

Real-Time Systems

Lecture 06: DC Properties I

2014-05-22

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Contents & Goals

Last Lecture:

- DC Syntax and Semantics: Abbreviations (“almost everywhere”)
- Satisfiable/Realisable/Valid (from 0)

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What are obstacles on proving a design correct in the real-world, and how to overcome them?
 - Facts: decidability properties.
 - What's the idea of the considered (un)decidability proofs?
- **Content:**
 - Semantical Correctness Proof
 - (Un-)Decidable problems of DC variants in discrete and continuous time

– 06 – 2014-05-22 – Prelim –

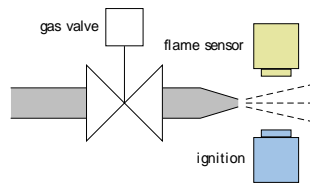
Specification and Semantics-based Correctness Proofs of Real-Time Systems with DC

Methodology: Ideal World...

- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide the **requirement/specification** 'Spec' as a conjunction of DC formulae (over 'Obs').
- (iii) Provide a description 'Ctrl' of the **controller** in form of a DC formula (over 'Obs').
- (iv) We say 'Ctrl' is **correct** (wrt. 'Spec') iff

$$\models_0 \text{Ctrl} \implies \text{Spec}.$$

Gas Burner Revisited



(i) Choose **observables**:

- two boolean observables G and F
(i.e. $\text{Obs} = \{G, F\}$, $\mathcal{D}(G) = \mathcal{D}(F) = \{0, 1\}$)
- $G = 1$: gas valve open
- $F = 1$: have flame
- define $L := G \wedge \neg F$ (leakage)

(output)

(input)

(ii) Provide the **requirement**:

$$\text{Req} : \iff \Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

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Gas Burner Revisited

(iii) Provide a description 'Ctrl' of the **controller** in form of a DC formula (over 'Obs'). Here, firstly consider a **design**:

- Des-1 : $\iff \Box(\lceil L \rceil \implies \ell \leq 1)$
- Des-2 : $\iff \Box(\lceil L \rceil ; \lceil \neg L \rceil ; \lceil L \rceil \implies \ell > 30)$

(iv) Prove **correctness**:

- We want (or do we want $\models_0 \dots?$):

$$\models (\text{Des-1} \wedge \text{Des-2} \implies \text{Req}) \quad (\text{Thm. 2.16})$$

- We do show

$$\models \text{Req-1} \implies \text{Req} \quad (\text{Lem. 2.17})$$

with the simplified requirement

$$\text{Req-1} := \Box(\ell \leq 30 \implies \int L \leq 1),$$

- and we show

$$\models (\text{Des-1} \wedge \text{Des-2}) \implies \text{Req-1}. \quad (\text{Lem. 2.19})$$

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Gas Burner Revisited: Lemma 2.17

Claim:

$$\models \underbrace{\square(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}} \implies \underbrace{\square(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)}_{\text{Req}}$$

Proof:

- Assume 'Req-1'.
- Let $L_{\mathcal{I}}$ be any interpretation of L , and $[b, e]$ an interval with $e - b \geq 60$.
- Show " $20 \cdot \int L \leq \ell$ ", i.e.

$$\mathcal{I} \models 20 \cdot \int L \leq \ell \text{ in } \mathcal{I} \text{ (s.t. } \mathcal{I} \models \text{Req-1})$$

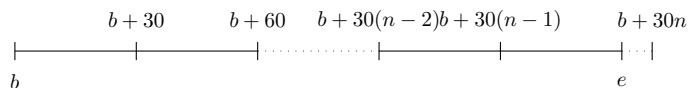
i.e.

$$20 \cdot \int_b^e L_{\mathcal{I}}(t) dt \leq (e - b)$$

Gas Burner Revisited: Lemma 2.17

$$\models \underbrace{\square(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}} \implies \square(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

- Set $n := \lceil \frac{e-b}{30} \rceil$, i.e. $n \in \mathbb{N}$ with $n - 1 < \frac{e-b}{30} \leq n$, and split the interval



$$20 \cdot \int_b^e L_{\mathcal{I}}(t) dt = 20 \cdot \left(\sum_{i=0}^{n-2} \int_{b+30i}^{b+(i+1)30} L_{\mathcal{I}}(t) dt + \int_{b+30 \cdot (n-1)}^e L_{\mathcal{I}}(t) dt \right)$$

$$\stackrel{\{\text{Req-1}\}}{\leq} 20 \cdot \sum_{i=0}^{n-2} 1 + 20 \cdot 1$$

$$= 20 \cdot n$$

$$\stackrel{\{\text{Req}\}}{\leq} 20 \cdot \left(\frac{e-b}{30} + 1 \right)$$

$$= \frac{2}{3}(e-b) + 20$$

$$\stackrel{\left\{ \begin{array}{l} e-b \geq 60 \\ 20 \leq \frac{2}{3}(e-b) \end{array} \right\}}{\leq} e-b$$

Some Laws of the DC Integral Operator

Theorem 2.18.

For all state assertions P and all real numbers $r_1, r_2 \in \mathbb{R}$,

- (i) $\models \int P \leq \ell$,
- (ii) $\models (\int P = r_1) ; (\int P = r_2) \implies \int P = r_1 + r_2$,
- (iii) $\models [\neg P] \implies \int P = 0$,
- (iv) $\models \square \implies \int P = 0$.

Gas Burner Revisited: Lemma 2.18

Claim: for all $I, V, [b \in \mathbb{C}]$

$$\models \underbrace{(\square([\perp] \implies \ell \leq 1))}_{\text{Des-1}} \wedge \underbrace{(\square([\perp]; [\neg L]; [\perp] \implies \ell > 30))}_{\text{Des-2}} \implies \underbrace{(\square(\ell \leq 30))}_{\text{Req-1}} \implies \int L \leq 1$$

(i) $\int P \leq \ell$ (ii) $\int P = r_1 ; \int P = r_2 \implies \int P = r_1 + r_2$
 (iii) $\int P = 0$ (iv) $\int P = 0$

Proof:

$$\begin{aligned} & \ell \leq 30 \\ & \implies \Gamma \perp \\ & \vee \Gamma \perp ; (\Gamma \vee \Gamma \perp) \\ & \vee \Gamma \perp ; (\Gamma \vee \Gamma \perp) \\ & \vee \Gamma \perp ; \Gamma \perp ; \Gamma \perp \end{aligned} \quad (*)$$

{Des-2} $\implies (*)$

{Des-1} $\implies \Gamma \perp$
 $\vee (\ell \leq 1) ; (\Gamma \vee \Gamma \perp)$
 $\vee \Gamma \perp ; (\Gamma \vee \Gamma \perp)$
 $\vee \Gamma \perp ; (\ell \leq 1) ; \Gamma \perp$

{(i)} $\implies \Gamma \perp$
 $\vee (\int L \leq 1) ; (\Gamma \vee \Gamma \perp)$
 $\vee \Gamma \perp ; (\Gamma \vee (\int L \leq 1))$
 $\vee \Gamma \perp ; (\int L \leq 1) ; \Gamma \perp$

{(iv)} $\implies \int L = 0$
 $\vee (\int L \leq 1) ; (L = 0 \vee \int L = 0)$
 $\vee (\int L = 0) ; (\int L = 0 \vee \int L \leq 1)$
 $\vee (\int L = 0) ; (\int L \leq 1) ; (\int L = 0)$

{(ii)} $\implies \int L = 0$
 $\vee \int L \leq 1 + 0$
 $\vee \int L \leq 0 + 1$
 $\vee \int L \leq 0 + 1 + 0$
 $\implies \int L \leq 1 \quad \square$

Obstacles in Non-Ideal World

Methodology: The World is Not Ideal...

- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide **specification** 'Spec' (conjunction of DC formulae (over 'Obs')).
- (iii) Provide a description 'Ctrl' of the **controller** (DC formula (over 'Obs')).
- (iv) Prove 'Ctrl' is **correct** (wrt. 'Spec').

That looks **too simple to be practical**. Typical **obstacles**:

- (i) It may be impossible to realise 'Spec' if it doesn't consider properties of **the plant**.
- (ii) There are typically intermediate **design levels** between 'Spec' and 'Ctrl'.
- (iii) 'Spec' and 'Ctrl' may use **different observables**.
- (iv) **Proving** validity of the implication is not trivial.

(i) Assumptions As A Form of Plant Model

- Often the controller will (or can) operate correctly only under some **assumptions**.
- For instance, with a level crossing
 - we may assume an upper bound on the speed of approaching trains, (otherwise we'd need to close the gates arbitrarily fast)
 - we may assume that trains are not arbitrarily slow in the crossing, (otherwise we can't make promises to the road traffic)
- We shall specify such assumptions as a DC formula 'Asm' on the **input observables** and verify correctness of 'Ctrl' wrt. 'Spec' by proving validity (from 0) of

$$\text{Ctrl} \wedge \text{Asm} \implies \text{Spec}$$

- Shall we **care** whether 'Asm' is satisfiable? **YES!**

(ii) Intermediate Design Levels

- A top-down development approach may involve
 - Spec — specification/requirements
 - Des — design
 - Ctrl — implementation
- Then correctness is established by proving validity of

$$\text{Ctrl} \implies \text{Des} \tag{1}$$

and

$$\text{Des} \implies \text{Spec} \tag{2}$$

(then concluding $\text{Ctrl} \implies \text{Spec}$ by transitivity)

- Any preference on the order?

(iii): Different Observables

- Assume, 'Spec' uses more abstract observables Obs_A and 'Ctrl' more concrete ones Obs_C .
- For instance:
 - in Obs_A : only consider gas valve open or closed ($\mathcal{D}(G) = \{0, 1\}$)
 - in Obs_C : may control two valves and care for intermediate positions, for instance, to react to different heating requests ($\mathcal{D}(G_1) = \{0, 1, 2, 3\}, \mathcal{D}(G_2) = \{0, 1, 2, 3\}$)
- To prove correctness, we need information how the observables are related — an **invariant** which **links** the data values of Obs_A and Obs_C .
- **If** we're given the linking invariant as a DC formula, say 'Link $_{C,A}$ ', **then** proving correctness of 'Ctrl' wrt. 'Spec' amounts to proving validity (from 0) of

$$Ctrl \wedge Link_{C,A} \implies Spec.$$

- For instance,

$$Link_{C,A} = \lceil G \Leftrightarrow (G_1 + G_2 > 0) \rceil$$

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Obstacle (iv): How to Prove Correctness?

- by hand on the basis of DC semantics,
- maybe supported by proof rules,
- sometimes a general theorem may fit (e.g. cycle times of PLC automata),
- algorithms as in Uppaal.

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DC Properties

Decidability Results: Motivation

- Recall:
Given **assumptions** as a DC formula 'Asm' on the input observables, verifying **correctness** of 'Ctrl' wrt. 'Spec' amounts to proving

$$\models_0 \text{Ctrl} \wedge \text{Asm} \implies \text{Spec} \quad (1)$$

- If 'Asm' is **not satisfiable** then (1) is trivially valid, and thus each 'Ctrl' correct wrt. 'Spec'.
- So: strong interest in assessing the **satisfiability** of DC formulae.
- Question: is there an automatic procedure to help us out?
(a.k.a.: is it **decidable** whether a given DC formula is satisfiable?)
- More interesting for 'Spec': is it **realisable** (from 0)?
- Question: is it **decidable** whether a given DC formula is realisable?

Decidability Results for Realisability: Overview

| Fragment | Discrete Time | Continuous Time |
|------------------------------------|----------------------------------|--------------------------------------|
| RDC | decidable | decidable |
| $\text{RDC} + \ell = r$ | decidable for $r \in \mathbb{N}$ | undecidable for $r \in \mathbb{R}^+$ |
| $\text{RDC} + \int P_1 = \int P_2$ | undecidable | undecidable |
| $\text{RDC} + \ell = x, \forall x$ | undecidable | undecidable |
| DC | — | — |

References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.