

Formal Methods for C

Seminar – Summer Semester 2014

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Function Pointers

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Functions in the System's Memory

```
1 void f() { return; }
```

the compiler chose to store the machine code of 'f' at memory cell with address 0x1001

0x1000	0x1001	0x1002	...	0x1004	0x1005	0x1006	0x1007
0x1000	RET	0x1002	...	0x1004	0x1005	0x1006	0x1007
0x1008	0x1009	0x100A	...	0x100C	0x100D	0x100E	0x100F
0x1010	0x1011	0x1012	0x1013	0x1014	0x1015	0x1016	0x1017
...

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Calling Functions

```
1 void f() { return; }
2 f();
```

2014-04 - pointers -

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Calling Functions

```
1 void f() { return; }
2 f();
```

calling 'f' means machine op CALL with address of callee (here f, address 0x1001)

0x1000	0x1001	0x1002	...	0x1004	0x1005	0x1006	0x1007
0x1000	RET	0x1002	...	0x1004	0x1005	0x1006	0x1007
0x1008	0x1009	0x100A	...	0x100C	0x100D	0x100E	0x100F
0x1010	0x1011	0x1012	CALL 0x10	0x1014	0x1015	0x1016	0x1017
...

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A Pointer to 'f' (16-bit Architecture)

- `void f() { return; }`
- `f();`
- `void (*p) () = &f;`

'p' is a variable which stores the address of a function (here: of 'f')

0x1000	0x1001	0x1002	...	0x1003	0x1004	0x1005	0x1006	0x1007
RET	RET	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			0x10	0x01	0x10	0x01	0x10	0x01
MOV	MOV	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			R	R	R	R	R	R

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A Pointer to 'f' (16-bit Architecture)

- `void f() { return; }`
- `f();`
- `void (*p) () = &f;`

'p' is a variable which stores the address of a function (here: of 'f')

0x1000	0x1001	0x1002	...	0x1003	0x1004	0x1005	0x1006	0x1007
RET	RET	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			0x10	0x01	0x10	0x01	0x10	0x01
MOV	MOV	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			R	R	R	R	R	R

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Dereference Function Pointers

- `void f() { return; }`
- `f();`
- `void (*p) () = &f;`
- `(*p)();`

0x1000	0x1001	0x1002	...	0x1003	0x1004	0x1005	0x1006	0x1007
RET	RET	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			0x10	0x01	0x10	0x01	0x10	0x01
MOV	MOV	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			R	R	R	R	R	R

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Dereference Function Pointers

- `void f() { return; }`
- `f();`
- `void (*p) () = &f;`
- `(*p)();`

calling via 'p' means read value of p (here: 0x1001) into register R...

0x1000	0x1001	0x1002	...	0x1003	0x1004	0x1005	0x1006	0x1007
RET	RET	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			0x10	0x01	0x10	0x01	0x10	0x01
MOV	MOV	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			R	R	R	R	R	R

40/128

Dereference Function Pointers

- `void f() { return; }`
- `f();`
- `void (*p) () = &f;`
- `(*p)();`

calling via 'p' means read value of p (here: 0x1001) into register R...

...and then machine op CALL with R, calls address stored in R

0x1000	0x1001	0x1002	...	0x1003	0x1004	0x1005	0x1006	0x1007
RET	RET	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			0x10	0x01	0x10	0x01	0x10	0x01
MOV	MOV	CALL	CALL	CALL	CALL	CALL	CALL	CALL
			R	R	R	R	R	R

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Pointers vs. Arrays

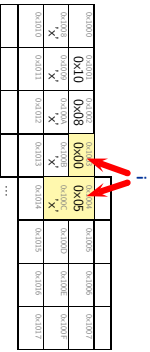
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Arrays

```

1 char a[5] = { 'H', 'e', 'l', 'l', 'o' };
2 int i;
3 for (i = 0; i < 5; ++i)
4 a[i] = 'x';

```

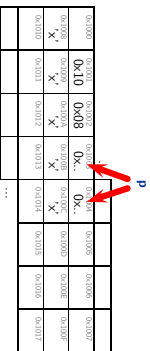


Arrays vs. Pointers

```

1 char a[5] = { 'H', 'e', 'l', 'l', 'o' };
2 char* p = a; // not &a !
3 for (int i = 0; i < 5; ++i, ++p)
4 *p = 'o';

```

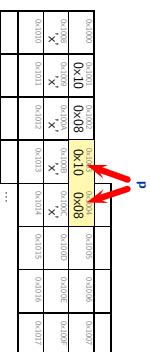


Arrays vs. Pointers

```

1 char a[5] = { 'H', 'e', 'l', 'l', 'o' };
2 char* p = a; // not &a !
3 for (int i = 0; i < 5; ++i, ++p)
4 *p = 'o';

```

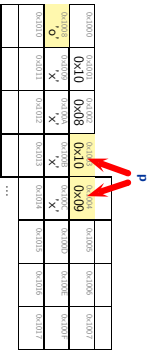


Arrays vs. Pointers

```

1 char a[5] = { 'H', 'e', 'l', 'l', 'o' };
2 char* p = a; // not &a !
3 for (int i = 0; i < 5; ++i, ++p)
4 *p = 'o';

```

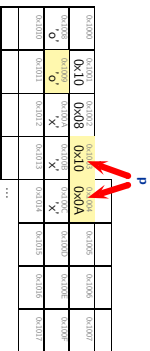


Arrays vs. Pointers

```

1 char a[5] = { 'H', 'e', 'l', 'l', 'o' };
2 char* p = a; // not &a !
3 for (int i = 0; i < 5; ++i, ++p)
4 *p = 'o';

```

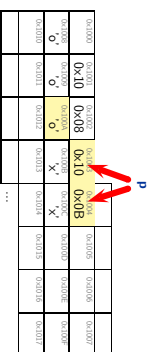


Arrays vs. Pointers

```

1 char a[5] = { 'H', 'e', 'l', 'l', 'o' };
2 char* p = a; // not &a !
3 for (int i = 0; i < 5; ++i, ++p)
4 *p = 'o';

```



Arrays vs. Pointers

```

1 char a[5] = {'H', 'e', 'l', 'l', 'o'};
2 char* p = a; // not &a !
3 for (int i = 0; i < 5; ++i, ++p)
4 *p = 'o';

```

0x1000	0x1001	0x1002	0x1003	0x1004	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x0C	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x08	...	0x1008	0x1009
0x1000	0x10	0x08	0x08	0x08	...	0x1008	0x1009
0x1000	0x0A	0x00	0x00	0x00	...	0x1008	0x1009
0x1000	0x00	0x00	0x00	0x00	...	0x1008	0x1009

Arrays vs. Pointers

```

1 char a[5] = {'H', 'e', 'l', 'l', 'o'};
2 char* p = a; // not &a !
3 for (int i = 0; i < 5; ++i, ++p)
4 *p = 'o';

```

0x1000	0x1001	0x1002	0x1003	0x1004	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x0D	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x08	...	0x1008	0x1009
0x1000	0x10	0x08	0x08	0x08	...	0x1008	0x1009
0x1000	0x0A	0x00	0x00	0x00	...	0x1008	0x1009
0x1000	0x00	0x00	0x00	0x00	...	0x1008	0x1009

Integer Arrays

```

1 int a[3] = { 10, 010, 0x1234 };
2 int i;
3 for (i = 0; i < 3; ++i)
4 a[i] = 0x27;

```

...and let a point
to that space

0x1000	0x1001	0x1002	0x1003	0x1004	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x0C	...	0x1008	0x1009
0x1000	0x10	0x0A	0x00	0x08	0x12	0x34	...
0x1000	0x00	0x00	0x02	0x08	0x12	0x34	...
0x1000	0x00	0x00	0x02	0x08	0x12	0x34	...
0x1000	0x00	0x00	0x02	0x08	0x12	0x34	...

Integer Arrays

```

1 int a[3] = { 10, 010, 0x1234 };
2 int i;
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```

0x1000	0x1001	0x1002	0x1003	0x1004	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x0C	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x08	...	0x1008	0x1009
0x1000	0x0A	0x00	0x08	0x12	0x34	...	0x1009
0x1000	0x00	0x00	0x00	0x00	...	0x1008	0x1009
0x1000	0x00	0x00	0x00	0x00	...	0x1008	0x1009

Integer Arrays

```

1 int a[3] = { 10, 010, 0x1234 };
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```

0x1000	0x1001	0x1002	0x1003	0x1004	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x0D	...	0x1008	0x1009
0x1000	0x27	0x00	0x08	0x12	0x34	...	0x1009
0x1000	0x00	0x00	0x02	0x08	0x12	0x34	...
0x1000	0x00	0x00	0x02	0x08	0x12	0x34	...
0x1000	0x00	0x00	0x02	0x08	0x12	0x34	...

Integer Arrays

```

1 int a[3] = { 10, 010, 0x1234 };
2 int i;
3 for (i = 0; i < 3; ++i)
4 a[i] = 0x27;

```

0x1000	0x1001	0x1002	0x1003	0x1004	...	0x1008	0x1009
0x1000	0x10	0x08	0x10	0x02	...	0x1008	0x1009
0x1000	0x27	0x00	0x27	0x12	0x34	...	0x1009
0x1000	0x00	0x00	0x27	0x08	0x12	0x34	...
0x1000	0x00	0x00	0x27	0x08	0x12	0x34	...
0x1000	0x00	0x00	0x27	0x08	0x12	0x34	...

Integer Arrays vs. Pointers

```
1 int a[3] = { 10, 010, 0x1234 };
2 int i;
3 for (i = 0; i < 3; ++i)
4 a[i] = 0x27;
```

0x0000	0x0004	0x0008	0x000C	0x0010	0x0014	0x0018	0x001C	0x0020	0x0024	0x0028	0x002C
0x10	0x08	0x00	0x03	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00
0x27	0x00	0x27	0x00	0x27	0x00	0x00	0x00	0x00	0x00	0x00	0x00
...

Integer Arrays vs. Pointers

```
1 int a[3] = { 10, 010, 0x1234 };
2 int* p = a;
3 for (int i = 0; i < 3; ++i)
4 *p = 0x3421;
```

0x0000	0x0004	0x0008	0x000C	0x0010	0x0014	0x0018	0x001C	0x0020	0x0024	0x0028	0x002C
0x10	0x08	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00
0x27	0x00	0x27	0x00	0x27	0x00	0x00	0x00	0x00	0x00	0x00	0x00
...

Integer Arrays vs. Pointers

```
1 int a[3] = { 10, 010, 0x1234 };
2 int* p = a;
3 for (int i = 0; i < 3; ++i)
4 *p = 0x3421;
```

0x0000	0x0004	0x0008	0x000C	0x0010	0x0014	0x0018	0x001C	0x0020	0x0024	0x0028	0x002C
0x10	0x08	0x10	0x0E	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00
0x27	0x00	0x27	0x00	0x27	0x00	0x00	0x00	0x00	0x00	0x00	0x00
...

Integer Arrays vs. Pointers

```
1 int a[3] = { 10, 010, 0x1234 };
2 int* p = a;
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4 *p = 0x3421;
```

0x0000	0x0004	0x0008	0x000C	0x0010	0x0014	0x0018	0x001C	0x0020	0x0024	0x0028	0x002C
0x10	0x08	0x10	0x0A	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00
0x27	0x00	0x27	0x00	0x27	0x00	0x00	0x00	0x00	0x00	0x00	0x00
...

Integer Arrays vs. Pointers

```
1 int a[3] = { 10, 010, 0x1234 };
2 int* p = a;
3 for (int i = 0; i < 3; ++i)
4 *p = 0x3421;
```

0x0000	0x0004	0x0008	0x000C	0x0010	0x0014	0x0018	0x001C	0x0020	0x0024	0x0028	0x002C
0x10	0x08	0x10	0x0C	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00
0x27	0x00	0x27	0x00	0x27	0x00	0x00	0x00	0x00	0x00	0x00	0x00
...

Integer Arrays vs. Pointers

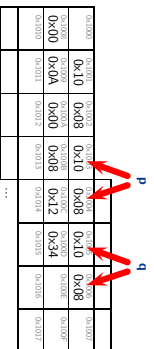
```
1 int a[3] = { 10, 010, 0x1234 };
2 int* p = a;
3 for (int i = 0; i < 3; ++i)
4 *p = 0x3421;
```

0x0000	0x0004	0x0008	0x000C	0x0010	0x0014	0x0018	0x001C	0x0020	0x0024	0x0028	0x002C
0x10	0x08	0x10	0x0E	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00
0x27	0x00	0x27	0x00	0x27	0x00	0x00	0x00	0x00	0x00	0x00	0x00
...

Pointers to 'void', Pointer Arithmetic

```

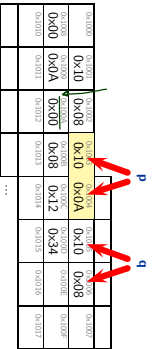
1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }
    
```



Pointer to 'void'

```

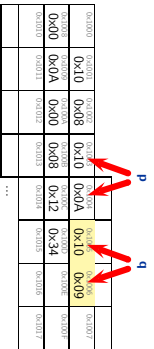
1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }
    
```



Pointer to 'void'

```

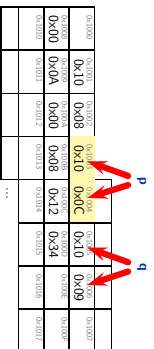
1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }
    
```



Pointer to 'void'

```

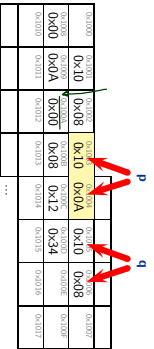
1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }
    
```



Pointer to 'void'

```

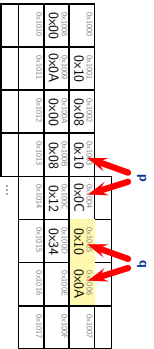
1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }
    
```



Pointer to 'void'

```

1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }
    
```

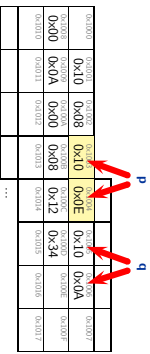


Pointer to 'void'

```

1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }

```

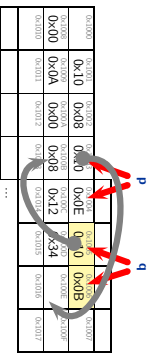


Pointer to 'void'

```

1 int[3] a = { 10, 010, 0x1234 };
2 int* p = a;
3 void* q = a;
4 for (int i = 0; i < 3; ++i) {
5     p++;
6     q++;
7 }

```



Pointers: Observation

- A variable of pointer type just stores an address.
- So do variables of array type.
- Pointers can point to a certain type, or to void.
- "A pointer to void shall have the same representation and alignment requirements as a pointer to a character type" (6.2.9.20)
- The effect of "incrementing" a pointer depends on the type pointed to.

```

1 int a[2];
2 int* p = a;
3 ++p; // points to a[1]
4 void* q = a;
5 q = &a[1]; // points to a[1]
6 ++q; // may point into the middle

```

Pointer Arithmetic

```

1 int[3] a = { 10, 010, 0x1234 }; i = 0;
2
3 int* p = a; // not &a !
4
5 if (a[0] == *p) i++; ✓
6 if (a[1] == *(p+1)) i++; ✓
7 if (a[2] == *(p+2)) i++; ✓
8
9 if (&a[2]) - p == 2) i++; ✓
10 void* q = a;
11
12 if (a[2] == *(int*)(q + (2 * sizeof(int)))) i++; ✓
13
14 // i == 5
15
void as such does not have values, we
need to cast 'q' here... note: void*
can be casted to everything

```

Pointers for Call By Reference

Call By Reference with Pointers

```

1 void f( int* x, int* y ) {
2     x++; y++;
3 }
4 void g( int* p, int* q ) {
5     (*p)++; (*q)++;
6 }
7 int a = 2, b = 5;
8 f( a, b );
9 g( &a, &b );

```


Call By Reference with Pointers

```

1 void f( int x, int y ) {
2   x++, y++;
3 }
4 void g( int* p, int* q ) {
5   (*p)++; (*q)++;
6 }
7 int a = 2, b = 5;
8 f( a, b );
9 g( &a, &b );

```

0x1000	0x1001	0x1002	...	0x1004	0x1005	...	0x1006	0x1007
0x1008	0x1009	0x100A	0x000	0x001	0x002	0x003	0x100E	0x100F
0x1010	0x1011	0x1012	0x...	0x...	0x...	0x...	0x1016	0x1017
0x1018	0x1019	0x101A	0x101E	0x101F

Call By Reference with Pointers

```

1 void f( int x, int y ) {
2   x++, y++;
3 }
4 void g( int* p, int* q ) {
5   (*p)++; (*q)++;
6 }
7 int a = 2, b = 5;
8 f( a, b );
9 g( &a, &b );

```

0x1000	0x1001	0x1002	...	0x1004	0x1005	...	0x1006	0x1007
0x1008	0x1009	0x100A	0x000	0x001	0x002	0x003	0x100E	0x100F
0x1010	0x1011	0x1012	0x...	0x...	0x...	0x...	0x1016	0x1017
0x1018	0x1019	0x101A	0x101E	0x101F

Call By Reference with Pointers

```

1 void f( int x, int y ) {
2   x++, y++;
3 }
4 void g( int* p, int* q ) {
5   (*p)++; (*q)++;
6 }
7 int a = 2, b = 5;
8 f( a, b );
9 g( &a, &b );

```

0x1000	0x1001	0x1002	...	0x1004	0x1005	...	0x1006	0x1007
0x1008	0x1009	0x100A	0x000	0x001	0x002	0x003	0x100E	0x100F
0x1010	0x1011	0x1012	0x...	0x...	0x...	0x...	0x1016	0x1017
0x1018	0x1019	0x101A	0x101E	0x101F

Call By Reference with Pointers

```

1 void f( int x, int y ) {
2   x++, y++;
3 }
4 void g( int* p, int* q ) {
5   (*p)++; (*q)++;
6 }
7 int a = 2, b = 5;
8 f( a, b );
9 g( &a, &b );

```

0x1000	0x1001	0x1002	...	0x1004	0x1005	...	0x1006	0x1007
0x1008	0x1009	0x100A	0x000	0x001	0x002	0x003	0x100E	0x100F
0x1010	0x1011	0x1012	0x...	0x...	0x...	0x...	0x1016	0x1017
0x1018	0x1019	0x101A	0x101E	0x101F

Call By Reference with Pointers

```

1 void f( int x, int y ) {
2   x++, y++;
3 }
4 void g( int* p, int* q ) {
5   (*p)++; (*q)++;
6 }
7 int a = 2, b = 5;
8 f( a, b );
9 g( &a, &b );

```

0x1000	0x1001	0x1002	...	0x1004	0x1005	...	0x1006	0x1007
0x1008	0x1009	0x100A	0x000	0x001	0x002	0x003	0x100E	0x100F
0x1010	0x1011	0x1012	0x...	0x...	0x...	0x...	0x1016	0x1017
0x1018	0x1019	0x101A	0x101E	0x101F

Call By Reference with Pointers

```

1 void f( int x, int y ) {
2   x++, y++;
3 }
4 void g( int* p, int* q ) {
5   (*p)++; (*q)++;
6 }
7 int a = 2, b = 5;
8 f( a, b );
9 g( &a, &b );

```

0x1000	0x1001	0x1002	...	0x1004	0x1005	...	0x1006	0x1007
0x1008	0x1009	0x100A	0x000	0x001	0x002	0x003	0x100E	0x100F
0x1010	0x1011	0x1012	0x...	0x...	0x...	0x...	0x1016	0x1017
0x1018	0x1019	0x101A	0x101E	0x101F

Dynamic Storage & Storage Duration

- 2014-04 - storage -

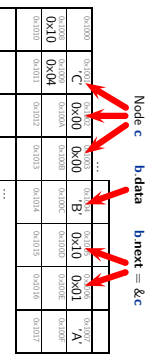
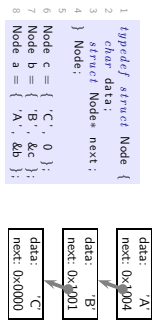
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Dynamic Storage Allocation

- 2014-04 - storage -

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A Linked List



- 2014-04 - storage -

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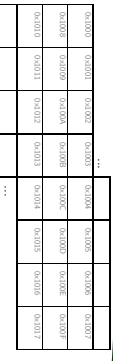
Dynamic Storage Allocation

- 2014-04 - storage -

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```

1 typedef struct Node {
2     char data; struct Node* next;
3 } Node;
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     Node* n = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');
    
```



allocate some space for a Node, return its address, may fail ("out of memory") malloc() yields 0 then head = hip

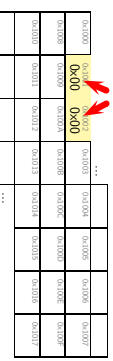
Dynamic Storage Allocation

- 2014-04 - storage -

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```

1 typedef struct Node {
2     char data; struct Node* next;
3 } Node;
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     Node* n = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');
    
```



head

Dynamic Storage Allocation

- 2014-04 - storage -

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```

1 typedef struct Node {
2     char data; struct Node* next;
3 } Node;
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     Node* n = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');
    
```



head

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3 char data = 0, *hip;
4 Node *head = 0, *hip;
5 void insert(char d) {
6     Node* newnode = (Node*) malloc(sizeof(Node));
7     hip->data = d;
8     hip->next = head;
9     head = hip;
10 }
11
12
13 insert('C');
14 insert('B');
15 insert('A');

```

0x000	0x00	0x10	0x13	0x005	0x006	0x007
0x005	0x00	0x00	0x00	0x008	0x009	0x00A
0x00A	0x00	0x00	0x00	0x00B	0x00C	0x00D
0x00D	0x0011	0x0010	0x0014	0x0015	0x0016	0x0017
			0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3 char data = 0, *hip;
4 Node *head = 0, *hip;
5 void insert(char d) {
6     Node* newnode = (Node*) malloc(sizeof(Node));
7     hip->data = d;
8     hip->next = head;
9     head = hip;
10 }
11
12
13 insert('C');
14 insert('B');
15 insert('A');

```

0x000	0x00	0x10	0x13	0x005	0x006	0x007
0x005	0x00	0x00	0x00	0x008	0x009	0x00A
0x00A	0x00	0x00	0x00	0x00B	0x00C	0x00D
0x00D	0x0011	0x0010	0x0014	0x0015	0x0016	0x0017
			0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3 char data = 0, *hip;
4 Node *head = 0, *hip;
5 void insert(char d) {
6     Node* newnode = (Node*) malloc(sizeof(Node));
7     hip->data = d;
8     hip->next = head;
9     head = hip;
10 }
11
12
13 insert('C');
14 insert('B');
15 insert('A');

```

0x000	0x10	0x13	0x005	0x006	0x007
0x005	0x00	0x00	0x008	0x009	0x00A
0x00A	0x00	0x00	0x00B	0x00C	0x00D
0x00D	0x0011	0x0010	0x0014	0x0015	0x0016
			0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3 char data = 0, *hip;
4 Node *head = 0, *hip;
5 void insert(char d) {
6     Node* newnode = (Node*) malloc(sizeof(Node));
7     hip->data = d;
8     hip->next = head;
9     head = hip;
10 }
11
12
13 insert('C');
14 insert('B');
15 insert('A');

```

0x000	0x00	0x10	0x13	0x005	0x006	0x007
0x005	0x00	0x00	0x00	0x008	0x009	0x00A
0x00A	0x00	0x00	0x00	0x00B	0x00C	0x00D
0x00D	0x0011	0x0010	0x0014	0x0015	0x0016	0x0017
			0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3 char data = 0, *hip;
4 Node *head = 0, *hip;
5 void insert(char d) {
6     Node* newnode = (Node*) malloc(sizeof(Node));
7     hip->data = d;
8     hip->next = head;
9     head = hip;
10 }
11
12
13 insert('C');
14 insert('B');
15 insert('A');

```

0x000	0x10	0x13	0x005	0x006	0x007
0x005	0x00	0x00	0x008	0x009	0x00A
0x00A	0x00	0x00	0x00B	0x00C	0x00D
0x00D	0x0011	0x0010	0x0014	0x0015	0x0016
			0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     hip = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');

```

data: 'C'
next: 0x0000

0x0000	0x0000	...	0x0008	0x0008	0x0007
0x0000	0x0009	0x0013	0x010	0x008	0x0000
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     hip = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');

```

data: 'C'
next: 0x0000

0x0000	0x0000	...	0x0008	0x0008	0x0007
0x0000	0x0009	0x0013	0x010	0x008	0x0000
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     hip = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');

```

data: 'C'
next: 0x0000

0x0000	0x0000	...	0x0008	0x0008	0x0007
0x0000	0x0009	0x0013	0x010	0x008	0x0000
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     hip = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');

```

data: 'B'
next: 0x013

0x0000	0x0000	...	0x0008	0x0008	0x0007
0x0000	0x0009	0x0013	0x010	0x008	0x0000
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     hip = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');

```

data: 'C'
next: 0x0000

0x0000	0x0000	...	0x0008	0x0008	0x0007
0x0000	0x0009	0x0013	0x010	0x008	0x0000
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert(char d) {
7     hip = malloc(sizeof(Node));
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert('C');
14 insert('B');
15 insert('A');

```

data: 'B'
next: 0x013

0x0000	0x0000	...	0x0008	0x0008	0x0007
0x0000	0x0009	0x0013	0x010	0x008	0x0000
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...
0x0000	0x...	0x...	0x...	0x...	0x...

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert( char d ) {
7     Node *newNode = (Node *) malloc( sizeof(Node) );
8     hip->next = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert( 'C' );
14 insert( 'B' );
15 insert( 'A' );
    
```

data: 'B'
next: 0x0013
data: 'C'
next: 0x0000

0x0000	0x0000	0x0000	...	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
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4 Node *head = 0, *hip;
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6 void insert( char d ) {
7     Node *newNode = (Node *) malloc( sizeof(Node) );
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert( 'C' );
14 insert( 'B' );
15 insert( 'A' );
    
```

data: 'B'
next: 0x0013
data: 'C'
next: 0x0000

0x0000	0x0000	0x0000	...	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert( char d ) {
7     Node *newNode = (Node *) malloc( sizeof(Node) );
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert( 'C' );
14 insert( 'B' );
15 insert( 'A' );
    
```

data: 'B'
next: 0x0013
data: 'C'
next: 0x0000

0x0000	0x0000	0x0000	...	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert( char d ) {
7     Node *newNode = (Node *) malloc( sizeof(Node) );
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert( 'C' );
14 insert( 'B' );
15 insert( 'A' );
    
```

data: 'B'
next: 0x0013
data: 'C'
next: 0x0000

0x0000	0x0000	0x0000	...	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000

Dynamic Storage Allocation

```

1 typedef struct Node {
2     char data; struct Node* next; } Node;
3
4 Node *head = 0, *hip;
5
6 void insert( char d ) {
7     Node *newNode = (Node *) malloc( sizeof(Node) );
8     hip->data = d;
9     hip->next = head;
10    head = hip;
11 }
12
13 insert( 'C' );
14 insert( 'B' );
15 insert( 'A' );
    
```

data: 'A'
next: 0x0008
data: 'B'
next: 0x0013
data: 'C'
next: 0x0000

0x0000	0x0000	0x0000	...	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000

Dynamic Storage Management

- Dynamic Storage Allocation:
- void* malloc(size_t size);
- "[]" allocates size bytes and returns a pointer to the allocated memory.
- The memory is not initialized. [...]"
- "On error, [this function] returns NULL."
- void free(void* ptr)
- " [...] frees the memory space pointed to by ptr, which must have been returned by a previous call to malloc(), [...]"
- "Otherwise, or if free(ptr) has already been called before, undefined behavior occurs."
- "If ptr is NULL, no operation is performed."
- No garbage collection!
- Management of dynamic storage is responsibility of the programmer. Unaccessible, not free'd memory is called **memory leak**.

Dynamic Storage Management Example

```

1 void remove() {
2   if (hlp == head) {
3     head = hlp->next;
4     free(hlp);
5   }
6 }
7 insert('C'); insert('B'); insert('A');
8 remove();
9 insert('X');

```

data: 'A'
next: 0x0008

data: 'B'
next: 0x0013

data: 'C'
next: 0x0000

0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
'B'	0x0010	0x0013	0x0020	0x0028	'A'	0x0010	0x0008
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
		'C'	0x0000	0x0000	0x0000	0x0000	

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Dynamic Storage Management Example

```

1 void remove() {
2   if (hlp == head) {
3     head = hlp->next;
4     free(hlp);
5   }
6 }
7 insert('C'); insert('B'); insert('A');
8 remove();
9 insert('X');

```

data: 'A'
next: 0x0008

data: 'B'
next: 0x0013

data: 'C'
next: 0x0000

0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0010	0x0013	0x0020	0x0028	'A'	0x0010	0x0008
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
		'C'	0x0000	0x0000	0x0000	0x0000	

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Dynamic Storage Management Example

```

1 void remove() {
2   if (hlp == head) {
3     head = hlp->next;
4     free(hlp);
5   }
6 }
7 insert('C'); insert('B'); insert('A');
8 remove();
9 insert('X');

```

data: 'B'
next: 0x0013

data: 'C'
next: 0x0000

0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0010	0x0013	0x0020	0x0028	'A'	0x0010	0x0008
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
		'C'	0x0000	0x0000	0x0000	0x0000	

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Dynamic Storage Management Example

```

1 void remove() {
2   if (hlp == head) {
3     head = hlp->next;
4     free(hlp);
5   }
6 }
7 insert('C'); insert('B'); insert('A');
8 remove();
9 insert('X');

```

data: 'B'
next: 0x0013

data: 'C'
next: 0x0000

0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0010	0x0013	0x0020	0x0028	'A'	0x0010	0x0008
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
		'C'	0x0000	0x0000	0x0000	0x0000	

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Dynamic Storage Management Example

```

1 void remove() {
2   if (hlp == head) {
3     head = hlp->next;
4     free(hlp);
5   }
6 }
7 insert('C'); insert('B'); insert('A');
8 remove();
9 insert('X');

```

data: 'B'
next: 0x0013

data: 'C'
next: 0x0000

0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0010	0x0013	0x0020	0x0028	'A'	0x0010	0x0008
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
		'C'	0x0000	0x0000	0x0000	0x0000	

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Dynamic Storage Management Example

```

1 void remove() {
2   if (hlp == head) {
3     head = hlp->next;
4     free(hlp);
5   }
6 }
7 insert('C'); insert('B'); insert('A');
8 remove();
9 insert('X');

```

data: 'X'
next: 0x0008

data: 'B'
next: 0x0013

data: 'C'
next: 0x0000

0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0008	0x0013	0x0020	0x0028	0x0030	0x0038	0x0040
0x0000	0x0010	0x0013	0x0020	0x0028	'A'	0x0010	0x0008
0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000	0x0000
		'C'	0x0000	0x0000	0x0000	0x0000	

59/128

Dynamic Storage Management Example

```

1 void remove() {
2     if (hlp == head) {
3         head = hlp->next;
4         free(hlp);
5     }
6 }
7 insert('C'); insert('B'); insert('A');
8 remove();
9 insert('X');

```

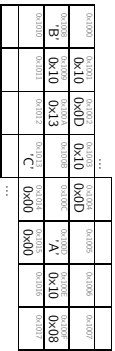


Dynamic Linked List Iteration

```

1 Node* find(char d) {
2     hlp = head;
3     while (hlp) {
4         if (hlp->data == d)
5             break;
6         hlp = hlp->next;
7     }
8     return hlp;
9 }
10 insert('C'); insert('B'); insert('A');
11 find('B'); // yields 0x1008
12 find('D'); // yields 0x0000, aka, NULL

```



Storage Duration of Objects (6.2.4)

- "static" – e.g. variables in program scope:
 - live from program start to end
 - if not explicitly initialised, set to 0 (6.7.8)
- "automatic" – non-static variables in local scope:
 - live from block entry to exit
 - `int` automatically initialised: "initial value [...] is indeterminate"
 - "allocated" – dynamic objects:
 - live from `malloc` to `free`
 - not automatically initialised

"If an object is referred to outside of its lifetime, **the behavior is undefined**. The value of a pointer becomes indeterminate when the object it points to reaches the end of its lifetime."

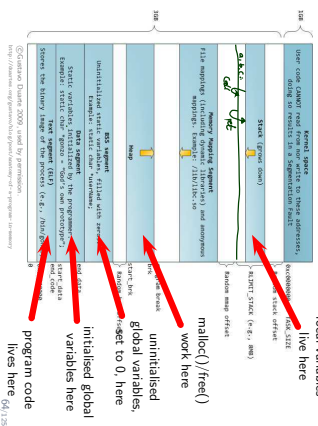
Pointers to Struct/Union — ': vs. '->'

```

1 typedef struct {
2     int x;
3     int y;
4 } coordinate;
5
6 coordinate pos = { 13, 27 };
7
8 coordinate* p = &pos;
9
10 int tmp; tmp = pos.x;
11
12 tmp = (*p).x;
13 (*p).x = (*p).y;
14 (*p).y = tmp;
15
16 tmp = p->x;
17 p->x = p->y;
18 p->y = tmp;

```

Example: Anatomy of a Linux Program in Memory



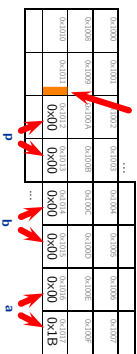
Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;

```

stack pointer – stack ends at 0x1012 in this case; stack grows downwards (to smaller addrs)



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;

```



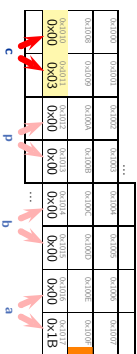
65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;

```



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;

```



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;

```



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;

```



x no longer alive!

65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```

(now) **y** – not explicitly initialised, thus initial value is indeterminate



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```



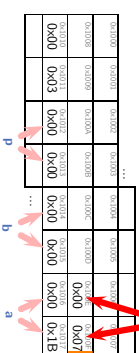
65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```

y no longer alive!



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```

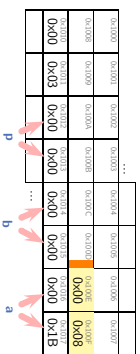


65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```



65/128

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```



65/128

Storage Classes and Qualifiers

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```



65/128

Storage Class Specifiers (6.7.1)

Storage Duration "Automatic" (Simplified)

```

1 void h() { int y; y++; }
2 void g() { int x = 5; x++; }
3 int* f() { int c = 3; g(); h(); return &c; }
4
5 int a = 27, b, *p;
6 p = f();
7 b = *p;
    
```



p refers to a non-static object, the behavior is undefined (everything may happen, from crash to ignore).

65/128

Storage Class Specifiers (6.7.1)

```

1 typedef char letter;
2
3 extern int x;
4 extern int f();
5
6 static int x; // two uses! (-> later)
7 static int f();
8
9 auto x; // "historic"
10
11 register y; // "historic"
12
    
```

Storage Class Specifiers: *extern* (6.7.1)

```

1 // not _defined_ here, "imported" ...
2 //
3 extern int x;
4 extern void f();
5
6 // declared _and_ defined here, "exported" ...
7 //
8 int y;
9
10 int g() {
11     x = y = 27;
12     f();
13 }

```

- modules, linking (later)
- usually only *extern* in headers (later)

69/128

Storage Class Specifiers: *static* (6.7.1)

```

1 // declared _and_ defined here,
2 // _not_ "exported" ...
3 //
4 static int x;
5 static void g();
6
7
8 int f() {
9     static int a = 0;
10    a++;
11    printf("%s\n", a);
12 }
13
14 f(); f(); f(); // yields 1, 2, 3

```

2014-04 - modifiers -

70/128

Qualifiers (6.7.3)

2014-04 - modifiers -

71/128

Qualifiers (6.7.3)

```

1 int x;
2
3 const int y;
4
5 volatile int z;
6
7 int* restrict p; // aliasing
8
9
10 const volatile int a;

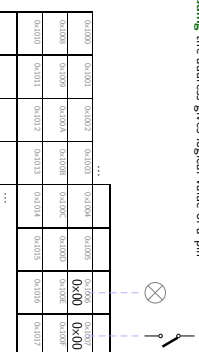
```

- “... lengthy (formal definition...)”
- “[...] If these requirements are not met, then the behavior is **undefined**.”
- use **extremely carefully** (i.e. if in doubt, not at all)

72/128

Excursion: Memory Mapped IO

- Intuition:** some memory addresses are wired to hardware
- writing to the address causes a pin to change logical value
- reading the address gives logical value of a pin

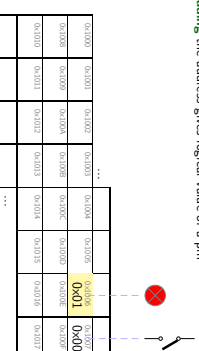


2014-04 - modifiers -

73/128

Excursion: Memory Mapped IO

- Intuition:** some memory addresses are wired to hardware
- writing to the address causes a pin to change logical value
- reading the address gives logical value of a pin

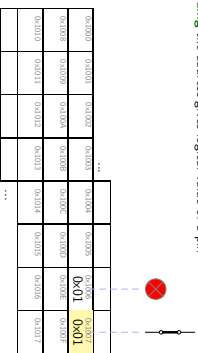


2014-04 - modifiers -

73/128

Excursion: Memory Mapped I/O

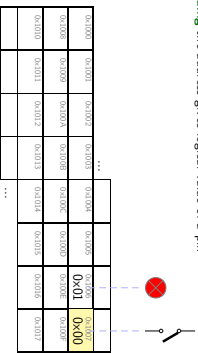
- **Intuition:** some memory addresses are wired to hardware
- **writing** to the address causes a pin to change logical value
- **reading** the address gives logical value of a pin



73125

Excursion: Memory Mapped I/O

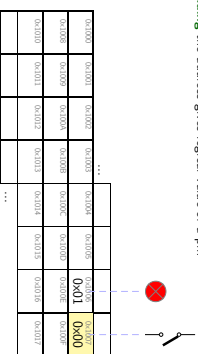
- **Intuition:** some memory addresses are wired to hardware
- **writing** to the address causes a pin to change logical value
- **reading** the address gives logical value of a pin



73126

Excursion: Memory Mapped I/O

- **Intuition:** some memory addresses are wired to hardware
- **writing** to the address causes a pin to change logical value
- **reading** the address gives logical value of a pin



73127

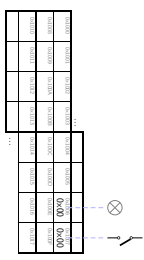
• The compiler does not know, "memory is memory".

Qualifiers: volatile (6.7.3)

```

1 volatile char* out = 0x1006;
2 volatile char* in = 0x1007;
3
4 kout = 0x01; // switch lamp on
5
6 if (&in & 0x01) { /* ... */ }
7
8 if (&in & 0x01) && (&in & 0x01) { /* ... */ }

```



74125

Strings & InputOutput

2014-04 - modifiers -

75126

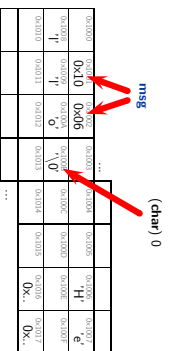
Strings

2014-04 - strings&i/o -

76126

Strings are 0-Terminated char Arrays

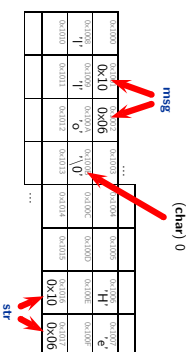
```
1 char* msg = "Hello";
2 char* str = msg;
```



7/128

Strings are 0-Terminated char Arrays

```
1 char* msg = "Hello";
2 char* str = msg;
```



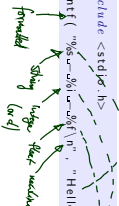
7/128

- `#include <string.h>` provides among others:
 - `strlen(const char* s)` [...] calculates length of string s, excluding the terminating null byte ('\0')
 - `strcmp(const char* s1, const char* s2)` [...] compares the two strings s1 and s2. It returns an integer less than, equal to, or greater than zero if s1 is found, respectively, to be less than, to match, or be greater than s2.
 - `strcpy(char* s1, const char* s2)` [...]The strcpy() function copies the string pointed to by s2, including the terminating null byte ('\0'), to the buffer pointed to by s1.
 - `char* strcpy(char* s1, const char* s2, size_t n)` None of these functions allocates memory!
- Allocate and copy: (not C99, but POSIX)
 - `char* strdup(const char* s)`

78/128

Printing

```
1 #include <stdio.h>
2 printf( "%s\n", "Hello" );
3 printf( "%s\n", "Hello", 27, 3, 14 );
```



Input/Output

79/128

80/128

Tools & Modules

81/128

Hello, Again

```
1 #include <stdio.h>
2
3 int g( int x ) { return x/2; }
4
5 int f() { return g(1); }
6
7 int main() {
8     printf( "Hello-World\n" );
9     return f();
10 }
```

```
• % gcc helloWorld.c
• % ls
• a.out helloWorld.c
• % ./a.out
• Hello World.
• %
```

82/125

Zoom In: Preprocessing, Compiling, Linking

```
1 #include <stdio.h>
2
3 int g( int x ) { return x/2; }
4
5 int f() { return g(1); }
6
7 int main() {
8     printf( "Hello-World\n" );
9     return f();
10 }
```

```
• % gcc -E helloWorld.c > helloWorld.i
• % gcc -c -o helloWorld.o helloWorld.i
• % ld -o helloWorld helloWorld.o [...]
• % ./helloWorld
• Hello World.
• %
```

83/125

Modules

```
1 #include <stdio.h>
2 int g( int x ) {
3     return x/2;
4 }
5
6 int f() {
7     return g(1);
8 }
9
10 int main() {
11     printf( "Hello-World\n" );
12     return f();
13 }
14 )
```

```
- 2014-04 - tools -
- 100 - 40 - 100 -
• % gcc -c g.c f.c \
helloWorld.c
• % ls *.o
• f.o g.o helloWorld.o
• % gcc g.o f.o helloWorld.o
• % ./a.out
• Hello World.
• %
```

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Modules

```
1 #include <stdio.h>
2
3 int g( int x ) {
4     return x/2;
5 }
6
7 int f() {
8     return g(1);
9 }
10
11 int main() {
12     printf( "Hello-World\n" );
13     return f();
14 }
```

Split into:

- h (header): declarations
- c: definitions, use headers to "import" declarations

84/125

Modules

```
1 #include <stdio.h>
2
3 int g( int x ) {
4     return x/2;
5 }
6
7 int f() {
8     return g(1);
9 }
10
11 int main() {
12     printf( "Hello-World\n" );
13     return f();
14 }
```

Split into:

- h (header): declarations
- c: definitions, use headers to "import" declarations

84/125

Modules At Work

```
1 #include <stdio.h>
2 int g( int x ) {
3     return x/2;
4 }
5
6 int f() {
7     return g(1);
8 }
9
10 int main() {
11     printf( "Hello-World\n" );
12     return f();
13 }
14 )
```

preprocess & compile:

```
• % gcc -c g.c f.c \
helloWorld.c
• % ls *.o
• f.o g.o helloWorld.o
link:
• % gcc g.o f.o helloWorld.o
• % ./a.out
• Hello World.
• %
```

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Modules At Work

```

g.h      f.h
1 #include <stdio.h>      1 #include "g.h"
2 #define GHI            2 #define FHI
3 #define PI 3.1415      3 int f(int x) {
4 extern int             4 extern int
5 f(int x);              5 f();
6 #endif                6 #endif

g.c      f.c
1 #include "g.h"          1 #include "g.h"
2 int g(int x) {         2 #include "f.h"
3     return x/2;        3 int f() {
4 }                      4     return g(1);
5                          5 }
6                          6 }

helloworld.c
1 #include <stdio.h>
2 #include "f.h"
3 int main() {
4     printf("Hi!\n");
5     return f();
6 }
    
```

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Modules At Work

```

g.h      f.h
1 #include <stdio.h>      1 #include "g.h"
2 #define GHI            2 #define FHI
3 #define PI 3.1415      3 int f(int x) {
4 extern int             4 extern int
5 f(int x);              5 f();
6 #endif                6 #endif

g.c      f.c
1 #include "g.h"          1 #include "g.h"
2 int g(int x) {         2 #include "f.h"
3     return x/2;        3 int f() {
4 }                      4     return g(1);
5                          5 }
6                          6 }

helloworld.c
1 #include <stdio.h>
2 #include "f.h"
3 int main() {
4     printf("Hi!\n");
5     return f();
6 }
    
```

85/128

Preprocessing

```

helloworld.c
1 #include <stdio.h>
2 #include "f.h"
3 int main() {
4     printf("HelloWorld\n");
5     return f();
6 }

helloworld.1
1 #include <stdio.h>
2 #include "f.h"
3 int main() {
4     printf("HelloWorld\n");
5     return f();
6 }
    
```

86/128

Preprocessing Directives (6.10)

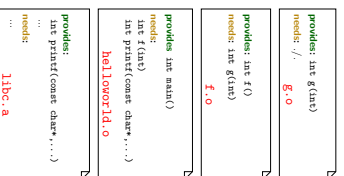
```

1 #include <stdio.h>
2 #include "battery.h"
3
4 #define PI 3.1415
5
6 #define DEBUG
7 #ifdef DEBUG
8     printf("stderr: \"konk\n\");
9 #endif
10
11 #if _GNUCC_ >= 3
12     #define __pure __attribute__((pure))
13 #else
14     #define __pure /* no pure */
15 #endif
16
17 extern int f() __pure;
    
```

2014-04 - tools -

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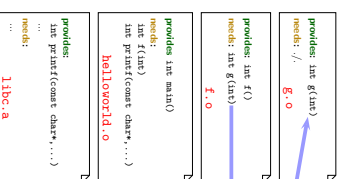
Linking



2014-04 - tools -

88/128

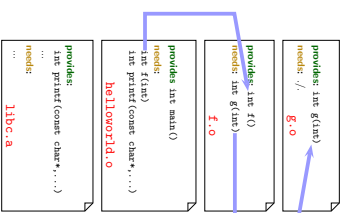
Linking



2014-04 - tools -

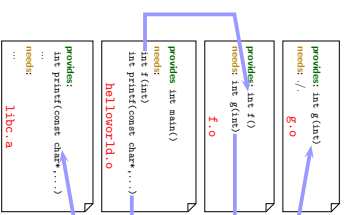
89/128

Linking



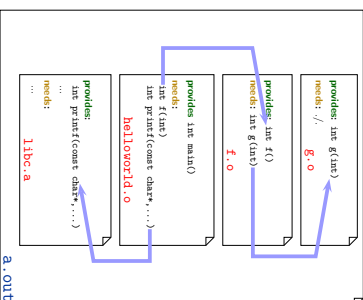
89/128

Linking



89/128

Linking



89/128

Compiler

gcc [OPTION]... -infile...

- E** – preprocess only
- c** – compile only, don't link
- o outfile** – write output to outfile
- g** – add debug information
- W, -Wall, ...** – enable warnings
- I dir** – add dir to library path for searching libraries
- D macro[=defn]** – define macro (to defn)
- l library** link against library (a.so), order matters
- x** cf. man gcc

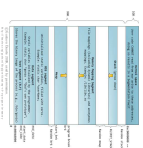
gdb(l), ddd(l), mm(l), mcket(l)

- **Command Line Debugger:**
gdb a.out [core]
 - **GUI Debugger:**
ddd a.out [core]
- (works best with debugging information compiled in (gcc -g))
- **Inspect Object Files:**
mm a.o
 - **Build Utility:**
make
- See battery controller exercise for an example.

90/128

Core Dumps

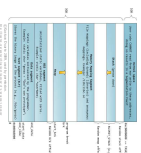
- **Recall:** Anatomy of a Linux Program in Memory
- **Core dump:** (basically) this memory written to a file.



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Core Dumps

- Recall: Anatomy of a Linux Program in Memory
- **Core dump**: (basically) this memory written to a file



```
1 int main() {
2     int *p;
3     *p = 27;
4     return 0;
5 }
```

```
1 % gcc -f core.c
2 coredumpctl ls
3 condumpsize 0 bytes
4 % limit condumpsize 1g
5 % /usr/bin/gdb ./core.c
6 % run
7 % ls --lh core
8 -rw-r--r-- 1 user user 23K Feb 29 11:11 core
9 % cat core
10 GNU gdb (GDB) 7.4.1-debian
11 [ ... ]
12 Program generated by "/usr/bin/gdb"
13 Program generated with "/usr/bin/gdb -segmentation-fault
14 /lib64/ld-linux-x86_64.so.2 /usr/bin/main() ./core.c:3
15 /usr/bin/main() ./core.c:3"
16 /usr/bin/main() ./core.c:3
17 $! core dump: 1) 2) 3)
18 (gdb) q
```

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Formal Methods for C

Correctness and Requirements

Correctness

- Correctness is defined **with respect to a specification**.
 - A program (function, ...) is **correct** (wrt. specification φ) **if and only if** it satisfies φ .
 - Definition of "satisfies": **in a minute**.
- Examples:**
- φ_1 : the return value is 10 divided by parameter (if parameter not 0)
 - φ_2 : the value of variable x is "always" strictly greater than 3
 - φ_3 : the value of i increases in each loop iteration
 - ...

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Common Patterns

- **State Invariants**:
"at this program point, the value of p must not be NULL."
"at all program points, the value of p must not be NULL"
(cf. **sequence points** (Amex C))
- **Data Invariants**:
"the value of n must be the length of s ."
- **(Function) Pre/Post Conditions**:
Pre-Condition: the parameter must not be 0
Post-Condition: the return value is 10 divided by the parameter
- **Loop Invariants**:
"the value of i is between 0 and array length minus 1"

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*Poor Man's Requirements Specification
aka. How to Formalize Requirements in C?*

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Diagnostics (7.2)

```
1 #include <assert.h>
2 void assert( /* scalar */ expression );
```

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1 #include <assert.h>
2 void assert( /* scalar */ expression );
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- "The assert macro puts diagnostic tests into programs: [...]"
- When it is executed, if *expression* (which shall have a scalar type) is false (that is, compares equal to 0), the assert macro
- writes information about the particular call that failed [...] on the standard error stream in an implementation-defined format.
 - It then calls the **abort** function."

- "The assert macro puts diagnostic tests into programs: [...]"
- When it is executed, if *expression* (which shall have a scalar type) is false (that is, compares equal to 0), the assert macro
- writes information about the particular call that failed [...] on the standard error stream in an implementation-defined format.
 - It then calls the **abort** function."

Pitfall:

- If macro `DEBUG` is defined when including `<assert.h>`, `expression` is not evaluated (thus should be side-effect free).

abort (7.20.4.1)

```
1 #include <stdlib.h>
2
3 void abort();
```

- "The abort function causes abnormal program termination to occur, unless [...]"
 - [...] An implementation-defined form of the status unsuccessful termination is returned to the host environment by means of the function call `raise(SIGABRT)`."
- (→ Core Dumps)

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Common Patterns with assert

- **State Invariants:**
"at this program point, the value of *p* must not be NULL."
"at all program points, the value of *p* must not be NULL."
(cf. [sequence points](#) (Annex C))
- **Data Invariants:**
"the value of *n* must be the length of *s*."
- **(Function) Pre/Post Conditions:**
Pre-Condition: the parameter must not be 0
Post-Condition: the return value is 10 divided by the parameter
- **Loop Invariants:**
"the value of *i* is between 0 and array length minus 1"

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State Invariants with <assert.h>

```
1 void f() {
2     int* p = (int*)malloc(sizeof(int));
3     if (!p)
4         return;
5     assert(p); // assume p is valid from here
6     // ...
7 }
8
9 void g() {
10    Node* p = find( 'a' );
11    assert(p); // we inserted 'a' before
12    // ...
13 }
14
15 }
16 }
```

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Data Invariants with <asserth>

```
1 typedef struct {
2   char* s;
3   int n;
4 } str;
5
6 str* construct( char* s ) {
7   str* x = (str*)malloc( sizeof(str) );
8   // ...
9   assert( (x->s == NULL && x->n == -1)
10          || (x->n == strlen( x->s ) ) );
11 }
```

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Pre/Post Conditions with <asserth>

```
1 int f( int x ) {
2   assert( x != 0 ); // pre-condition
3
4   int r = 10/x;
5
6   assert( r == 10/x ); // post-condition
7
8   return r;
9 }
```

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Loop Invariants with <asserth>

```
1 void f( int a[], int n ) {
2   int i = 0;
3
4   // holds before the loop
5   assert( 0 <= i && i <= n );
6   assert( i < 1 || a[i-1] == 0 );
7
8   while ( i < n ) {
9     // holds before each iteration
10    assert( 0 <= i && i <= n );
11    assert( i < 1 || a[i-1] == 0 );
12
13    a[i++] = 0;
14  }
15  // holds after exiting the loop
16  assert( 0 <= i && i <= n );
17  assert( i < 1 || a[i-1] == 0 );
18
19  return;
20 }
```

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Old Variables, Ghost Variables

```
1 void xorSwap( unsigned int* a, unsigned int* b ) {
2   #ifdef NDEBUG
3     unsigned int *old_a = a, *old_b = b;
4   #endif
5   assert( a && b ); assert( a != b ); // pre-condition
6
7   *a = *a + *b;
8   *b = *a - *b;
9   *a = *a - *b;
10
11   assert( *a == *old_b && *b == *old_a ); // post-con-
12   assert( a == old_a && b == old_b ); // ditto
13 }
```

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Outlook

- Some verification tools simply verify for each assert statement: When executed, expression is not false.
- Some verification tools support sophisticated requirements specification languages like ACSL with explicit support for
 - pre/post conditions
 - ghost variables, old values
 - data invariants
 - loop invariants
 - ...

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Dependable Verification (Jackson)

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Dependability

- "The program has been verified." tells us

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Dependability

- "The program has been verified." tells us **not very much**.

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 - Which specifications have been considered?

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Dependability

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- One wants to know (and should state):
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 - Under **which assumptions** was the verification conducted?
 - Platform assumptions: (finite words (size²), mathematical integers, ...)
 - Environment assumptions, input values, ...Assumptions are often implicit: "in the tool"!

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Dependability

- "The program has been verified." tells us **not very much**.
- One wants to know (and should state):
 - Which specifications have been considered?
 - Under **which assumptions** was the verification conducted?
 - Platform assumptions: (finite words (size²), mathematical integers, ...)
 - Environment assumptions, input values, ...Assumptions are often implicit: "in the tool"!
 - And **what does verification mean** after all?
 - In some contexts: **testing**.
 - In some contexts: **review**.
 - In some contexts: **model-checking procedure**. ("We verified the program" – "What did the tool say?" – "Verification failed.")
 - In some contexts: **model-checking tool claims correctness**.

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Distinguish

Most **generic errors** boil down to:

- specified but **unwanted behaviour**,
e.g. under/overflows
- **initialisation issues**
e.g. automatic block scope objects
- **unspecified behaviour** (J1)
e.g. order of evaluation in some cases
- **undefined behaviour** (J2)
- **implementation defined behaviour** (J3)

Conformance (4)

- "A program that is
 - correct in all other aspects,
 - operating on correct data,
 - containing **unspecified behaviour**
- shall be a correct program and act in accordance with 5.1.1.2.3. (Program Execution)
- A conforming program is one that is acceptable to a conforming implementation.
 - Strictly conforming programs are intended to be maximally portable among conforming implementations.
 - An implementation [of C, a compiler] shall be accompanied by a document that defines all implementation-defined and local-specific characteristics and all extensions.

Common Errors

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Over- and Underflows, Casting

- Not specific to C...

Over- and Underflows

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```
1 void f( short a, int b ) {
2     a = b; // Spng 'ok', but...
3 }
4 short a; // provisioning, implicit cast
5 if (++a < 0) { /* no */ }
6 if (++i > MAXINT) {
7     /* no */ }
8
9
10
11
12 int e = 0;
13
14 void set-error() { e++; }
15 void clear-error() { e = 0; }
16
17 void g() { if (e) { /* ... */ } }
```

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Initialisation (6.7.8)

Initialisation (6.7.8)

- If an object that has automatic storage duration is not initialized explicitly, its value is indeterminate.

```
1 void f() {
2     int a;
3
4     printf( "%i\n", a ); // surprise...
5 }
```

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Unspecified Behaviour (1.1)

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Unspecified Behaviour (1.1)

Each implementation (of a compiler) documents how the choice is made.

For example

- whether two string literals result in distinct arrays (6.4.5)
 - the order in which the function designator, arguments, and subexpressions within the arguments are evaluated in a function call (6.5.2.2)
 - the layout of storage for function parameters (6.9.1)
 - the result of rounding when the value is out of range (7.12.9.5, ...)
 - the order and contiguity of storage allocated by successive calls to malloc (7.20.3)
- etc. pp.

```
1 char a[] = "hello", b[] = "hello"; // a == b?
2
3 i = 0; f( ++i, ++i, ++i ); // f(1,2,3)?
4
5 int g() { int a, b; } // &a > &b ?
6
7 int* p = malloc( sizeof( int ) );
8 int* q = malloc( sizeof( int ) ); // q > p?
9
```

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Undefined Behaviour (3.4.3)

"Behaviour, upon use of a non-portable or erroneous program construct or of erroneous data, for which this International Standard imposes no requirements."

Possible undefined behaviour ranges from

- ignoring the situation completely with **unpredictable results**,
- to behaving during **translation or program execution** in a documented manner characteristic of the environment (with or without the issuance of a diagnostic message),
- to terminating a **translation or execution** (with the issuance of a diagnostic message)""

"An example of undefined behaviour is the behaviour on **integer overflow**."

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Undefined Behaviour (1.2)

More examples:

- an identifier [...] contains an invalid multibyte character (5.2.1.2)

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Undefined Behaviour (1.2)

More examples:

- an identifier [...] contains an invalid multibyte character (5.2.1.2)
- an object is referred to outside of its lifetime (6.2.4)

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Undefined Behaviour (1.2)

More examples:

- an identifier [...] contains an invalid multibyte character (5.2.1.2)
- an object is referred to outside of its lifetime (6.2.4)
- the value of a pointer to an object whose lifetime has ended is used (6.2.4)

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- an identifier [...] contains an invalid multibyte character (5.2.1.2)
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- conversion to or from an integer type produces a value outside the range that can be represented (6.3.1.4)

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- an exceptional condition occurs during the evaluation of an expression (6.5)
- the value of the second operand of the / or % operator is zero (6.5.5)

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- the program removes the definition of a macro whose name begins with an underscore and either an uppercase letter or another underscore (7.1.3)

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- etc. pp.

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Null-Pointer

```
1 int main() {
2     int *p;
3     *p = 27;
4     return 0;
5 }
```

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Null-Pointer

```
1 int main() {
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```

- "An integer constant expression with the value 0, or such an expression cast to type `void*` is called a **null pointer constant** [...]".
- "The macro **NULL** is defined in `<stddef.h>` (and other headers) as a null pointer constant; see 7.17".
- "Among the invalid values for dereferencing a pointer by the unary `*` operator are a null pointer [...] (0.5.3.2)".

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Segmentation Violation

```
1 int main() {
2     int *p = (int*)0x12345678;
3     *p = 27;
4     *(int*)((void*)p) + 1 = 13;
5     return 0;
6 }
7 }
```

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- Modern operating systems provide **memory protection**.
- Accessing memory which the process is not allowed to access is observed by the operating system.
- Typically an instance of "accessing an object outside its lifetime".
- **But:** other way round does not hold, accessing an object outside its lifetime does not imply a segmentation violation.

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- Typically an instance of "accessing an object outside its lifetime".
- **But:** other way round does not hold, accessing an object outside its lifetime does not imply a segmentation violation.
- Some platforms (e.g. SPARC) unaligned memory access, i.e. outside word boundaries, not supported by hardware ("bus error").
- Operating system notifies process, default handler: terminate, dump core.

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Implementation-Defined Behaviour (1.3)

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Implementation-Defined Behaviour (1.3)

"A conforming implementation is required to document its choice of behavior in each of the areas listed in this subclause. The following are implementation-defined:"

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Implementation-Defined Behaviour (J.3)

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- J.3.2 Environment, e.g.
- The set of signals, their semantics, and their default handling (7.14)

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- J.3.4 Characters, e.g.
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- J.3.5 Integers, e.g.
- Any extended integer types that exist in the implementation (6.2.5)

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- Any extended integer types that exist in the implementation (6.2.5)
- J.3.6 Floating Point, e.g.
- The accuracy of the floating-point operations [...] (5.2.4.2.2)

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- J.3.7 Arrays and Pointers, e.g.
- The result of converting a pointer to an integer or vice versa (6.3.2.3)

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- The result of converting a pointer to an integer or vice versa (6.3.2.3)
- etc. pp.

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Locale and Common Extensions (J.4, J.5)

- J.4 Locale-specific behaviour

- J.5 Common extensions

"The following extensions are widely used in many systems, but are not portable to all implementations."

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References

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