

# *Software Design, Modelling and Analysis in UML*

## *Lecture 17: Hierarchical State Machines Ib*

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# Contents & Goals

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## Last Lecture:

- State Machines and OCL
- Rhapsody Demo II

## This Lecture:

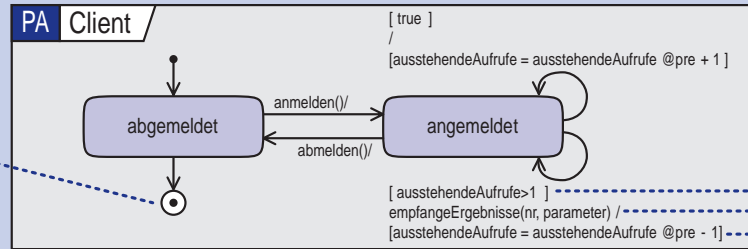
- **Educational Objectives:** Capabilities for following tasks/questions.
  - What does this State Machine mean? What happens if I inject this event?
  - Can you please model the following behaviour.
  - What does this **hierarchical** State Machine mean? What **may happen** if I inject this event?
  - What is: AND-State, OR-State, pseudo-state, entry/exit/do, final state, ...
- **Content:**
  - Hierarchical State Machines Syntax
  - Initial and Final State
  - Composite State Semantics
  - The Rest

# *Hierarchical State Machines*

# UML State-Machines: What do we have to cover?

[Störrle, 2005]

Wenn der **Endzustand** eines Zustandsautomaten erreicht wird, wird die Region beendet, in der der Endzustand liegt.



Die Zustandsübergänge von Protokoll-Zustandsautomaten verfügen über eine **Vorbedingung**, einen **Auslöser** und eine **Nachbedingung** (alle optional) – jedoch nicht über einen Effekt.

**Protokollzustandsautomaten** beschreiben das Verhalten von Softwaresystemen, Nutzfällen oder technischen Geräten.

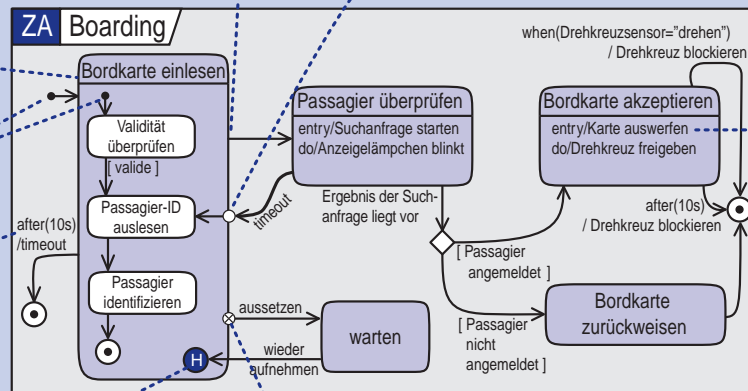
Reguläre Beendigung löst ein **completion**-Ereignis aus.

Ein **Eintrittspunkt** definiert, dass ein komplexer Zustand an einer anderen Stelle betreten wird, als durch den Anfangszustand definiert ist.

Ein **komplexer Zustand** mit einer Region.

Der **Anfangszustand** markiert den voreingestellten Startpunkt von „Boarding“ bzw. „Bordkarte einlesen“.

Das **Zeitereignis** after(10s) löst einen Abbruch von „Bordkarte einlesen“ aus.



Ein Zustand löst von sich aus bestimmte Ereignisse aus:

- **entry** beim Betreten;
- **do** während des Aufenthaltes;
- **completion** beim Erreichen des Endzustandes einer Unter-Zustandsmaschine
- **exit** beim Verlassen.

Diese und andere Ereignisse können als Auslöser für Aktivitäten herangezogen werden.

Der **Gedächtniszustand** sorgt dafür, dass nach dem Wieder-aufnehmen der gleiche Zustand wie vor dem Aussetzen eingenommen wird.

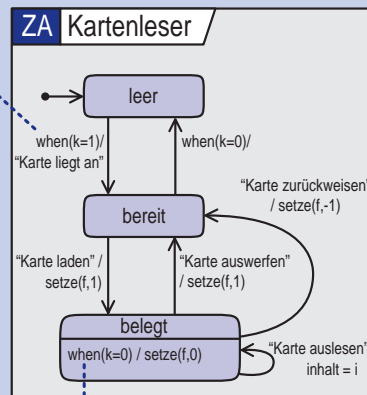
Der **Austrittspunkt** erlaubt es, von einem definierten inneren Zustand aus den Oberzustand zu verlassen.

Ein Zustand kann eine oder mehrere **Regionen** enthalten, die wiederum Zustandsautomaten enthalten können. Wenn ein Zustand mehrere Regionen enthält, werden diese in verschiedenen Abteilen angezeigt, die durch gestrichelte Linien voneinander getrennt sind. Regionen können benannt werden. Alle Regionen werden parallel zueinander abgearbeitet.

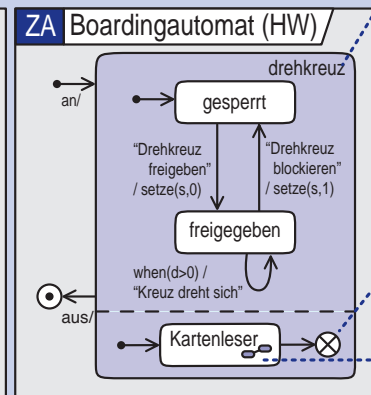
Auch Zeit- und Änderungsereignisse können Zustandsübergänge auslösen:

- **after** definiert das Verstreichen eines Intervalls;
- **when** definiert einen Zustandswechsel.

Zustände und zeitlicher Bezugsrahmen werden über den umgebenden Classifier definiert, hier die Werte der Ports, siehe das Montage-diagramm „Abfertigung“ links oben.



Ereignisse können innerhalb eines Zustands Aktionen auslösen.



Wenn ein **Regionsendzustand** erreicht wird, wird der gesamte **komplexe** Zustand beendet, also auch alle parallelen Regionen.

Ein **verfeinerter Zustand** verweist auf einen Zustandsautomaten (angedeutet von dem Symbol unten links), der das Verhalten des Zustandes definiert.

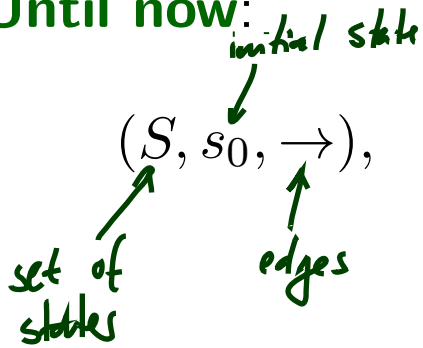
# The Full Story

UML distinguishes the following **kinds of states**:

|  | example |                         | example |
|--|---------|-------------------------|---------|
| <p><i>reserved keywords</i></p> <p><b>simple state</b></p> <p><i>E</i> →</p> |         | <b>pseudo-state</b>     |         |
| <b>final state</b>   |         | fork/join               |         |
| <b>composite state</b>   |         | junction, choice        |         |
| OR   |         | entry point             |         |
| AND  |         | exit point              |         |
|  |         | terminate               |         |
|  |         | <b>submachine state</b> |         |

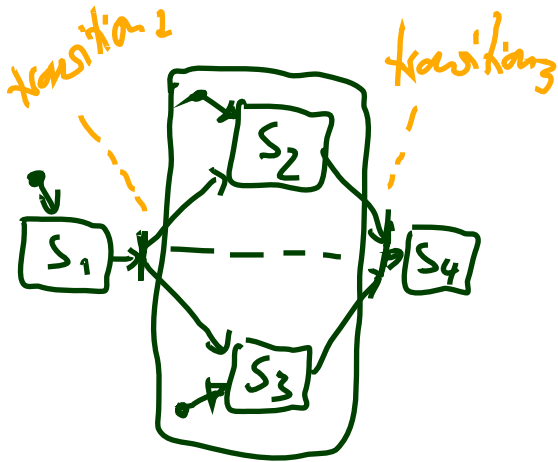
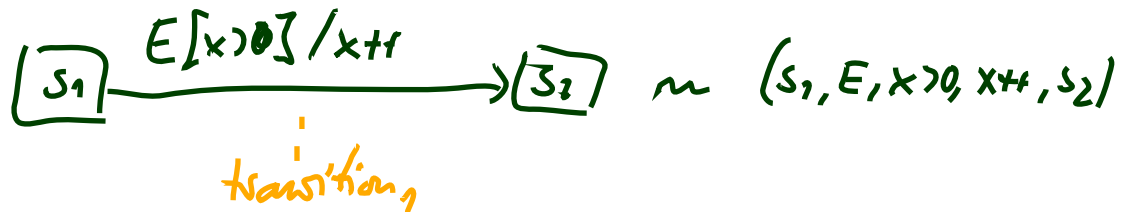
# Representing All Kinds of States

- Until now:



$$s_0 \in S, \rightarrow \subseteq S \times (\mathcal{E} \cup \{-\}) \times Expr_{\mathcal{G}} \times Act_{\mathcal{G}} \times S$$

source state  $\downarrow$   
 $\uparrow$  trigger       $\uparrow$  guard       $\uparrow$  action  
 destination state  $\downarrow$



NEW:

states
transitions

$$(\{s_1, s_2, s_3, s_4\}, \{\text{transition}_2, \text{transition}_3\}, \{\text{transition}_2 \mapsto (\{s_1\}, \{s_2, s_3\}), \dots\})$$

incidence function

# Representing All Kinds of States

- **Until now:**

$$(S, s_0, \rightarrow), \quad s_0 \in S, \rightarrow \subseteq S \times (\mathcal{E} \cup \{-\}) \times \text{Expr}_{\mathcal{F}} \times \text{Act}_{\mathcal{F}} \times S$$

- **From now on: (hierarchical) state machines**

$$(S, \text{kind}, \text{region}, \rightarrow, \psi, \text{annot})$$



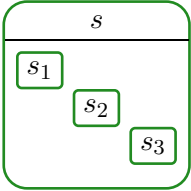
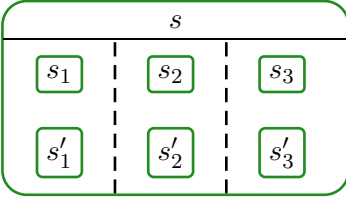

where

*region name*  
↓

- $S \supseteq \{top\}$  is a finite set of states (as before),
- $\text{kind} : S \rightarrow \{st, init, fin, shist, dhist, fork, join, junc, choi, ent, exi, term\}$  is a function which labels states with their **kind**, (new)
- $\text{region} : S \rightarrow 2^{2^S}$  is a function which characterises the **regions** of a state, (new)  
*sets of sets of states*
- $\rightarrow$  is a set of transitions (*or: edges*) – *just names* (changed)
- $\psi : (\rightarrow) \mapsto 2^S \times 2^S$  is an **incidence function**, and (new)
- $\text{annot} : (\rightarrow) \rightarrow (\mathcal{E} \cup \{-\}) \times \text{Expr}_{\mathcal{F}} \times \text{Act}_{\mathcal{F}}$  provides an annotation for each transition. (new)

# From UML to Hierarchical StM: By Example

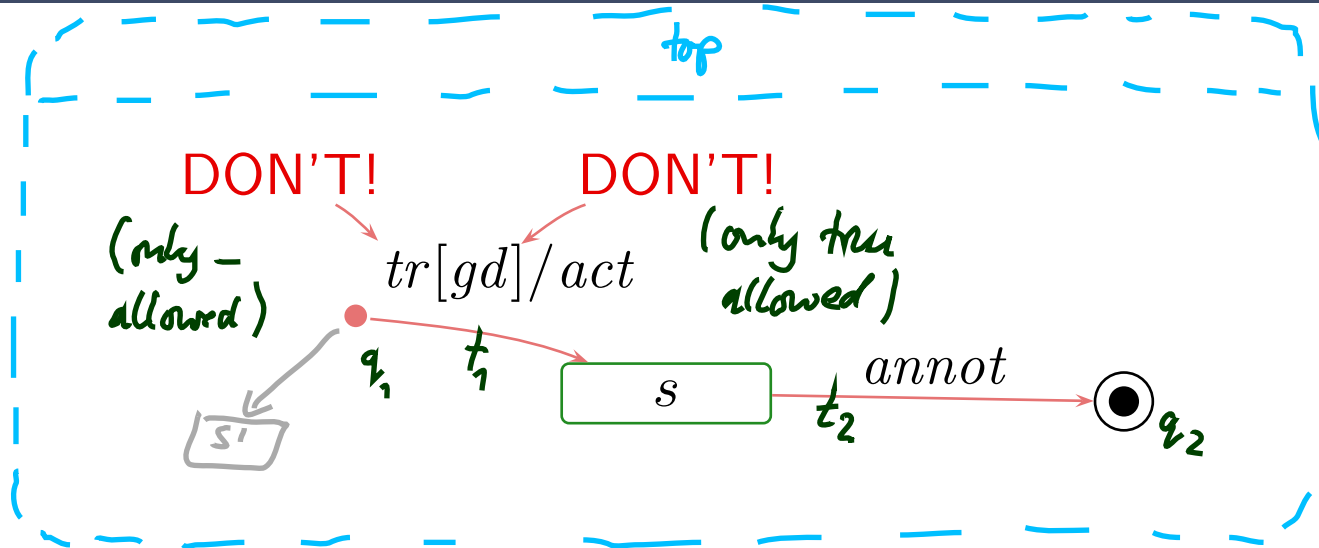
$(S, kind, region, \rightarrow, \psi, annot)$

|  | example   | $\in S$ | kind                 | region  |
|--|---|---------|----------------------|---|
| <b>simple state</b><br>(nothing nested within) |                                    | $s$     | $st$                 | $\emptyset$                                       |
| <b>final state</b>                             |  <i>fresh name</i> $\rightarrow q$ | $q$     | $fin$                | $\emptyset$                                       |
| <b>composite state</b>                         |                                    | $s$     | $st$                 | $\{\{s_1, s_2, s_3\}\}$                           |
| OR   |   |         |                      | $\uparrow$<br>region                              |
| <b>AND</b>                                     |                                  | $s$     | $st$                 | $\{\{s_1, s_1'\}, \{s_3, s_3'\}, \{s_2, s_2'\}\}$ |
| <b>submachine state</b>                        | (later)   | -       | -                    |   |
| <b>pseudo-state</b>                            |                                  | $q$     | $init, start, \dots$ | $\emptyset$                                       |

$(s, kind(s))$  for short



# From UML to Hierarchical StM: By Example



... translates to  $(S, kind, region, \rightarrow, \psi, annot) =$

$$\begin{aligned}
 & \underbrace{(\{ (s, st), (q_1, init), (q_2, fin), (top, st) \})}_{S, kind}, \\
 & \underbrace{\{ q_2 \mapsto \emptyset, q_1 \mapsto \emptyset, s \mapsto \emptyset, top \mapsto \{ \{ q_1, s, q_2 \} \} \}}_{region}, \\
 & \underbrace{\{ t_1, t_2 \}}_{\rightarrow}, \quad \underbrace{\{ t_1 \mapsto (\{ q_1 \}, \{ s \}), t_2 \mapsto (\{ s \}, \{ q_2 \}) \}}_{\psi}, \\
 & \underbrace{\{ t_1 \mapsto (tr, gd, act), t_2 \mapsto annot \}}_{annot}
 \end{aligned}$$

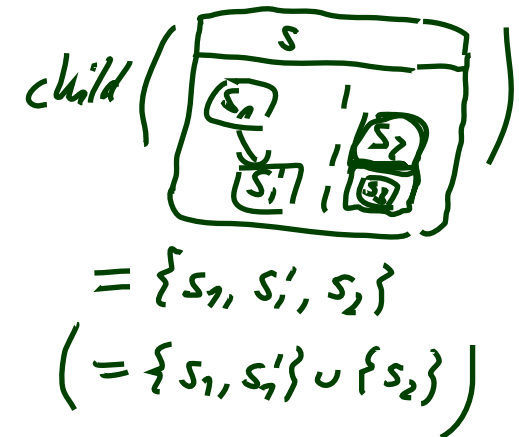
# Well-Formedness: Regions (follows from diagram)

|                           | $\in S$ | $kind$        | $region \subseteq 2^S, S_i \subseteq S$ | $child \subseteq S$       |
|---------------------------|---------|---------------|---|---------------------------|
| <b>simple state</b>       | $s$     | $st$          | $\emptyset$                             | $\emptyset$               |
| <b>final state</b>        | $s$     | $fin$         | $\emptyset$                             | $\emptyset$               |
| <b>composite state</b>    | $s$     | $st$          | $\{S_1, \dots, S_n\}, n \geq 1$         | $S_1 \cup \dots \cup S_n$ |
| <b>pseudo-state</b>       | $s$     | $init, \dots$ | $\emptyset$                             | $\emptyset$               |
| <b>implicit top state</b> | $top$   | $st$          | $\{S_1\}$                               | $S_1$                     |

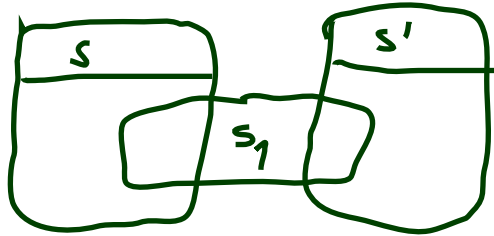
Def.

- Each state (except for  $top$ ) lies in exactly one region,
- States  $s \in S$  with  $kind(s) = st$  **may comprise** regions.
  - No region: simple state.
  - One region: OR-state.
  - Two or more regions: AND-state.
- Final and pseudo states **don't comprise** regions.
- The region function induces a **child** function.

} composite states



- each state lies in exactly one region



$$\text{region}(s) = \{s_1\}$$

$$\text{region}(s') = \{s_1\}$$

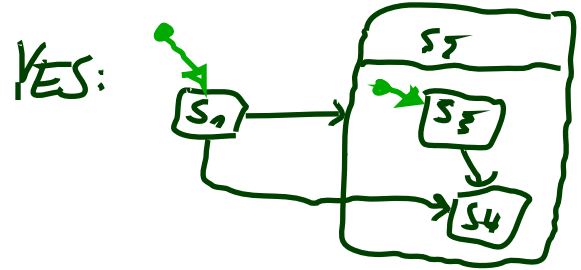
}

- typing ok

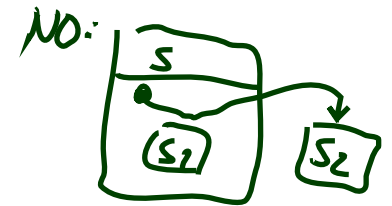
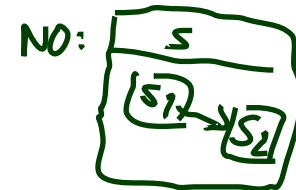
- not well-formed

# Well-Formedness: Initial State (requir. on diagram)

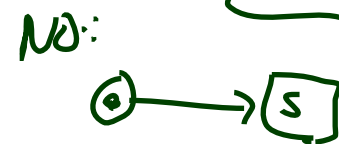
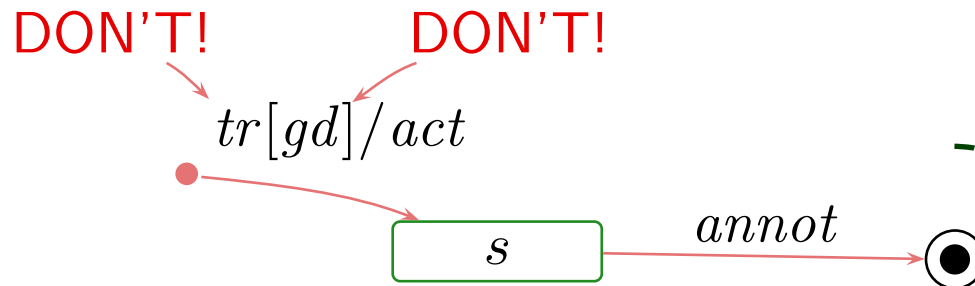
- Each non-empty region has exactly one initial pseudo-state and at least one transition from there, i.e.
  - for each  $s \in S$  with  $region(s) = \{S_1, \dots, S_n\}$ ,  $n \geq 1$ , for each  $1 \leq i \leq n$ ,
  - there exists exactly one initial pseudo-state  $(s_1^i, init) \in S_i$  and at least one transition  $t \in \rightarrow$  with  $s_1^i$  as source,
  - and such transition's target  $s_2^i$  is in  $S_i$ , and **(for simplicity!)**  $kind(s_2^i) = st$ , and  $annot(t) = (-, true, act)$ .



- No ingoing transitions to initial states.
- No outgoing transitions from final states **(for simplicity!)**.



- Recall:



# Plan

|                        | example |                         | example |
|------------------------|---------|-------------------------|---------|
| <b>simple state</b>    |         | <b>pseudo-state</b>     |         |
| <b>final state</b>     |         | fork/join               |         |
| <b>composite state</b> |         | junction, choice        |         |
| OR                     |         | entry point             |         |
| AND                    |         | exit point              |         |
|                        |         | terminate               |         |
|                        |         | <b>submachine state</b> |         |

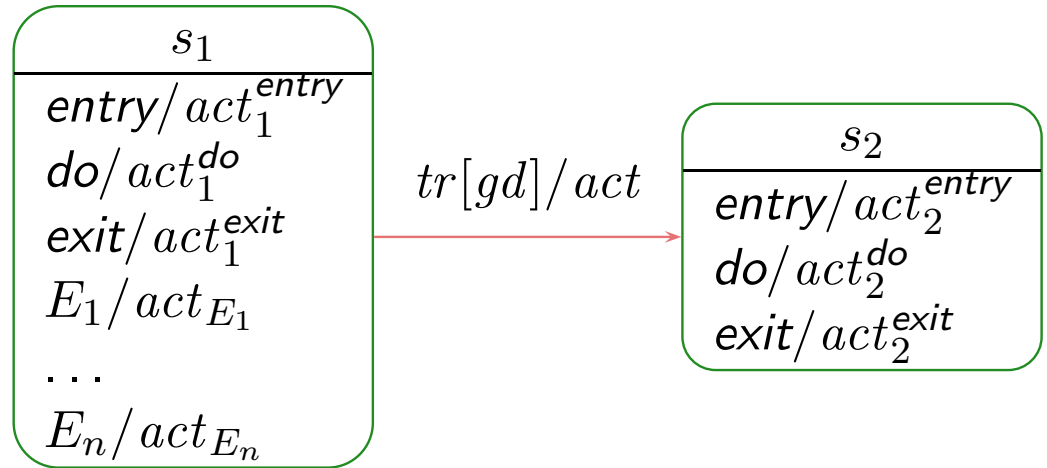
- Entry/do/exit actions, internal transitions.
- Initial pseudostate, final state.
- Composite states.
- History and other pseudostates, the rest.

## *Entry/Do/Exit Actions, Internal Transitions*

# Entry/Do/Exit Actions

- In general, with each state  $s \in S$  there is associated
  - an **entry**, a **do**, and an **exit** action (default: **skip**)
  - a possibly empty set of trigger/action pairs called **internal transitions**, (default: empty).

**Note:**  $E_1, \dots, E_n \in \mathcal{E}$ , 'entry', 'do', 'exit' are reserved names!



- Recall: each action's supposed to have a transformer. Here:  $t_{act_1^{entry}}$ ,  $t_{act_1^{exit}}$ ,  $\dots$
- Taking the transition above then amounts to applying

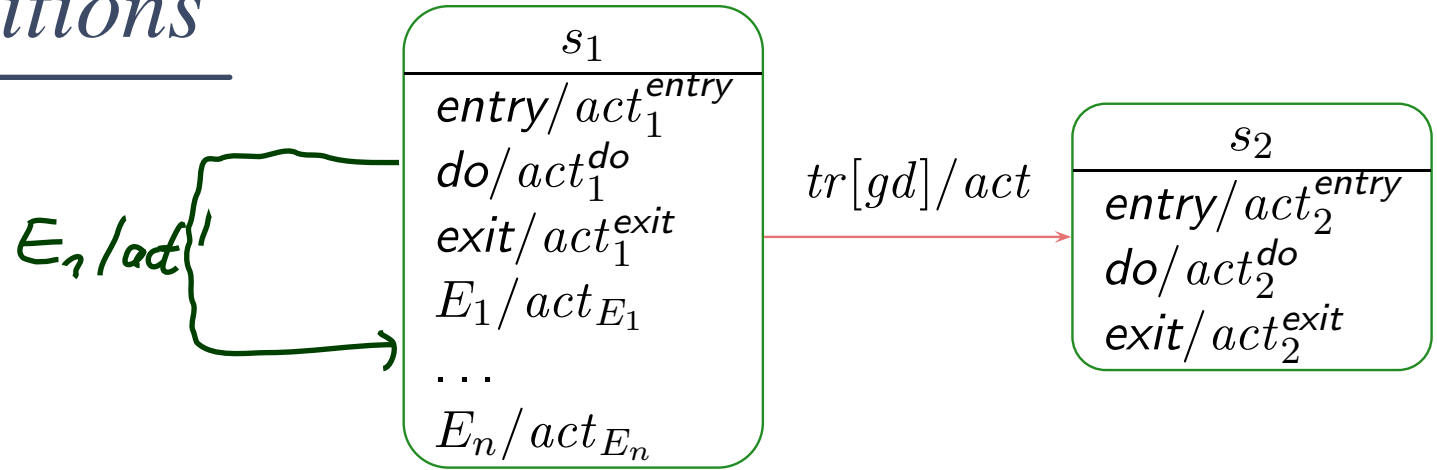
$$t_{act_{s_2}^{entry}} \circ t_{act} \circ t_{act_{s_1}^{exit}}$$

instead of only

$$t_{act}$$

$\rightsquigarrow$  adjust (2.), (3.) accordingly.

# Internal Transitions

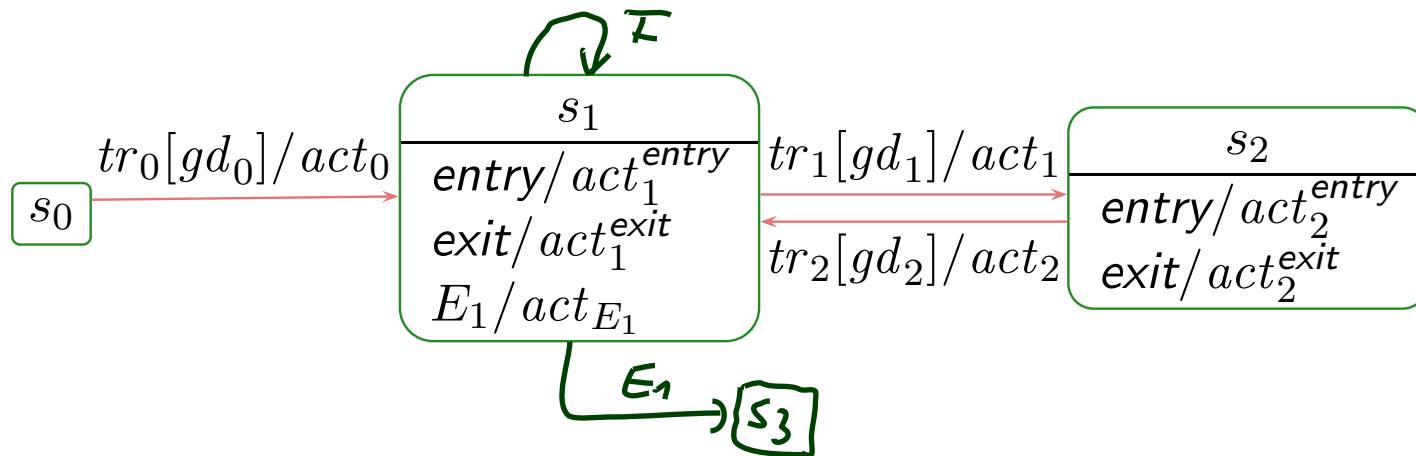


- For **internal transitions**, taking the one for  $E_1$ , for instance, **still** amounts to taking **only**  $t_{act_{E_1}}$ .
- Intuition: The state is neither left nor entered, so: no exit, no entry.  
 $\rightsquigarrow$  adjust (2.) accordingly.
- **Note:** internal transitions also start a run-to-completion step.
- **Note:** the standard seems not to clarify whether internal transitions have **priority** over regular transitions with the same trigger at the same state.

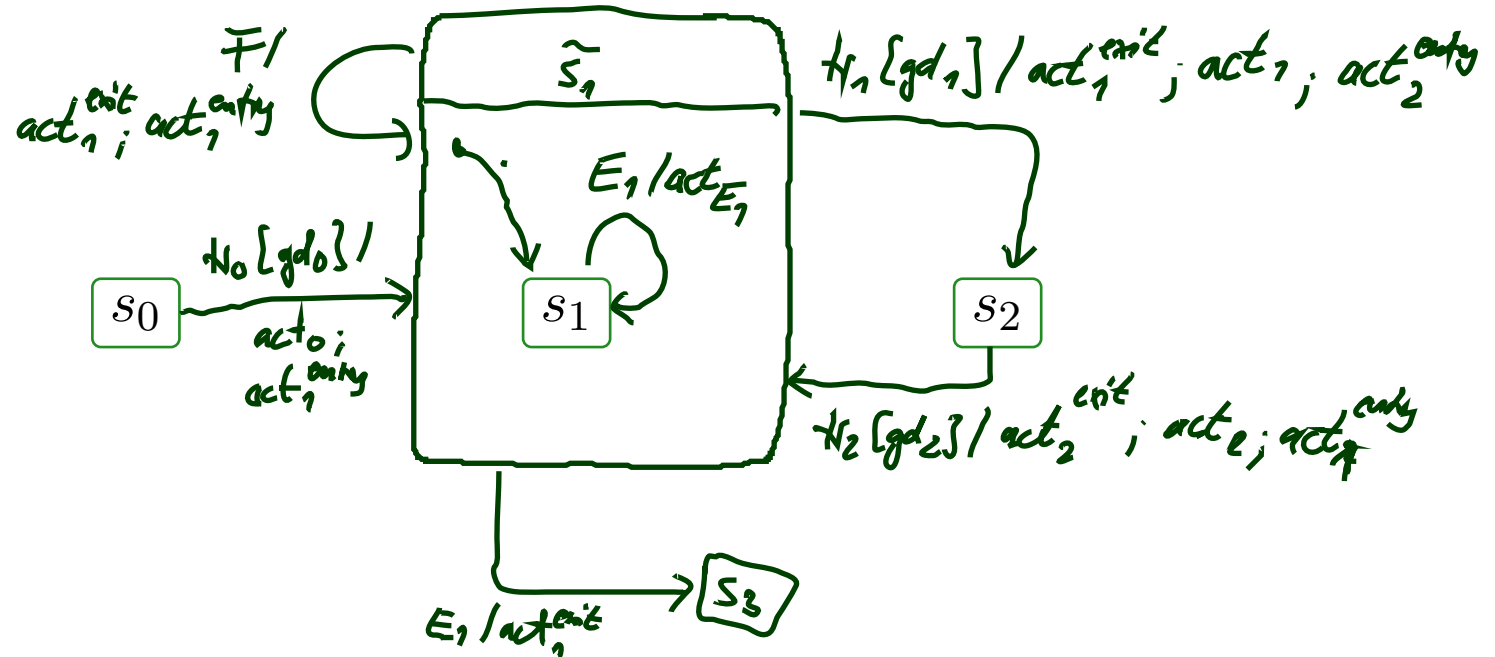
Some code generators assume that internal transitions have priority!



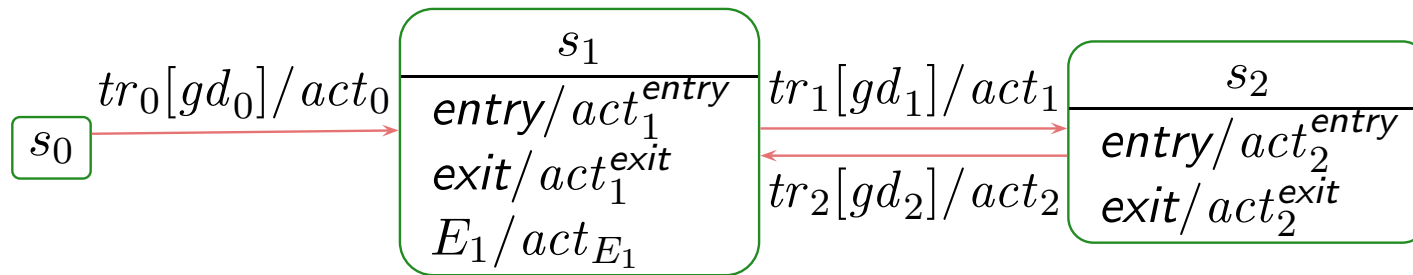
# Alternative View: ... as Abbreviations



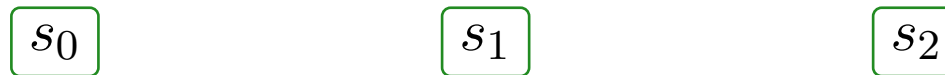
- ... as abbreviation for ...



# Alternative View: ... as Abbreviations

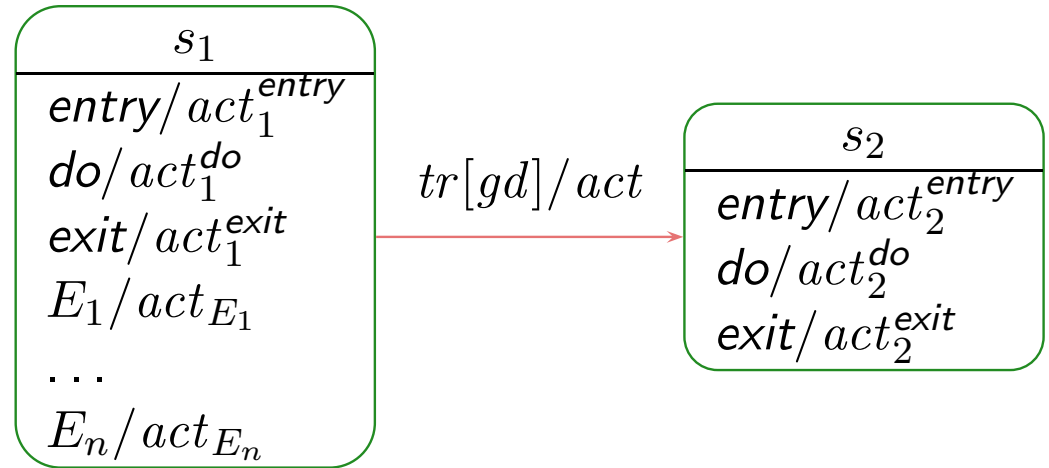


- ... as abbreviation for ...



- That is: Entry/Internal/Exit don't add expressive power to Core State Machines. If internal actions should have priority,  $s_1$  can be embedded into an OR-state (later).
- Abbreviation view may avoid confusion in context of hierarchical states (later).

# Do Actions



- **Intuition:** after entering a state, start its do-action.
- If the do-action terminates,
  - then the state is considered **completed** ( $\rightarrow$  later),
- otherwise,
  - if the state is left before termination, the do-action is stopped.
- Recall the overall UML State Machine philosophy:
  - **“An object is either idle or doing a run-to-completion step.”**
- Now, what is it exactly while the do action is executing...?

# *References*

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