

Software Design, Modelling and Analysis in UML

Lecture 17: Reflective Description of Behaviour Live Sequence Charts I

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Contents & Goals

Last Lecture:

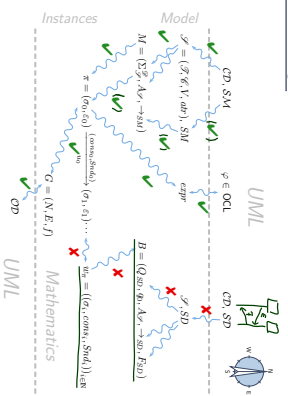
- Hierarchical State Machines
- Later: Remaining pseudo-states, such as shallow/deep history, active vs. passive, behavioural feature.

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions:
 - What does this LSC mean?
 - Are this UML model's state machines consistent with the interactions?
 - Please provide a UML model which is consistent with this LSC.
 - What is: activation, hot/cold condition, pre-chart, etc.?
- **Content:**
 - Reflective description of behaviour.
 - LSC concrete and abstract syntax.
 - LSC inductive semantics.
 - Symbolic Burch Automata (TBA) and its (accepted) language.

You are here.

Course Map



Motivation: Reflective, Dynamic Descriptions of Behaviour

Recall: Constructive vs. Reflective Descriptions

[Harel, 1997] proposes to distinguish constructive and reflective descriptions:

- "A language is **constructive** if it contributes to the dynamic semantics of the model. That is, its constructs contain information needed in executing the model or in translating it into executable code."
- A constructive description tells **how** things are computed (which can then be desired or undesired).

- "Other languages are **reflective or assertive**, and can be used by the system modeler to capture parts of the thinking that go into building the model — behavior included —, to derive and present views of the model, statically or during execution, or to set constraints on behavior in preparation for verification."

A reflective description tells **what** shall or shall not be computed.

Note: No sharp boundaries!

Recall: What is a Requirement?

- Recall:**
- The semantics of the UML model $\mathcal{M} = (\mathcal{C}, \mathcal{G}, \mathcal{S}, \mathcal{R}, \mathcal{O}, \mathcal{D})$ is the transition system $(S \rightarrow S_0)$ constructed according to discard/discardy/commerce-rules.
 - The computations of \mathcal{M} , denoted by $\llbracket \mathcal{M} \rrbracket$, are the computations of $(S \rightarrow S_0)$.

Now:

A reflexive description tells what shall or shall not be computed.

More formally: a requirement ϑ is a property of computations, sth. which is either satisfied or not satisfied by a computation

$$\pi = (\sigma_0, \varepsilon_0) \xrightarrow{(consum, \text{Send}_0)} (\sigma_1, \varepsilon_1) \xrightarrow{(consum, \text{Send}_1)} \dots \in \llbracket \mathcal{M} \rrbracket$$

denoted by $\pi \models \vartheta$ and $\pi \not\models \vartheta$, resp.

OCL as Reflexive Description of Certain Properties

- invariants:** $\mathcal{M} \models \vartheta \iff \forall \pi \in \llbracket \mathcal{M} \rrbracket \forall i \in \mathbb{N} : \pi^i \models \vartheta$, *the "GADT" part is \mathcal{M}*
- non-reachability of configurations:** $\nexists \pi \in \llbracket \mathcal{M} \rrbracket \exists i \in \mathbb{N} : \pi^i \models \vartheta$
- reachability of configurations:** $\exists \pi \in \llbracket \mathcal{M} \rrbracket \exists i \in \mathbb{N} : \pi^i \models \vartheta$
- $\iff \neg(\forall \pi \in \llbracket \mathcal{M} \rrbracket \forall i \in \mathbb{N} : \pi^i \models \neg\vartheta)$

where ϑ is an OCL expression or an object diagram and \models is the corresponding OCL satisfaction or the "is represented by object diagram" relation.

In General Not OCL: Temporal Properties

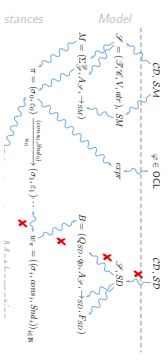
- Dynamic (by example)**
- reactive behaviour
 - "for each C instance, each reception of E is finally answered by F "
 - $\forall \pi \in \llbracket \mathcal{M} \rrbracket : \pi \models \vartheta$
 - non-reachability of system configuration sequences**
 - "there mustn't be a system run where C first receives E and then sends F "
 - $\exists \pi \in \llbracket \mathcal{M} \rrbracket : \pi \models \vartheta$
 - reachability of system configuration sequences**
 - "there must be a system run where C first receives E and then sends F "
 - $\exists \pi \in \llbracket \mathcal{M} \rrbracket : \pi \models \vartheta$

But: what is " \models " and what is " ϑ "?

Interactions: Problem and Plan

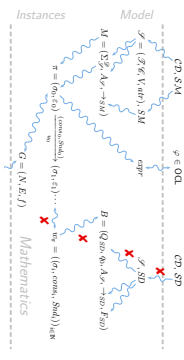
In general $\forall \exists \pi \in \llbracket \mathcal{M} \rrbracket : \pi \models \vartheta$ and what is " ϑ "?

- Plan:**
- Define the language $\mathcal{L}(I)$ of an interaction I — via Buchi automata
 - Define the language $\mathcal{L}(\mathcal{M})$ of a model \mathcal{M} — basically its computations
 - Each computation $\pi \in \llbracket \mathcal{M} \rrbracket$ corresponds to a word w_π .
 - Then (conceptually) $\pi \models \vartheta$ if and only if $w_\pi \in \mathcal{L}(I)$.



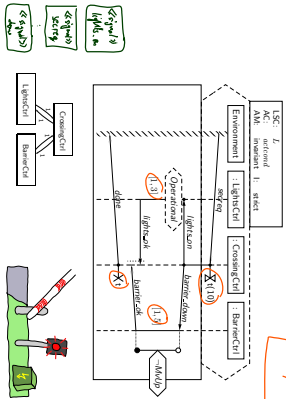
Interactions: Plan

- In the following, we consider Sequence Diagrams as Interaction I ,
 - more precisely: Live Sequence Charts [Damm and Harel, 2001].
 - We define the language $\mathcal{L}(I)$ of an LSC — via Buchi automata
 - Then (conceptually) $\pi \models \vartheta$ if and only if $w_\pi \in \mathcal{L}(I)$.
- Why LSC, relation LSCs/UML SDs, other kinds of interactions, later.



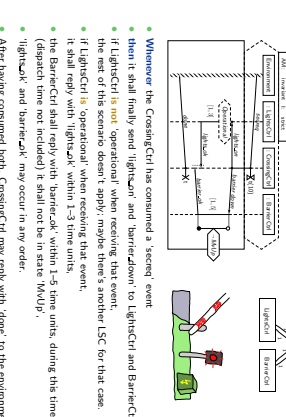
Live Sequence Charts — Concrete Syntax

Example



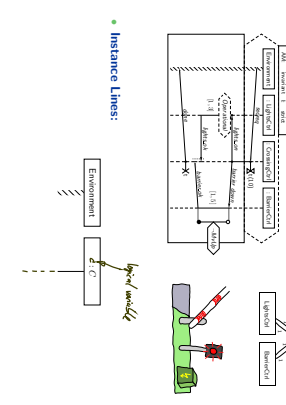
ASPER7,5/REUR,
Lehane Red/Time
Systems Summer
2018

Example: What Is Required?

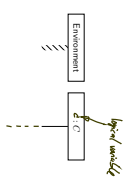


- Whenever the CrossingCtrl has consumed a 'secret' event
- then it shall finally send 'lightdown' and 'barrierdown' to LightCtrl and BarrierCtrl
- if LightCtrl is not 'operational' when receiving that event, the rest of the scenario doesn't apply; maybe there's another LSC for that case.
- if LightCtrl is 'operational' when receiving that event, it shall reply with 'lightup' within 1-3 time units.
- the BarrierCtrl shall reply with 'barrierdown' within 1-3 time units, during this time (elapsed time not included) it shall not be in state 'WdUp'.
- 'lightup' and 'barrierdown' may occur in any order.
- After having consumed both, CrossingCtrl may reply with 'done' to the environment.

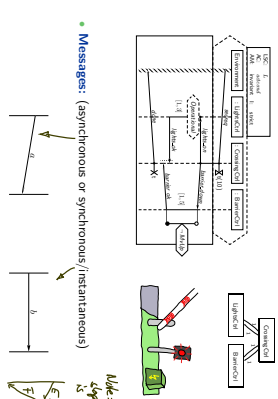
Building Blocks



Instance Lines:



Building Blocks

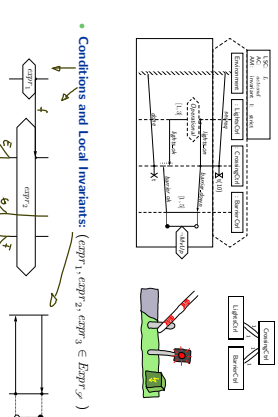


Messages: (asynchronous or synchronous/instantaneous)

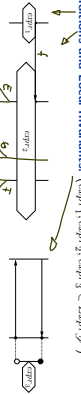


Note: couple of
light messages
is not relevant
as
T and T2
are sporadic.

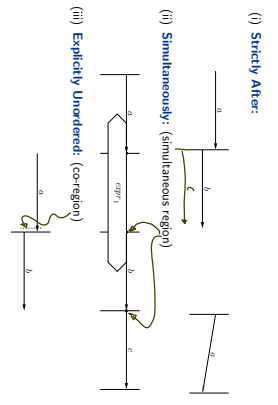
Building Blocks



Conditions and Local Invariants: (expr₁, expr₂, expr₃ ∈ Expr[∞])



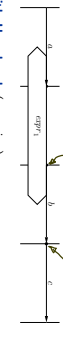
Intuitive Semantics: A Partial Order on Simulaclasses



(i) Strictly After:



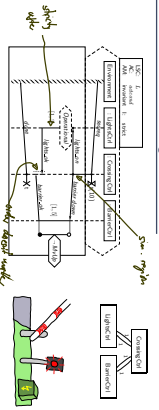
(ii) Simultaneously: (simultaneous region)



(iii) Explicitly Undercut: (co-region)

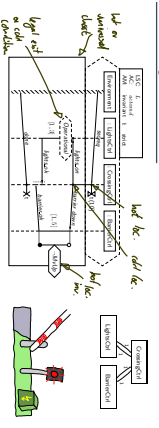
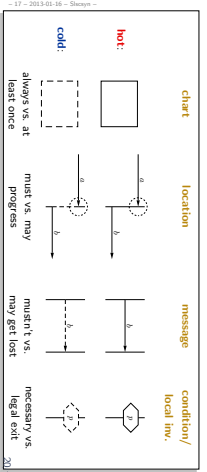


Intuition: A computation path **violates** an LSC if the occurrence of some events doesn't adhere to the partial order obtained as the **transitive closure** of (i) to (iii).



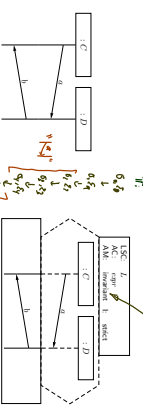
- Whenever the CrossingCtrl has consumed a 'secret' event
- then it shall finally send 'lightscri' and 'barrierack' to LightScri and BarrierCrt.
- if LightScri is not 'operational' when receiving that event, the rest of this scenario doesn't apply, maybe there's another LSC for that case.
- if LightScri is 'operational' when receiving that event, it shall reply with 'lightscriack' within 1-5 time units.
- the BarrierCrt shall reply with 'barrierack' within 1-5 time units, during this time (obscure time not included) it shall not be in state WOLP.
- 'lightscriack' and 'barrierack' may occur in any order.
- After having consumed both, CrossingCtrl may reply with 'done' to the environment.

- With LSCs,
- whole charts,
 - locations, and
 - elements
- have a mode — one of **hot** or **cold** (graphically indicated by outline).

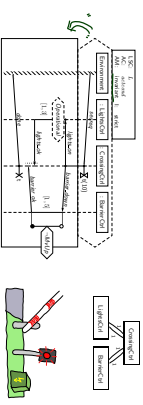


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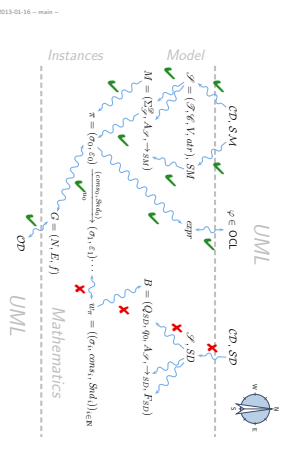
One major defect of MSCs and SDS: they don't say when the scenario has activation mode (AM ∈ {init, end}) to/may be observed.



- LSCs: Activation condition (AC ∈ Expr_x), activation mode (AM ∈ {init, end}), to/may be observed.
- Intuition: (universal case)
- given a computation π , whenever expr holds in a configuration (α, λ, β) of $(\mathcal{P}, \mathcal{M} = \text{initial})$ (AM = invariant)
 - which is initial, i.e. $k = 0$, or
 - whose k is not further restricted, and if the pre-chart is observed from k to $k+n$, then the main-chart has to follow from $k+n+1$.



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References

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