

Real-Time Systems

Lecture 08: DC Implementables

2013-05-28

Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

Contents & Goals

Last Lectures:

- (Un)decidability results for fragments of DC
in discrete and continuous time.

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What does this standard forms mean? Give a satisfying interpretation.
 - What are implementables? What is a control automaton?
 - Please specify (and prove correct) a controller which satisfies this requirement.
- **Content:**
 - DC Standard Forms
 - Control Automata
 - DC Implementables
 - Example

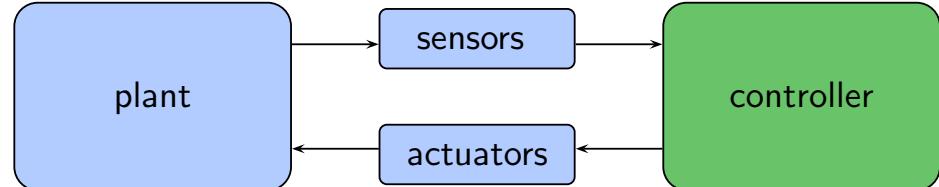
DC Implementables

Requirements vs. Implementations

- **Problem:** in general, a DC requirement doesn't tell **how** to achieve it, how to build a controller/write a program which ensures it.

- What a controller (clearly) can do is:

- consider inputs now,
- change (local) state, or
- wait,
- set outputs now.



(But not, e.g., consider future inputs now.)

- So, if we have

- a DC requirement '**Req**',
- a description '**Impl**' in DC,
which "uses" **just these** operations,

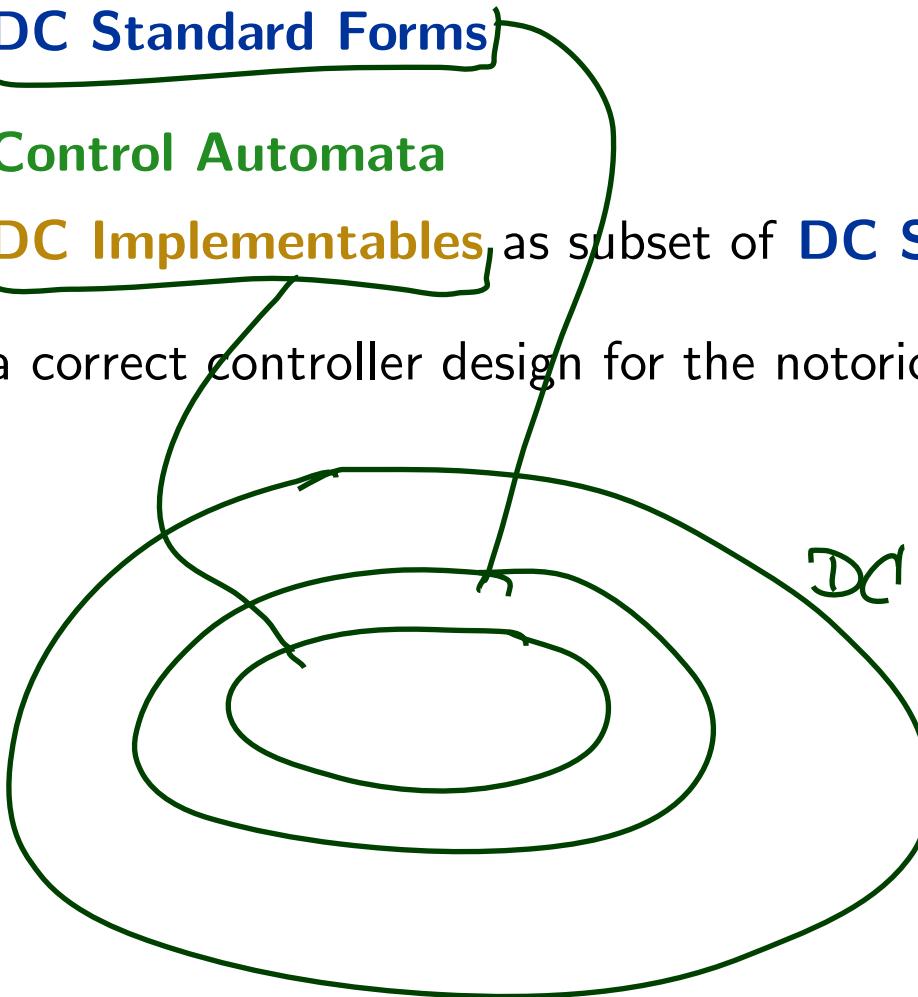
then

- proving correctness amounts to proving $\models_0 \text{Impl} \implies \text{Req}$ (**in DC**)
- and we (more or less) know how to program (the correct) '**Impl**'
in a PLC language, or in C on a real-time OS, or or or...

Approach: Control Automata and DC Implementables

Plan:

- Introduce **DC Standard Forms**
- Introduce **Control Automata**
- Introduce **DC Implementables** as subset of **DC Standard Forms**
- Example: a correct controller design for the notorious Gas Burner



DC Standard Forms: Followed-by

no ℓ ,
no ℓ'

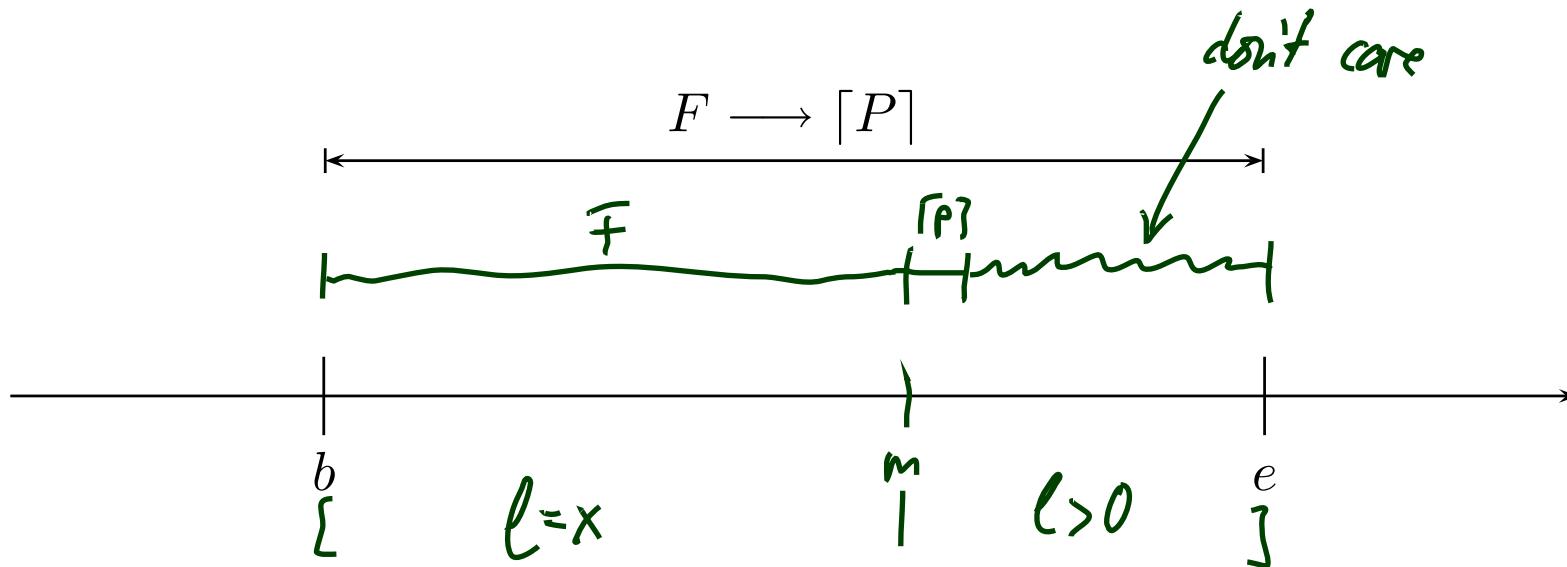
In the following: F is a DC **formula**, P a **state assertion**, θ a **rigid term**.

- **Followed-by:**

$$F \xrightarrow{P} : \iff \neg \Diamond(F ; \lceil \neg P \rceil) \iff \Box \neg(F ; \lceil \neg P \rceil)$$

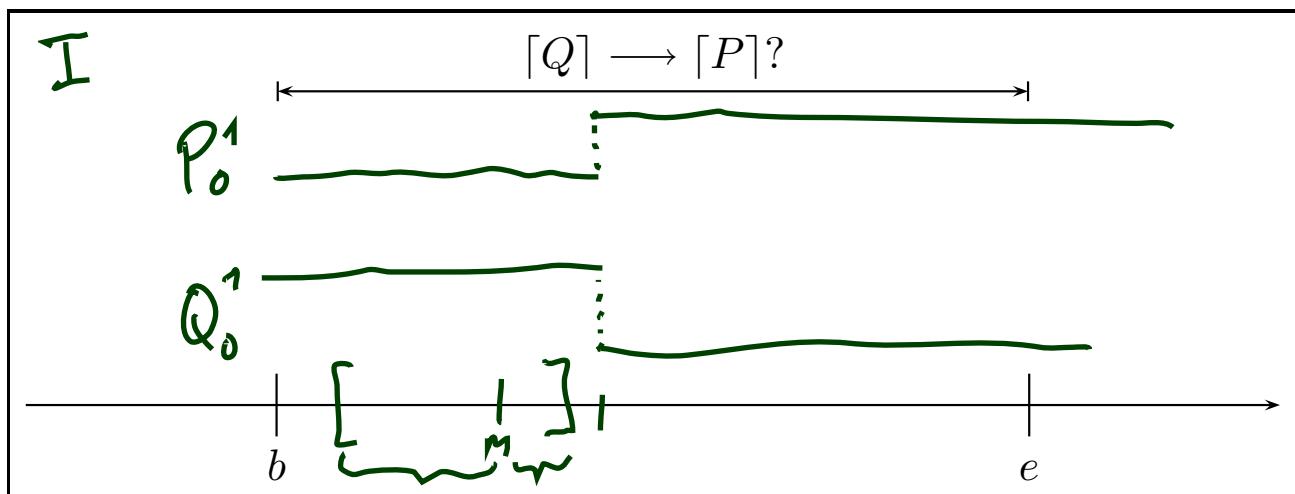
in other symbols

$$\forall x \bullet \Box((F \wedge \ell = x) ; \ell > 0 \implies (F \wedge \ell = x) ; \lceil P \rceil ; \text{true})$$

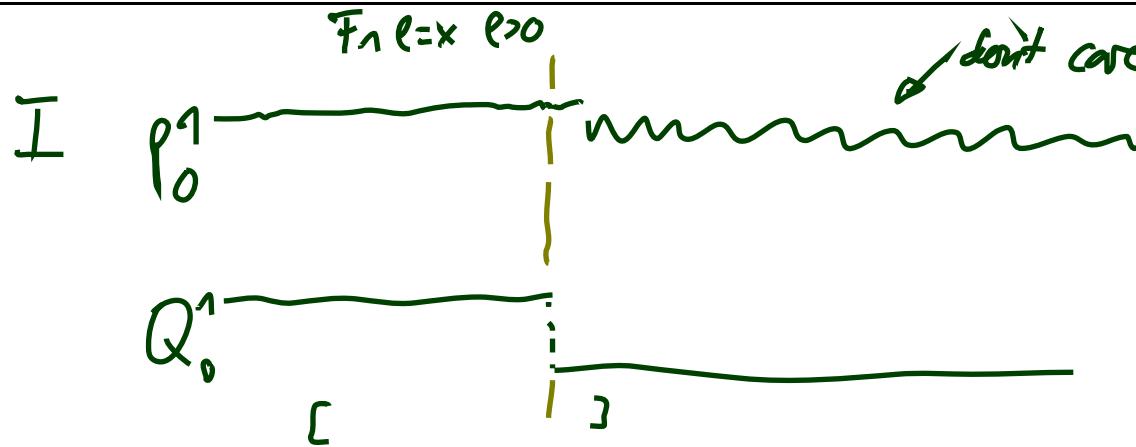


DC Standard Forms: Followed-by Examples

$$\forall x \bullet \square((F \wedge \ell = x) ; \ell > 0 \implies (F \wedge \ell = x) ; [P] ; \text{true})$$

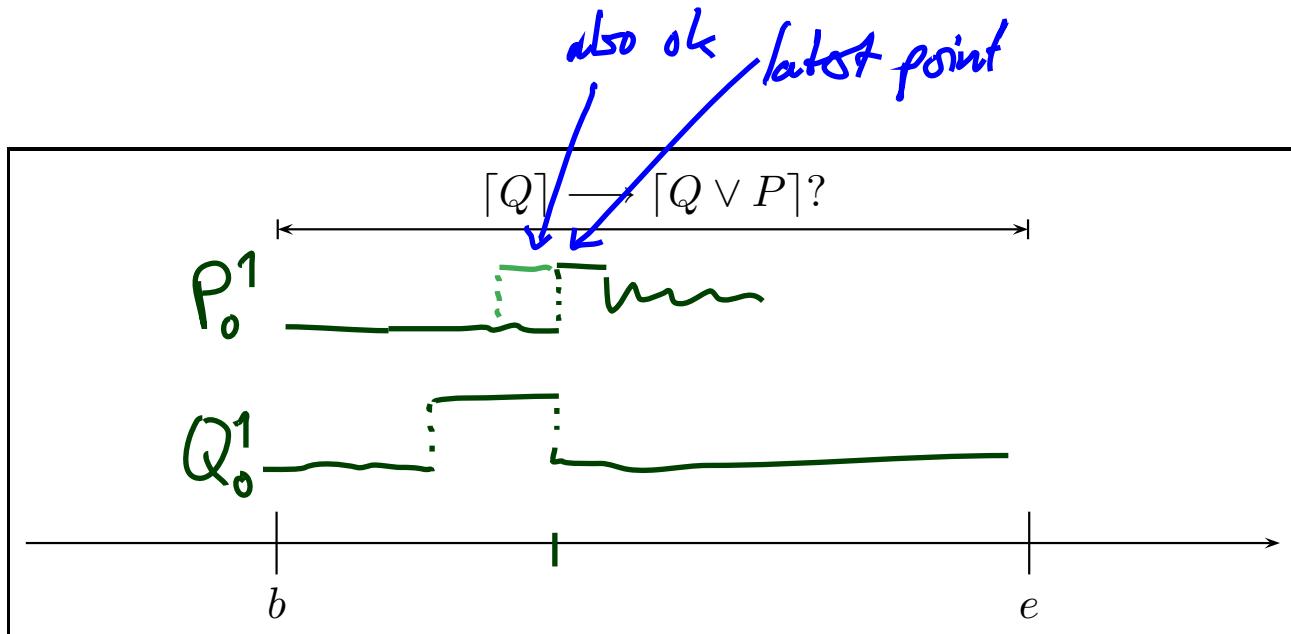


I on $\{b, e\}$
does not
satisfy
 $TQ \rightarrow TP$



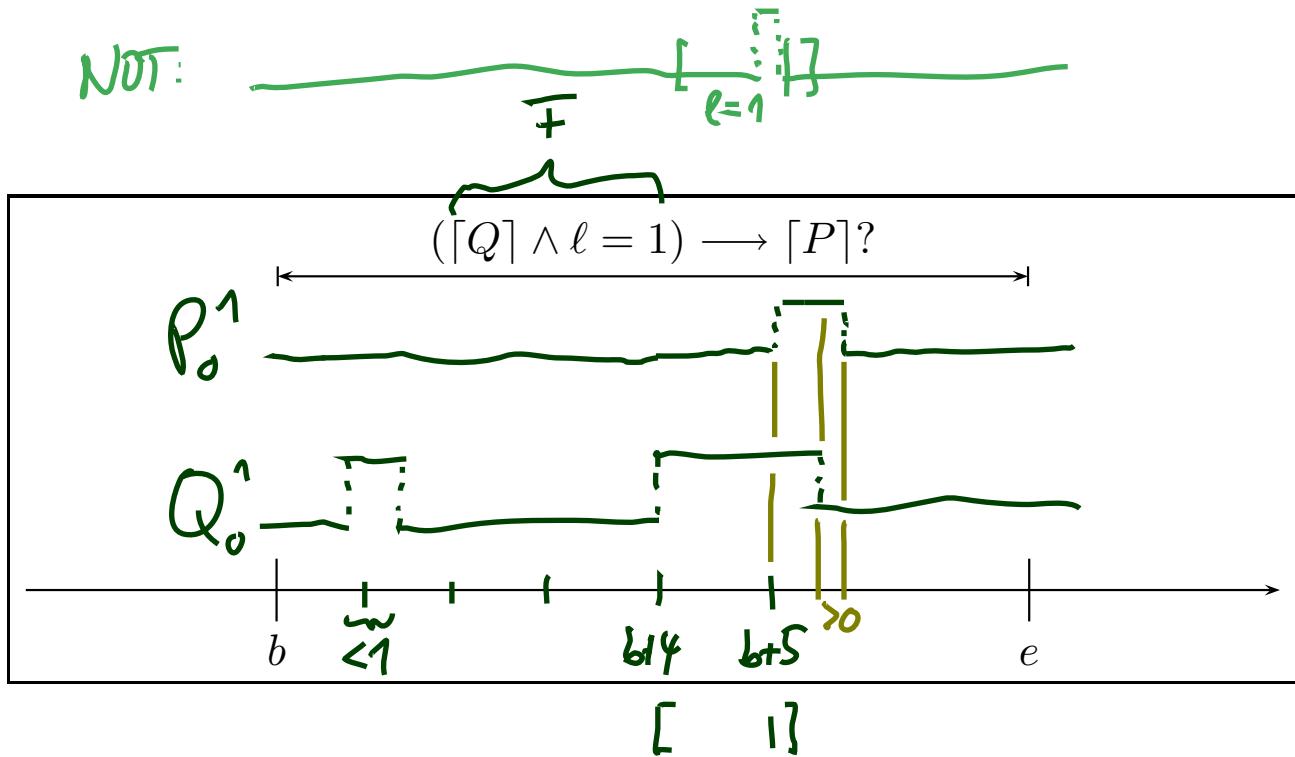
DC Standard Forms: Followed-by Examples

$$\forall x \bullet \square((F \wedge \ell = x) ; \ell > 0 \implies (F \wedge \ell = x) ; [P] ; \text{true})$$



DC Standard Forms: Followed-by Examples

$$\forall x \bullet \square((F \wedge \ell = x) ; \ell > 0 \implies (F \wedge \ell = x) ; \lceil P \rceil ; \text{true})$$

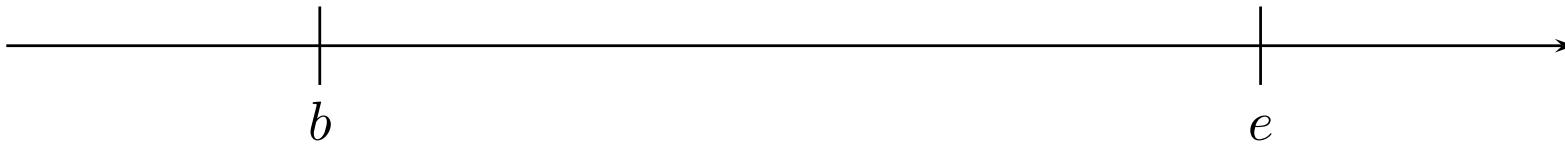
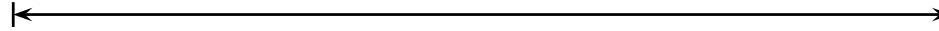


DC Standard Forms: (Timed) leads-to

- (Timed) leads-to:

$$F \xrightarrow{\theta} \lceil P \rceil : \iff (F \wedge \ell = \theta) \longrightarrow \lceil P \rceil$$

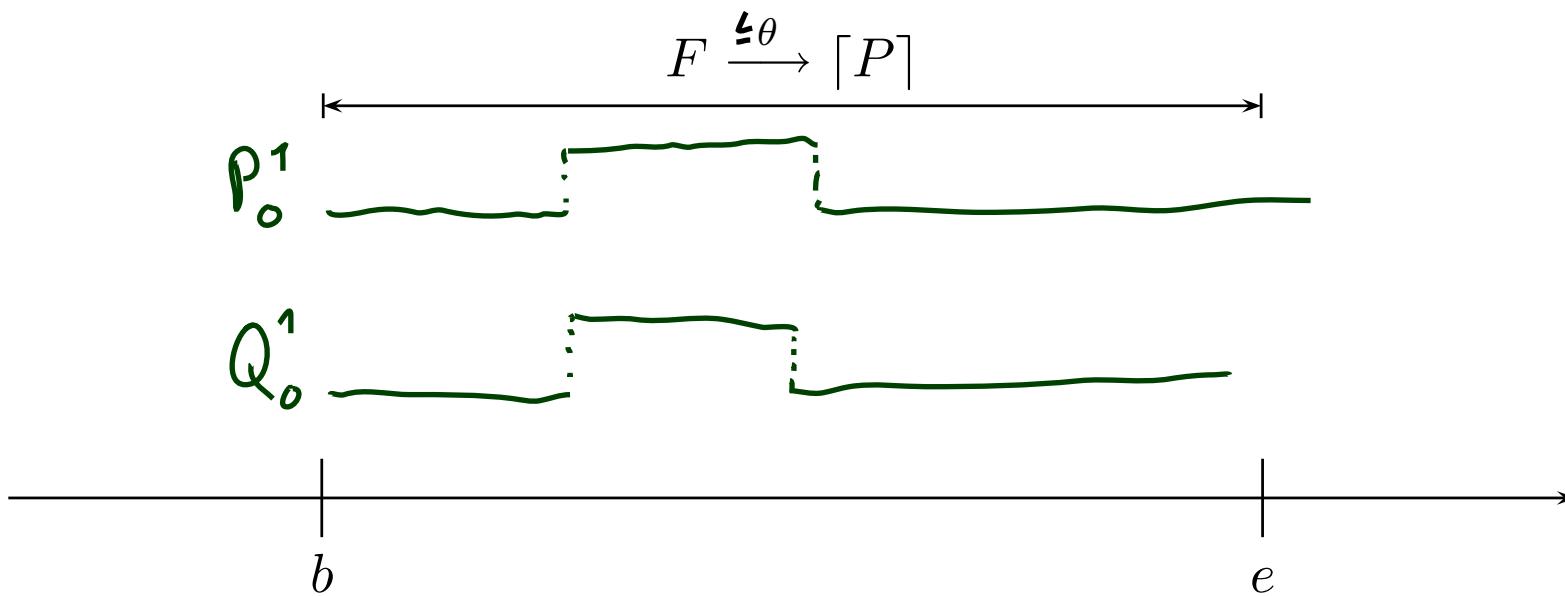
$$F \xrightarrow{\theta} \lceil P \rceil$$



DC Standard Forms: (Timed) up-to

- **(Timed) up-to:**

$$F \xrightarrow{\leq \theta} \lceil P \rceil : \iff (F \wedge \ell \leq \theta) \longrightarrow \lceil P \rceil$$

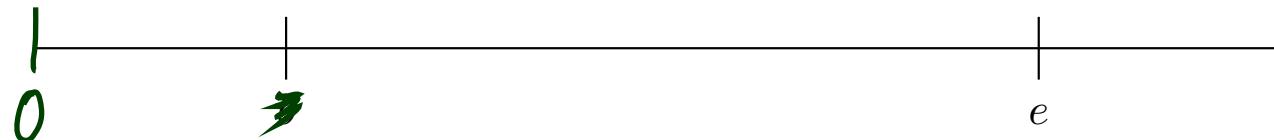


DC Standard Forms: Initialisation

- **Followed-by-initially:**

$$F \longrightarrow_0 [P] : \iff \neg(F ; [\neg P])$$

$$\xleftarrow{\hspace{1cm}} F \longrightarrow_0 [P] \xrightarrow{\hspace{1cm}}$$



- **(Timed) up-to-initially:**

$$F \xrightarrow{\leq \theta} [P] : \iff (F \wedge \ell \leq \theta) \longrightarrow_0 [P]$$

- **Initialisation:**

$$\Box \vee ([P] ; \text{true})$$

Control Automata

- Let X_1, \dots, X_k be k state variables ranging over **finite** domains $\mathcal{D}(X_1), \dots, \mathcal{D}(X_k)$.
- With a DC formula ‘Impl’ ranging over X_1, \dots, X_k we have a **system of k control automata**.
- ‘Impl’ is typically a conjunction of **DC implementables**.
- A state assertion of the form

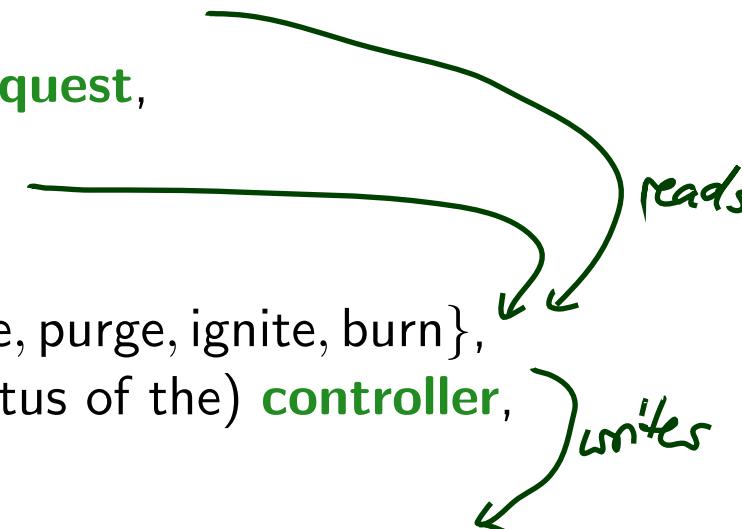
$$X_i = d_i, \quad d_i \in \mathcal{D}(X_i),$$

which constrains the values of X_i , is called **basic phase** of X_i .

- A **phase** of X_i is a Boolean combination of basic phases of X_i .
- **Abbreviations:**
 - Write X_i instead of $X_i = 1$, if X_i is Boolean.
 - Write d_i instead of $X_i = d_i$, if $\mathcal{D}(X_i)$ is disjoint from $\mathcal{D}(X_j)$, $i \neq j$.

Control Automata: Example

Model of Gas Burner controller as a system of four control automata:

- H Boolean,
representing **heat request**,

(input)
- F Boolean,
representing **flame**,
(input)
- C with $\mathcal{D}(C) = \{\text{idle}, \text{purge}, \text{ignite}, \text{burn}\}$,
representing the (status of the) **controller**,
(local)
- G Boolean,
representing **gas valve**.
(output)

- **Basic phase** of C :

$$C = \text{purge} \quad (\text{or only: purge})$$

- **Phase** of C :

$$\text{purge} \vee \text{idle}$$

DC Implementables

- DC Implementables
are special patterns of DC Standard Forms (due to A.P. Ravn).
- Within one pattern,
 - π, π_1, \dots, π_n , $n \geq 0$, denote **phases** of the same state variable X_i ,
 - φ denotes a state assertion not depending on X_i .
- θ denotes a **rigid** term.

- **Initialisation:**

$$\square \vee [\pi] ; \text{true}$$

- **Sequencing:**

$$[\pi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$

- **Progress:**

$$[\pi] \xrightarrow{\theta} [\neg\pi]$$

- **Synchronisation:**

$$[\pi \wedge \varphi] \xrightarrow{\theta} [\neg\pi]$$

DC Implementables Cont'd

- **Bounded Stability:**

$$\underbrace{(\lceil \neg\pi \rceil ; \lceil \pi \wedge \varphi \rceil)}_{\tau} \xrightarrow{\leq\theta} \lceil \underbrace{\pi \vee \pi_1 \vee \cdots \vee \pi_n}_{\rho} \rceil$$

- **Unbounded Stability:**

$$\lceil \neg\pi \rceil ; \lceil \pi \wedge \varphi \rceil \longrightarrow \lceil \pi \vee \pi_1 \vee \cdots \vee \pi_n \rceil$$

- **Bounded initial stability:**

$$\lceil \pi \wedge \varphi \rceil \xrightarrow{\leq\theta}_0 \lceil \pi \vee \pi_1 \vee \cdots \vee \pi_n \rceil$$

- **Unbounded initial stability:**

$$\lceil \pi \wedge \varphi \rceil \longrightarrow_0 \lceil \pi \vee \pi_1 \vee \cdots \vee \pi_n \rceil$$

Specification by DC Implementables

- Let X_1, \dots, X_k be a system of k control automata.
- Let ‘Impl’ be a conjunction of **DC implementables**.
- Then ‘Impl’ **specifies** all interpretations \mathcal{I} of X_1, \dots, X_k and all valuations \mathcal{V} such that

$$\mathcal{I}, \mathcal{V} \models_0 \text{Impl}$$

- Hmm: And what does this have to do with controllers...?

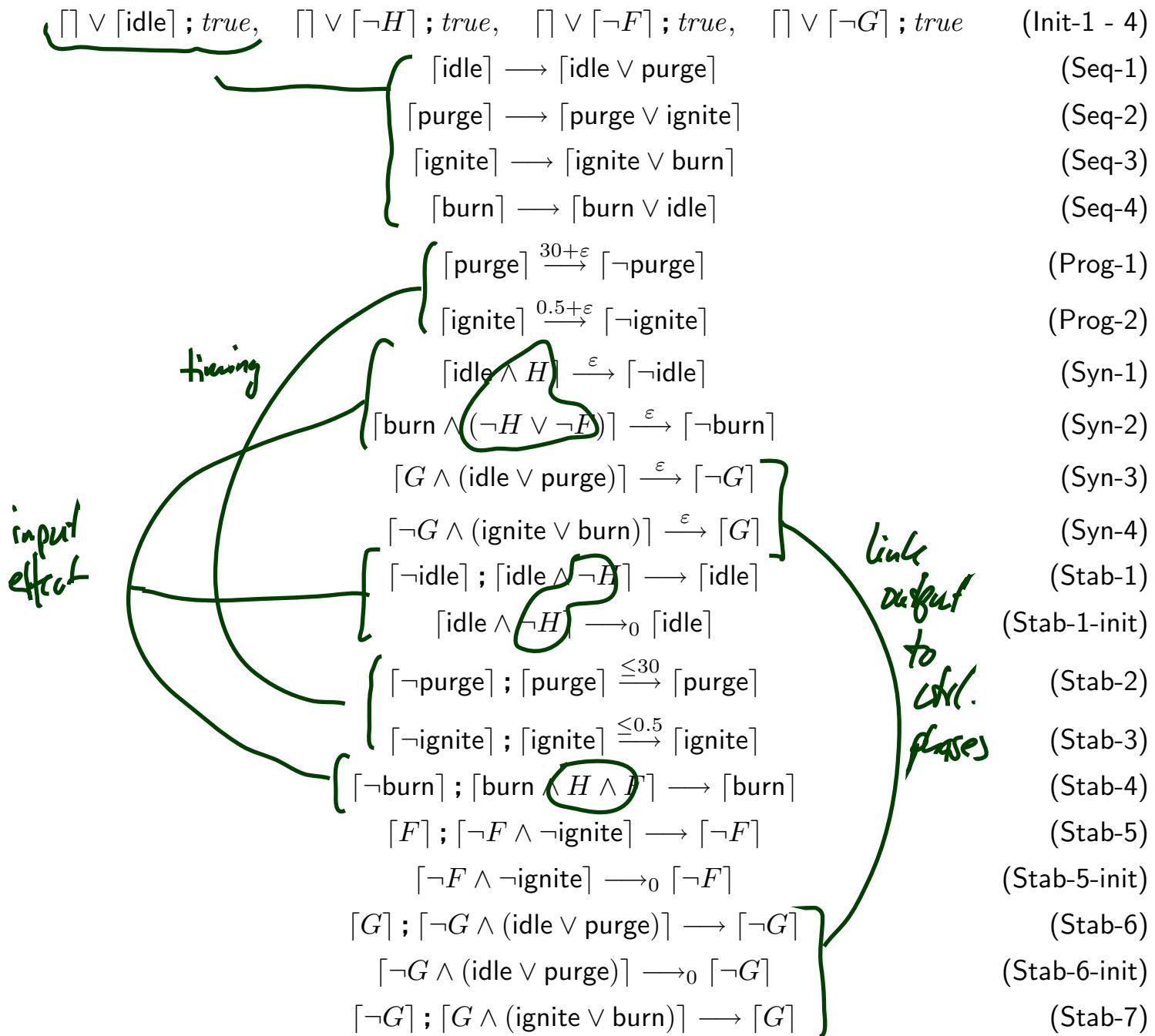
Example: Gas Burner

Recall: Control Automata

Model of Gas Burner controller as a system of four control automata:

- H : Boolean,
representing **heat request**, (input)
- F : Boolean,
representing **flame**, (input)
- C with $\mathcal{D}(C) = \{\text{idle}, \text{purge}, \text{ignite}, \text{burn}\}$,
representing the **controller**, (local)
- G : Boolean,
representing **gas valve**. (output)

Gas Burner Controller Specification



Gas Burner Controller Specification: Untimed

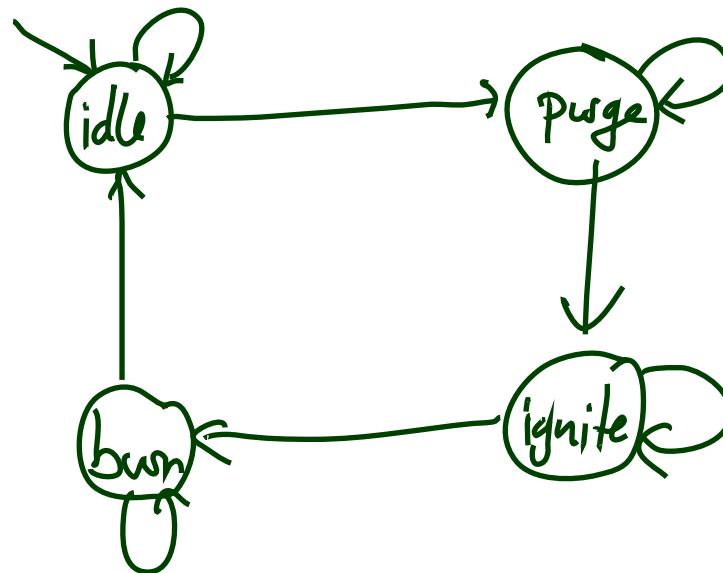
$\square \vee [\text{idle}] ; \text{true}$ (Init-1)

$[\text{idle}] \longrightarrow [\text{idle} \vee \text{purge}]$ (Seq-1)

$[\text{purge}] \longrightarrow [\text{purge} \vee \text{ignite}]$ (Seq-2)

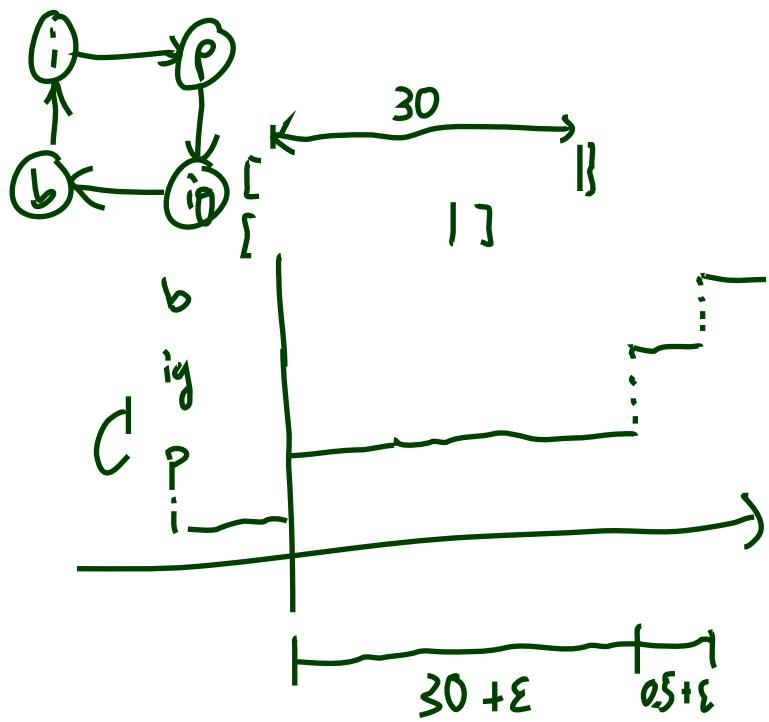
$[\text{ignite}] \longrightarrow [\text{ignite} \vee \text{burn}]$ (Seq-3)

$[\text{burn}] \longrightarrow [\text{burn} \vee \text{idle}]$ (Seq-4)

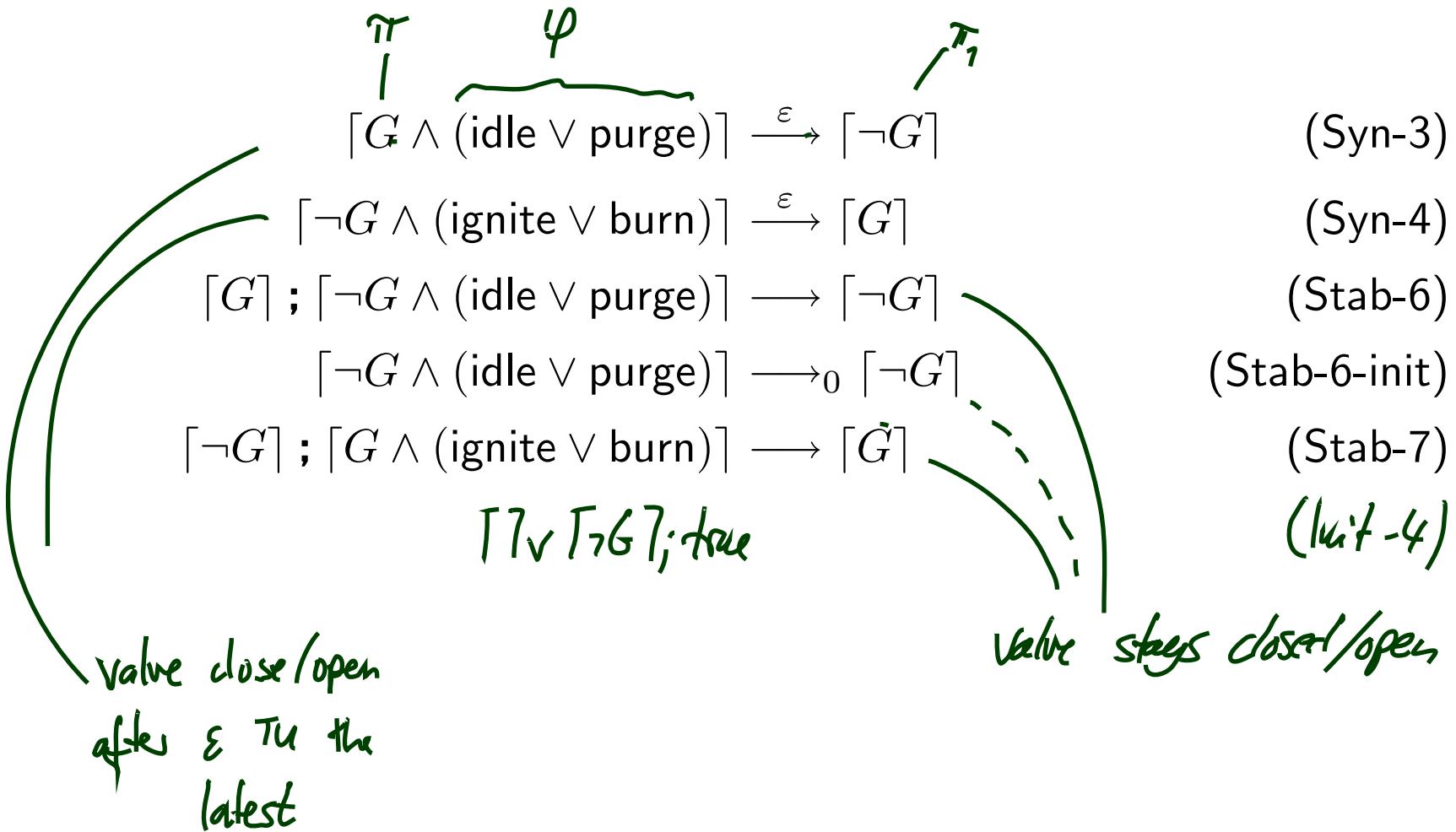


Gas Burner Controller Specification: Timing

$$\begin{array}{l} [\text{purge}] \xrightarrow{30+\varepsilon} [\neg\text{purge}] \\ (\text{Prog-1}) \end{array}$$
$$\begin{array}{l} [\text{ignite}] \xrightarrow{0.5+\varepsilon} [\neg\text{ignite}] \\ (\text{Prog-2}) \end{array}$$
$$\begin{array}{l} [\neg\text{purge}] ; [\text{purge}] \xrightarrow{\leq 30} [\text{purge}] \\ (\text{Stab-2}) \end{array}$$
$$\begin{array}{l} [\neg\text{ignite}] ; [\text{ignite}] \xrightarrow{\leq 0.5} [\text{ignite}] \\ (\text{Stab-3}) \end{array}$$



Gas Burner Controller Specification: Outputs



Gas Burner Controller Specification: Inputs

if H is "on" for less than ϵ , we need not change phase

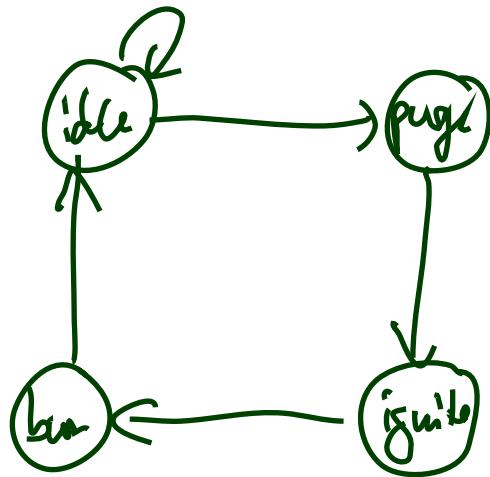
$$[\text{idle} \wedge H] \xrightarrow{\epsilon} [\neg \text{idle}] \quad (\text{Syn-1})$$

$$[\text{burn} \wedge (\neg H \vee \neg F)] \xrightarrow{\epsilon} [\neg \text{burn}] \quad (\text{Syn-2})$$

$$[\neg \text{idle}] ; [\text{idle} \wedge \neg H] \longrightarrow [\text{idle}] \quad (\text{Stab-1})$$

$$[\text{idle} \wedge \neg H] \longrightarrow_0 [\text{idle}] \quad (\text{Stab-1-init})$$

$$[\neg \text{burn}] ; [\text{burn} \wedge H \wedge F] \longrightarrow [\text{burn}] \quad (\text{Stab-4})$$



Gas Burner Controller Specification: Assumptions

$$\square \vee \neg H ; \text{true} \quad (\text{Init-2})$$

$$\square \vee \neg F ; \text{true} \quad (\text{Init-3})$$

~~$$\square \vee \neg G ; \text{true} \quad (\text{Init-4})$$~~

$$[F] ; [\neg F \wedge \neg \text{ignite}] \longrightarrow [\neg F] \quad (\text{Stab-5})$$

$$[\neg F \wedge \neg \text{ignite}] \longrightarrow_0 [\neg F] \quad (\text{Stab-5-init})$$

no spontaneous flame

Gas Burner Controller Correctness Proof

$$\text{GB-Ctrl} := \text{Init-1} \wedge \dots \wedge \text{Stab-7} \wedge \varepsilon > 0$$

Recall:

$$\text{Req} : \iff \square(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

and (cf. [Olderog and Dierks, 2008])

$$\models \text{Req-1} \implies \text{Req}$$

for the **simplified**

$$\text{Req-1} := \square(\ell \leq 30 \implies \int L \leq 1).$$

Here we show

$$\models \text{GB-Ctrl} \wedge A(\varepsilon) \implies \text{Req-1}.$$

Lemma 3.15

$$\models_{\text{GB-Ctrl}} [c, d] \Rightarrow \square \left(\begin{array}{l} (\lceil \text{idle} \rceil \Rightarrow \int G \leq \varepsilon) \\ \wedge (\lceil \text{purge} \rceil \Rightarrow \int G \leq \varepsilon) \\ \wedge (\lceil \text{ignite} \rceil \Rightarrow \ell \leq 0.5 + \varepsilon) \\ \wedge (\lceil \text{burn} \rceil \Rightarrow \int \neg F \leq 2\varepsilon) \end{array} \right) \quad (*)$$

Proof: Let \mathcal{I} be an interpretation, \mathcal{V} a valuation, and $[c, d]$ an interval with $\mathcal{I}, \mathcal{V}, [c, d] \models \text{GB-Ctrl}$. Let $[b, e] \subseteq [c, d]$.

- Case 1: $\mathcal{I}, \mathcal{V}, [b, e] \models \lceil \text{idle} \rceil$

$$[G \wedge (\text{idle} \vee \text{purge})] \xrightarrow{\varepsilon} [\neg G] \quad (\text{Syn-3})$$

$$[G] ; [\neg G \wedge (\text{idle} \vee \text{purge})] \longrightarrow [\neg G] \quad (\text{Stab-6})$$

conclude

$$\mathcal{I}, \mathcal{V}, [b, e] \models \square([G] \Rightarrow \ell \leq \varepsilon) \wedge \neg \diamond([G] ; [\neg G] ; [G])$$

$\triangleright (*)$

gas value doesn't open
up again in idle phase

- Case 2: $\mathcal{I}, \mathcal{V}, [b, e] \models \lceil \text{purge} \rceil$ Analogously to case 1.

Lemma 3.15 Cont'd

- Case 3: $\mathcal{I}, \mathcal{V}, [b, e] \models \lceil \text{ignite} \rceil$

- ([idle] \implies $\int G \leq \varepsilon$)
- ([purge] \implies $\int G \leq \varepsilon$)
- ([ignite] \implies $\ell \leq 0.5 + \varepsilon$)
- ([burn] \implies $\int \neg F \leq 2\varepsilon$)

(*)

$$[\text{ignite}] \xrightarrow{0.5+\varepsilon} [\neg\text{ignite}] \quad (\text{Prog-2})$$


 $\mathcal{I}, \mathcal{V}, [b, e] \models \ell \leq 0.5 + \varepsilon$

- Case 4: $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{burn}]$

$$\lceil \text{burn} \wedge (\neg H \vee \neg F) \rceil \xrightarrow{\varepsilon} \lceil \neg \text{burn} \rceil \quad (\text{Syn-2})$$

$$[F] ; [\neg F \wedge \neg \text{ignite}] \longrightarrow [\neg F] \quad (\text{Stab-5})$$

$$[\neg F] ; [\neg F \wedge \neg \text{ignite}] \longrightarrow [\neg F] \quad (\text{Stab-5})$$


 $\mathcal{I}, \mathcal{V}, [b, e] \models \square(\neg F \implies \ell \leq \varepsilon) \wedge \neg \lozenge([\neg F] ; [\neg F] ; [F])$
















Lemma 3.16

$$\models \exists \varepsilon \bullet \text{GB-Ctrl} \implies \underbrace{\square(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}}$$

Proof Sketch

Choose $I, V, [b, e]$ s.t. $I, V, [b, e] \models \text{GB-Ctrl} \wedge \ell \leq 30$

Distinguish 5 cases:

- | | |
|--|-----|
| $I, V, [b, e] \models \Gamma_7$ | (0) |
| $\vee(\Gamma_{idle}, \text{true} \wedge \ell \leq 30)$ | (1) |
| $\vee(\Gamma_{prog}, \text{true} \wedge \ell \leq 30)$ | (2) |
| $\vee(\Gamma_{ignite}, \text{true} \wedge \ell \leq 30)$ | (3) |
| $\vee(\Gamma_{burn}, \text{true} \wedge \ell \leq 30)$ | (4) |

Lemma 3.16 Cont'd

- Case 0: $\mathcal{I}, \mathcal{V}, [b, e] \models \sqcap$ ✓
- Case 1: $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{idle}] ; \text{true} \wedge \ell \leq 30$

$$[\text{idle}] \longrightarrow [\text{idle} \vee \text{purge}] \quad (\text{Seq-1})$$

$$[\neg \text{purge}] ; [\text{purge}] \xrightarrow{\leq 30} [\text{purge}] \quad (\text{Stab-2})$$

→ $\mathcal{I}, \mathcal{V}, [b, e] \models T_{\text{idle}} \vee T_{\text{idle}} ; T_{\text{purge}}$

3.15 → $\mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq \varepsilon \vee \int L \leq \varepsilon ; \int L \leq \varepsilon$

→ $\mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq 2\varepsilon$

Thus $\boxed{\varepsilon \leq 0.5}$ is sufficient for Reg-1 in this case.

Lemma 3.16 Cont'd

- Case 2: $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{burn}] ; \text{true} \wedge \ell \leq 30$

$$[\text{burn}] \longrightarrow [\text{burn} \vee \text{idle}] \quad (\text{Seq-4})$$

$$\begin{array}{c} \xrightarrow{\quad} \mathcal{I}, \mathcal{V}, [b, e] \models (\Gamma_{\text{burn}}) \cup \Gamma_{\text{burn}}; \underbrace{\Gamma_{\text{idle}}; \text{true}}_{\text{idle}} \wedge \ell \leq 30 \\ 3.15, (1) \xrightarrow{\quad} \mathcal{I}, \mathcal{V}, [b, e] \models (\int_L \leq 2\varepsilon \vee \int_L \leq 2\varepsilon; \int_L \leq 2\varepsilon) \wedge \ell \leq 30 \\ \xrightarrow{\quad} \mathcal{I}, \mathcal{V}, [b, e] \models \int_L \leq 4\varepsilon \end{array}$$

Thus $\boxed{\varepsilon \leq 0.25}$ sufficient for Reg-1.

Lemma 3.16 Cont'd

- Case 3: $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{ignite}] ; \text{true} \wedge l \leq 30$

$$[\text{ignite}] \longrightarrow [\text{ignite} \vee \text{burn}] \quad (\text{Seq-3})$$

$$\begin{aligned} & \mathcal{I}, \mathcal{V}, [b, e] \models ([\text{ignite}] \vee [\text{ignite}; \text{burn}], \text{true}) \wedge l \leq 30 \\ 35, (2) \quad & \mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq 0.5 + \varepsilon \vee (\int L \leq 0.5 + \varepsilon; \int L \leq 4\varepsilon) \wedge l \leq 30 \\ & \mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq 0.5 + 5\varepsilon \end{aligned}$$

So $\boxed{\varepsilon \leq 0.1}$ is sufficient for Reg-1.

Lemma 3.16 Cont'd

- Case 4: $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{purge}] ; \text{true} \wedge l \leq 30$

$$[\text{purge}] \longrightarrow [\text{purge} \vee \text{ignite}] \quad (\text{Seq-2})$$

$$\Delta \vdash \mathcal{I}, \mathcal{V}, [b, e] \models ([\text{purge}] \vee [\text{ignite}]); [\text{ignite}] ; \text{true}, l \leq 30$$

$$3.15, (3) \Delta \vdash \mathcal{I}, \mathcal{O}, [b, e] \models \int L \leq \varepsilon \vee (\int L \leq \varepsilon; \int L \leq 0.5 + \varepsilon)$$

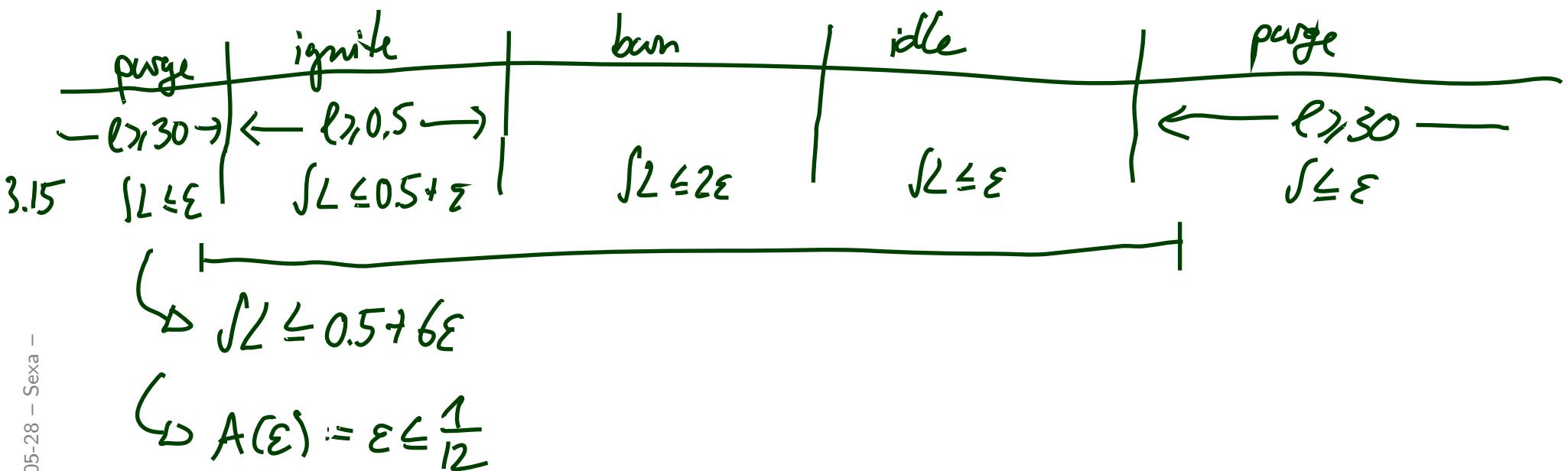
$$\Delta \vdash \mathcal{I}, \mathcal{O}, [b, e] \models \int L \leq 0.5 + 6\varepsilon$$

Thus $\boxed{\varepsilon \leq \frac{1}{12}}$ is sufficient for Reg-1 in this case.

Correctness Result

Theorem 3.17.

$$\models \left(\text{GB-Ctrl} \wedge \varepsilon \leq \frac{1}{12} \right) \implies \text{Req}$$



Discussion

- We used only

'Seq-1', 'Seq-2', 'Seq-3', 'Seq-4',
'Prog-2', 'Syn-2', 'Syn-3',
'Stab-2', 'Stab-5', 'Stab-6'.

What about

$$\text{Prog-1} = [\text{purge}] \xrightarrow{30+\varepsilon} [\neg\text{purge}]$$

for instance?

Naja, there is the requirement (not noted down) that the system does something finally,
e.g. get the heating going on request.

References

References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.