

Software Design, Modelling and Analysis in UML

Lecture 10: Constructive Behaviour; State Machines Overview

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Contents & Goals

- Last Lecture:**
 - (Mostly) completed discussion of modelling **structure**.

This Lecture:

- Educational Objectives:** Capabilities for following tasks/questions:
 - Discuss the style of this class diagram.
 - What's the difference between reflective and constructive descriptions of behaviour?
 - What's the purpose of a behavioural model?
 - What does this State Machine mean? What happens if I inject this event?
 - Can you please model the following behaviour.

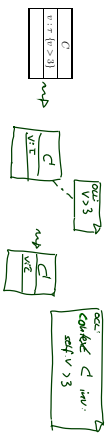
Content:

- For completeness: Modelling Guidelines for Class Diagrams
- Purposes of Behavioural Models
- Constructive vs. Reflective
- UML Core State Machines (first half)

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OCL Constraints in (Class) Diagrams

Invariant in Class Diagram Example

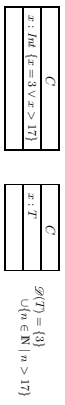


If $\mathcal{C} \in \mathcal{G}$ consists of only $C'D$ with the single class C , then

- $Inv(\mathcal{C} \in \mathcal{G}) = Inv(C'D) = \{state \mid C \text{ has } v > 3\}$

Constraints vs. Types

Find the 10 differences:



- $x = 4$ is well-typed in the left context, a system state satisfying $x = 4$ violates the constraints of the diagram.
- $x = 4$ is not even well-typed in the right context, there cannot be a system state with $\sigma^{(U)}(x) = 4$ because $\sigma^{(U)}(x)$ is supposed to be in $\mathcal{D}(T)$ (by definition of system state).

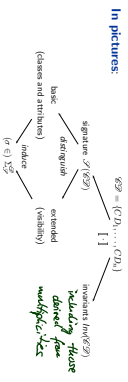
Rule-of-thumb:

- If something "feels like" a type (one criterion: has a natural correspondence in the application domain), then make it a type.
- If something is a requirement or restriction of an otherwise useful type, then make it a constraint.

Semantics of a Class Diagram

Definition. Let $\mathcal{C} \in \mathcal{G}$ be a set of class diagrams. We say, the semantics of $\mathcal{C} \in \mathcal{G}$ is the signature it induces and the set of OCL constraints occurring in $\mathcal{C} \in \mathcal{G}$, denoted $[[\mathcal{C} \in \mathcal{G}]] = \langle \mathcal{S}(\mathcal{C} \in \mathcal{G}), Inv(\mathcal{C} \in \mathcal{G}) \rangle$.

Given a structure \mathcal{D} of \mathcal{S} (and thus of $\mathcal{C} \in \mathcal{G}$), the class diagrams describe the system states $\Sigma_{\mathcal{D}}^{\mathcal{C} \in \mathcal{G}}$. Of those, some satisfy $Inv(\mathcal{C} \in \mathcal{G})$ and some don't. We call a system state $\sigma \in \Sigma_{\mathcal{D}}^{\mathcal{C} \in \mathcal{G}}$ consistent, if and only if $\sigma \models Inv(\mathcal{C} \in \mathcal{G})$.



Pragmatics

Recall: a UML model is an image or preimage of a software system.

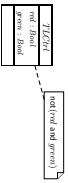
A set of class diagrams $\mathcal{C}\mathcal{D}$ with invariants $Inv(\mathcal{C}\mathcal{D})$ describes the **structure** of system states.

Together with the invariants it can be used to state:

- **Pre-image:** Dear programmer, please provide an implementation which **uses only system states** that satisfy $Inv(\mathcal{C}\mathcal{D})$.
- **Post-image:** Dear user/maintainer, in the existing system, only system states which satisfy $Inv(\mathcal{C}\mathcal{D})$ are used.

(The exact meaning of "use" will become clear when we talk about behaviour — In English: "the system states that are reachable from the initial system state(s) by calling method(s) or firing transition(s) in state machines")

Example: highly abstract model of traffic lights controller:



Addendum: Semantics of OCL Boolean Operations

Correct Semantics of OCL Boolean Operations

Table A.2 - Semantics of boolean operations

h_1	h_2	$h_1 \text{ and } h_2$	$h_1 \text{ or } h_2$	$h_1 \text{ xor } h_2$	$h_1 \text{ implies } h_2$	$\text{not } h_1$
false	false	false	false	false	true	true
false	true	false	true	true	true	false
true	false	false	true	true	false	false
true	true	true	true	false	true	true
false	\perp	false	\perp	\perp	\perp	\perp
true	\perp	\perp	\perp	\perp	\perp	\perp

Table A.3 - Semantics of boolean operations
Object Constraint Language, v2.0

\perp	false	true	\perp	true	\perp	\perp
\perp	\perp	\perp	\perp	\perp	\perp	\perp
false	false	true	true	true	true	true
true	true	true	true	true	true	true

Design Guidelines for (Class) Diagram

(partly following (Anker, 2005))

Be careful whose advice you buy, but be patient with those who supply it.

— Ben-Lurmann/Mary-Schmitt

- semantics of operators is monotone

(\perp propagates through, and a sub-expression evaluates to \perp , the whole expression does)

$$T(h_1 \wedge h_2) = \begin{cases} \text{true} & \text{if } h_1 \wedge h_2 \\ \perp & \text{otherwise} \end{cases}$$

$$T(h_1 \vee h_2) = \begin{cases} \text{true} & \text{if } h_1 \vee h_2 \\ \perp & \text{otherwise} \end{cases}$$

then not relevant (only if $h_1 \vee h_2 > 0$ so $\text{not relevant}(h_1 \vee h_2)$ or $\text{not } h_1 \wedge h_2 > 0$ would not do what we want

then not relevant (only if $h_1 \wedge h_2 > 0$ so $\text{not relevant}(h_1 \wedge h_2)$ or $\text{not } h_1 \vee h_2 > 0$ would not do what we want

Main and General Modelling Guideline (subheuristic: trivial and obvious)

Be good to your audience.

"Imagine you're given your diagram D and asked to conduct task T ."

- Can you do T with D ? (semantics sufficiently clear? all necessary information available? ...)
- Does doing T with D cost you more nerves/time/money/... than it should? (practical well-formedness? readability? insertion of deletions from standard syntax clear? reasonable selection of information? layout? ...)

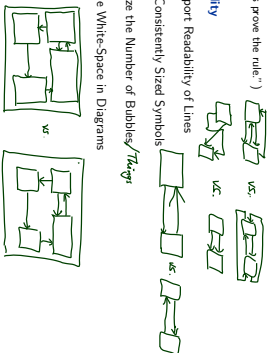
In other words:

- the things **most relevant** for T , do they **stand out** in D ? **YES**
 - the things **less relevant** for T , do they **disturb** in D ? **NO**
- for a good design 12/96

- Q: When is a (class) diagram a good diagram?
 - A: If it serves its purpose/makes its point.
- Examples for purposes and points and rules-of-thumb:
- **Analysis/Design**
 - realizable, no contradictions
 - abstract, focused, admitting degrees of freedom for (more detailed) design
 - platform independent – as far as possible but not (artificially) fater
 - **Implementation/A**
 - close to target platform
 - (C++, B easy for Java, C, comes at a cost – other way round for RDB)
 - **Implementation/B**
 - complete, executable
 - **Documentation**
 - Right level of abstraction: "If you've only one diagram to spend, illustrate the concepts, the architecture, the difficult part"
 - The more detailed the documentation, the higher the probability for regression "outdated/wrong documentation is worse than none"

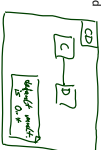
(Note: "Exceptions prove the rule.")

- **2.1 Readability**
 - 1-3. Support Readability of Lines
 - 4. Apply Consistently Sized Symbols
 - 9. Minimize the Number of Bubbles/Tags
 - 10. Include White-Space in Diagrams

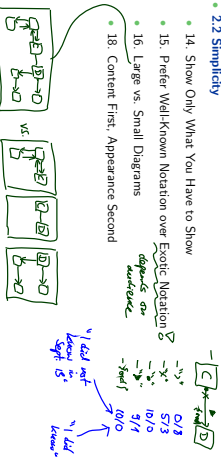


(Note: "Exceptions prove the rule.")

- **2.1 Readability**
 - 1-3. Support Readability of Lines
 - 4. Apply Consistently Sized Symbols
 - 9. Minimize the Number of Bubbles
 - 10. Include White-Space in Diagrams
- 13. Provide a Notational Legend



- **2.2 Simplicity**
 - 14. Show Only What You Have to Show
 - 15. Prefer Well-Known Notation over Exotic Notation
 - 16. Large vs. Small Diagrams
 - 18. Content First, Appearance Second



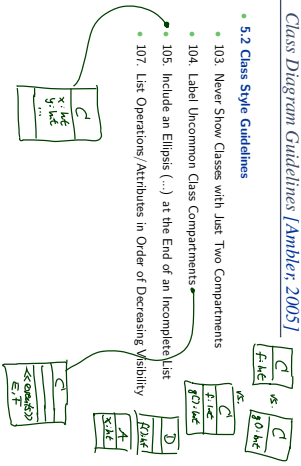
- **2.2 Simplicity**
 - 14. Show Only What You Have to Show
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- **2.3 Naming**
 - 20. Set and (23. Consistently) Follow Effective Naming Conventions

- **2.4 General**
 - 24. Indicate Unknowns with Question-Marks
 - 25. Consider Applying Color to Your Diagram
 - 26. Apply Color Sparingly

- **5.1 General Guidelines**
 - 88. Indicate Visibility Only on Design Models (in contrast to analysis models)
- **5.2 Class Style Guidelines**
 - 96. Prefer Complete Singular Nouns for Class Names
 - 97. Name Operations with Strong Verbs
 - 99. Do Not Model Scaffolding Code [Except for Exceptions]
 - e.g. *getfield methods*

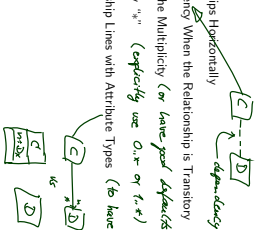
Class Diagram Guidelines [Ambler, 2005]

- 5.2 Class Style Guidelines
- 103. Never Show Classes with Just Two Compartments
- 104. Label Uncommon Class Compartments
- 105. Include an Ellipsis (...) at the End of an Incomplete List
- 107. List Operations/Attributes in Order of Decreasing Visibility



Class Diagram Guidelines [Ambler, 2005]

- 5.3 Relationships
- 112. Model Relationships Horizontally
- 115. Model a Dependency When the Relationship is Transitory
- 117. Always Indicate the Multiplicity (or have your software)
- 118. Avoid Multiplicity "*" (specifying use 0..* or 1..*)
- 119. Replace Relationship Lines with Attribute Types (to have fewer lines)



Class Diagram Guidelines [Ambler, 2005]

- 5.4 Associations
 - 127. Indicate Role Names When Multiple Associations Between Two Classes Exist
 - 129. Make Associations Bidirectional Only When Collaboration Occurs in Both Directions
 - 131. Avoid Indicating Non-Navigability (it is assumed to be OK -> D)
 - 133. Question Multiplicities Involving Minimums (and Maximums)
- 3:16 \xrightarrow{g} \xrightarrow{g}

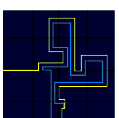
Example: Modeling Games

[...] *But first we on the screen.*
Beit Ludwigsmüller/Schmidt

Task: Game Development

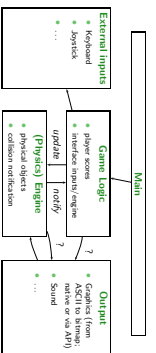
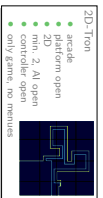
Task: develop a video game. **Genre:** Racing. **Rest:** open, i.e.

Degrees of freedom:	Exemplary choice: 2D-Ton
<ul style="list-style-type: none"> • simulation vs. arcade • platform (SDK or not, open or proprietary, hardware capabilities...) • graphics (3D, 2D, ...) • number of players, AI • controller • game experience 	<ul style="list-style-type: none"> • arcade • open • 2D • min. 2, AI open • open (later determined by platform) • minimal: main menu and game



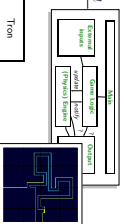
Modelling Structure: 2D-Tron

- In many domains, there are canonical architectures – and adept readers try to see/find/match this!
- For games:



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Modelling Structure: 2D-Tron



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Stocktaking...

- Have:** Means to model the **structure** of the system.
 - Class diagrams graphically, concisely describe sets of system states.
 - OCL expressions logically state constraints/invariants on system states.

- Want:** Means to model **behaviour** of the system.
 - Means to describe how system states **evolve over time**, that is, to describe sets of **sequences**

$$s_0, s_1, \dots \in \Sigma^*$$

not not-time, just counting steps here

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What Can Be Purposes of Behavioural Models?

(We will discuss this in more detail in Lecture 22)

- Example: Pre-Image** (the UML model is supposed to be the blue-print for a software system).

Image

- A description of behaviour could serve the following purposes:
 - Require Behaviour:** "This sequence of inserting money and requesting and getting water must be possible." (Otherwise the software for the vending machine is completely broken.)
 - Allow Behaviour:** "System does subset of this" (After inserting money and choosing a drink, the drink is dispensed (if in stock).) (If the implementation insists on taking the money first, that's a fair choice.)
 - Forbid Behaviour:** "This sequence of getting both, a water and all money back, must not be possible." (Otherwise the software is broken.)

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Modelling Behaviour

Constructive vs. Reflective Descriptions

- [Harel, 1997] proposes to distinguish constructive and reflective descriptions:
 - "A language is **constructive** if it contributes to the dynamic semantics of the model. That is, its constructs contain information needed in executing the model or in translating it into executable code."
 - A constructive description tells **how** things are computed (which can then be desired or undesired).
 - "Other languages are **reflective** or **assertive**, and can be used by the system modeller to capture parts of the thinking that go into building the model – behavior included –, to derive and present views of the model, statically or during execution, or to set constraints on behavior in preparation for verification."

Note: No sharp boundaries!

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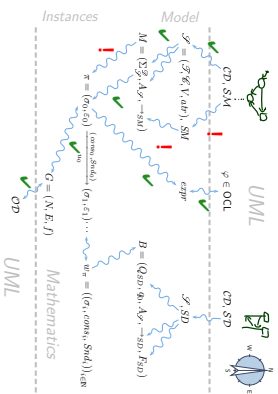
UML provides two visual formalisms for constructive description of behaviours:

- Activity Diagrams
- State-Machine Diagrams

We (exemplary) focus on State-Machines because

- somehow "practice proven" (in different flavours),
- prevalent in embedded systems community,
- indicated useful by [Dobing and Parsons, 2006] survey, and
- Activity Diagram's intuition changed (between UML 1.x and 2.x) from Transition-system-like to petri-net-like...

Example state machine:



References

References

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