

Real-Time Systems

Lecture 15: The Universality Problem for TBA

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Contents & Goals

Last Lecture:

- Extended Timed Automata

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What's a TBA and what's the difference to (extended) TA?
 - What's undecidable for timed (Büchi) automata?
 - What's the idea of the proof?
- **Content:**
 - Uppaal Query Language
 - Timed Büchi Automata and timed regular languages [Alur and Dill, 1994].
 - The Universality Problem is undecidable for TBA [Alur and Dill, 1994]
 - Why this is unfortunate.
 - Timed regular languages are not everything.

The Logic of Uppaal

The Uppaal Fragment of Timed Computation Tree Logic

Consider $\mathcal{N} = \mathcal{C}(\mathcal{A}_1, \dots, \mathcal{A}_n)$ over data variables V .

- **basic formula:**

$$atom ::= \mathcal{A}_i.l \mid \varphi$$

where $l \in L_i$ is a location and φ a constraint over X_i and V .

- **configuration formulae:**

$$term ::= atom \mid \neg term \mid term_1 \wedge term_2$$

- **existential path formulae:** (“exists finally”, “exists globally”)

$$e\text{-formula} ::= \exists \diamond term \mid \exists \square term$$

- **universal path formulae:** (“always finally”, “always globally”, “leads to”)

$$a\text{-formula} ::= \forall \diamond term \mid \forall \square term \mid term_1 \longrightarrow term_2$$

- **formulae:**

$$F ::= e\text{-formula} \mid a\text{-formula}$$

Configurations at Time t

- Recall: **computation path** (or path) **starting in** $\langle \vec{\ell}_0, \nu_0 \rangle, t_0$:

$$\xi = \langle \vec{\ell}_0, \nu_0 \rangle, t_0 \xrightarrow{\lambda_1} \langle \vec{\ell}_1, \nu_1 \rangle, t_1 \xrightarrow{\lambda_2} \langle \vec{\ell}_2, \nu_2 \rangle, t_2 \xrightarrow{\lambda_3} \dots$$

which is **infinite or maximally finite**.

- Given ξ and $t \in \text{Time}$, we use $\xi(t)$ to denote the set

$$\{ \langle \vec{\ell}, \nu \rangle \mid \exists i \in \mathbb{N}_0 : t_i \leq t \leq t_{i+1} \wedge \vec{\ell} = \vec{\ell}_i \wedge \nu = \nu_i + t - t_i \}.$$

of **configurations at time t** .

- Why is it a set?
- Can it be empty?

$$\xi(0) = \{ \langle \vec{\ell}_0, \nu_0 \rangle \}$$

$$\xi(0.2) = \{ \langle \vec{\ell}_0, \nu_0 + 0.2 \rangle \}$$

$$\xi(3.0) = \{ \langle \vec{\ell}_1, \nu_1 \rangle, \langle \vec{\ell}_2, \nu_2 \rangle \}$$

Satisfaction of Uppaal-Logic by Configurations

- We define a **satisfaction relation**

$$\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \models F$$

between **time stamped configurations**

$$\langle \vec{\ell}_0, \nu_0 \rangle, t_0$$

of a network $\mathcal{C}(\mathcal{A}_1, \dots, \mathcal{A}_n)$ and **formulae** F of the Uppaal logic.

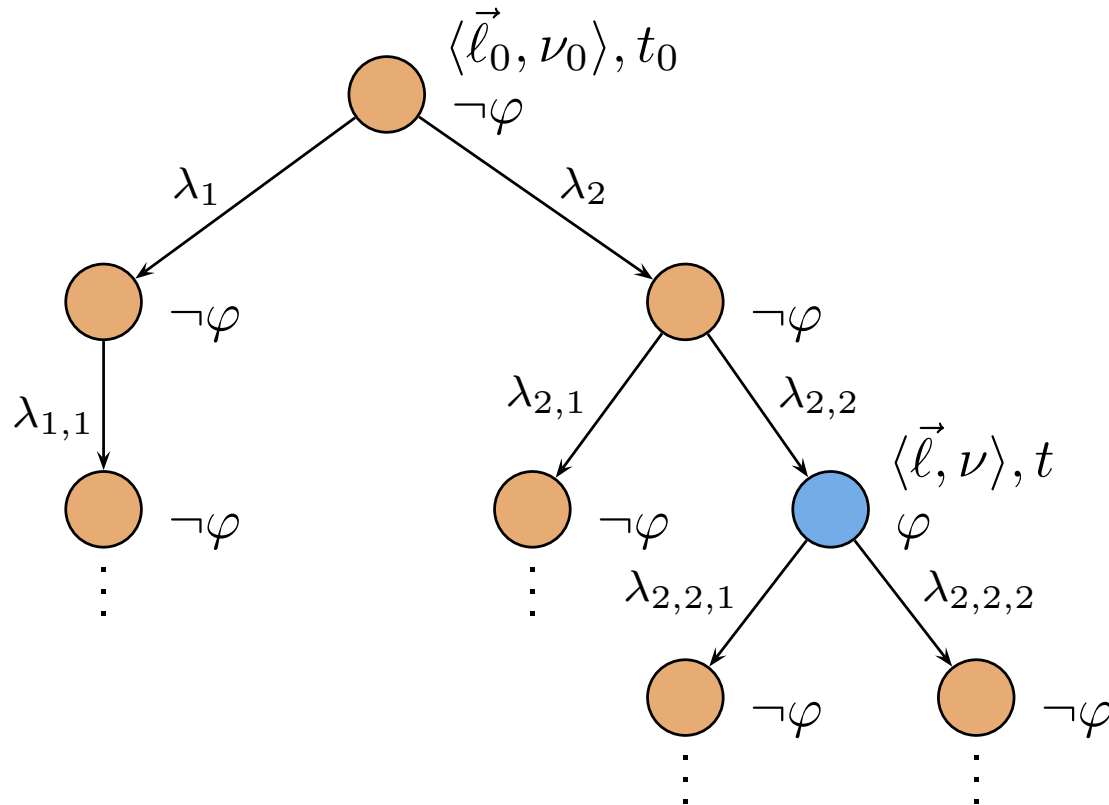
- It is defined inductively as follows:
 - $\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \models \mathcal{A}_i.l$ iff $\ell_{0,i} = l$ *(i -th location in $\vec{\ell}_0$)*
 - $\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \models \varphi$ iff $\nu_0 \models \varphi$
 - $\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \models \neg term$ iff $\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \not\models term$
 - $\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \models term_1 \wedge term_2$ iff $\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \models term_i, i=1,2$

Satisfaction of Uppaal-Logic by Configurations

Exists finally:

- $\langle \vec{\ell}_0, \nu_0 \rangle, t_0 \models \exists \diamond term$ iff \exists path ξ of \mathcal{N} starting in $\langle \vec{\ell}_0, \nu_0 \rangle, t_0$
 $\exists t \in \text{Time}, \langle \vec{\ell}, \nu \rangle \in \text{Conf} :$
 $t_0 \leq t \wedge \langle \vec{\ell}, \nu \rangle \in \underline{\xi}(t) \wedge \langle \vec{\ell}, \nu \rangle, t \models term$

Example: $\exists \diamond \varphi$



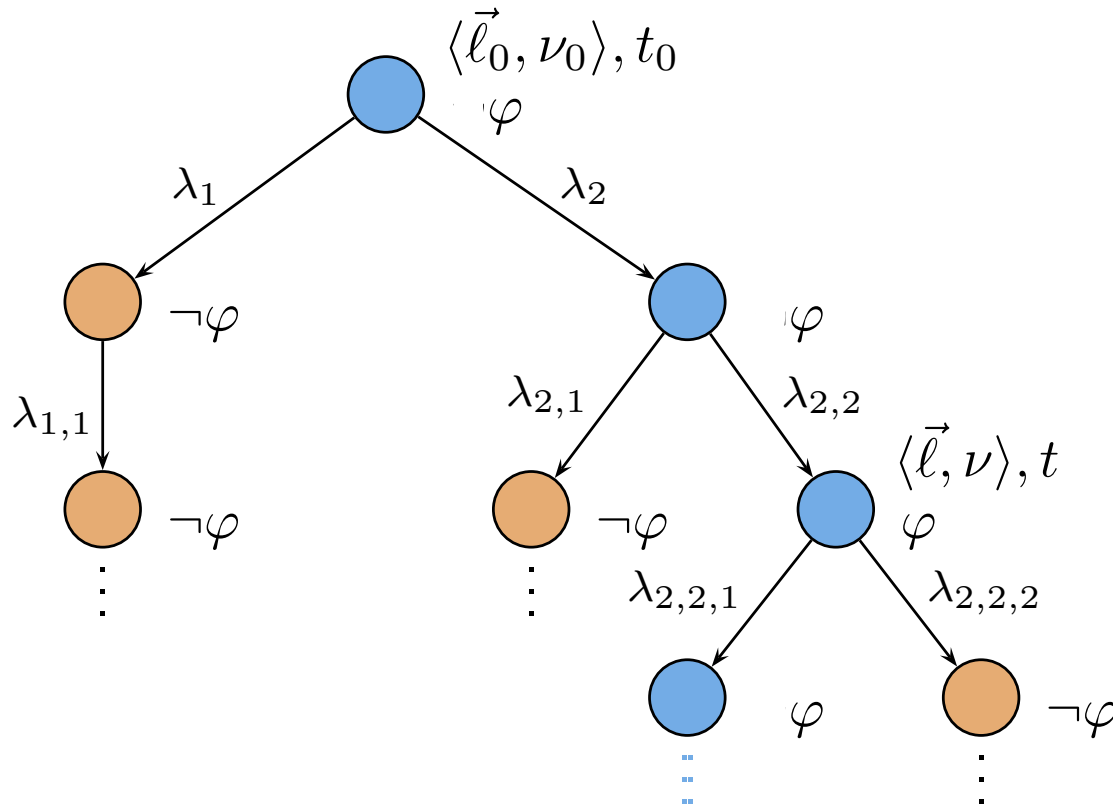
Satisfaction of Uppaal-Logic by Configurations

Exists globally:

- $\langle \vec{l}_0, \nu_0 \rangle, t_0 \models \exists \square \text{ term}$ iff \exists path ξ of \mathcal{N} starting in $\langle \vec{l}_0, \nu_0 \rangle, t_0$
 $\forall t \in \text{Time}, \langle \vec{l}, \nu \rangle \in \text{Conf} :$
 $t_0 \leq t \wedge \langle \vec{l}, \nu \rangle \in \xi(t) \implies \langle \vec{l}, \nu \rangle, t \models \text{term}$

note: universally quantifying over elements in $\xi(t)$

Example: $\exists \square \varphi$



Satisfaction of Uppaal-Logic by Configurations

- **Always finally:** $\langle \vec{l}_0, \nu_0 \rangle, t_0 \models \forall \diamond term$ iff $\langle \vec{l}_0, \nu_0 \rangle, t_0 \not\models \exists \square \neg term$
Handwritten annotations: "∀ path" above the first ∀, "∃ t ∈ Time" above the ∃.

- **Always globally:** $\langle \vec{l}_0, \nu_0 \rangle, t_0 \models \forall \square term$ iff $\langle \vec{l}_0, \nu_0 \rangle, t_0 \not\models \exists \diamond \neg term$
Handwritten annotations: "∀ path" below the first ∀, "∀ t ∈ Time" below the second ∀.

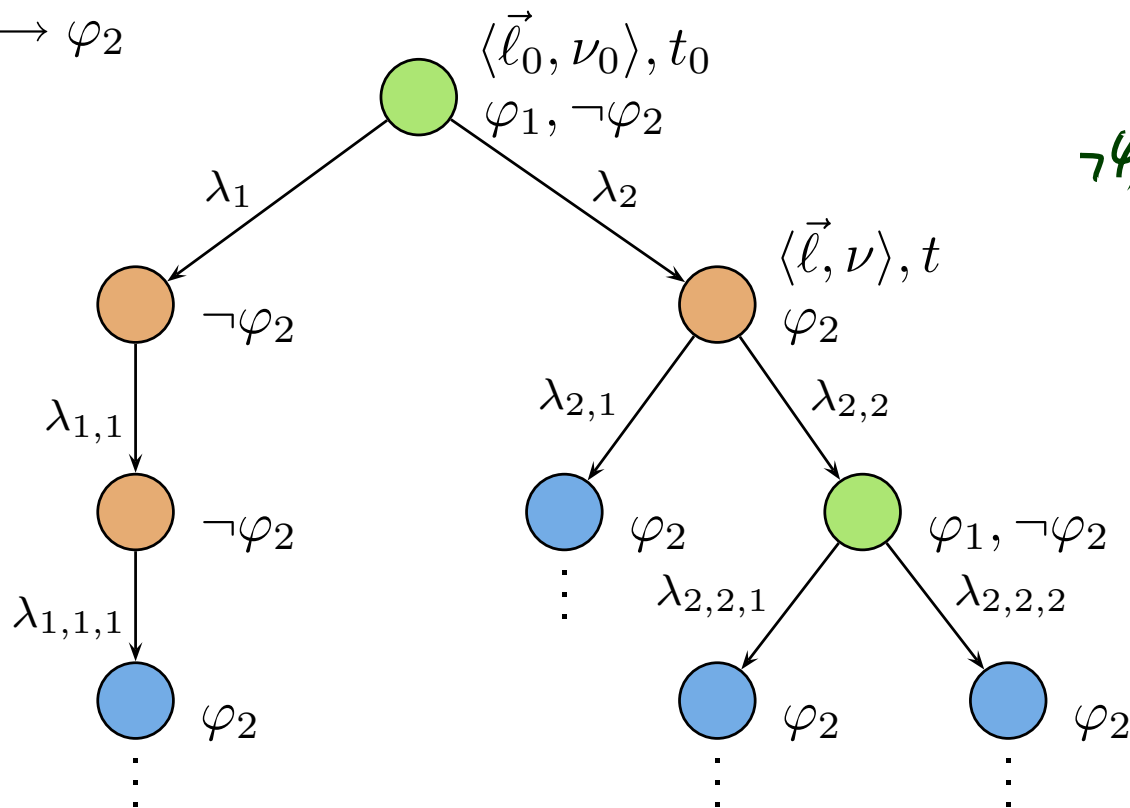
Satisfaction of Uppaal-Logic by Configurations

CTL: $AG(\text{term}_1 \Rightarrow AF\text{term}_2)$

Leads to:

- $\langle \vec{l}_0, \nu_0 \rangle, t_0 \models \text{term}_1 \xrightarrow{\text{not DC (of cause)}} \text{term}_2$ iff \forall path ξ of \mathcal{N} starting in $\langle \vec{l}_0, \nu_0 \rangle, t_0$
 - $\forall t \in \text{Time}, \langle \vec{l}, \nu \rangle \in \text{Conf} :$
 - $t_0 \leq t \wedge \langle \vec{l}, \nu \rangle \in \xi(t)$
 - $\wedge \langle \vec{l}, \nu \rangle, t \models \text{term}_1$
 - implies $\langle \vec{l}, \nu \rangle, t \models \forall \Diamond \text{term}_2$

Example: $\varphi_1 \longrightarrow \varphi_2$



$\neg\varphi_1$ if not given

Satisfaction of Uppaal-Logic by Networks

- We write

$$\mathcal{N} \models e\text{-formula}$$

if and only if

$$\text{for some } \langle \vec{\ell}_0, \nu_0 \rangle \in C_{ini}, \langle \vec{\ell}_0, \nu_0 \rangle, 0 \models e\text{-formula}, \quad (1)$$

and

$$\mathcal{N} \models a\text{-formula}$$

if and only if

$$\text{for all } \langle \vec{\ell}_0, \nu_0 \rangle \in C_{ini}, \langle \vec{\ell}_0, \nu_0 \rangle, 0 \models a\text{-formula}, \quad (2)$$

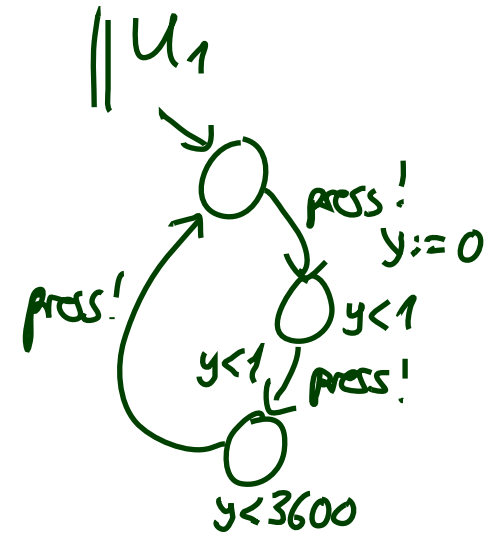
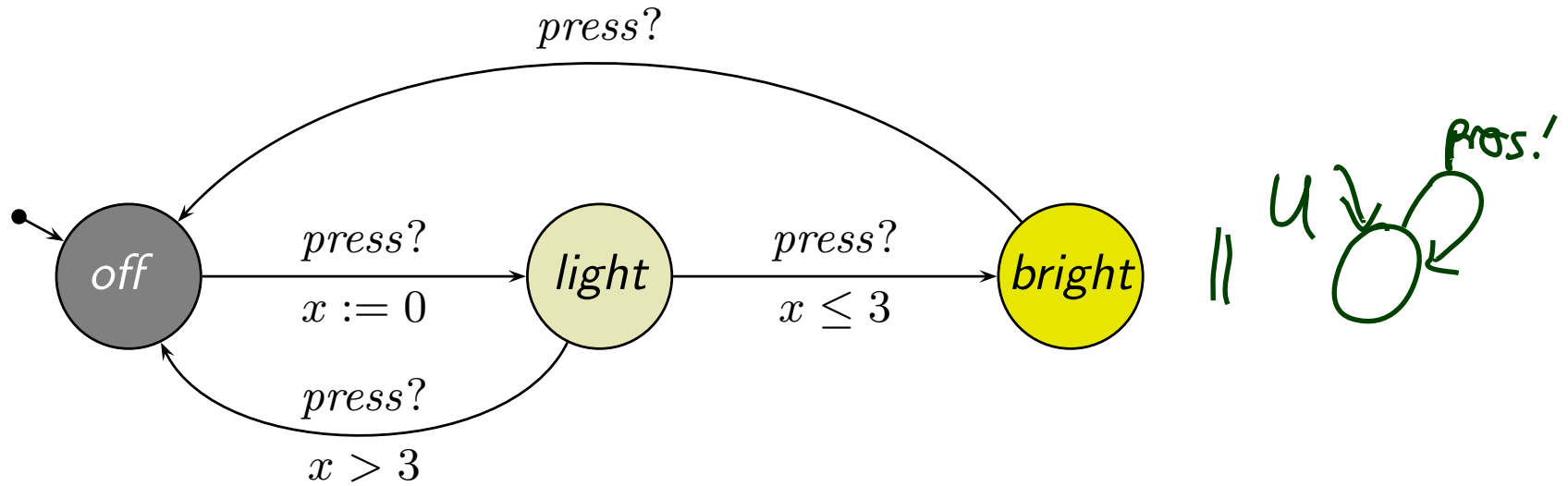
where C_{ini} are the initial configurations of $\mathcal{T}_e(\mathcal{N})$.

- If $C_{ini} = \emptyset$, (1) is a contradiction and (2) is a tautology.
- If $C_{ini} \neq \emptyset$, then

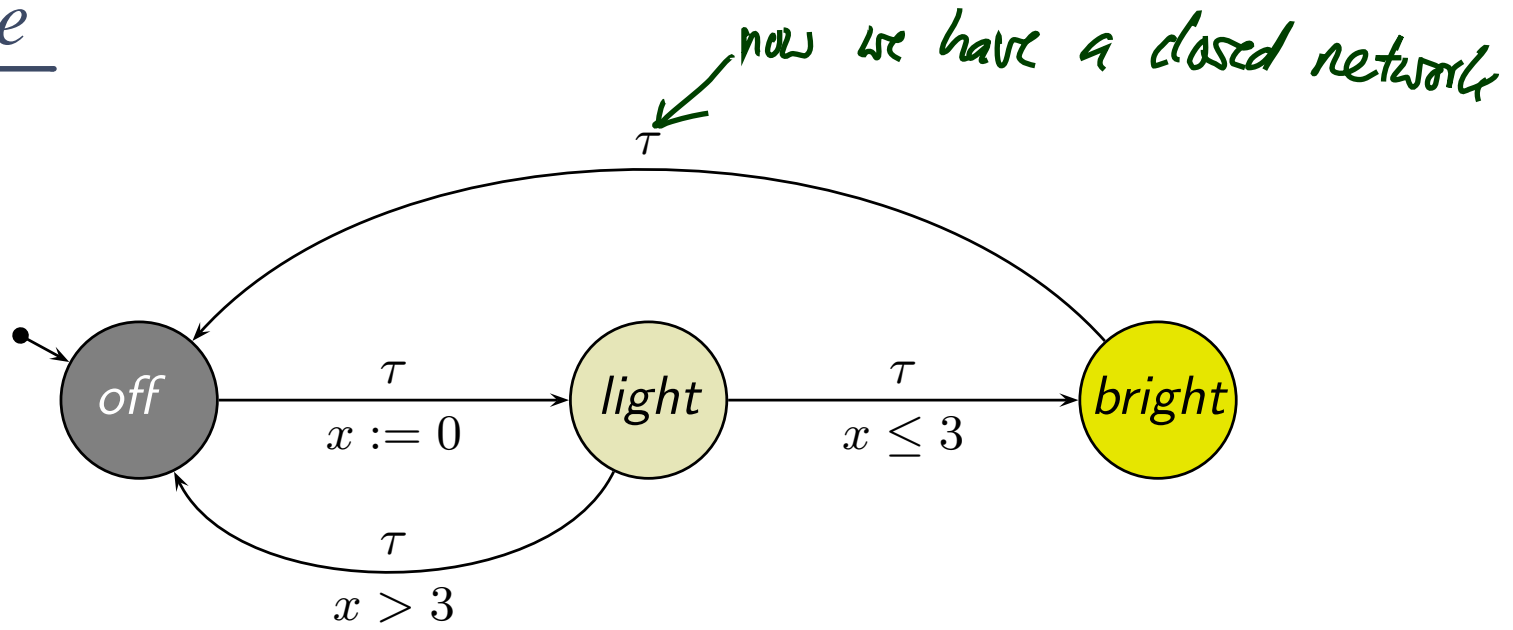
$$\mathcal{N} \models F \text{ if and only if } \langle \vec{\ell}_{ini}, \nu_{ini} \rangle, 0 \models F.$$

Example

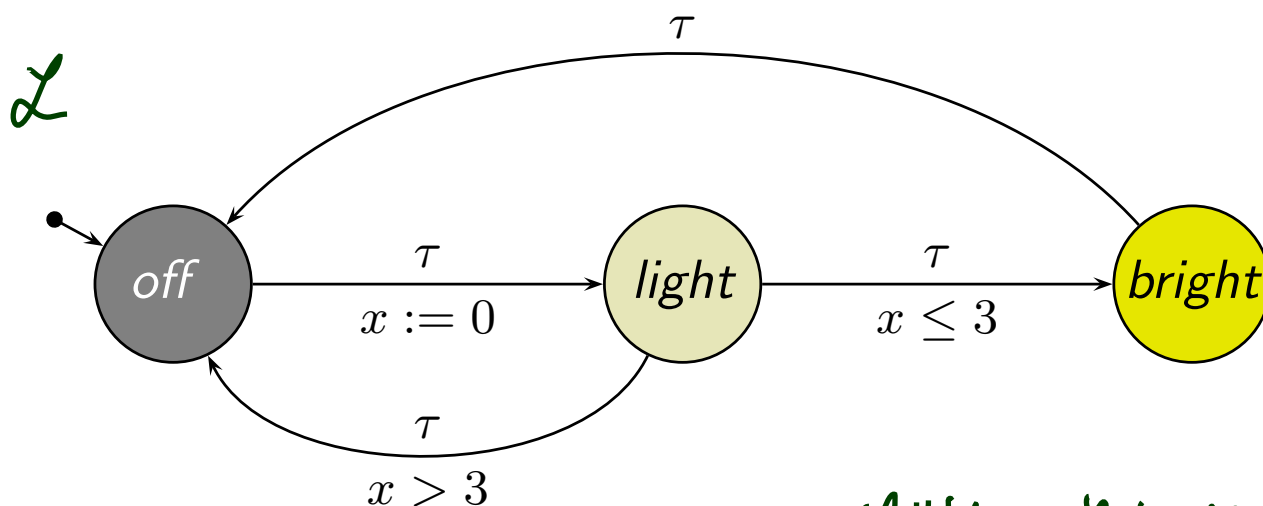
\mathcal{L}



Example



Example



because not satisfied in some zero paths

~~X~~ prev. Def

$\mathcal{L} \parallel U_1 \models \mathcal{L}.bright \rightarrow \mathcal{L}.off?$ *Uppaal*

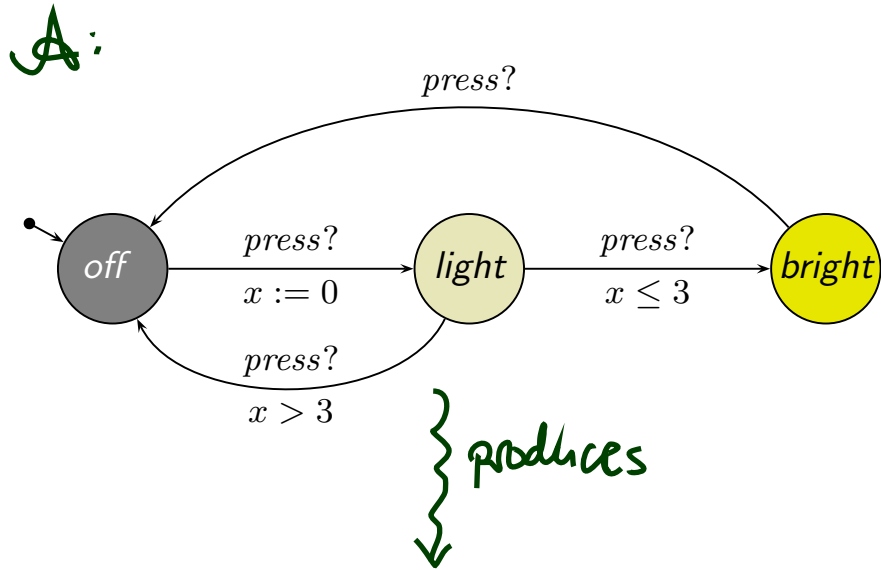
(because the tool uses \Rightarrow paths, not comp. paths actually)

- $\mathcal{N} \models \exists \diamond \mathcal{L}.bright?$
- $\mathcal{N} \models \exists \square \mathcal{L}.bright?$ (we must be in light before bright)
- $\mathcal{N} \models \exists \square \mathcal{L}.off?$ (*)
- $\mathcal{N} \models \forall \diamond \mathcal{L}.light?$ (because *)
- $\mathcal{N} \models \forall \square (\mathcal{L}.bright \Rightarrow x \geq 3)?$ (can have $\mathcal{L}.bright$ and $x < 3$)
- $\mathcal{N} \models \mathcal{L}.bright \rightarrow \mathcal{L}.off?$ ^{term}

Timed Büchi Automata

[Alur and Dill, 1994]

... vs. Timed Automata

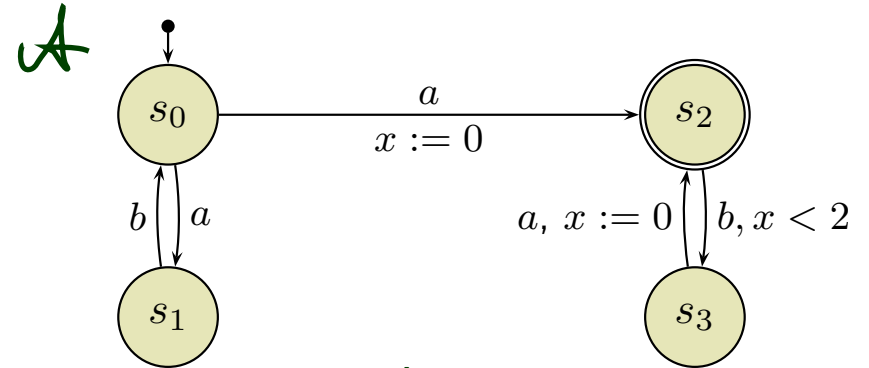


$$\xi = \langle \text{off}, 0 \rangle, 0 \xrightarrow{1} \langle \text{off}, 1 \rangle, 1$$

$$\xrightarrow{\text{press?}} \langle \text{light}, 0 \rangle, 1 \xrightarrow{3} \langle \text{light}, 3 \rangle, 4$$

$$\xrightarrow{\text{press?}} \langle \text{bright}, 3 \rangle, 4 \ddot{\rightarrow} \dots$$

ξ is a computation path and run of \mathcal{A} .



New: Given a **timed word** \uparrow **accept**

$(a, 1), (b, 2), (a, 3), (b, 4), (a, 5), (b, 6), \dots,$

does \mathcal{A} **accept** it?

New: acceptance criterion is **visiting accepting state infinitely often.**

Definition. A **time sequence** $\tau = \tau_1, \tau_2, \dots$ is an infinite sequence of time values $\tau_i \in \mathbb{R}_0^+$, satisfying the following constraints:

(i) **Monotonicity:**

τ increases **strictly** monotonically, i.e. $\tau_i < \tau_{i+1}$ for all $i \geq 1$.

(ii) **Progress:** For every $t \in \mathbb{R}_0^+$, there is some $i \geq 1$ such that $\tau_i > t$.

set of infinite words over Σ

Definition. A **timed word** over an alphabet Σ is a pair (σ, τ) where

- $\sigma = \sigma_1, \sigma_2, \dots \in \Sigma^\omega$ is an infinite word over Σ , and
- τ is a time sequence.

Definition. A **timed language** over an alphabet Σ is a set of timed words over Σ .

Example: Timed Language

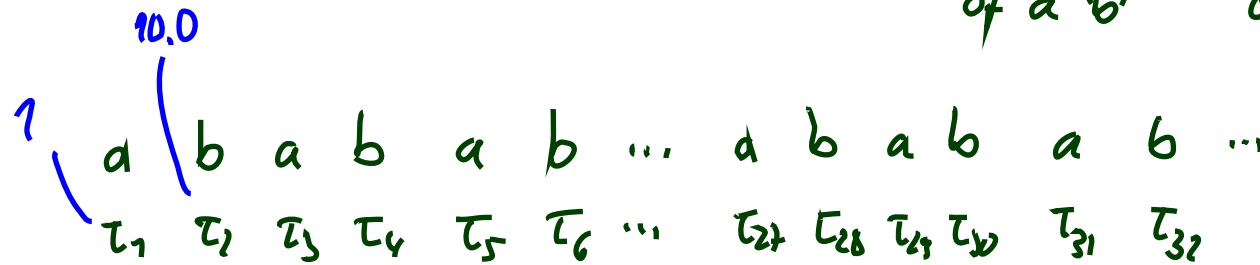
Timed word over alphabet Σ : a pair (σ, τ) where

- $\sigma = \sigma_1, \sigma_2, \dots$ is an infinite word over Σ , and
- τ is a time sequence (strictly (!) monotonic, non-Zeno).

a could be 'system beeps'
 b could be 'system flashes light'

$$L_{crt} = \{((ab)^\omega, \tau) \mid \exists i \forall j \geq i : (\tau_{2j} < \tau_{2j-1} + 2)\}$$

↑
 timestamp
 of a 'b'
 ↑
 timestamp
 of the 'a' before



$$\tau_{2j} < \tau_{2j+1} + 2$$

„but most (not including) 2 time units after the a before

Timed Büchi Automata

not simple! (negation, but no differences)

Definition. The set $\Phi(X)$ of **clock constraints** over X is defined inductively by

$$\delta ::= x \leq c \mid c \leq x \mid \neg\delta \mid \delta_1 \wedge \delta_2$$

where $x \in X$ and $c \in \mathbb{Q}$ is a rational constant.

Definition. A **timed Büchi automaton** (TBA) \mathcal{A} is a tuple $(\Sigma, S, S_0, X, E, F)$, where

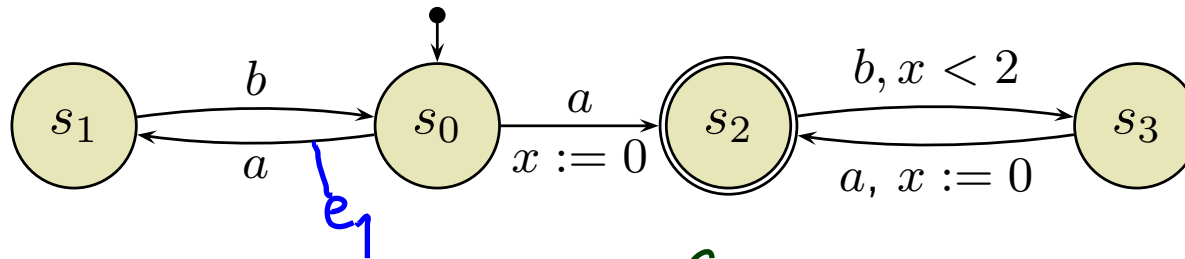
- Σ is an alphabet,
- S is a finite set of states, $S_0 \subseteq S$ is a set of start states,
- X is a finite set of clocks, and
- $E \subseteq S \times S \times \Sigma \times 2^X \times \Phi(X)$ gives the set of transitions.

An edge $(s, s', a, \lambda, \delta)$ represents a transition from state s to state s' on input symbol a . The set $\lambda \subseteq X$ gives the clocks to be reset with this transition, and δ is a clock constraint over X .

- $F \subseteq S$ is a set of **accepting states**.

Example: TBA

$$\mathcal{A} = (\Sigma, S, S_0, X, E, F)$$
$$(s, s', a, \lambda, \delta) \in E$$



- $\Sigma = \{a, b\}$

- $S = \{s_1, s_0, s_2, s_3\}$

- $S_0 = \{s_0\}$

- $X = \{x\}$

- $F = \{s_2\}$

$$E = \{ (s_0, s_1, a, \emptyset, true) = e_1, \\ (s_1, s_0, b, \emptyset, true), \\ (s_0, s_2, a, \{x\}, true), \\ (s_2, s_3, b, \emptyset, x < 2), \\ (s_3, s_2, a, \{x\}, true) \}$$

References

References

- [Alur and Dill, 1994] Alur, R. and Dill, D. L. (1994). A theory of timed automata. *Theoretical Computer Science*, 126(2):183–235.
- [Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.