

Contents & Goals

Last Lecture:

- Missing transformers: create and destroy
- Step and run-to-completion (RTC) step, divergence

This Lecture:

Educational Objectives: Capabilities for following tasks/questions.

- What does this State Machine mean? What happens if I inject this event?
- Can you please model the following behaviour?
- What does this hierarchical State Machine mean? What may happen if I inject this event?
- What is: AND-State, OR-State, pseudo-state, entry/exit, do, final state, ...

Content:

- Putting it all together: UML model semantics (so far)
- State Machines and OCL
- Hierarchical State Machines Syntax
- Initial and Final State

Putting It All Together

The Missing Piece: Initial States

Recall: a labelled transition system is  $(S \rightarrow S_0)$ . We have

- $S$ : system configurations  $(\alpha, \varepsilon)$
- $\rightarrow$ : labelled transition relation  $(\alpha, \varepsilon) \xrightarrow[\alpha]{(\text{form}, \text{Signal})} (\alpha', \varepsilon')$

Wanted: initial states  $S_0$

Proposal:

Require a (finite) set of object diagrams  $OD$  as part of a UML model

$(\mathcal{C}\mathcal{G}, \mathcal{S}\mathcal{M}, \mathcal{O}\mathcal{D})$ .

And set

$S_0 = \{(\alpha, \varepsilon) \mid \sigma \in \mathcal{C}^{-1}(OD), OD \in \mathcal{O}\mathcal{D}, \varepsilon \text{ empty}\}$ .

Other Approach: (used by Rhapsody tool) multiplicity of classes. We can read that as an abbreviation for an object diagram.

Semantics of UML Model — So Far

The semantics of the UML model

$\mathcal{M} = (\mathcal{C}\mathcal{G}, \mathcal{S}\mathcal{M}, \mathcal{O}\mathcal{D})$

where

- some classes in  $\mathcal{C}\mathcal{G}$  are stereotyped as 'signal' (standard) some signals and attributes are stereotyped as 'external' (non-standard)
- there is a 1-to-1 relation between classes and state machines.
- $\mathcal{O}\mathcal{D}$  is a set of object diagrams over  $\mathcal{C}\mathcal{G}$ .

is the transition system  $(S \rightarrow S_0)$  constructed on the previous slide.

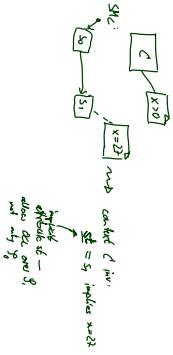
The computations of  $\mathcal{M}$  are the computations of  $(S \rightarrow S_0)$ .

State Machines and OCL

## OCL Constraints and Behaviour

- Let  $M = (\mathcal{B}, \mathcal{S}, \mathcal{M}, \theta, \mathcal{D})$  be a UML model.
  - We call  $M$  consistent iff, for each OCL constraint  $expr \in Inv(\mathcal{B}, \mathcal{D}) \vee Inv(\mathcal{S}, \mathcal{D})$ 
    - $\sigma \models expr$  for each "reasonable point"  $(\sigma, \varepsilon)$  of computations of  $M$ .
- (Cf. exercises and tutorial for discussion of "reasonable point".)

Note: we could define  $Inv(\mathcal{S}, \mathcal{M})$  similar to  $Inv(\mathcal{B}, \mathcal{D})$ .



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Note: we could define  $Inv(\mathcal{S}, \mathcal{M})$  similar to  $Inv(\mathcal{B}, \mathcal{D})$ .

→ OUR CHOICE: check for each  $(\sigma, \varepsilon)$  in a computation (step-by-step)

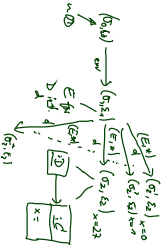
### Pragmatics:

- In UML-as-blueprint mode, if  $\mathcal{S}, \mathcal{M}$  doesn't exist yet, then  $M = (\mathcal{B}, \mathcal{D}, \mathcal{M}, \theta, \mathcal{D})$  is typically asking the developer to provide  $\mathcal{S}, \mathcal{M}$  such that  $M = (\mathcal{B}, \mathcal{S}, \mathcal{M}, \theta, \mathcal{D})$  is consistent.
- If the developer makes a mistake, then  $M'$  is inconsistent.
- Not common:** if  $\mathcal{S}, \mathcal{M}$  is given, then constraints are also considered when choosing transitions in the RT-Algorithm. In other words, even in presence of mistakes, the  $\mathcal{S}, \mathcal{M}$  never move to inconsistent configurations.

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IN EACH SYSTEM STATE  $\sigma$ ,  
FOR EACH ALIVE OBJECT  $v \in \text{obj}(\sigma)$ ,  $v \in \text{obj}(c)$   
EACH OF ITS ATTRIBUTES HAS  
A DEFINITE VALUE!

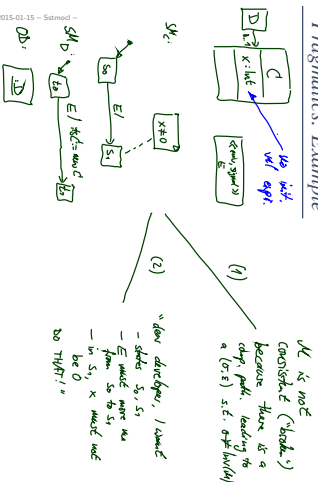
$$\forall v \in \text{obj}(c) \bullet \sigma(c).v \in \mathcal{D}(type(v))$$



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## Rhapsody Demo II

## Pragmatics: Example



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