

Softwaretechnik / Software-Engineering
Lecture 12: Structural Software Modelling II

2018-06-18

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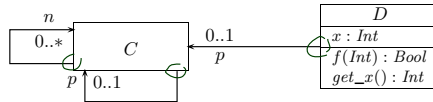
- D - 2018-06-18 - main -

Topic Area Architecture & Design: Content

VL 11	<ul style="list-style-type: none">● Introduction and Vocabulary● Software Modelling<ul style="list-style-type: none">● model; views / viewpoints; 4+1 view
⋮	
VL 12	<ul style="list-style-type: none">● Modelling structure<ul style="list-style-type: none">● (simplified) class & object diagrams● (simplified) object constraint logic (OCL)
⋮	
VL 13	<ul style="list-style-type: none">● Principles of Design<ul style="list-style-type: none">● modularity, separation of concerns● information hiding and data encapsulation● abstract data types, object orientation
⋮	
VL 14	<ul style="list-style-type: none">● Design Patterns● Modelling behaviour<ul style="list-style-type: none">● communicating finite automata (CFA)● Uppaal query language● CFA vs. Software<ul style="list-style-type: none">● Unified Modelling Language (UML)<ul style="list-style-type: none">● basic state-machines● an outlook on hierarchical state-machines
⋮	
	● Model-driven/-based Software Engineering

- D - 2018-06-18 - Stückelmann -

From Abstract to Concrete Syntax



$$\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, \text{atr}, F, \text{mth})$$

- $\mathcal{T} = \{Int, Bool\}$
- $\mathcal{C} = \{C, D\}$
- $V = \{ \{x: Int, p: C, n: C_*\} \}$
- $\text{atr} = \{ C \mapsto \{p, n\}, D \mapsto \{x, p\} \}$
- $F = \{ f: Int \rightarrow Bool, \text{get}_x: Int \}$
- $\text{mth} = \{ C \mapsto \emptyset, D \mapsto \{f, \text{get}_x\} \}$

- 11 - 2018-06-14 - Sonntag -

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- 12 - 2018-06-18 - Montag -

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Content

- **Class Diagrams**
 - semantics: system states.
- **Object Diagrams**
 - concrete syntax,
 - dangling references,
 - partial vs. complete,
 - object diagrams at work.
- **Proto-OCL**
 - syntax, semantics,
 - Proto-OCL vs. OCL.
 - Putting It All Together: Proto-OCL vs. Software

- 12 - 2018-06-18 - Sonntag -

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A More Abstract Class Diagram Semantics

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Object System Structure

Definition. An Object System **Structure** of signature

$$\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr, F, mth)$$

is a **domain function** \mathcal{D} which assigns to each type a domain, i.e.

- $\tau \in \mathcal{T}$ is mapped to $\mathcal{D}(\tau)$,
- $C \in \mathcal{C}$ is mapped to an infinite set $\mathcal{D}(C)$ of (object) identities.
 - object identities of different classes are disjoint, i.e.
 $\forall C, D \in \mathcal{C} : C \neq D \rightarrow \mathcal{D}(C) \cap \mathcal{D}(D) = \emptyset$,
 - on object identities, (only) comparison for equality "=" is defined.
- C_* and $C_{0,1}$ for $C \in \mathcal{C}$ are mapped to $2^{\mathcal{D}(C)}$.

We use $\mathcal{D}(\mathcal{C})$ to denote $\bigcup_{C \in \mathcal{C}} \mathcal{D}(C)$; analogously $\mathcal{D}(\mathcal{C}_*)$.

-D-2018-06-18-Summary-

Note: We identify **objects** and **object identities**, because both uniquely determine each other (cf. OCL 2.0 standard).

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Basic Object System Structure Example

Wanted: a structure for signature

$$\mathcal{S}_0 = (\{Int, Bool\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{p, x\}\}, \{f : Int \rightarrow Bool, get_x : Int\}, \{C \mapsto \emptyset, D \mapsto \{f, get_x\}\})$$

A structure \mathcal{D} maps

- $\tau \in \mathcal{T}$ to **some** $\mathcal{D}(\tau)$, $C \in \mathcal{C}$ to **some** identities $\mathcal{D}(C)$ (infinite, pairwise disjoint),
- C_* and $C_{0,1}$ for $C \in \mathcal{C}$ to $\mathcal{D}(C_{0,1}) = \mathcal{D}(C_*) = 2^{\mathcal{D}(C)}$.

$$\begin{aligned} \mathcal{D}(Bool) &= \{true, false\} & \mathcal{D}(Atr) &= \{red, green\} & & = \{\$, \$, \$, \star\} & \mathcal{D}(Bool) &= \{-1, 0, 1\} \\ \mathcal{D}(Int) &= \mathbb{Z} & & & & = \{one, two, three\} \\ \mathcal{D}(C) &= \mathbb{N}^+ \times \{C\} \cong \{1_C, 2_C, 3_C, \dots\} & & & & = \{a, aa, aaa, \dots\} \\ \mathcal{D}(D) &= \mathbb{N}^+ \times \{D\} \cong \{1_D, 2_D, \dots\} & & & & = \{\cdot, \cdot, \cdot, \cdot, \cdot, \dots\} \\ \mathcal{D}(C_{0,1}) &= \mathcal{D}(C_*) = 2^{\mathcal{D}(C)} \\ \mathcal{D}(D_{0,1}) &= \mathcal{D}(D_*) = 2^{\mathcal{D}(D)} \end{aligned}$$

-12-2018-06-18 - Summary-

System State

Definition. Let \mathcal{D} be a structure of $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr, F, mth)$. A **system state** of \mathcal{S} wrt. \mathcal{D} is a **type-consistent** mapping

$$\sigma : \mathcal{D}(\mathcal{C}) \rightarrow (V \rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$$

That is, for each $u \in \mathcal{D}(C)$, $C \in \mathcal{C}$, if $u \in \text{dom}(\sigma)$

- $\text{dom}(\sigma(u)) = atr(C)$
- $(\sigma(u))(v) \in \mathcal{D}(\tau)$ if $v : \tau, \tau \in \mathcal{T}$
- $(\sigma(u))(v) \in \mathcal{D}(D_*)$ if $v : D_{0,1}$ or $v : D_*$ with $D \in \mathcal{C}$
 $= 2^{\mathcal{D}(D)}$

We call $u \in \mathcal{D}(\mathcal{C})$ **alive** in σ if and only if $u \in \text{dom}(\sigma)$.

We use $\Sigma_{\mathcal{D}}^{\mathcal{S}}$ to denote the set of all system states of \mathcal{S} wrt. \mathcal{D} .

-12-2018-06-18 - Summary-

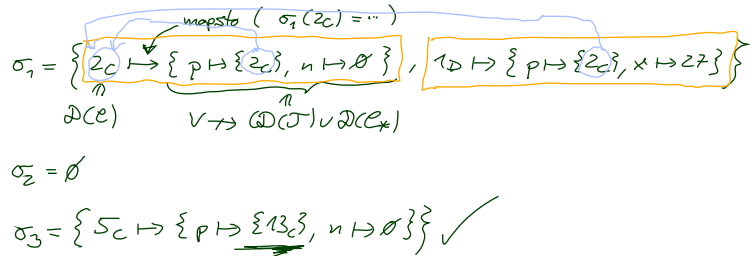
System State Examples

$$\mathcal{S}_0 = (\{Int, Bool\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{p, x\}\}, \\ \{f : Int \rightarrow Bool, get_x : Int\}, \{C \mapsto \emptyset, D \mapsto \{f, get_x\}\})$$

$$\mathcal{D}(\mathcal{C}_{Bool}) = \begin{cases} true \\ false \end{cases} \quad \mathcal{D}(Int) = \mathbb{Z}, \quad \mathcal{D}(C) = \{1_C, 2_C, 3_C, \dots\}, \quad \mathcal{D}(D) = \{1_D, 2_D, 3_D, \dots\}$$

A system state is a partial function $\sigma : \mathcal{D}(\mathcal{C}) \rightarrow (V \rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$ such that

- $\text{dom}(\sigma(u)) = \text{atr}(C)$,
- $\sigma(u)(v) \in \mathcal{D}(\tau)$ if $v : \tau, \tau \in \mathcal{T}$,
- $\sigma(u)(v) \in \mathcal{D}(C_*)$ if $v : D_*$ or $v : D_{0,1}$ with $D \in \mathcal{C}$.



-D-2018-06-18 - Semantics -

Content

- **Class Diagrams**
 - semantics: system states. ✓
- **Object Diagrams**
 - concrete syntax,
 - dangling references,
 - partial vs. complete,
 - object diagrams at work.
- **Proto-OCL**
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-D-2018-06-18 - Semantics -

Object Diagrams

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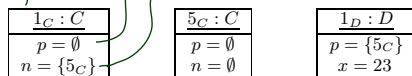
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Object Diagrams

$$\mathcal{S}_0 = (\{Int, Bool\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{p, x\}\}, \\ \{f : Int \rightarrow Bool, get_x : Int\}, \{C \mapsto \emptyset, D \mapsto \{f, get_x\}\}), \quad \mathcal{D}(Int) = \mathbb{Z}$$

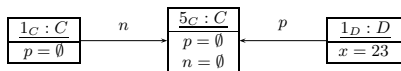
$$\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{p \mapsto \{5_C\}, x \mapsto 23\}\}$$

- We may **represent** σ graphically as follows:

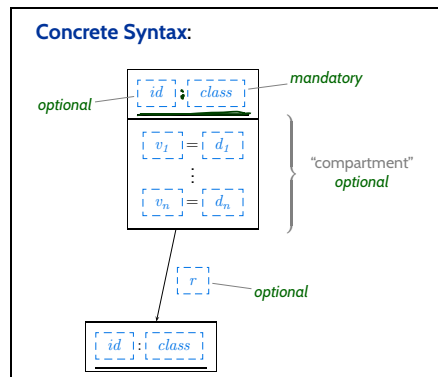
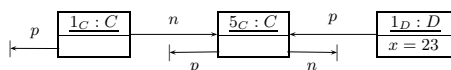


This is an **object diagram**.

- Alternative notation:



- Alternative **non-standard** notation:



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Special Case: Dangling Reference

Definition.

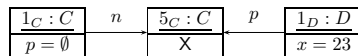
Let $\sigma \in \Sigma_{\mathcal{O}}$ be a system state and $u \in \text{dom}(\sigma)$ an alive object of class C in σ .

We say $r \in \text{atr}(C)$ is a **dangling reference** in u if and only if $r : C_{0,1}$ or $r : C_*$ and u refers to a **non-alive** object via v , i.e.

$$(\sigma(u))(r) \notin \text{dom}(\sigma).$$

Example:

- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 1_D \mapsto \{p \mapsto \{5_C\}, x \mapsto 23\}\}$
- Object diagram representation:

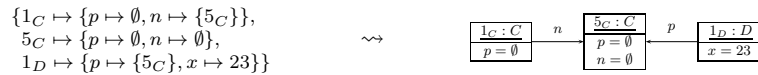


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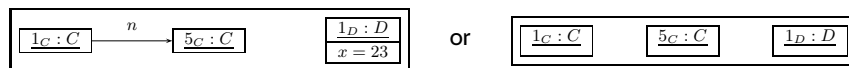
Partial vs. Complete Object Diagrams

- By now we discussed “**object diagram represents system state**”:



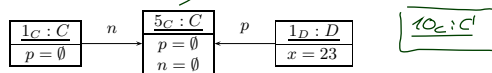
What about the other way round...?

- Object diagrams** can be **partial**, e.g.



→ we may omit information.

- Is the following object diagram **partial** or **complete**?



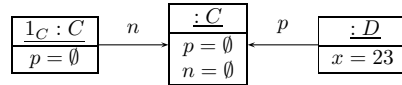
- If an object diagram
 - has values for **all** attributes of **all** objects in the diagram, and
 - if we **say that** it is meant to be **complete**
 then we can **uniquely** reconstruct a system state σ .

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Special Case: Anonymous Objects

If the object diagram



is considered as **complete**, then it denotes the set of all system states

$$\{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{c\}\}, c \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, d \mapsto \{p \mapsto \{c\}, x \mapsto 23\}\}$$

where $c \in \mathcal{D}(C)$, $d \in \mathcal{D}(D)$, $c \neq 1_C$.

Intuition: different boxes represent different objects.

Content

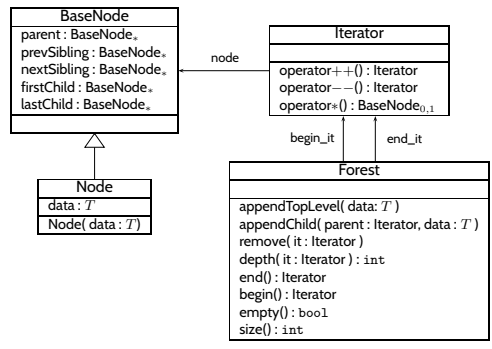
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Object Diagrams at Work

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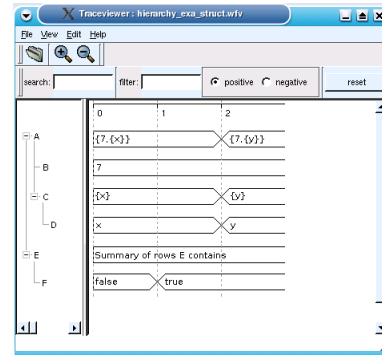
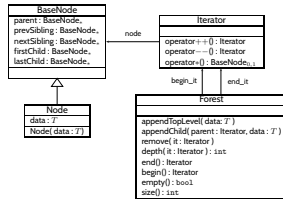
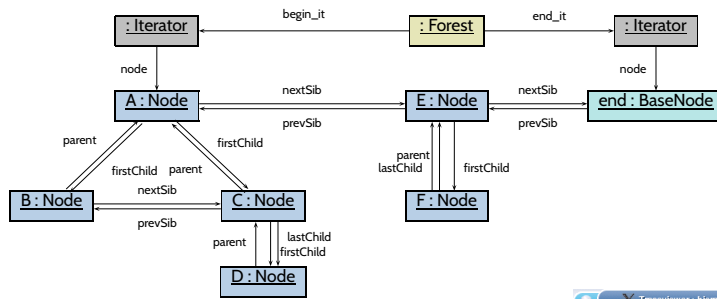
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Example: Data Structure (Schumann et al., 2008)



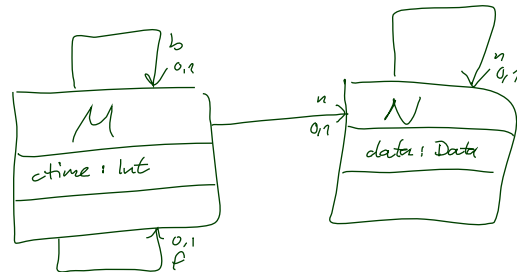
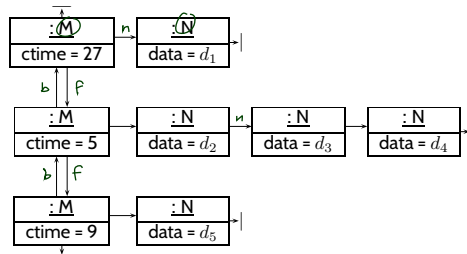
- D - 2018-06-18 - Solution -

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-12-2018-06-18 - Solution 1

Object Diagrams for Analysis

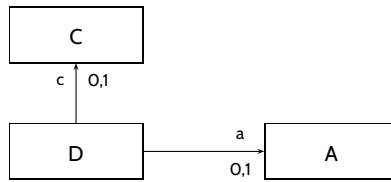


-12-2018-06-18 - Solution 1

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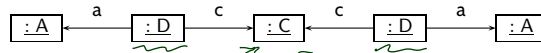
Towards Object Constraint Logic (OCL)
— “Proto-OCL” —

Motivation



- How do I **precisely, formally** tell **my developers** that All D-instances having a link to the same C object must ~~should~~ have links to the same A.

- That is, the following system state is **forbidden** in the software:



Note: formally, it is a **proper system state**.

- Use **(Proto-)OCL**: "Dear developers, please only use system states which satisfy:"

$$\forall d_1 \in allInstances_D \bullet \forall d_2 \in allInstances_D \bullet c(d_1) = c(d_2) \implies a(d_1) = a(d_2)$$

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Constraints on System States

C
x : Int

- Example:** for all C-instances, x should never have the value 27. $\neq (\times \mathcal{C}, 27)$

$$\forall c \in \underbrace{allInstances_C}_{\mathcal{F}_1} \bullet \underbrace{x(c) \neq 27}_{\mathcal{F}_2} \quad \checkmark$$

- Proto-OCL Syntax** wrt. signature $(\mathcal{F}, \mathcal{C}, V, atr, F, mth)$, c is a **logical variable**, $C \in \mathcal{C}$:

$$\begin{aligned}
 F ::= & c && : \tau_C \\
 | & allInstances_C && : 2^{\tau_C} \\
 | & v(F) && : \tau_C \rightarrow \tau_{\perp}, && \text{if } v : \tau \in atr(C), \tau \in \mathcal{F} \\
 | & v(F) && : \tau_C \rightarrow \tau_D, && \text{if } v : \underline{D_{0,1}} \in atr(C) \\
 | & v(F) && : \tau_C \rightarrow \tau_{\underline{D}}, && \text{if } v : \underline{D_*} \in atr(C) \\
 | & f(F_1, \dots, F_n) && : \tau_1 \times \dots \times \tau_n \rightarrow \tau, && \text{if } f : \tau_1 \times \dots \times \tau_n \rightarrow \tau \\
 | & \forall c \in F_1 \bullet F_2 && : \tau_C \times 2^{\tau_C} \times \mathbb{B}_{\perp} \rightarrow \tau_{\perp}
 \end{aligned}$$

- The formula above in **prefix normal form**: $\forall c \in allInstances_C \bullet \neq (x(c), 27)$

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Semantics

- **Proto-OCL Types:**
 - $\mathcal{I}[\tau_C] = \mathcal{D}(C) \dot{\cup} \{\perp\}$, $\mathcal{I}[\tau_{\perp}] = \mathcal{D}(\tau) \dot{\cup} \{\perp\}$, $\mathcal{I}[2^{\tau_C}] = \mathcal{D}(C_*) \dot{\cup} \{\perp\}$
 - $\mathcal{I}[\mathbb{B}_{\perp}] = \{true, false\} \dot{\cup} \{\perp\}$, $\mathcal{I}[\mathbb{Z}_{\perp}] = \mathbb{Z} \dot{\cup} \{\perp\}$
- **Functions:**
 - We assume $f_{\mathcal{I}}$ given for each function symbol f (\rightarrow in a minute).
- **Proto-OCL Semantics** (interpretation function):
 - $\mathcal{I}[c](\sigma, \beta) = \beta(c)$ (assuming β is a type-consistent valuation of the logical variables),
 - $\mathcal{I}[allInstances_C](\sigma, \beta) = \text{dom}(\sigma) \cap \mathcal{D}(C)$,
 - $\mathcal{I}[v(F)](\sigma, \beta) = \begin{cases} \sigma(\mathcal{I}[F](\sigma, \beta))(v) & , \text{if } \mathcal{I}[F](\sigma, \beta) \in \text{dom}(\sigma) \\ \perp & , \text{otherwise} \end{cases}$ (if not $v : C_{0,1}$)
 - $\mathcal{I}[v(F)](\sigma, \beta) = \begin{cases} u' & , \text{if } \mathcal{I}[F](\sigma, \beta) \in \text{dom}(\sigma) \text{ and } \sigma(\mathcal{I}[F](\sigma, \beta))(v) = \{u'\} \\ \perp & , \text{otherwise} \end{cases}$ (if $v : C_{0,1}$)
 - $\mathcal{I}[f(F_1, \dots, F_n)](\sigma, \beta) = f_{\mathcal{I}}(\mathcal{I}[F_1](\sigma, \beta), \dots, \mathcal{I}[F_n](\sigma, \beta))$,
 - $\mathcal{I}[\forall c \in F_1 \bullet F_2](\sigma, \beta) = \begin{cases} true & , \text{if } \mathcal{I}[F_2](\sigma, \beta[c := u]) = true \text{ for all } u \in \mathcal{I}[F_1](\sigma, \beta) \\ false & , \text{if } \mathcal{I}[F_2](\sigma, \beta[c := u]) = false \text{ for some } u \in \mathcal{I}[F_1](\sigma, \beta) \\ \perp & , \text{otherwise} \end{cases}$

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Semantics Cont'd

- Proto-OCL is a **three-valued** logic: a formula evaluates to *true*, *false*, or \perp .
- **Example:** $\wedge_{\mathcal{I}}(\cdot, \cdot) : \{true, false, \perp\} \times \{true, false, \perp\} \rightarrow \{true, false, \perp\}$ is defined as follows:

x_1	$\begin{pmatrix} true & true \\ true & false \end{pmatrix}$	$true$	$\begin{pmatrix} false & false \\ true & false \end{pmatrix}$	$false$	\perp	\perp	\perp
x_2	$\begin{pmatrix} true & true \\ true & false \end{pmatrix}$	\perp	$\begin{pmatrix} false & false \\ true & false \end{pmatrix}$	\perp	$true$	$false$	\perp
$\wedge_{\mathcal{I}}(x_1, x_2)$	$\begin{pmatrix} true & true \\ true & false \end{pmatrix}$	\perp	$\begin{pmatrix} false & false \\ true & false \end{pmatrix}$	$false$	\perp	$false$	\perp

We assume common logical connectives $\neg, \wedge, \vee, \dots$ with canonical 3-valued interpretation.

- **Example:** $+_{\mathcal{I}}(\cdot, \cdot) : (\mathbb{Z} \dot{\cup} \{\perp\}) \times (\mathbb{Z} \dot{\cup} \{\perp\}) \rightarrow \mathbb{Z} \dot{\cup} \{\perp\}$

$$+_{\mathcal{I}}(x_1, x_2) = \begin{cases} x_1 + x_2 & , \text{if } x_1 \neq \perp \text{ and } x_2 \neq \perp \\ \perp & , \text{otherwise} \end{cases}$$

We assume common arithmetic operations $-, /, *, \dots$ and relation symbols $>, <, \leq, \dots$ with **monotone** 3-valued interpretation.

- And we assume the special unary function symbol *isUndefined*:

$$isUndefined_{\mathcal{I}}(x) = \begin{cases} true & , \text{if } x = \perp, \\ false & , \text{otherwise} \end{cases}$$

$isUndefined_{\mathcal{I}}$ is **definite**: it never yields \perp .

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Example: Evaluate Formula for System State

$$\sigma : \begin{array}{|l} \hline 1_C : C \\ \hline x = 13 \\ \hline \end{array} \qquad \begin{array}{|l} \hline C \\ \hline x : Int \\ \hline \end{array}$$

$$\underbrace{\qquad\qquad\qquad}_{\forall c \in allInstances_C \bullet x(c) \neq 27}$$

- Recall **prefix notation**: $\forall c \in allInstances_C \bullet \neq(x(c), 27)$
Note: \neq is a binary function symbol, 27 is a 0-ary function symbol.

Example: Evaluate Formula for System State

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- Example:** $\{c\}$
 $\mathcal{I}[\forall c \in allInstances_C \bullet \neq(x(c), 27)](\sigma, \emptyset) = true, \text{ because...}$
 $\mathcal{I}[\neq(x(c), 27)](\sigma, \beta), \quad \beta := \emptyset[c := 1_C] = \{c \mapsto 1_C\}$
 =

Example: Evaluate Formula for System State

$\sigma :$	<table border="1" style="display: inline-table;"><tr><td>$1_C : C$</td></tr><tr><td>$x = 13$</td></tr></table>	$1_C : C$	$x = 13$
$1_C : C$			
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C
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- Example:**

$$\mathcal{I}[\forall c \in allInstances_C \bullet \neq(x(c), 27)](\sigma, \emptyset) = \text{true, because...}$$

$$\mathcal{I}[\neq(x(c), 27)](\sigma, \beta), \quad \beta := \emptyset[c := 1_C] = \{c \mapsto 1_C\}$$

$$= \neq_{\mathcal{I}}(\mathcal{I}[x(c)](\sigma, \beta), \mathcal{I}[27](\sigma, \beta))$$

=

Example: Evaluate Formula for System State

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$$= \neq_{\mathcal{I}}(\mathcal{I}[x(c)](\sigma, \beta), \mathcal{I}[27](\sigma, \beta))$$

$$= \neq_{\mathcal{I}}(\mathcal{I}[\underline{\mathcal{I}[c]}(\sigma, \beta)](x), 27_{\mathcal{I}})$$

=

Example: Evaluate Formula for System State

$\sigma :$	<table border="1" style="display: inline-table;"><tr><td>$1_C : C$</td></tr><tr><td>$x = 13$</td></tr></table>	$1_C : C$	$x = 13$
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C
$x : Int$

$$\forall c \in allInstances_C \bullet x(c) \neq 27$$

- Recall **prefix notation**: $\forall c \in allInstances_C \bullet \neq(x(c), 27)$

Note: \neq is a binary function symbol, 27 is a 0-ary function symbol.

- Example:**

$$\mathcal{I}[\forall c \in allInstances_C \bullet \neq(x(c), 27)](\sigma, \emptyset) = \text{true, because...}$$

$$\mathcal{I}[\neq(x(c), 27)](\sigma, \beta), \quad \beta := \emptyset[c := 1_C] = \{c \mapsto 1_C\}$$

$$= \neq_{\mathcal{I}}(\mathcal{I}[x(c)](\sigma, \beta), \mathcal{I}[27](\sigma, \beta))$$

$$= \neq_{\mathcal{I}}(\sigma(\mathcal{I}[c](\sigma, \beta))(x), 27_{\mathcal{I}})$$

$$= \neq_{\mathcal{I}}(\sigma(\beta(c))(x), 27_{\mathcal{I}})$$

$$= \neq_{\mathcal{I}}(\sigma(1_C)(x), 27_{\mathcal{I}})$$

=

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Example: Evaluate Formula for System State

$\sigma :$	<table border="1" style="display: inline-table;"><tr><td>$1_C : C$</td></tr><tr><td>$x = 13$</td></tr></table>	$1_C : C$	$x = 13$
$1_C : C$			
$x = 13$			

C
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$$= \neq_{\mathcal{I}}(\sigma(1_C)(x), 27_{\mathcal{I}})$$

$$= \neq_{\mathcal{I}}(13, 27) = \text{true} \quad \dots \text{and } 1_C \text{ is the only } C\text{-object in } \sigma: \mathcal{I}[allInstances_C](\sigma, \emptyset) = \{1_C\}.$$

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More Interesting Example



$$\forall c : allInstances_C \bullet x(n(c)) \neq 27$$

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More Interesting Example



$$\forall c : allInstances_C \bullet x(n(c)) \neq 27$$

- Similar to the previous slide, we need the value of

$$\mathcal{I}[x(n(c))](\sigma, \beta), \beta = \{c \mapsto 1_C\}$$

- $\mathcal{I}[c](\sigma, \beta) = \beta(c) = 1_C$
- $\mathcal{I}[n(c)](\sigma, \beta) = \perp$ since $\sigma(\mathcal{I}[c](\sigma, \beta))(n) = \emptyset \neq \{u'\}$ by rule

$$\mathcal{I}[v(F)](\sigma, \beta) = \begin{cases} u' & , \text{if } \mathcal{I}[F](\sigma, \beta) \in \text{dom}(\sigma) \text{ and } \sigma(\mathcal{I}[F](\sigma, \beta))(v) = \{u'\} \\ \perp & , \text{otherwise} \end{cases} \quad (\text{if } v : C_{0,1})$$

- $\mathcal{I}[x(n(c))](\sigma, \beta) = \perp$ since $\mathcal{I}[n(c)](\sigma, \beta) = \perp$ by rule

$$\mathcal{I}[v(F)](\sigma, \beta) = \begin{cases} \sigma(\mathcal{I}[F](\sigma, \beta))(v) & , \text{if } \mathcal{I}[F](\sigma, \beta) \in \text{dom}(\sigma) \\ \perp & , \text{otherwise} \end{cases} \quad (\text{if not } v : C_{0,1})$$

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More Interesting Example



$$\forall c : allInstances_C \bullet x(n(c)) \neq 27$$

- Similar to the previous slide, we need the value of

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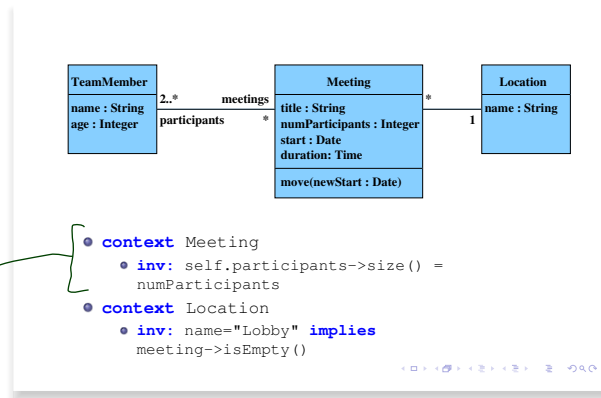
- $\mathcal{I}[x(n(c))](\sigma, \beta) = \perp$ since $\mathcal{I}[n(c)](\sigma, \beta) = \perp$ by rule

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Object Constraint Language (OCL)

OCL is the same — just with less readable (?) syntax.

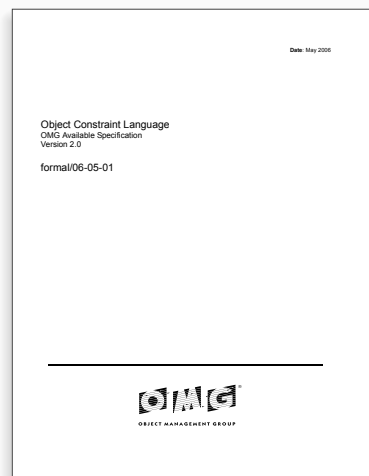
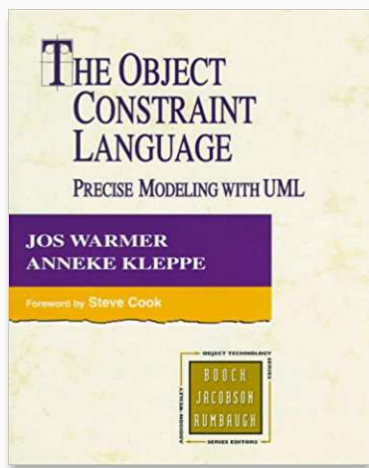
Literature: (OMG, 2006; Warmer and Kleppe, 1999).



- **context** Meeting
 - **inv:** self.participants->size() = numParticipants
- **context** Location
 - **inv:** name="Lobby" **implies** meeting->isEmpty()

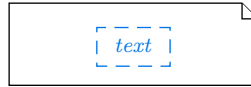
✓ self : all instances meeting
 size (participants (self)) = num Participants (self)

Literature



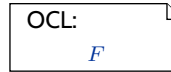
Where To Put OCL Constraints?

- **Notes:** A UML **note** is a diagram element of the form



text can principally be **everything**, in particular **comments** and **constraints**.

Sometimes, content is **explicitly classified** for clarity:



- **Conventions:**



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Content

- **Class Diagrams**
 - semantics: system states.
- **Object Diagrams**
 - concrete syntax,
 - dangling references,
 - partial vs. complete,
 - object diagrams at work.
- **Proto-OCL**
 - syntax, semantics,
 - Proto-OCL vs. OCL.
 - Putting It All Together: Proto-OCL vs. Software

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Putting It All Together

Modelling Structure with Class Diagrams

Definition. **Software** is a finite description S of a (possibly infinite) set $\llbracket S \rrbracket$ of (finite or infinite) **computation paths** of the form $\sigma_0 \xrightarrow{\alpha_1} \sigma_1 \xrightarrow{\alpha_2} \sigma_2 \dots$ where

- $\sigma_i \in \Sigma$, $i \in \mathbb{N}_0$, is called **state** (or **configuration**), and
- $\alpha_i \in A$, $i \in \mathbb{N}_0$, is called **action** (or **event**).

The (possibly partial) function $\llbracket \cdot \rrbracket : S \mapsto \llbracket S \rrbracket$ is called **interpretation** of S .

- The set of **states** Σ could be the set of **system states** as defined by a class diagram, e.g.

$$\Sigma := \Sigma_{\mathcal{C}} \qquad \mathcal{C} : \begin{array}{|c|} \hline \mathbf{C} \\ \hline x : \text{Int} \\ \hline \end{array}$$

- A corresponding **computation path** of a software S could be

$$\begin{array}{|c|} \hline \mathbf{27C} : \mathbf{C} \\ \hline x = 0 \\ \hline \end{array} \xrightarrow{\tau} \begin{array}{|c|} \hline \mathbf{27C} : \mathbf{C} \\ \hline x = 1 \\ \hline \end{array} \xrightarrow{\tau} \begin{array}{|c|} \hline \mathbf{27C} : \mathbf{C} \\ \hline x = 3 \\ \hline \end{array} \xrightarrow{\tau} \begin{array}{|c|} \hline \mathbf{27C} : \mathbf{C} \\ \hline x = 4 \\ \hline \end{array} \xrightarrow{\tau} \dots$$

- If a requirement is formalised by the Proto-OCL constraint

$$F = \forall c \in \text{allInstances}_{\mathbf{C}} \bullet x(c) < 4$$

then S **does not** satisfy the requirement.

More General: Software vs. Proto-OCL

- Let \mathcal{S} be an **object system signature** and \mathcal{D} a **structure**.
- Let S be a **software** with
 - states $\Sigma \subseteq \Sigma_{\mathcal{D}}$, and
 - **computation paths** $\llbracket S \rrbracket$.
- Let F be a Proto-OCL constraint over \mathcal{S} .
- We say $\llbracket S \rrbracket$ **satisfies** F , denoted by $\llbracket S \rrbracket \models F$, if and only if for all

$$\sigma_0 \xrightarrow{\alpha_1} \sigma_1 \xrightarrow{\alpha_2} \sigma_2 \cdots \in \llbracket S \rrbracket$$

and all $i \in \mathbb{N}_0$,

$$\mathcal{I}\llbracket F \rrbracket(\sigma_i, \emptyset) = \text{true}.$$

- We say $\llbracket S \rrbracket$ **does not satisfy** F , denoted by $\llbracket S \rrbracket \not\models F$, if and only if there exists $\sigma_0 \xrightarrow{\alpha_1} \sigma_1 \xrightarrow{\alpha_2} \sigma_2 \cdots \in \llbracket S \rrbracket$ and $i \in \mathbb{N}_0$, such that $\mathcal{I}\llbracket F \rrbracket(\sigma_i, \emptyset) = \text{false}$.
- **Note:** $\neg(\llbracket S \rrbracket \not\models F)$ does not imply $\llbracket S \rrbracket \models F$.

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Tell Them What You've Told Them...

- **Class Diagrams** can be used to **graphically**
 - visualise code,
 - define an **object system structure** \mathcal{S} .
- An **Object System Structure** \mathcal{S} (together with a structure \mathcal{D})
 - defines a set of **system states** $\Sigma_{\mathcal{D}}$.
- A **System State** $\sigma \in \Sigma_{\mathcal{D}}$
 - can be **visualised** by an **object diagram**.
- **Proto-OCL** constraints can be evaluated on **system states**.
- A **software** over $\Sigma_{\mathcal{D}}$ satisfies a Proto-OCL constraint F if and only if F evaluates to **true** in all system states of all the software's computation paths.

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References

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