

Real-Time Systems

Lecture 06: DC Properties I

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Contents & Goals

Last Lecture:

- DC Syntax and Semantics: Abbreviations (“almost everywhere”)
- Satisfiable/Realisable/Valid (from 0)

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What are obstacles on proving a design correct in the real-world, and how to overcome them?
 - Facts: decidability properties.
 - What’s the idea of the considered (un)decidability proofs?
- **Content:**
 - Semantical Correctness Proof
 - (Un-)Decidable problems of DC variants in discrete and continuous time

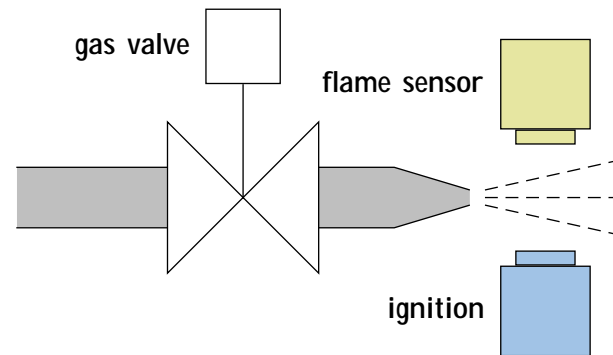
Specification and Semantics-based Correctness Proofs of Real-Time Systems with DC

Methodology: Ideal World...

- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide the **requirement/specification** 'Spec' as a conjunction of DC formulae (over 'Obs').
- (iii) Provide a description 'Ctrl' of the **controller** in form of a DC formula (over 'Obs').
- (iv) We say 'Ctrl' is **correct** (wrt. 'Spec') iff

$$\models_0 \text{Ctrl} \implies \text{Spec}.$$

Gas Burner Revisited



(i) Choose **observables**:

- two boolean observables G and F
(i.e. $\text{Obs} = \{G, F\}$, $\mathcal{D}(G) = \mathcal{D}(F) = \{0, 1\}$)
- $G = 1$: gas valve open
- $F = 1$: have flame
- define $L := G \wedge \neg F$ (leakage)

(output)

(input)

(ii) Provide the **requirement**:

$$\text{Req} : \iff \square(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

Gas Burner Revisited

(iii) Provide a description 'Ctrl' of the **controller** in form of a DC formula (over 'Obs'). Here, firstly consider a **design**:

- Des-1 : $\iff \Box([\mathit{L}] \implies \ell \leq 1)$
- Des-2 : $\iff \Box([\mathit{L}] ; [\neg \mathit{L}] ; [\mathit{L}] \implies \ell > 30)$

(iv) Prove **correctness**:

- We want (or do we want $\models_0 \dots ?$):

$$\models (\text{Des-1} \wedge \text{Des-2} \implies \text{Req}) \quad (\text{Thm. 2.16})$$

- We do show

$$\models \text{Req-1} \implies \text{Req} \quad (\text{Lem. 2.17})$$

with the simplified requirement

$$\text{Req-1} := \Box(\ell \leq 30 \implies \int L \leq 1),$$

- and we show

$$\models (\text{Des-1} \wedge \text{Des-2}) \implies \text{Req-1}. \quad (\text{Lem. 2.19})$$

Gas Burner Revisited: Lemma 2.17

Claim:

$$\models \underbrace{\Box(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}} \implies \underbrace{\Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)}_{\text{Req}}$$

Proof:

- Assume 'Req-1'.
- Let $L_{\mathcal{I}}$ be any interpretation of L , and $[b, e]$ an interval with $e - b \geq 60$.
- Show “ $20 \cdot \int L \leq \ell$ ”, i.e.

s.t. $\mathcal{I} \models \text{Req-1}$

$$\mathcal{I} \models \Box [20 \cdot \int L \leq \ell] (\mathcal{V}, [b, e]) = \#$$

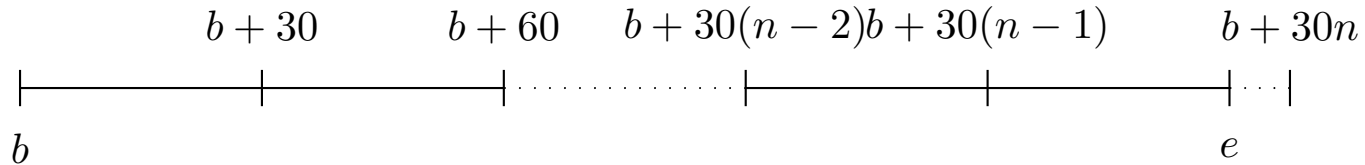
i.e.

$$20 \cdot \int_b^e L_{\mathcal{I}}(t) dt \leq (e - b)$$

Gas Burner Revisited: Lemma 2.17

$$\models \underbrace{\square(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}} \implies \square(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

- Set $n := \lceil \frac{e-b}{30} \rceil$, i.e. $n \in \mathbb{N}$ with $n - 1 < \frac{e-b}{30} \leq n$, and split the interval ^(*)



$$20 \cdot \int_b^e L_I(t) dt = 20 \cdot \left(\sum_{i=0}^{n-2} \underbrace{\int_{b+30i}^{b+(i+1)30} L_I(t) dt}_{\leq 1} + \int_{b+30(n-1)}^e L_I(t) dt \right)$$

$$\{ \text{Req-1} \} \leq 20 \cdot \sum_{i=0}^{n-2} 1 + 20 \cdot 1$$

$$= 20 \cdot n$$

$$\{ (*) \} < 20 \cdot \left(\frac{e-b}{30} + 1 \right)$$

$$= \frac{2}{3}(e-b) + 20$$

$$\leq e-b$$

$$\{ e-b \geq 60 \}$$

$$\{ 20 \leq \frac{2}{3}(e-b) \}$$

Some Laws of the DC Integral Operator

Theorem 2.18.

For all state assertions P and all real numbers $r_1, r_2 \in \mathbb{R}$,

$$(i) \models \int P \leq \ell,$$

$$(ii) \models (\int P = r_1) ; (\int P = r_2) \implies \int P = r_1 + r_2,$$

$$(iii) \models [\neg P] \implies \int P = 0,$$

$$(iv) \models \square \implies \int P = 0.$$

Gas Burner Revisited: Lemma 2.18

(i) $\int P \leq \ell$ (ii) $\Gamma \neg P \Rightarrow \int P = 0$
 (iii) $(\int P = r_1) \wedge (\int P = r_2) \Rightarrow \int P = r_1 + r_2$
 (iv) $\Gamma \neg \Rightarrow \int P = 0$

Claim: for all $I, V, [b \in \mathcal{I}]$

$$\models \underbrace{(\Box([L] \Rightarrow \ell \leq 1))}_{\text{Des-1}} \wedge \underbrace{\Box([L]; [\neg L]; [L] \Rightarrow \ell > 30)}_{\text{Des-2}} \Rightarrow \underbrace{\Box(\ell \leq 30 \Rightarrow \int L \leq 1)}_{\text{Req-1}}$$

Proof:

$\ell \leq 30$

$$\Rightarrow \Gamma \left\{ \begin{array}{l} \vee \Gamma L; (\Gamma \vee \Gamma \neg L) \\ \vee \Gamma \neg L; (\Gamma \vee \Gamma L) \\ \vee \Gamma \neg L; \Gamma L; \Gamma \neg L \end{array} \right\} (*)$$

$\vee \ell \leq 30 \wedge \Diamond(\Gamma L; \Gamma \neg L; \Gamma L) \Downarrow \text{Des-2}$

$\{ \text{Des-2} \} \Rightarrow (*)$

$\{ \text{Des-1} \} \Rightarrow \Gamma \left\{ \begin{array}{l} \vee (\ell \leq 1); (\Gamma \vee \Gamma \neg L) \\ \vee \Gamma \neg L; (\Gamma \vee (\ell \leq 1)) \\ \vee \Gamma \neg L; (\ell \leq 1); \Gamma \neg L \end{array} \right.$

$\{ (i) \} \Rightarrow \Gamma \left\{ \begin{array}{l} \vee (\int L \leq 1); (\Gamma \vee \Gamma \neg L) \\ \vee \Gamma \neg L; (\Gamma \vee (\int L \leq 1)) \\ \vee \Gamma \neg L; (\int L \leq 1); \Gamma \neg L \end{array} \right.$

$\{ (iv), (ii) \} \Rightarrow \int L = 0 \left\{ \begin{array}{l} \vee (\int L \leq 1); (\int L = 0 \vee \int L = 0) \\ \vee (\int L = 0); (\int L = 0 \vee \int L \leq 1) \\ \vee (\int L = 0); (\int L \leq 1); (\int L = 0) \end{array} \right.$

$\{ (ii) \} \Rightarrow \int L = 0 \left\{ \begin{array}{l} \vee \int L \leq 1 + 0 \\ \vee \int L \leq 0 + 1 \\ \vee \int L \leq 0 + 1 + 0 \end{array} \right.$

$\Rightarrow \int L \leq 1 \quad \square$

Obstacles in Non-Ideal World

Methodology: The World is Not Ideal...

- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide **specification** 'Spec' (conjunction of DC formulae (over 'Obs')).
- (iii) Provide a description 'Ctrl' of the **controller** (DC formula (over 'Obs')).
- (iv) Prove 'Ctrl' is **correct** (wrt. 'Spec').

That looks **too simple to be practical**. Typical **obstacles**:

- (i) It may be impossible to realise 'Spec' if it doesn't consider properties of **the plant**.
- (ii) There are typically intermediate **design levels** between 'Spec' and 'Ctrl'.
- (iii) 'Spec' and 'Ctrl' may use **different observables**.
- (iv) **Proving** validity of the implication is not trivial.

(i) Assumptions As A Form of Plant Model

- Often the controller will (or can) operate correctly only under some **assumptions**.
- For instance, with a level crossing
 - we may assume an upper bound on the speed of approaching trains, (otherwise we'd need to close the gates arbitrarily fast)
 - we may assume that trains are not arbitrarily slow in the crossing, (otherwise we can't make promises to the road traffic)
- We shall specify such assumptions as a DC formula 'Asm' on the **input observables** and verify correctness of 'Ctrl' wrt. 'Spec' by proving validity (from 0) of

$$\text{Ctrl} \wedge \text{Asm} \implies \text{Spec}$$

- Shall we **care** whether 'Asm' is satisfiable? **YES!**

(ii) Intermediate Design Levels

- A top-down development approach may involve
 - Spec — specification/requirements
 - Des — design
 - Ctrl — implementation
- Then correctness is established by proving validity of

$$\text{Ctrl} \implies \text{Des} \quad (1)$$

and

$$\text{Des} \implies \text{Spec} \quad (2)$$

(then concluding $\text{Ctrl} \implies \text{Spec}$ by transitivity)

- Any preference on the order?

(iii): Different Observables

- Assume, 'Spec' uses more abstract observables Obs_A and 'Ctrl' more concrete ones Obs_C .
- For instance:
 - in Obs_A : only consider gas valve open or closed ($\mathcal{D}(G) = \{0, 1\}$)
 - in Obs_C : may control two valves and care for intermediate positions, for instance, to react to different heating requests ($\mathcal{D}(G_1) = \{0, 1, 2, 3\}, \mathcal{D}(G_2) = \{0, 1, 2, 3\}$)
- To prove correctness, we need information how the observables are related — an **invariant** which **links** the data values of Obs_A and Obs_C .
- **If** we're given the linking invariant as a DC formula, say 'Link $_{C,A}$ ', **then** proving correctness of 'Ctrl' wrt. 'Spec' amounts to proving validity (from 0) of

$$\text{Ctrl} \wedge \text{Link}_{C,A} \implies \text{Spec}.$$

- For instance,

$$\text{Link}_{C,A} = \top G \iff (G_1 + G_2 > 0)?$$

Obstacle (iv): How to Prove Correctness?

- by hand on the basis of DC semantics,
- maybe supported by proof rules,
- sometimes a general theorem may fit (e.g. cycle times of PLC automata),
- algorithms as in Uppaal.

DC Properties

Decidability Results: Motivation

- Recall:

Given **assumptions** as a DC formula 'Asm' on the input observables, verifying **correctness** of 'Ctrl' wrt. 'Spec' amounts to proving

$$\models_0 \text{Ctrl} \wedge \text{Asm} \implies \text{Spec} \quad (1)$$

- If 'Asm' is **not satisfiable** then (1) is trivially valid, and thus each 'Ctrl' correct wrt. 'Spec'.
- So: strong interest in assessing the **satisfiability** of DC formulae.
- Question: is there an automatic procedure to help us out?
(a.k.a.: is it **decidable** whether a given DC formula is satisfiable?)
- More interesting for 'Spec': is it **realisable** (from 0)?
- Question: is it **decidable** whether a given DC formula is realisable?

Decidability Results for Realisability: Overview

Fragment	Discrete Time	Continuous Time
RDC	decidable	decidable
$\text{RDC} + \ell = r$	decidable for $r \in \mathbb{N}$	undecidable for $r \in \mathbb{R}^+$
$\text{RDC} + \int P_1 = \int P_2$	undecidable	undecidable
$\text{RDC} + \ell = x, \forall x$	undecidable	undecidable
DC	— —	— —

References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). **Real-Time Systems - Formal Specification and Automatic Verification**. Cambridge University Press.