Softwaretechnik / Software-Engineering

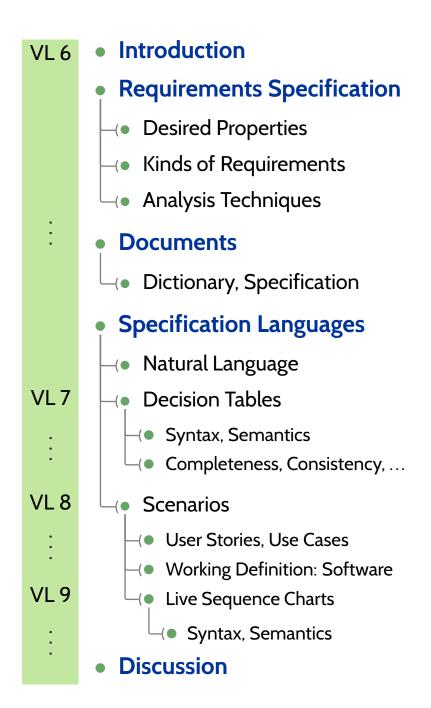
Lecture 7: Formal Methods for Requirements Engineering

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Prof. Dr. Andreas Podelski, Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

Topic Area Requirements Engineering: Content



Content

- (Basic) Decision Tables
- Syntax, Semantics
- ...for Requirements Specification
- ...for Requirements Analysis
 - → Completeness,
 - Useless Rules,
 - Determinism
- Domain Modelling
 - Conflict Axiom,
- Relative Completeness,
- ✓ Vacuous Rules,
- ← Conflict Relation
- Collecting Semantics
- Discussion



Decision Tables

Decision Tables: Example

T	r_1	r_2	r_3
c_1	×	×	—
c_2	×	_	*
c_3	_	×	*
a_1	×	_	_
a_2	_	×	_

Decision Table Syntax

• Let C be a set of conditions and A be a set of actions s.t. $C \cap A = \emptyset$.

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- A decision table T over C and A is a labelled $(m+k) \times n$ matrix

T: de	T: decision table		• • •	r_n
c_1	description of condition c_1	$v_{1,1}$	• • •	$v_{1,n}$
:	: :	:	٠.	:
c_m	description of condition c_m	$v_{m,1}$	• • •	$v_{m,n}$
a_1	description of action a_1	$w_{1,1}$	• • •	$w_{1,n}$
:		:		:
a_k	description of action a_k	$w_{k,1}$	• • •	$w_{k,n}$

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- where

 - $c_1, \ldots, c_m \in C$, $v_{1,1}, \ldots, v_{m,n} \in \{-, \times, *\}$ and

 - $a_1, \ldots, a_k \in A$, $w_{1,1}, \ldots, w_{k,n} \in \{-, \times\}$.
- Columns $(v_{1,i},\ldots,v_{m,i},w_{1,i},\ldots,w_{k,i})$, $1\leq i\leq n$, are called rules,
- r_1, \ldots, r_n are rule names.
- $(v_{1,i},\ldots,v_{m,i})$ is called **premise** of rule r_i , $(w_{1,i},\ldots,w_{k,i})$ is called **effect** of r_i .

Decision Table Semantics

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Each rule $r \in \{r_1, \dots, r_n\}$ of table T

<i>T</i> : de	ecision table	r_1	• • •	r_n
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is assigned to a propositional logical formula $\mathcal{F}(r)$ over signature $C\mathrel{\dot{\cup}} A$ as follows:

- Let (v_1, \ldots, v_m) and (w_1, \ldots, w_k) be premise and effect of r.
- Then

$$\mathcal{F}(r) := \underbrace{F(v_1, c_1) \wedge \cdots \wedge F(v_m, c_m)}_{=:\mathcal{F}_{pre}(r)} \wedge \underbrace{F(w_1, a_1) \wedge \cdots \wedge F(w_k, a_k)}_{=:\mathcal{F}_{eff}(r)}$$

where

$$F(v,x) = egin{cases} x & ext{, if } v = imes \ \neg x & ext{, if } v = - \ ext{true} & ext{, if } v = * \end{cases}$$

Decision Table Semantics: Example

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$$\wedge F(v_1, a_1) \wedge \cdots \wedge F(v_k, a_k)$$

$$F(v, x) = \begin{cases} x & \text{, if } v = \times \\ \neg x & \text{, if } v = - \\ \text{true} & \text{, if } v = * \end{cases}$$

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c_1	×	×	_
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- $\mathcal{F}(r_1) = c_1 \wedge c_2 \wedge \neg c_3 \wedge a_1 \wedge \neg a_2$
- $\mathcal{F}(r_2) = c_1 \wedge \neg c_2 \wedge c_3 \wedge \neg a_1 \wedge a_2$
- $\mathcal{F}(r_3) = \neg c_1 \land \mathsf{true} \land \mathsf{true} \land \neg a_1 \land \neg a_2$

We can use decision tables to model (describe or prescribe) the behaviour of software!

Example:

Ventilation system of lecture hall 101-0-026.

T: roo	T: room ventilation		r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

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• We can observe whether button is pressed and whether room ventilation is on or off, and whether (we intend to) start ventilation of stop ventilation.

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- We can observe whether button is pressed and whether room ventilation is on or off, and whether (we intend to) start ventilation of stop ventilation.
- We can model our observation by a boolean valuation $\sigma:C\cup A\to \mathbb{B}$, e.g., set

 $\sigma(b) := \textit{true}$, if button pressed now and $\sigma(b) := \textit{false}$, if button not pressed now.

 $\sigma(go) := true$, we plan to start ventilation and $\sigma(go) := false$, we plan to stop ventilation.

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• A valuation $\sigma: C \cup A \to \mathbb{B}$ can be used to assign a **truth value** to a propositional formula φ over $C \cup A$. As usual, we write $\sigma \models \varphi$ iff φ evaluates to *true* under σ (and $\sigma \not\models \varphi$ otherwise).

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- Rule formulae $\mathcal{F}(r)$ are propositional formulae over $C \cup A$ thus, given σ , we have either $\sigma \models \mathcal{F}(r)$ or $\sigma \not\models \mathcal{F}(r)$.
- Let σ be a model of an observation of C and A. We say, σ is allowed by decision table T if and only if there exists a rule r in T such that $\sigma \models \mathcal{F}(r)$.

T: room ventilation		r_1	r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×	_	_
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$\mathcal{F}(r_1) = b \land off \land \neg on \land go \land \neg stop$
$\mathcal{F}(r_2) = b \land \neg off \land on \land \neg go \land stop$
$\mathcal{F}(r_3) = \neg b \wedge \mathit{true} \wedge \mathit{true} \wedge \neg go \wedge \neg stop$

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(i) Assume: button pressed, ventilation off, we (only) plan to start the ventilation.

T: roc	m ventilation	r_1	r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

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- (i) **Assume**: button pressed, ventilation off, we (only) plan to start the ventilation.
 - Corresponding valuation: $\sigma_1 = \{b \mapsto \textit{true}, off \mapsto \textit{true}, on \mapsto \textit{false}, start \mapsto \textit{true}, stop \mapsto \textit{false}\}.$

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 - Is our intention (to start the ventilation now) allowed by T?

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b	button pressed?	×	×	_
off	ventilation off?	×	_	*
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 - Is our intention (to start the ventilation now) allowed by T? Yes! (Because $\sigma_1 \models \mathcal{F}(r_1)$)

Example

T: roo	m ventilation	r_1	r_2	r_3
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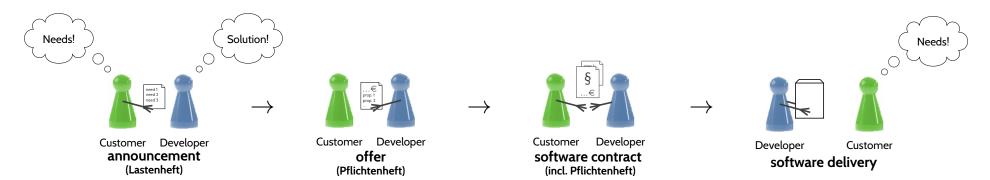
- (i) Assume: button pressed, ventilation off, we (only) plan to start the ventilation.
 - Corresponding valuation: $\sigma_1 = \{b \mapsto \textit{true}, off \mapsto \textit{true}, on \mapsto \textit{false}, start \mapsto \textit{true}, stop \mapsto \textit{false}\}.$
 - Is our intention (to start the ventilation now) allowed by T? Yes! (Because $\sigma_1 \models \mathcal{F}(r_1)$)
- (ii) Assume: button pressed, ventilation on, we (only) plan to stop the ventilation.
 - Corresponding valuation: $\sigma_2 = \{b \mapsto true, off \mapsto false, on \mapsto true, start \mapsto false, stop \mapsto true\}.$
 - Is our intention (to stop the ventilation now) allowed by T? Yes. (Because $\sigma_2 \models \mathcal{F}(r_2)$)

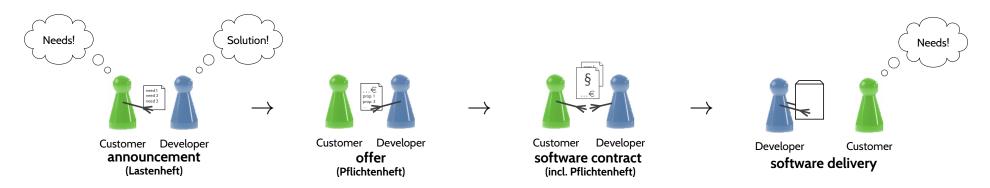
T: roo	m ventilation	r_1	r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

$$\mathcal{F}(r_1) = b \land off \land \neg on \land go \land \neg stop$$

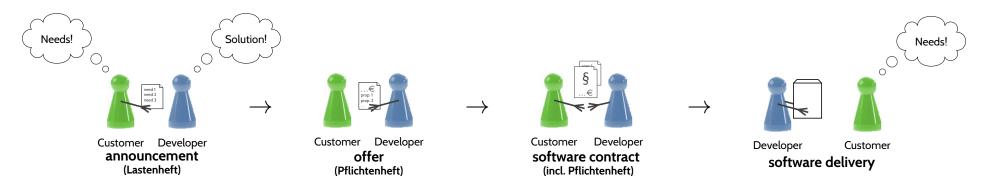
 $\mathcal{F}(r_2) = b \land \neg off \land on \land \neg go \land stop$
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 - Is our intention (to start the ventilation now) allowed by T? Yes! (Because $\sigma_1 \models \mathcal{F}(r_1)$)
- (ii) Assume: button pressed, ventilation on, we (only) plan to stop the ventilation.
 - Corresponding valuation: $\sigma_2 = \{b \mapsto \textit{true}, \textit{off} \mapsto \textit{false}, \textit{on} \mapsto \textit{true}, \textit{start} \mapsto \textit{false}, \textit{stop} \mapsto \textit{true}\}.$
 - Is our intention (to stop the ventilation now) allowed by T? Yes. (Because $\sigma_2 \models \mathcal{F}(r_2)$)
- (iii) Assume: button not pressed, ventilation on, we (only) plan to stop the ventilation.
 - Corresponding valuation:
 - Is our intention (to stop the ventilation now) allowed by T?



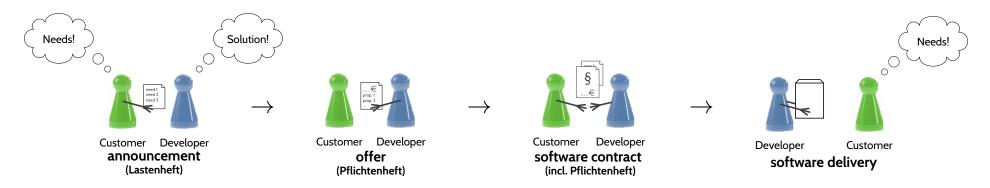


Decision Tables can be used to objectively describe desired software behaviour.

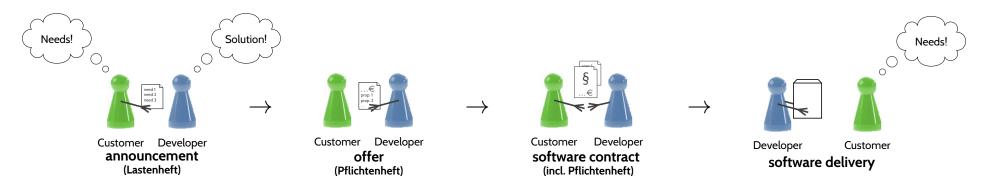


- Decision Tables can be used to objectively describe desired software behaviour.
- Example: Dear developer, please provide a program such that
 - in each situation (button pressed, ventilation on/off),
 - whatever the software does (action start/stop)
 - is allowed by decision table *T*.

T: roo	m ventilation	r_1	r_2	r_3
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- Decision Tables can be used to objectively describe desired software behaviour.
- Another Example: Customer session at the bank:



- Decision Tables can be used to objectively describe desired software behaviour.
- Another Example: Customer session at the bank:

<i>T</i> 1:	cash a cheque	r_1	r_2	else
c_1	credit limit exceeded?	×	×	
c_2	payment history ok?	X	_	
c_3	overdraft $< 500 \in ?$	_	*	
a_1	cash cheque	×	_	X
a_2	do not cash cheque	_	×	_
a_3	offer new conditions	×	_	_
			(Balze	rt, 2009)

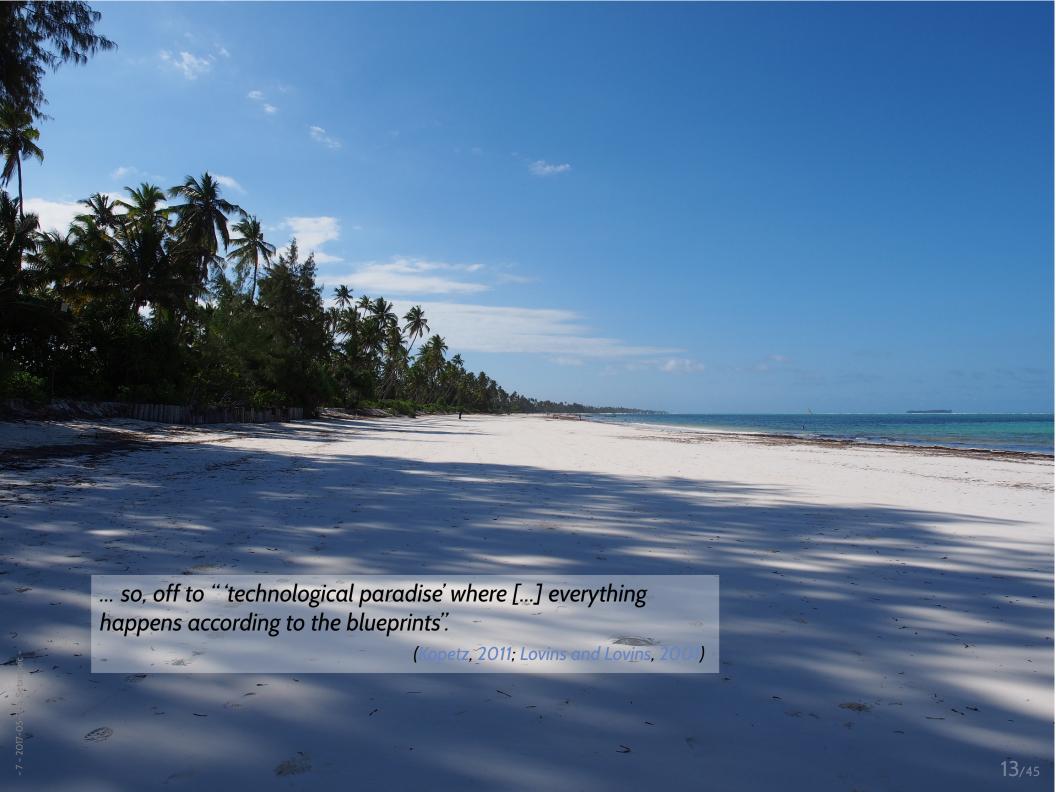
- clerk checks database state (yields σ for c_1, \ldots, c_3),
- database says: credit limit exceeded over 500 €, but payment history ok,
- ullet clerk cashes cheque but offers new conditions (according to T1).

Requirements on Requirements Specifications

A requirements specification should be

- correct
 - it correctly represents the wishes/needs of the customer,
- complete $\overset{\nabla}{\circ}$
 - all requirements (existing in somebody's head, or a document, or ...) should be present,
- relevant
 - things which are not relevant to the project should not be constrained.
- consistent, free of contradictions
 each requirement is compatible with all other requirements; otherwise the requirements are not realisable.

- neutral abstract
 - a requirements specification does not constrain the realisation more than necessary,
- traceable, comprehensible
 - the sources of requirements are documented, requirements are uniquely identifiable,
- testable, objective
 - the final product can **objectively** be checked for satisfying a requirement.
- Correctness and completeness are defined relative to something which is usually only in the customer's head.
 - \rightarrow is is difficult to be sure of correctness and completeness.
- "Dear customer, please tell me what is in your head!" is in almost all cases not a solution!
 It's not unusual that even the customer does not precisely know...!
 For example, the customer may not be aware of contradictions due to technical limitations.



Recall Once Again

Requirements on Requirements Specifications

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Completeness

Definition. [Completeness] A decision table T is called **complete** if and only if the disjunction of all rules' premises is a tautology, i.e. if

$$\models \bigvee_{r \in T} \mathcal{F}_{pre}(r).$$

Completeness: Example

T: roo	m ventilation	r_1	r_2	r_3
b	button pressed?	×	×	_
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• Is T complete?

Completeness: Example

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ullet Is T complete?

No. (Because there is no rule for, e.g., the case $\sigma(b) = \textit{true}$, $\sigma(\textit{on}) = \textit{false}$, $\sigma(\textit{off}) = \textit{false}$).

Completeness: Example

T: room ventilation		r_1	r_2	r_3
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Recall:

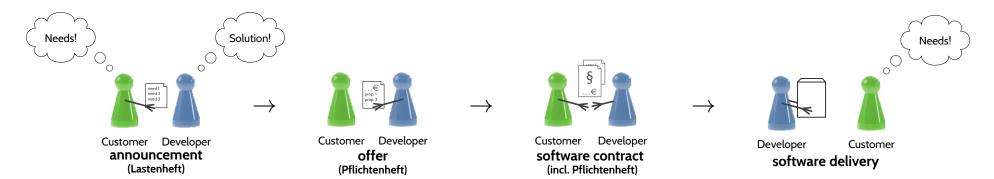
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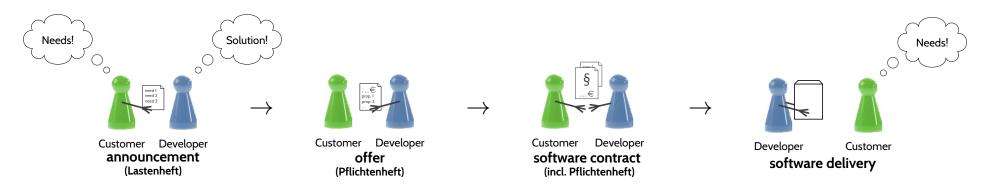
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$$\mathcal{F}_{pre}(r_1) \vee \mathcal{F}_{pre}(r_2) \vee \mathcal{F}_{pre}(r_3)$$

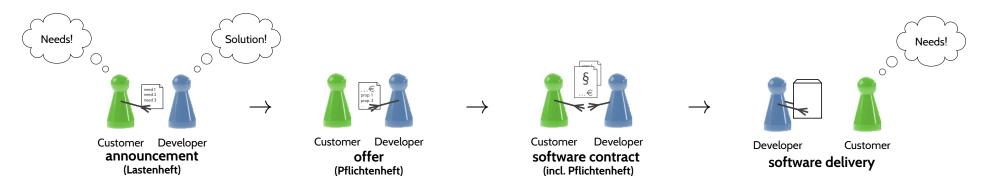
$$= (c_1 \wedge c_2 \wedge \neg c_3) \vee (c_1 \wedge \neg c_2 \wedge c_3) \vee (\neg c_1 \wedge \textit{true} \wedge \textit{true})$$

is not a tautology.



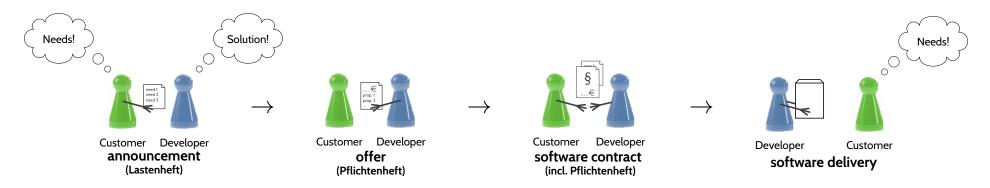


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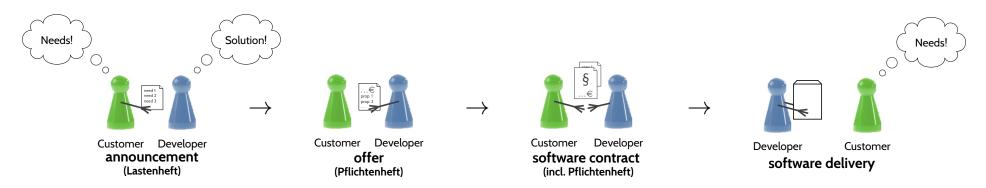


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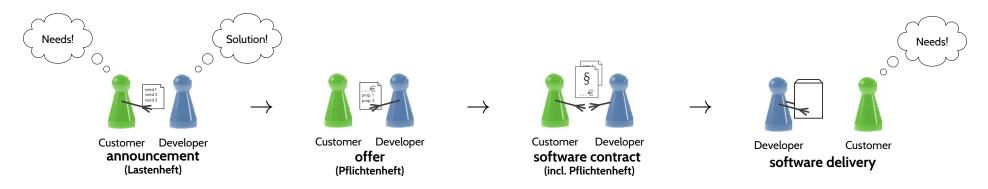
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 If there are no misunderstandings, then we did discuss all cases.

Note:

- Whether T is (formally) complete is decidable.
- ullet Deciding whether T is complete reduces to plain SAT.
- There are efficient tools which decide SAT.
- In addition, decision tables are often much easier to understand than natural language text.

For Convenience: The 'else' Rule

Syntax:

T: decision table		r_1	• • •	r_n	else
c_1	description of condition c_1	$v_{1,1}$		$v_{1,n}$	
:	:	:		:	
c_m	description of condition c_m	$v_{m,1}$	• • •	$v_{m,n}$	
a_1	description of action a_1	$w_{1,1}$		$w_{1,n}$	$w_{1,e}$
	:				
a_k	description of action a_k	$w_{k,1}$	• • •	$w_{k,n}$	$w_{k,e}$

Semantics:

$$\mathcal{F}(\mathsf{else}) := \neg \left(\bigvee_{r \in T \setminus \{\mathsf{else}\}} \mathcal{F}_{pre}(r) \right) \wedge F(w_{1,e}, a_1) \wedge \cdots \wedge F(w_{k,e}, a_k)$$

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a_1	description of action a_1	$w_{1,1}$		$w_{1,n}$	$w_{1,e}$
	:	:			
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Proposition. If decision table T has an 'else'-rule, then T is complete.

Definition. [Uselessness] Let T be a decision table.

A rule $r \in T$ is called **useless** (or: **redundant**) if and only if there is another (different) rule $r' \in T$

- ullet whose premise is implied by the one of r and
- whose effect is the same as r's,

i.e. if

$$\exists r' \neq r \in T \bullet \models (\mathcal{F}_{pre}(r) \implies \mathcal{F}_{pre}(r')) \land (\mathcal{F}_{eff}(r) \iff \mathcal{F}_{eff}(r')).$$

r is called subsumed by r'.

Again: uselessness is decidable; reduces to SAT.

Uselessness: Example

T: roc	m ventilation	r_1	r_2	r_3	r_4
b	button pressed?	×	×	_	_
off	ventilation off?	×	_	*	_
on	ventilation on?	_	×	*	×
go	start ventilation	×	_	_	_
stop	stop ventilation	_	×	_	

• Rule r_4 is subsumed by r_3 .

Uselessness: Example

T: roc	m ventilation	r_1	r_2	r_3	r_4
b	button pressed?	×	×	_	_
off	ventilation off?	×	_	*	_
on	ventilation on?	_	×	*	×
go	start ventilation	×	_	_	_
stop	stop ventilation	_	×	_	_

- Rule r_4 is subsumed by r_3 .
- Rule r_3 is **not** subsumed by r_4 .

Uselessness: Example

T: room ventilation		r_1	r_2	r_3	r_4
b	button pressed?	×	×	_	_
off	ventilation off?	×	_	*	_
on	ventilation on?	_	×	*	×
go	start ventilation	×	_	_	_
stop	stop ventilation	_	×	_	_

- Rule r_4 is subsumed by r_3 .
- Rule r_3 is **not** subsumed by r_4 .

- Useless rules "do not hurt" as such.
- Yet useless rules should be removed to make the table more readable, yielding an **easier usable** specification.

Useless

Requirements on Requirements Specification Documents

The representation and form of a requirements specification should be:

- easily understandable,
 not unnecessarily complicated –
 all affected people should be able to
 understand the requirements specification,
- precise –

 the requirements specification should not introduce new unclarities or rooms for interpretation (→ testable, objective).
- easily maintainable –
 creating and maintaining the requirements
 specification should be easy and should not
 need unnecessary effort,
 - easily usable –
 storage of and access to the requirements
 specification should not need significant effort.

• Rule r_{λ}

Note: Once again, it's about

Note: Once again, it's about compromises.

- ullet Rule r_{\sharp}
- A very precise objective requirements specification may not be easily understandable by every affected person.
 - \rightarrow provide redundant explanations.
- It is not trivial to have both, low maintenance effort and low access effort.
- → value low access effort higher, a requirements specification document is much more often read than changed or written (and most changes require reading beforehand).

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- Useless rules "do not hurt" as such.
- Yet useless rules should be removed to make the table more readable, yielding an easier usable specification.

Determinism

Definition. [Determinism]

A decision table T is called $\operatorname{deterministic}$ if and only if the premises of all rules are pairwise disjoint, i.e. if

$$\forall r_1 \neq r_2 \in T \bullet \models \neg (\mathcal{F}_{pre}(r_1) \land \mathcal{F}_{pre}(r_2)).$$

Otherwise, T is called **non-deterministic**.

And again: determinism is decidable; reduces to SAT.

Determinism: Example

T: room ventilation		r_1	r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×		_
stop	stop ventilation	_	×	_

• Is T deterministic?

Determinism: Example

T: room ventilation		r_1	r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×		_
stop	stop ventilation	_	×	_

• Is T deterministic? Yes.

T_{abstr}	: room ventilation	r_1	r_2	r_3
b	button pressed?	X	×	_
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

• Is T_{abstr} determistic?

T_{abstr}	: room ventilation	r_1	r_2	r_3
b	button pressed?	X	×	_
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

• Is T_{abstr} determistic? No.

T_{abstr}	: room ventilation	r_1	r_2	r_3
b	button pressed?	×	×	_
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

• Is T_{abstr} determistic? No.

By the way...

• Is non-determinism a bad thing in general?

T_{abstr}	: room ventilation	r_1	r_2	r_3
b	button pressed?	×	×	_
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

• Is T_{abstr} determistic? No.

By the way...

- Is non-determinism a bad thing in general?
 - Just the opposite: non-determinism is a very, very powerful modelling tool.
 - Read table T_{abstr} as:
 - the button may switch the ventilation on under certain conditions (which I will specify later), and
 - the button may switch the ventilation off under certain conditions (which I will specify later).

We in particular state that we do not (under any condition) want to see on and off executed together, and that we do not (under any condition) see go or stop without button pressed.

On the other hand: non-determinism may not be intended by the customer.

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T: room ventilation		r_1	r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
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go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

• If on and off model opposite output values of one and the same sensor for "room ventilation on/off", then $\sigma \models on \land off$ and $\sigma \models \neg on \land \neg off$ never happen in reality for any observation σ .

Example:

T: room ventilation		r_1	r_2	r_3
b	button pressed?	×	×	_
off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_

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- Decision table T is incomplete for exactly these cases.
 (T "does not know" that on and off can be opposites in the real-world).

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- We should be able to "tell" T that on and off are opposites (if they are). Then T would be relative complete (relative to the domain knowledge that on/off are opposites).

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Bottom-line:

- Conditions and actions are abstract entities without inherent connection to the real world.
- When modelling real-world aspects by conditions and actions, we may also want to represent relations between actions/conditions in the real-world (→ domain model (Bjørner, 2006)).

Conflict Axioms for Domain Modelling

• A conflict axiom over conditions C is a propositional formula φ_{confl} over C.

Intuition: a conflict axiom characterises all those cases,
i.e. all those combinations of condition values which 'cannot happen'
– according to our understanding of the domain.

Note: the decision table semantics remains unchanged!

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Example:

• Let $\varphi_{confl} = (on \wedge off) \vee (\neg on \wedge \neg off)$.

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Notation:

T: room ventilation		r_1	r_2	r_3
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off	ventilation off?	×	_	*
on	ventilation on?	_	×	*
go	start ventilation	×	_	_
stop	stop ventilation	_	×	_
$\neg [(\mathit{on} \land \mathit{off}) \lor (\neg \mathit{on} \land \neg \mathit{off})]$				

- 7 - 2017-05-29 - Setconflax

"Airbus A320-200 overran runway at Warsaw Okecie Intl. Airport on 14 Sep. 1993."



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• To stop a plane after touchdown, there are spoilers and thrust-reverse systems.



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- To stop a plane after touchdown, there are spoilers and thrust-reverse systems.
- Enabling one of those while in the air, can have fatal consequences.



rhansa Flight 2904 crash site Siecinski" by Mariusz Siecinski -//www.airlines.net/photo/Lufthansa/Airbus-A320-211/0265541/L/, nsed under GFDL via Wikimedia Commons -//commons.wikimedia.org/wiki/Filet.Lufthansa_Flight_2904_crash_site_Siecinski

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- To stop a plane after touchdown, there are spoilers and thrust-reverse systems.
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- Design decision: the software should block activation of spoilers or thrust-revers while in the air.



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- To stop a plane after touchdown, there are spoilers and thrust-reverse systems.
- Enabling one of those while in the air, can have fatal consequences.
- Design decision: the software should block activation of spoilers or thrust-revers while in the air.
- Simplified decision table of blocking procedure:

T		r_1	r_2	r_3	else
splq	spoilers requested	×	×	_	
thrq	thrust-reverse requested	_	_	×	
lgsw	at least 6.3 tons weight on each landing gear strut	X	*	×	
spd	wheels turning faster than 133 km/h	*	X	*	
spl	enable spoilers	×	×	_	_
thr	enable thrust-reverse	_	_	×	_

Idea: if conditions lgsw and spd not satisfied, then aircraft is in the air.



Pitfalls in Domain Modelling (Wikipedia, 2015)

"Airbus A320-200 overran runway at Warsaw Okecie Intl. Airport on 14 Sep. 1993."

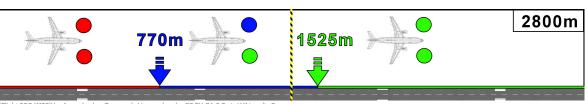
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Idea: if conditions lgsw and spd not satisfied, then aircraft is in the air.

14 Sep. 1993:

- wind conditions not as announced from tower, tail- and crosswinds.
- anti-crosswind manoeuvre puts too little weight on landing gear
- wheels didn't turn fast due to hydroplaning.





"Lufthansa Flight 2904 crash site Siecinski" by Mariusz Siecinski – http://www.airliners.ner/photos/Lufthansa/Airbus-A320-211/0265541/L/. Licensed under GFDL via Wkimedia Commons – http://commons.wikimedia.org/wiki/FlieLufthansa_Flight_2904_crash_site_Siec

Definition. [Completeness wrt. Conflict Axiom]

A decision table T is called complete wrt. conflict axiom φ_{confl} if and only if the disjunction of all rules' premises and the conflict axiom is a tautology, i.e. if

$$\models \varphi_{confl} \vee \bigvee_{r \in T} \mathcal{F}_{pre}(r).$$

Intuition: a relative complete decision table explicitly cares for all cases which 'may happen'.

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- Intuition: a relative complete decision table explicitly cares for all cases which 'may happen'.
- Note: with $\varphi_{confl} = false$, we obtain the previous definitions as a special case.

Fits intuition: $\varphi_{confl} = \textit{false}$ means we don't exclude any states from consideration.

Example

T: roo	m ventilation	r_1	r_2	r_3	
b	button pressed?	×	×	_	
off	ventilation off?	×	_	*	
on	ventilation on?	_	×	*	
go	start ventilation	×	_	_	
stop	stop ventilation	_	×	_	
$\neg [(on \land off) \lor (\neg on \land \neg off)]$					

ullet T is complete wrt. its conflict axiom.

T: roo	m ventilation	r_1	r_2	r_3	
b	button pressed?	×	×	_	
off	ventilation off?	×	_	*	
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go	start ventilation	×	_	_	
stop	stop ventilation	_	×	_	
$\neg [(on \land off) \lor (\neg on \land \neg off)]$					

- *T* is complete wrt. its conflict axiom.
- Pitfall: if on and off are outputs of two different, independent sensors, then $\sigma \models on \land off$ is possible in reality (e.g. due to sensor failures). Decision table T does not tell us what to do in that case!

Vacuity wrt. Conflict Axiom

Definition. [Vacuitiy wrt. Conflict Axiom]

A rule $r \in T$ is called vacuous wrt. conflict axiom φ_{confl} if and only if the premise of r implies the conflict axiom, i.e. if $\models \mathcal{F}_{pre}(r) \to \varphi_{confl}$.

• Intuition: a vacuous rule would only be enabled in states which 'cannot happen'.

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T: roo	m ventilation	r_1	r_2	r_3	r_4
b	button pressed?	×	×	_	×
off	ventilation off?	×	_	*	×
on	ventilation on?	_	×	*	×
go	start ventilation	×	_	_	_
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b	button pressed?	×	×	_	×	
off	ventilation off?	×	_	*	×	
on	ventilation on?	_	×	*	×	
go	start ventilation	×	_	_	_	
stop	stop ventilation	_	×	_	×	
	$\neg [(\mathit{on} \land \mathit{off}) \lor (\neg \mathit{on} \land \neg \mathit{off})]$					

- Vacuity wrt. φ_{confl} : Like uselessness, vacuity doesn't hurt as such but
 - May hint on inconsistencies on customer's side. (Misunderstandings with conflict axiom?)
 - Makes using the table less easy! (Due to more rules.)
 - Implementing vacuous rules is a waste of effort!

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Definition. [Conflict Relation] A conflict relation on actions A is a transitive and symmetric relation $\nleq \subseteq (A \times A)$.

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Definition. [Consistency] Let r be a rule of decision table T over C and A.

(i) Rule r is called **consistent with conflict relation** $\not \subseteq$ if and only if there are no conflicting actions in its effect, i.e. if

$$\models \mathcal{F}_{eff}(r) \to \bigwedge_{(a_1, a_2) \in \mathcal{I}} \neg (a_1 \land a_2).$$

(ii) T is called **consistent** with f iff all rules $r \in T$ are consistent with f.

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(ii) T is called **consistent** with f iff all rules $r \in T$ are consistent with f.

Again: consistency is decidable; reduces to SAT.

Example: Conflicting Actions

T: roo	m ventilation	r_1	r_2	r_3	
b	button pressed?	×	×	_	
off	ventilation off?	×	_	*	
on	ventilation on?	_	×	*	
go	start ventilation	×	_	_	
stop	stop ventilation	×	×	_	
$\neg [(\mathit{on} \land \mathit{off}) \lor (\neg \mathit{on} \land \neg \mathit{off})]$					

- Let $\normaller{\no$
- Then rule r_1 is inconsistent with ξ .

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T: room ventilation		r_1	r_2	r_3	
b	button pressed?	×	×	_	
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go	start ventilation	×	_	_	
stop	stop ventilation	×	×	_	
$\neg [(\mathit{on} \land \mathit{off}) \lor (\neg \mathit{on} \land \neg \mathit{off})]$					

- Let \normalfont be the transitive, symmetric closure of $\{(stop, go)\}$. "actions stop and go are not supposed to be executed at the same time"
- Then rule r_1 is inconsistent with ξ .

- A decision table with inconsistent rules may do harm in operation!
- Detecting an inconsistency only late during a project can incur significant cost!
- Inconsistencies in particular in (multiple) decision tables, created and edited by multiple people, as well as in requirements in general – are not always as obvious as in the toy examples given here! (would be too easy...)
- And is even less obvious with the **collecting semantics** (\rightarrow in a minute).

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Collecting Semantics

• Let T be a decision table over C and A and σ be a model of an observation of C and A. Then

$$\mathcal{F}_{coll}(T) := \bigwedge_{a \in A} a \leftrightarrow \bigvee_{r \in T, r(a) = \times} \mathcal{F}_{pre}(r)$$

is called the collecting semantics of T.

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Example:

T: roo	m ventilation	r_1	r_2	r_3	r_4	
b	button pressed?	×	×	_	×	
off	ventilation off?	×	_	*	*	
on	ventilation on?	_	×	*	*	
go	start ventilation	×	_	_	_	
stop	stop ventilation	_	×	_	_	
blnk	blink button	_	_	_	×	
	$\neg [(on \land off) \lor (\neg on \land \neg off)]$					

"Whenever the button is pressed, let it blink (in addition to go/stop action."

Definition. [Consistency in the Collecting Semantics]

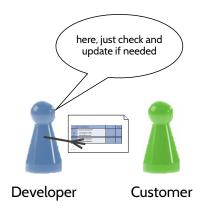
Decision table T is called **consistent with conflict relation** f in the collecting semantics (under conflict axiom φ_{confl}) if and only if there are no conflicting actions in the effect of jointly enabled transitions, i.e. if

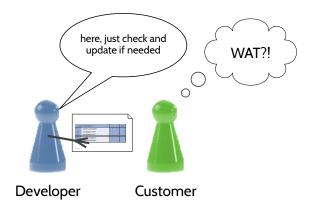
$$\models \mathcal{F}_{coll}(T) \land \varphi_{confl} \rightarrow \bigwedge_{(a_1, a_2) \in \mathcal{I}} \neg (a_1 \land a_2).$$

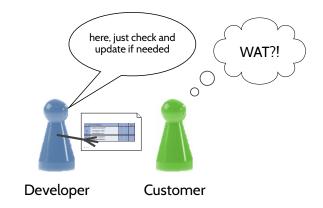
Discussion

Speaking of Formal Methods

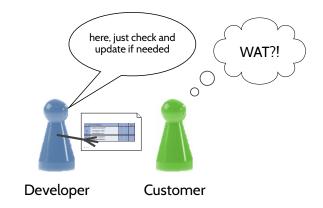
"Es ist aussichtslos, den Klienten mit formalen Darstellungen zu kommen; [...]"







- ... of course it is vast majority of customers is not trained in formal methods.
- formalisation is (first of all) for developers analysts have to translate for customers.
- formalisation is the description of the analyst's understanding, in a most precise form.
 Precise/objective: whoever reads it whenever to whomever, the meaning will not change.



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- formalisation is (first of all) for developers analysts have to translate for customers.
- formalisation is the description of the analyst's understanding, in a most precise form.
 Precise/objective: whoever reads it whenever to whomever, the meaning will not change.
- Recommendation: (Course's Manifesto?)
 - use formal methods for the most important/intricate requirements (formalising all requirements is in most cases not possible),
 - use the most appropriate formalism for a given task,
 - use formalisms that you know (really) well.

Tell Them What You've Told Them...

- Decision Tables: one example for a formal requirements specification language with
 - formal syntax,
 - formal semantics.
- Requirements analysts can use DTs to
 - formally (objectively, precisely)

describe their understanding of requirements.

Customers may need translations/explanation!

- DT properties like
 - (relative) completeness, determinism,
 - uselessness,

can be used to **analyse** requirements.

The discussed DT properties are decidable, there can be automatic analysis tools.

- Domain modelling formalises assumptions on the context of software; for DTs:
 - conflict axioms, conflict relation,

Note: wrong assumptions can have serious consequences.

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