal{I}, \nu, [k, d] \models \Box([\mathcal{I}] \Rightarrow \ell \leq \epsilon) \wedge \neg \Box([\mathcal{I}] : \neg \text{C1}) : [\mathcal{I}]$

• Case 2: $\mathcal{I}, \nu, [k, d] \models \text{purge}$ Analogously to case 1.

Lemma 3.15 Cont'd

$(\text{idle}) \Rightarrow J.G \leq \epsilon$
$(\text{purge}) \Rightarrow J.G \leq \epsilon$
$(\text{ignite}) \Rightarrow \ell \leq 0.5 + \epsilon$
$(\text{burn}) \Rightarrow J.F1 \leq 2\epsilon$

• Case 3: $\mathcal{I}, \nu, [k, d] \models \text{ignite}$
 $\models \text{ignite} \Rightarrow \text{ignite} \quad (\text{Prog-2})$

$$\mathcal{I}, \nu, [k, d] \models \ell \leq 0.5 + \epsilon$$

• Case 4: $\mathcal{I}, \nu, [k, d] \models \text{burn}$

$$\begin{array}{l} \text{burn} \wedge (\neg \text{F1} \vee \neg \text{F2}) \xrightarrow{c} \neg \text{burn} \\ [F1] : \neg F1 \wedge \neg \text{ignite} \rightarrow \neg F1 \end{array} \quad \begin{array}{l} (\text{Syn-2}) \\ (\text{Stab-5}) \end{array}$$

$\mathcal{I}, \nu, [k, d] \models \Box(\neg F1) \Rightarrow \ell \leq \epsilon) \wedge \neg \Box([\mathcal{I}] : \neg F1) : [\mathcal{I}]$

References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automate Verification*. Cambridge University Press.