

Real-Time Systems

Lecture 03: Duration Calculus I

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Contents & Goals

Last Lecture:

- Model of timed behaviour: state variables and their interpretation
- First order predicate-logic for requirements and system properties
- Classes of requirements (safety, liveness, etc.)

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - Read (and at best also write) Duration Calculus formulae.
- **Content:**
 - Duration Calculus:
Assertions, Terms, Formulae, Abbreviations, Examples

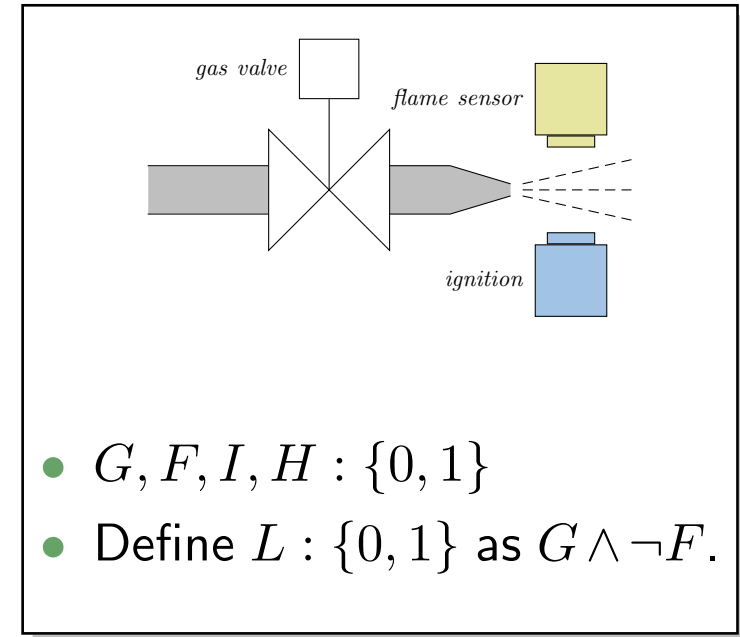
Duration Calculus

Duration Calculus: Preview

- Duration Calculus is an **interval logic**.
- Formulae are evaluated in an **(implicitly given)** interval.

Strangest operators:

- **everywhere** — Example: $\lceil G \rceil$
(Holds in a given interval $[b, e]$ iff the gas valve is open almost everywhere.)
- **chop** — Example: $(\lceil \neg I \rceil ; \lceil I \rceil ; \lceil \neg I \rceil) \implies \ell \geq 1$
(Ignition phases last at least one time unit.)
- **integral** — Example: $\ell \geq 60 \implies \int L \leq \frac{\ell}{20}$
(At most 5% leakage time within intervals of at least 60 time units.)



Duration Calculus: Overview

We will introduce three (or five) syntactical “levels”:

(i) **Symbols:**

$f, g, \text{ true, false, =, <, >, \leq, \geq, } x, y, z, X, Y, Z, d$

(ii) **State Assertions:**

$P ::= 0 \mid 1 \mid X = d \mid \neg P_1 \mid P_1 \wedge P_2$

(iii) **Terms:**

$\theta ::= x \mid \ell \mid f P \mid f(\theta_1, \dots, \theta_n)$

(iv) **Formulae:**

$F ::= p(\theta_1, \dots, \theta_n) \mid \neg F_1 \mid F_1 \wedge F_2 \mid \forall x \bullet F_1 \mid F_1 ; F_2$

(v) **Abbreviations:**

$\llbracket \cdot \rrbracket, \llbracket P \rrbracket, \llbracket P \rrbracket^t, \llbracket P \rrbracket^{\leq t}, \diamond F, \square F$

Symbols: Syntax

- f, g : **function symbols**, each with arity $n \in \mathbb{N}_0$.
Called **constant** if $n = 0$.
Assume: constants $0, 1, \dots \in \mathbb{N}_0$; binary $'+'$ and $'\cdot'$.
- p, q : **predicate symbols**, also with arity.
Assume: constants $true, false$; binary $=, <, >, \leq, \geq$.
- $x, y, z \in \text{GVar}$: **global variables**.
- $X, Y, Z \in \text{Obs}$: **state variables** or **observables**, each of a data type \mathcal{D} (or $\mathcal{D}(X), \mathcal{D}(Y), \mathcal{D}(Z)$ to be precise).
Called **boolean observable** if data type is $\{0, 1\}$.
- d : **elements** taken from data types \mathcal{D} of observables.

Symbols: Semantics

- **Semantical domains** are
 - the **truth values** $\mathbb{B} = \{\text{tt}, \text{ff}\}$,
 - the **real numbers** \mathbb{R} ,
 - **time** Time,
(mostly $\text{Time} = \mathbb{R}_0^+$ (continuous), exception $\text{Time} = \mathbb{N}_0$ (discrete time))
 - and **data types** \mathcal{D} .
- The semantics of an n -ary **function symbol** f is a (mathematical) function from \mathbb{R}^n to \mathbb{R} , denoted \hat{f} , i.e.

$$\hat{f} : \mathbb{R}^n \rightarrow \mathbb{R}.$$

- The semantics of an n -ary **predicate symbol** p is a function from \mathbb{R}^n to \mathbb{B} , denoted \hat{p} , i.e.

$$\hat{p} : \mathbb{R}^n \rightarrow \mathbb{B}.$$

Symbols: Examples

- The **semantics** of the function and predicate symbols **assumed above** is fixed throughout the lecture:
 - $\hat{true} = tt$, $\hat{false} = ff$
 - $\hat{0} \in \mathbb{R}$ is the (real) number **zero**, etc.
 - $\hat{+} : \mathbb{R}^2 \rightarrow \mathbb{R}$ is the **addition** of real numbers, etc.
 - $\hat{=} : \mathbb{R}^2 \rightarrow \mathbb{B}$ is the **equality** relation on real numbers,
 - $\hat{<} : \mathbb{R}^2 \rightarrow \mathbb{B}$ is the **less-than** relation on real numbers, etc.
- “Since the semantics is the expected one, we shall often simply use the symbols $0, 1, +, \cdot, =, <$ when we mean their semantics $\hat{0}, \hat{1}, \hat{+}, \hat{\cdot}, \hat{=}, \hat{<}$.”

Symbols: Semantics

- The semantics of a **global variable** is not fixed (throughout the lecture) but given by a **valuation**, i.e. a mapping

$$\mathcal{V} : \text{GVar} \rightarrow \mathbb{R}$$

assigning each global variable $x \in \text{GVar}$ a real number $\mathcal{V}(x) \in \mathbb{R}$.

We use Val to denote the set of all valuations, i.e. $\text{Val} = (\text{GVar} \rightarrow \mathbb{R})$.

Global variables are though **fixed over time** in system evolutions.

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Global variables are though **fixed over time** in system evolutions.

- The semantics of a **state variable** is **time-dependent**. It is given by an interpretation \mathcal{I} , i.e. a mapping

$$\mathcal{I} : \text{Obs} \rightarrow (\text{Time} \rightarrow \mathcal{D})$$

assigning each state variable $X \in \text{Obs}$ a function

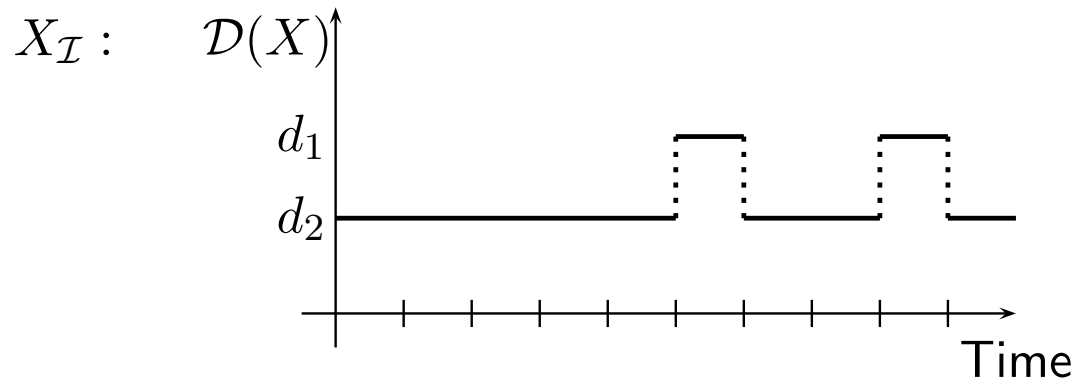
$$\mathcal{I}(X) : \text{Time} \rightarrow \mathcal{D}(X)$$

such that $\mathcal{I}(X)(t) \in \mathcal{D}(X)$ denotes the value that X has at time $t \in \text{Time}$.

Symbols: Representing State Variables

- For convenience, we shall abbreviate $\mathcal{I}(X)$ to $X_{\mathcal{I}}$.
- An **interpretation** (of a state variable) can be displayed in form of a **timing diagram**.

For instance,



with $\mathcal{D}(X) = \{d_1, d_2\}$.

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State Assertions: Syntax

- The set of **state assertions** is defined by the following grammar:

$$P ::= 0 \mid 1 \mid X = d \mid \neg P_1 \mid P_1 \wedge P_2$$

with $d \in \mathcal{D}(X)$.

We shall use P, Q, R to denote state assertions.

- **Abbreviations:**
 - We shall write X instead of $X = 1$ if $\mathcal{D}(X) = \mathbb{B}$.
 - Define \vee, \implies, \iff as usual.

State Assertions: Semantics

- The **semantics** of **state assertion** P is a function

$$\mathcal{I}[[P]] : \text{Time} \rightarrow \{0, 1\}$$

i.e. $\mathcal{I}[[P]](t)$ denotes the truth value of P at time $t \in \text{Time}$.

- The value is defined **inductively** on the structure of P :

$$\mathcal{I}[[0]](t) = 0,$$

$$\mathcal{I}[[1]](t) = 1,$$

$$\mathcal{I}[[X = d]](t) = \begin{cases} 1 & , \text{ if } X_{\mathcal{I}} = d \\ 0 & , \text{ otherwise,} \end{cases}$$

$$\mathcal{I}[[\neg P_1]](t) = 1 - \mathcal{I}[[P_1]](t)$$

$$\mathcal{I}[[P_1 \wedge P_2]](t) = \begin{cases} 1 & , \text{ if } \mathcal{I}[[P_1]](t) = \mathcal{I}[[P_2]](t) = 1 \\ 0 & , \text{ otherwise,} \end{cases}$$

State Assertions: Notes

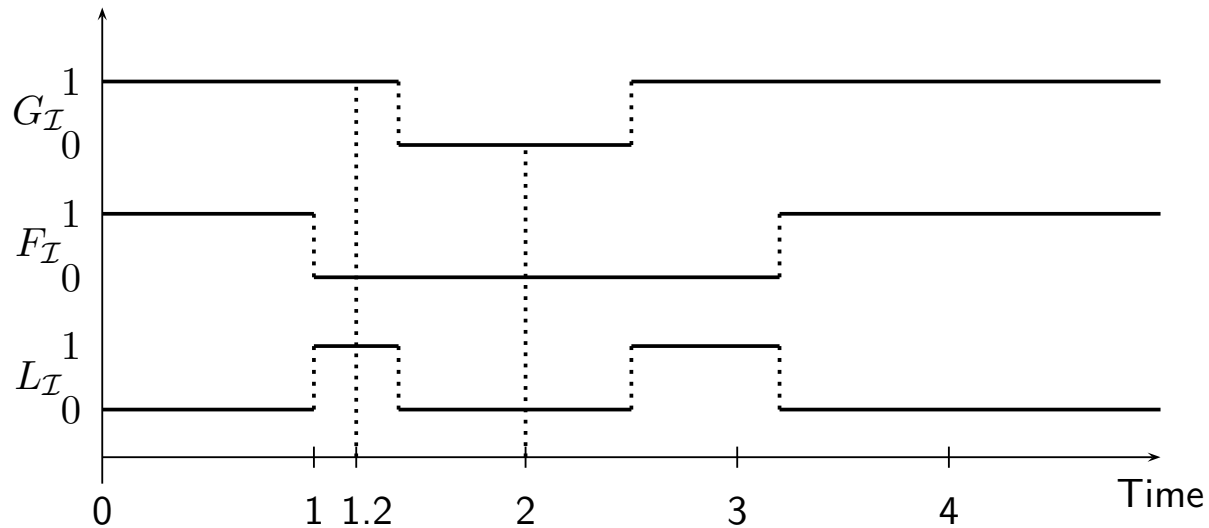
- $\mathcal{I}[[X]](t) = \mathcal{I}[[X = 1]](t) = \mathcal{I}(X)(t) = X_{\mathcal{I}}(t)$, if X boolean.
- $\mathcal{I}[[P]]$ is also called **interpretation** of P .

We shall write $P_{\mathcal{I}}$ for it.

- Here we prefer 0 and 1 as boolean values (instead of tt and ff) — for reasons that will become clear immediately.

State Assertions: Example

- Boolean observables G and F .
- State assertion $L := G \wedge \neg F$.



- $L_I(1.2) = 1$, because
- $L_I(2) = 0$, because

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Terms: Syntax

- **Duration terms** (DC terms or just terms) are defined by the following grammar:

$$\theta ::= x \mid \ell \mid \int P \mid f(\theta_1, \dots, \theta_n)$$

where x is a global variable, ℓ and f are special symbols, P is a state assertion, and f a function symbol (of arity n).

- ℓ is called **length operator**, f is called **integral operator**
- Notation: we may write function symbols in **infix notation** as usual, i.e. write $\theta_1 + \theta_2$ instead of $+(\theta_1, \theta_2)$.

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Definition 1. [*Rigid*]

A term **without** length and integral symbols is called **rigid**.

Terms: *Semantics*

- Closed **intervals** in the time domain

$$\text{Intv} := \{[b, e] \mid b, e \in \text{Time and } b \leq e\}$$

Point intervals: $[b, b]$

Terms: Semantics

- The **semantics** of a **term** is a function

$$\mathcal{I}[\theta] : \text{Val} \times \text{Intv} \rightarrow \mathbb{R}$$

i.e. $\mathcal{I}[\theta](\mathcal{V}, [b, e])$ is the real number that θ denotes under interpretation \mathcal{I} and valuation \mathcal{V} in the interval $[b, e]$.

- The value is defined **inductively** on the structure of θ :

$$\mathcal{I}[x](\mathcal{V}, [b, e]) = \mathcal{V}(x),$$

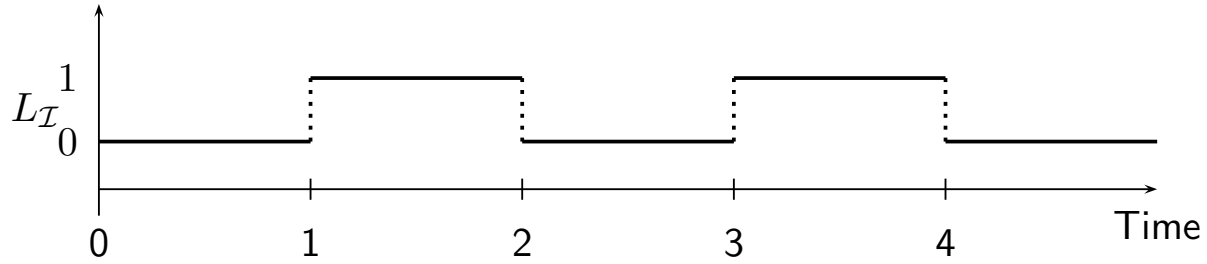
$$\mathcal{I}[\ell](\mathcal{V}, [b, e]) = e - b,$$

$$\mathcal{I}[f P](\mathcal{V}, [b, e]) = \int_b^e P_{\mathcal{I}}(t) dt,$$

$$\mathcal{I}[f(\theta_1, \dots, \theta_n)](\mathcal{V}, [b, e]) = \hat{f}(\mathcal{I}[\theta_1](\mathcal{V}, [b, e]), \dots, \mathcal{I}[\theta_n](\mathcal{V}, [b, e])),$$

Terms: Example

$$\theta = x \cdot \int L$$



$$\mathcal{V}(x) = 20.$$

Terms: Semantics Well-defined?

- So, $\mathcal{I}[\llbracket f P \rrbracket](\mathcal{V}, [b, e])$ is $\int_b^e P_{\mathcal{I}}(t) dt$ — but does the integral always exist?

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- IOW: is there a $P_{\mathcal{I}}$ which is not (Riemann-)integrable? Yes. For instance

$$P_{\mathcal{I}}(t) = \begin{cases} 1 & , \text{ if } t \in \mathbb{Q} \\ 0 & , \text{ if } t \notin \mathbb{Q} \end{cases}$$

Terms: Semantics Well-defined?

- So, $\mathcal{I}[\int P](\mathcal{V}, [b, e])$ is $\int_b^e P_{\mathcal{I}}(t) dt$ — but does the integral always exist?
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- To exclude such functions, DC considers only interpretations \mathcal{I} satisfying the following condition of **finite variability**:

For each state variable X and each interval $[b, e]$ there is a **finite partition** of $[b, e]$ such that the interpretation $X_{\mathcal{I}}$ is **constant on each part**.

Thus on each interval $[b, e]$ the function $X_{\mathcal{I}}$ has only **finitely many points of discontinuity**.

Remark 2.5. The semantics $\mathcal{I}[\theta]$ of a term is insensitive against changes of the interpretation \mathcal{I} at individual time points.

Remark 2.6. The semantics $\mathcal{I}[\theta](\mathcal{V}, [b, e])$ of a **rigid** term does not depend on the interval $[b, e]$.

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Formulae: Syntax

- The set of **DC formulae** is defined by the following grammar:

$$F ::= p(\theta_1, \dots, \theta_n) \mid \neg F_1 \mid F_1 \wedge F_2 \mid \forall x \bullet F_1 \mid F_1 ; F_2$$

where p is a predicate symbol, θ_i a term, x a global variable.

- **chop operator**: ‘;’
 - **atomic formula**: $p(\theta_1, \dots, \theta_n)$
 - **rigid formula**: all terms are rigid
 - **chop free**: ‘;’ doesn’t occur
 - usual notion of **free** and **bound** (global) variables
-
- Note: quantification only over (**first-order**) global variables, not over (**second-order**) state variables.

Formulae: Priority Groups

- To avoid parentheses, we define the following five priority groups from highest to lowest priority:

- \neg (negation)
- $;$ (chop)
- \wedge, \vee (and/or)
- \implies, \iff (implication/equivalence)
- \exists, \forall (quantifiers)

Examples:

- $\neg F ; F \vee H$
- $\forall x \bullet F \wedge G$

Syntactic Substitution...

...of a term θ for a variable x in a formula F .

- We use

$$F[x := \theta]$$

to denote the formula that results from performing the following steps:

- (i) transform F into \tilde{F} by (consistently) renaming bound variables such that no free occurrence of x in \tilde{F} appears within a quantified subformula $\exists z \bullet G$ or $\forall z \bullet G$ for some z occurring in θ ,
- (ii) textually replace all free occurrences of x in \tilde{F} by θ .

Examples: $F := (x \geq y \implies \exists z \bullet z \geq 0 \wedge x = y + z)$, $\theta_1 := \ell$,
 $\theta_2 := \ell + z$,

- $F[x := \theta_1] = (x \geq y \implies \exists z \bullet z \geq 0 \wedge x = y + z)$
- $F[x := \theta_2] = (x \geq y \implies \exists z \bullet z \geq 0 \wedge x = y + z)$

Formulae: Semantics

- The **semantics** of a **formula** is a function

$$\mathcal{I}[[F]] : \text{Val} \times \text{Intv} \rightarrow \{\text{tt}, \text{ff}\}$$

i.e. $\mathcal{I}[[F]](\mathcal{V}, [b, e])$ is the truth value of F under interpretation \mathcal{I} and valuation \mathcal{V} in the interval $[b, e]$.

- This value is defined **inductively** on the structure of F :

$$\mathcal{I}[[p(\theta_1, \dots, \theta_n)]](\mathcal{V}, [b, e]) = \hat{p}(\mathcal{I}[[\theta_1]](\mathcal{V}, [b, e]), \dots, \mathcal{I}[[\theta_n]](\mathcal{V}, [b, e])),$$

$$\mathcal{I}[[\neg F_1]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff } \mathcal{I}[[F_1]](\mathcal{V}, [b, e]) = \text{ff},$$

$$\mathcal{I}[[F_1 \wedge F_2]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff } \mathcal{I}[[F_1]](\mathcal{V}, [b, e]) = \mathcal{I}[[F_2]](\mathcal{V}, [b, e]) = \text{tt},$$

$$\mathcal{I}[[\forall x \bullet F_1]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff for all } a \in \mathbb{R},$$

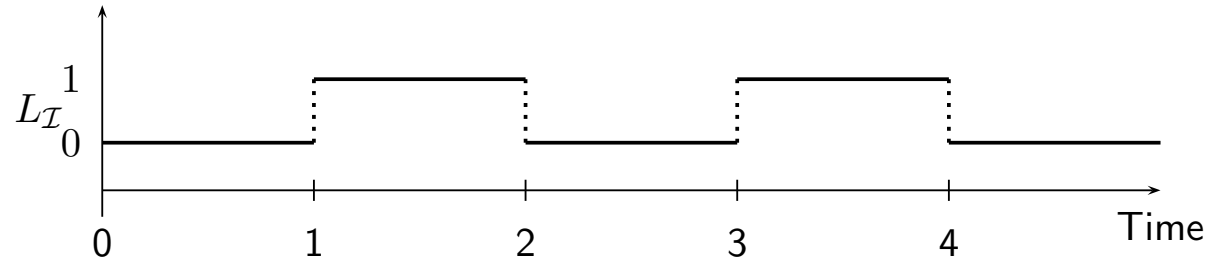
$$\mathcal{I}[[F_1[x := a]]](\mathcal{V}, [b, e]) = \text{tt}$$

$$\mathcal{I}[[F_1 ; F_2]](\mathcal{V}, [b, e]) = \text{tt} \text{ iff there is an } m \in [b, e] \text{ such that}$$

$$\mathcal{I}[[F_1]](\mathcal{V}, [b, m]) = \mathcal{I}[[F_2]](\mathcal{V}, [m, e]) = \text{tt}. \quad 27/33$$

Formulae: Example

$$F := \int L = 0 ; \int L = 1$$



- $\mathcal{I}[[F]](\mathcal{V}, [0, 2]) =$

Remark 2.10. [*Rigid and chop-free*] Let F be a duration formula, \mathcal{I} an interpretation, \mathcal{V} a valuation, and $[b, e] \in \text{Intv}$.

- If F is **rigid**, then

$$\forall [b', e'] \in \text{Intv} : \mathcal{I}[[F]](\mathcal{V}, [b, e]) = \mathcal{I}[[F]](\mathcal{V}, [b', e']).$$

- If F is **chop-free** or θ is **rigid**, then in the calculation of the semantics of F , every occurrence of θ denotes the same value.

Substitution Lemma

Lemma 2.11. [Substitution]

Consider a formula F , a global variable x , and a term θ such that F is **chop-free** or θ is **rigid**.

Then for all interpretations \mathcal{I} , valuations \mathcal{V} , and intervals $[b, e]$,

$$\mathcal{I}[[F[x := \theta]]](\mathcal{V}, [b, e]) = \mathcal{I}[[F]](\mathcal{V}[x := a], [b, e])$$

where $a = \mathcal{I}[[\theta]](\mathcal{V}, [b, e])$.

- $F := \ell = x ; \ell = x \implies \ell = 2 \cdot x, \quad \theta := \ell$

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References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.