

Software Design, Modelling and Analysis in UML

Lecture 20: Live Sequence Charts

2015-02-03

Prof. Dr. Andreas Podelski, **Dr. Bernd Westphal**

Albert-Ludwigs-Universität Freiburg, Germany

– 20 – 2015-02-03 – main –

Contents & Goals

Last Lecture:

- Hierarchical State Machines completed.
- Behavioural feature (aka. methods).

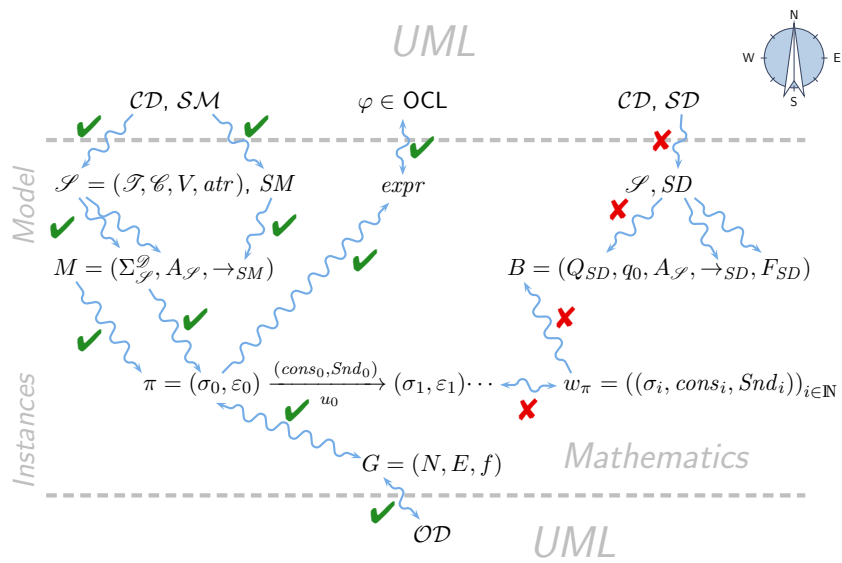
This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What does this LSC mean?
 - Are this UML model's state machines consistent with the interactions?
 - Please provide a UML model which is consistent with this LSC.
 - What is: activation, hot/cold condition, pre-chart, etc.?
- **Content:**
 - Reflective description of behaviour.
 - LSC concrete and abstract syntax.
 - LSC semantics.

– 20 – 2015-02-03 – Prelim –

You are here.

Course Map



Motivation: Reflective, Dynamic Descriptions of Behaviour

Recall: Constructive vs. Reflective Descriptions

[Harel, 1997] proposes to distinguish constructive and reflective descriptions:

- “A language is **constructive** if it contributes to the dynamic semantics of the model. That is, its constructs contain information needed in executing the model or in translating it into executable code.”

A constructive description tells **how** things are computed (which can then be desired or undesired).

- “Other languages are **reflective** or **assertive**, and can be used by the system modeler to capture parts of the thinking that go into building the model – behavior included –, to derive and present views of the model, statically or during execution, or to set constraints on behavior in preparation for verification.”

A reflective description tells **what** shall or shall not be computed.

Note: No sharp boundaries!

Recall: What is a Requirement?

Recall:

- The **semantics** of the **UML model** $\mathcal{M} = (\mathcal{CD}, \mathcal{SM}, \mathcal{OD})$ is the **transition system** (S, \rightarrow, S_0) constructed according to discard/dispatch/commence-rules.
- The **computations of** \mathcal{M} , denoted by $\llbracket \mathcal{M} \rrbracket$, are the computations of (S, \rightarrow, S_0) .

Now:

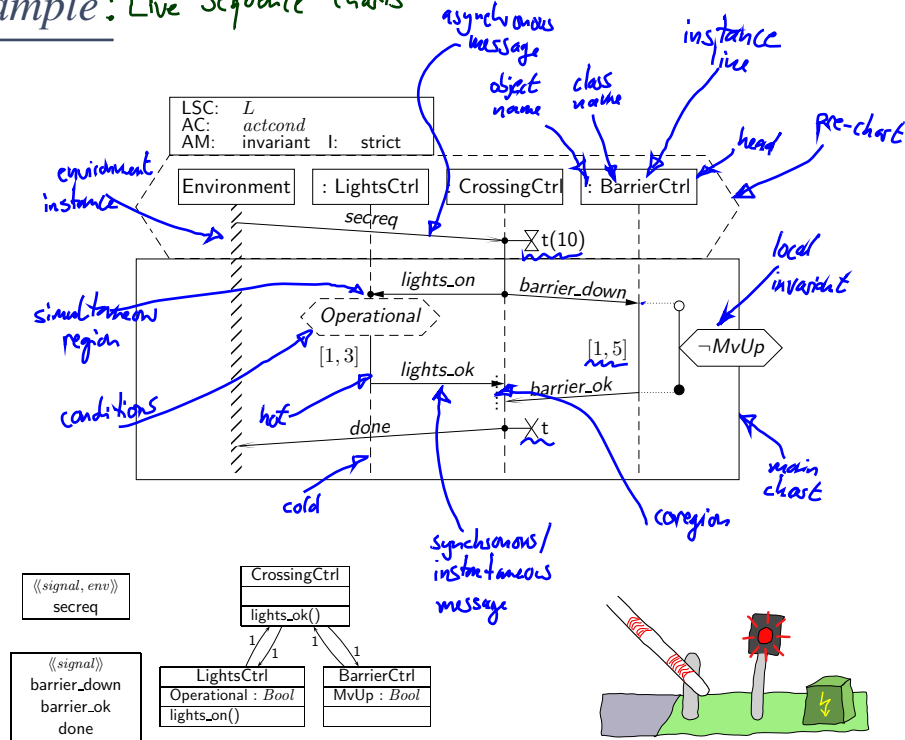
A reflective description tells **what** shall or shall not be computed.

More formally: a requirement ϑ is a property of computations; something which is either satisfied or not satisfied by a computation

$$\pi = (\sigma_0, \varepsilon_0) \xrightarrow{(cons_0, Snd_0)} (\sigma_1, \varepsilon_1) \xrightarrow{(cons_1, Snd_1)} \dots \in \llbracket \mathcal{M} \rrbracket,$$

denoted by $\pi \models \vartheta$ and $\pi \not\models \vartheta$, resp.
Simplest case: OCL constraint.

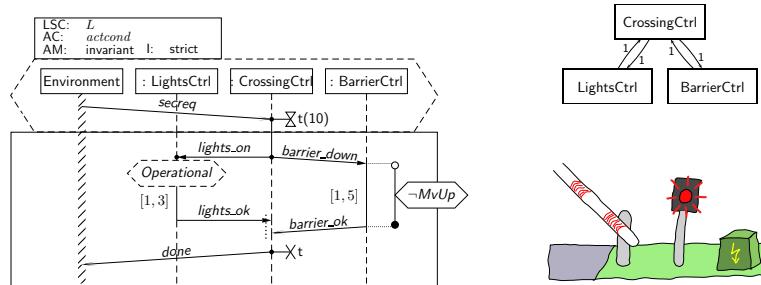
Example: Live Sequence Charts



— 20 — 2015-02-03 — Silesyn —

9/51

Example: What Is Required?

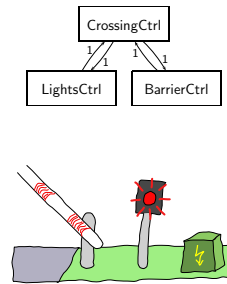
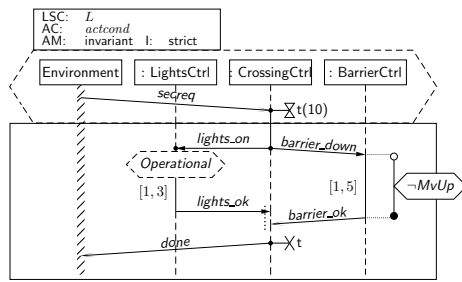


- **Whenever** the CrossingCtrl has consumed a 'secreq' event
- **then** it shall finally send 'lights_on' and 'barrier_down' to LightsCtrl and BarrierCtrl,
- if LightsCtrl **is not** 'operational' when receiving that event, the rest of this scenario doesn't apply; maybe there's another LSC for that case.
- if LightsCtrl **is** 'operational' when receiving that event, it shall reply with 'lights_ok' within 1–3 time units,
- the BarrierCtrl shall reply with 'barrier_ok' within 1–5 time units, during this time (dispatch time not included) it shall not be in state 'MvUp',
- 'lights_ok' and 'barrier_ok' may occur in any order.
- After having consumed both, CrossingCtrl may reply with 'done' to the environment.

— 20 — 2015-02-03 — Silesyn —

10/51

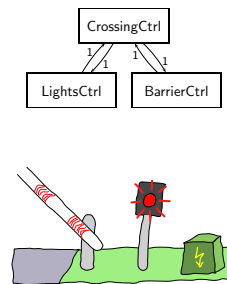
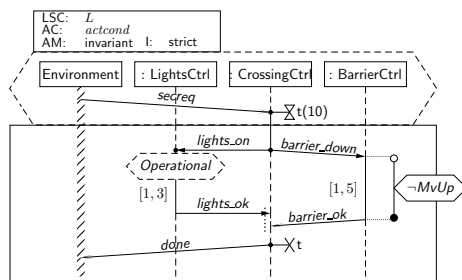
Building Blocks



- Instance Lines:



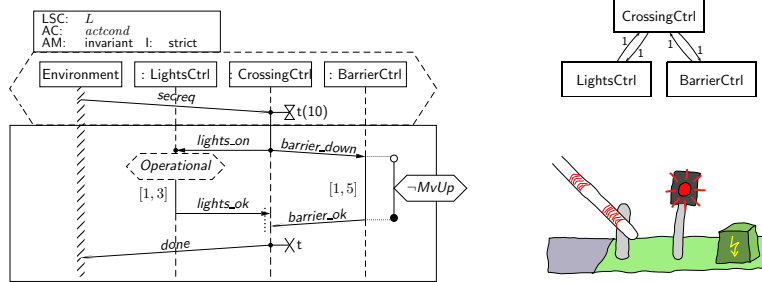
Building Blocks



- Messages: (asynchronous or synchronous/instantaneous)

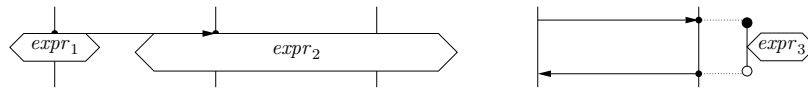


Building Blocks



- **Conditions and Local Invariants:** ($expr_1, expr_2, expr_3 \in Expr_{\mathcal{F}}$)

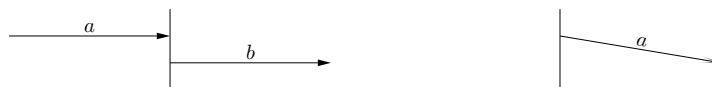
- 20 - 2015-02-03 - Silcsyn -



13/51

Intuitive Semantics: A Partial Order on Simclasses

- (i) **Strictly After:**



- (ii) **Simultaneously:** (simultaneous region)



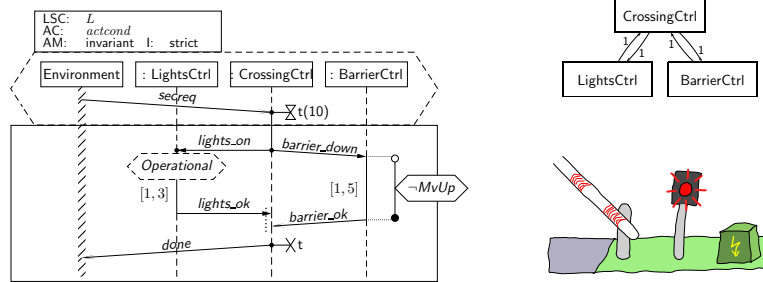
- (iii) **Explicitly Unordered:** (co-region)



- 20 - 2015-02-03 - Silcsyn -

14/51

Partial Order Requirements



- **Whenever** the CrossingCtrl has consumed a 'secreq' event
- **then** it shall finally send 'lights_on' and 'barrier_down' to LightsCtrl and BarrierCtrl,
- if LightsCtrl **is not** 'operational' when receiving that event, the rest of this scenario doesn't apply; maybe there's another LSC for that case.
- if LightsCtrl **is** 'operational' when receiving that event, it shall reply with 'lights_ok' within 1–3 time units,
- the BarrierCtrl shall reply with 'barrier_ok' within 1–5 time units, during this time (dispatch time not included) it shall not be in state 'MvUp',
- 'lights_ok' and 'barrier_ok' may occur in any order.
- After having consumed both, CrossingCtrl may reply with 'done' to the environment.

- 20 - 2015-02-03 - Slidesyn -

15/51

LSC Specialty: Modes

With LSCs,

- whole charts,
- locations, and
- elements

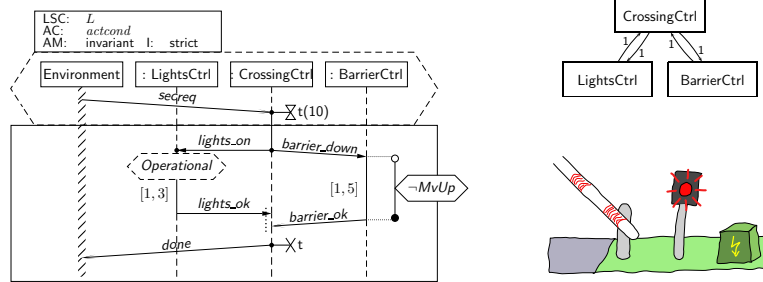
have a **mode** — one of **hot** or **cold** (graphically indicated by outline).

	chart	location	message	condition/ local inv.
hot:				
cold:				
	always vs. at least once	must vs. may progress	mustn't vs. may get lost	necessary vs. legal exit

- 20 - 2015-02-03 - Slidesyn -

16/51

Example: Modes



- **Whenever** the CrossingCtrl has consumed a 'secreq' event
- **then** it shall finally send 'lights_on' and 'barrier_down' to LightsCtrl and BarrierCtrl,
- if LightsCtrl is **not** 'operational' when receiving that event, the rest of this scenario doesn't apply; maybe there's another LSC for that case.
- if LightsCtrl is 'operational' when receiving that event, it shall reply with 'lights_ok' within 1–3 time units,
- the BarrierCtrl shall reply with 'barrier_ok' within 1–5 time units, during this time (dispatch time not included) it shall not be in state 'MvUp',
- 'lights_ok' and 'barrier_ok' may occur in any order.
- After having consumed both, CrossingCtrl **may** reply with 'done' to the environment.

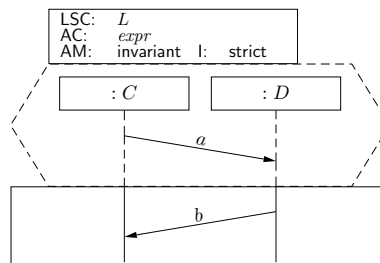
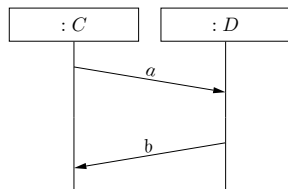
- 20 - 2015-02-03 - Slsesyn -

17/51

LSC Specialty: Activation

One **major defect** of **MSCs and SDs**: they don't say **when** the scenario has to/may be observed.

LSCs: Activation condition ($AC \in Expr_{\neq}$), activation mode ($AM \in \{init, inv\}$), and pre-chart.



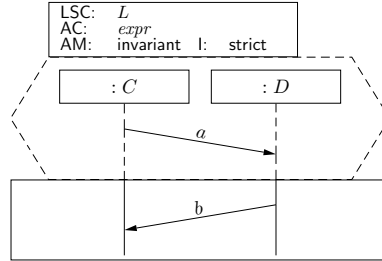
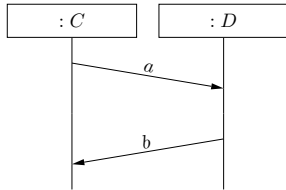
- 20 - 2015-02-03 - Slsesyn -

18/51

LSC Specialty: Activation

One **major defect** of **MSCs and SDs**: they don't say **when** the scenario has to/may be observed.

LSCs: Activation condition ($AC \in Expr_{\mathcal{F}}$), activation mode ($AM \in \{init, inv\}$), and pre-chart.

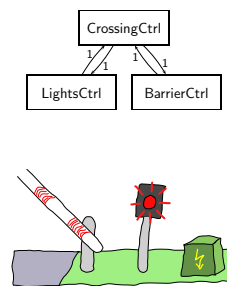
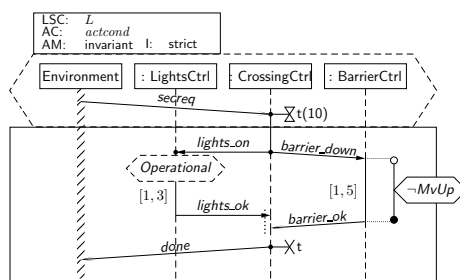


Intuition: (universal case)

- given a computation π , **whenever** $expr$ holds in a configuration $(\sigma_i, \varepsilon_i)$ of ξ
 - which is initial, i.e. $k = 0$, or $(AM = initial)$
 - whose k is not further restricted, $(AM = invariant)$
- and if** the pre-chart is observed from k to $k + n$,
- then** the main-chart has to follow from $k + n + 1$.

18/51

Example: What Is Required?



- Whenever** the CrossingCtrl has consumed a 'secreq' event
- then** it shall finally send 'lights_on' and 'barrier_down' to LightsCtrl and BarrierCtrl,
- if LightsCtrl **is not** 'operational' when receiving that event, the rest of this scenario doesn't apply; maybe there's another LSC for that case.
- if LightsCtrl **is** 'operational' when receiving that event, it shall reply with 'lights_ok' within 1–3 time units,
- the BarrierCtrl shall reply with 'barrier_ok' within 1–5 time units, during this time (dispatch time not included) it shall not be in state 'MvUp',
- 'lights_ok' and 'barrier_ok' may occur in any order.
- After having consumed both, CrossingCtrl may reply with 'done' to the environment.

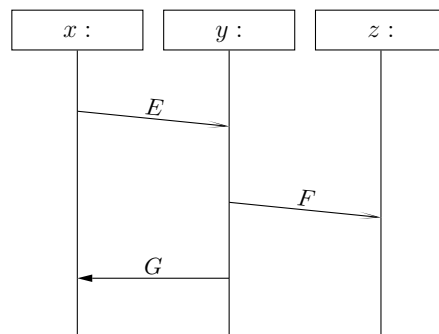
19/51

Live Sequence Charts — Semantics in a Nutshell

– 20 – 2015-02-03 – main –

20/51

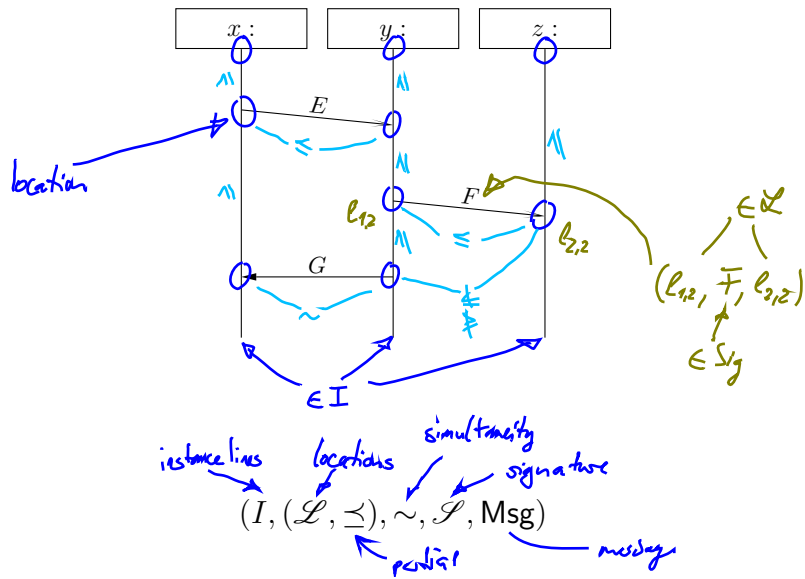
Restricted Syntax



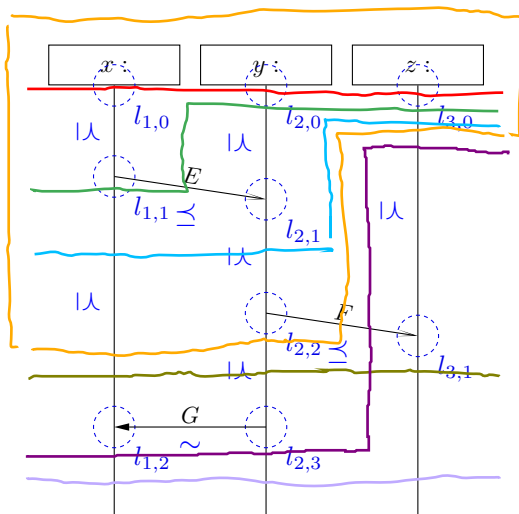
– 20 – 2015-02-03 – main –

21/51

Restricted Abstract Syntax



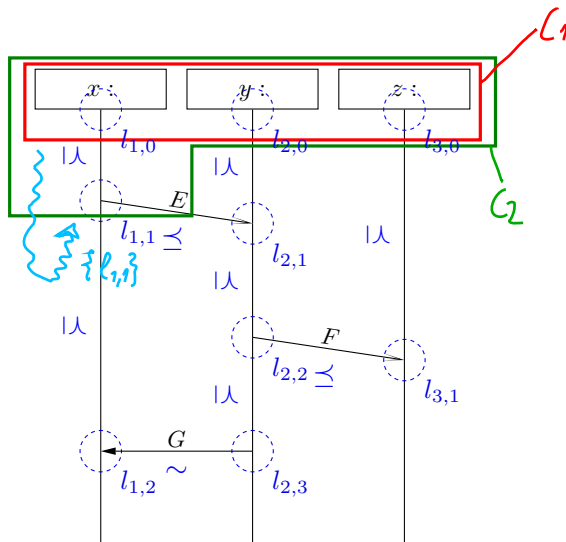
Cuts



A set $C \subseteq \mathcal{L}$ is called cut iff

- downward closed wrt. \preceq
- closed wrt. \sim
- at least one loc. per instance line (if more than one, then unordered)

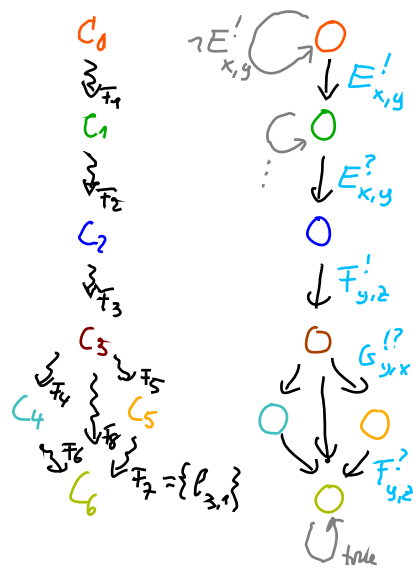
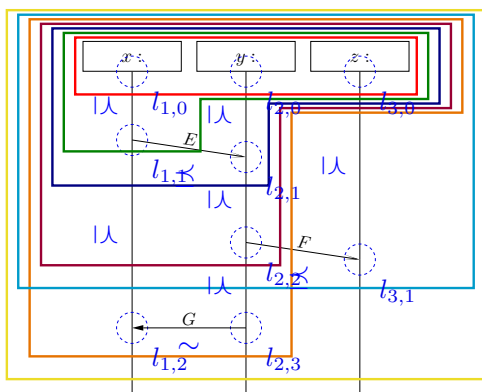
Firedsets



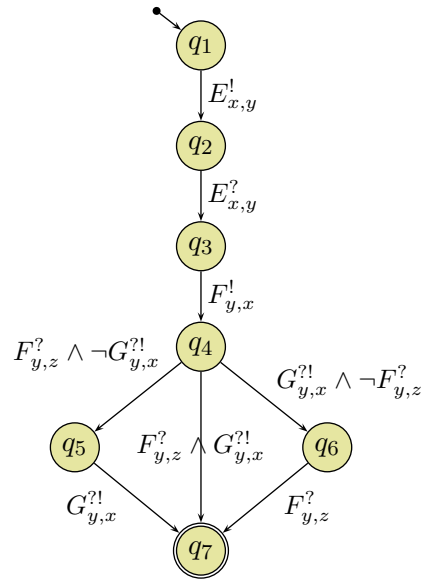
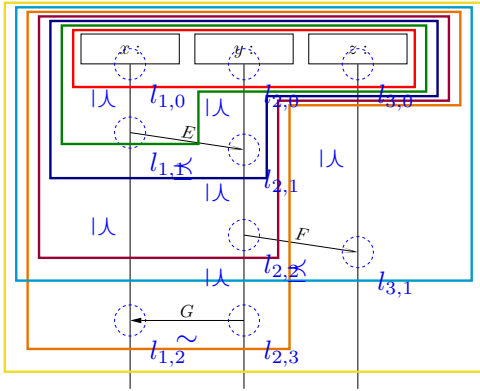
$C \mapsto_F C'$ iff

- $F \neq \emptyset$
- $C' \setminus C = F$
- for all event receptions in F , the sendings are in C
- direct successor: $\forall e \in F \exists e' \in C \bullet e' \leq e$
 $\wedge \forall e' \in C \bullet e' \leq e \Rightarrow e' \leq e'$

Towards Automata

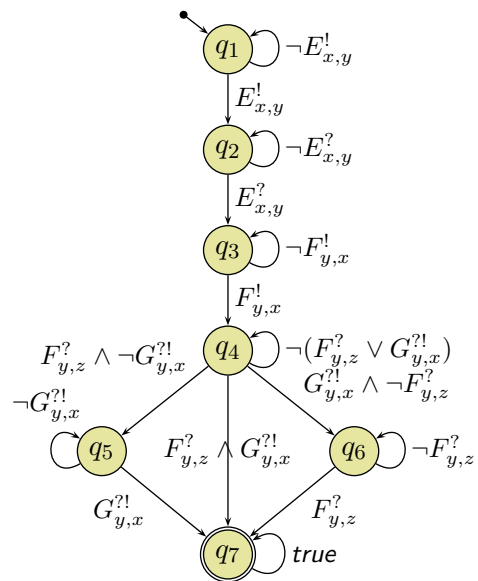
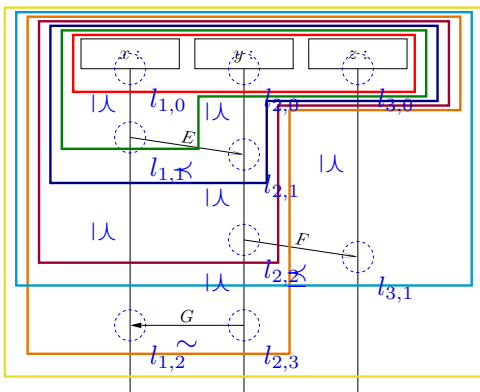


Alphabet — Progress Transitions



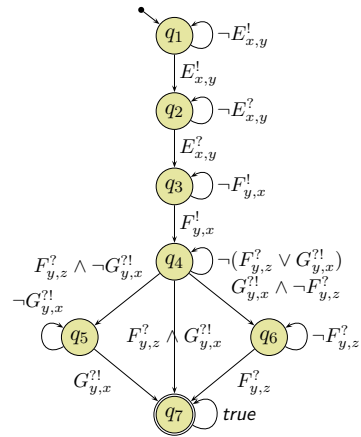
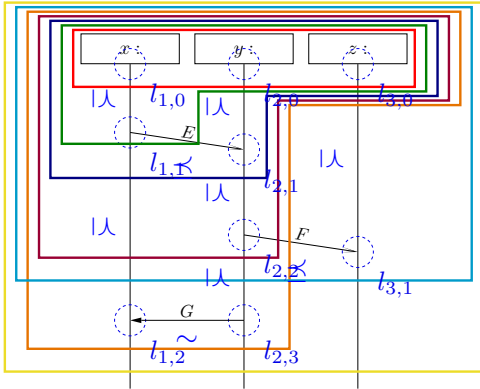
— 20 — 2015-02-03 — main —

Loops



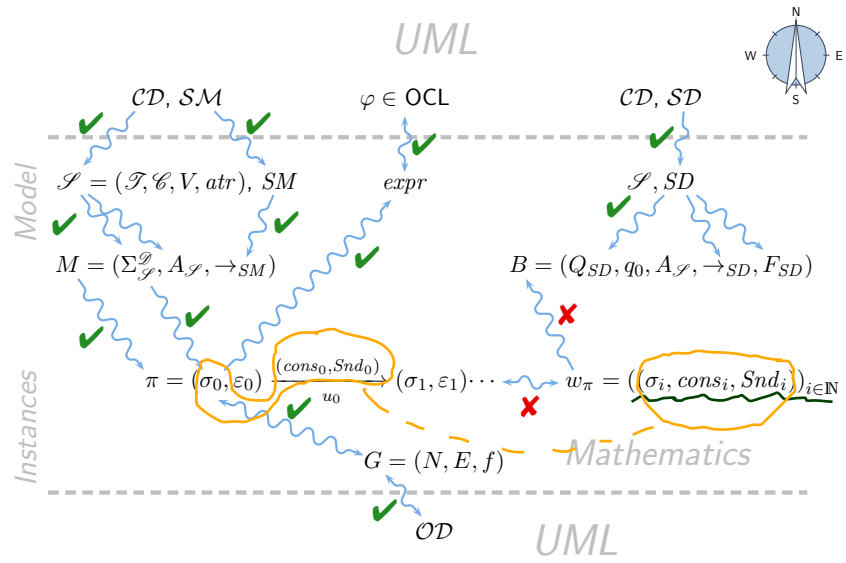
— 20 — 2015-02-03 — main —

Language



You are here.

Course Map



Language of a Model

Words over Signature

Definition. Let $\mathcal{S} = (\mathcal{I}, \mathcal{C}, V, atr, \mathcal{E})$ be a signature and \mathcal{D} a structure of \mathcal{S} . A **word** over \mathcal{S} and \mathcal{D} is an infinite sequence

$$(\sigma_i, cons_i, Snd_i)_{i \in \mathbb{N}_0} \in \left(\Sigma_{\mathcal{S}}^{\mathcal{D}} \times 2^{\mathcal{D}(\mathcal{C}) \times Evs(\mathcal{E}, \mathcal{D}) \times \mathcal{D}(\mathcal{C})} \times 2^{\mathcal{D}(\mathcal{C}) \times Evs(\mathcal{E}, \mathcal{D}) \times \mathcal{D}(\mathcal{C})} \right)^\omega.$$

The Language of a Model

Recall: A UML model $\mathcal{M} = (\mathcal{C}\mathcal{D}, \mathcal{I}\mathcal{M}, \mathcal{O}\mathcal{D})$ and a structure \mathcal{D} denotes a set $[[\mathcal{M}]]$ of (initial and consecutive) **computations** of the form

$$(\sigma_0, \varepsilon_0) \xrightarrow{a_0} (\sigma_1, \varepsilon_1) \xrightarrow{a_1} (\sigma_2, \varepsilon_2) \xrightarrow{a_2} \dots \text{ where}$$

$$a_i = (cons_i, Snd_i, u_i) \in \underbrace{2^{\mathcal{D}(\mathcal{C}) \times Evs(\mathcal{E}, \mathcal{D}) \times \mathcal{D}(\mathcal{C})} \times 2^{\mathcal{D}(\mathcal{C}) \times Evs(\mathcal{E}, \mathcal{D}) \times \mathcal{D}(\mathcal{C})}}_{=: \tilde{A}} \times \mathcal{D}(\mathcal{C}).$$

For the connection between models and interactions, we **disregard** the configuration of **the other** and **who** made the step, and define as follows:

Definition. Let $\mathcal{M} = (\mathcal{C}\mathcal{D}, \mathcal{I}\mathcal{M}, \mathcal{O}\mathcal{D})$ be a UML model and \mathcal{D} a structure. Then

$$\mathcal{L}(\mathcal{M}) := \{ (\sigma_i, cons_i, Snd_i)_{i \in \mathbb{N}_0} \in (\Sigma_{\mathcal{S}}^{\mathcal{D}} \times \tilde{A})^\omega \mid \exists (\varepsilon_i, u_i)_{i \in \mathbb{N}_0} : (\sigma_0, \varepsilon_0) \xrightarrow[u_0]{(cons_0, Snd_0)} (\sigma_1, \varepsilon_1) \cdots \in [[\mathcal{M}]] \}$$

is the **language** of \mathcal{M} .

Example: The Language of a Model

$$\mathcal{L}(\mathcal{M}) := \{(\sigma_i, cons_i, Snd_i)_{i \in \mathbb{N}_0} \in (\Sigma_{\mathcal{S}} \times \tilde{A})^\omega \mid \\ \exists (\varepsilon_i, u_i)_{i \in \mathbb{N}_0} : (\sigma_0, \varepsilon_0) \xrightarrow[u_0]{(cons_0, Snd_0)} (\sigma_1, \varepsilon_1) \cdots \in \llbracket \mathcal{M} \rrbracket\}$$

Signal and Attribute Expressions

- Let $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr, \mathcal{E})$ be a signature and X a set of logical variables,
- The signal and attribute expressions $Expr_{\mathcal{S}}(\mathcal{E}, X)$ are defined by the grammar:

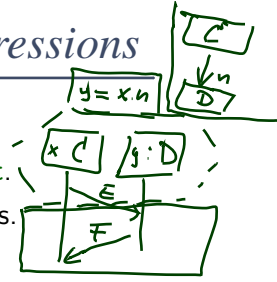
$$\psi ::= true \mid expr \mid E_{x,y}^! \mid E_{x,y}^? \mid \neg\psi \mid \psi_1 \vee \psi_2 \mid E_{x,y}^{!?}$$

where $expr : Bool \in Expr_{\mathcal{S}}$, $E \in \mathcal{E}$, $x, y \in X$.

↖ set of variables

Satisfaction of Signal and Attribute Expressions

- Let $(\sigma, cons, Snd) \in \Sigma_{\mathcal{S}}^{\mathcal{D}} \times \tilde{A}$ be a triple consisting of **system state**, **consume set**, and **send set**.
- Let $\beta : X \rightarrow \mathcal{D}(\mathcal{C})$ be a valuation of the logical variables.



Then

- $(\sigma, cons, Snd) \models_{\beta} true$
- $(\sigma, cons, Snd) \models_{\beta} \neg\psi$ if and only if not $(\sigma, cons, Snd) \models_{\beta} \psi$
- $(\sigma, cons, Snd) \models_{\beta} \psi_1 \vee \psi_2$ if and only if $(\sigma, cons, Snd) \models_{\beta} \psi_1$ or $(\sigma, cons, Snd) \models_{\beta} \psi_2$
- $(\sigma, cons, Snd) \models_{\beta} expr$ if and only if $I[expr](\sigma, \beta) = 1$
- $(\sigma, cons, Snd) \models_{\beta} E_{x,y}^!$ if and only if $\exists \vec{d} \bullet (\beta(x), (E, \vec{d}), \beta(y)) \in Snd$
- $(\sigma, cons, Snd) \models_{\beta} E_{x,y}^?$ if and only if $\exists \vec{d} \bullet (\beta(x), (E, \vec{d}), \beta(y)) \in cons$

Observation: semantics of models **keeps track** of sender and receiver at sending and consumption time. We disregard the event identity.

Alternative: keep track of event identities.

36/51

- 20 - 2015-02-03 - Smodelling -

TBA over Signature

Definition. A TBA

$$\mathcal{B} = (Expr_{\mathcal{B}}(X), X, Q, q_{ini}, \rightarrow, Q_F)$$

where $Expr_{\mathcal{B}}(X)$ is the set of **signal and attribute expressions** $Expr_{\mathcal{S}}(\mathcal{C}, X)$ over signature \mathcal{S} is called **TBA over \mathcal{S}** .

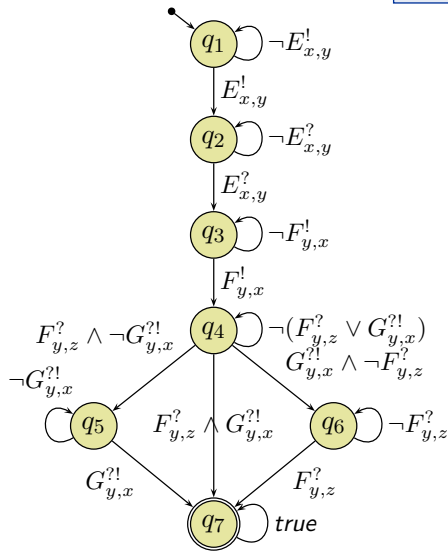
- Any word over \mathcal{S} and \mathcal{D} is then a word for \mathcal{B} .
(By the satisfaction relation defined on the previous slide; $\mathcal{D}(X) = \mathcal{D}(\mathcal{C})$.)
- Thus a TBA over \mathcal{S} accepts words of models with signature \mathcal{S} .
(By the previous definition of TBA.)

- 20 - 2015-02-03 - Smodelling -

37/51

TBA over Signature Example

$(\sigma, cons, Snd) \models_{\beta} expr$ iff $I[expr](\sigma, \beta) = 1$;
 $(\sigma, cons, Snd) \models_{\beta} E_{x,y}^!$ iff $(\beta(x), (E, \vec{d}), \beta(y)) \in Snd$

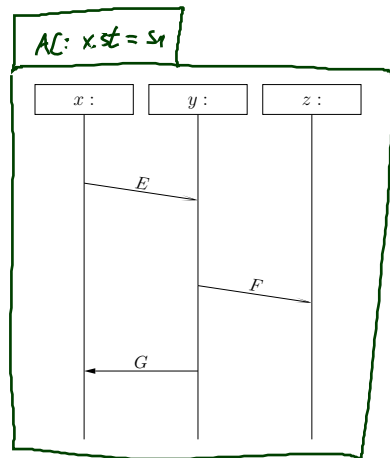


– 20 – 2015-02-03 – Smodellang –

Activation, Chart Mode

– 20 – 2015-02-03 – main –

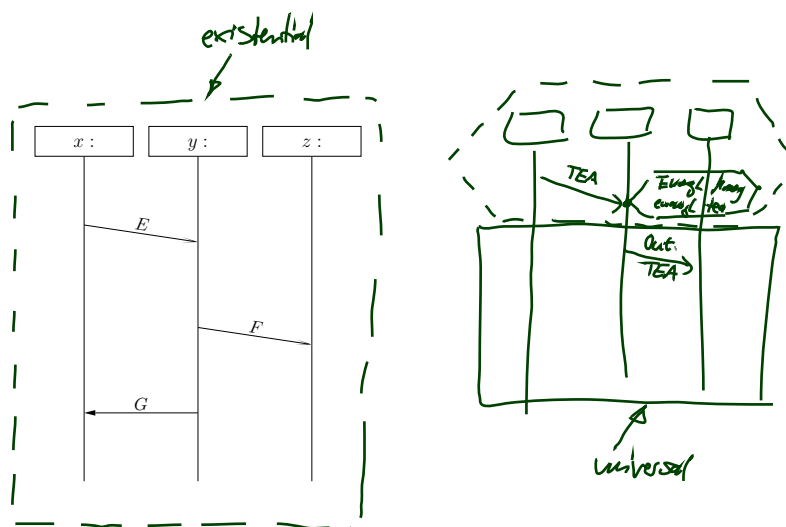
Activation Condition



- 20 - 2015-02-03 - main -

40/51

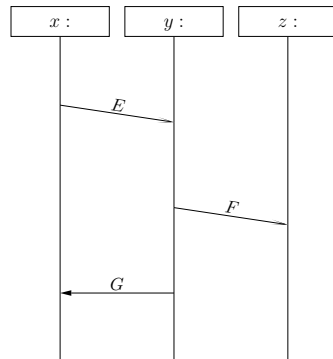
Universal vs. Existential Charts



- 20 - 2015-02-03 - main -

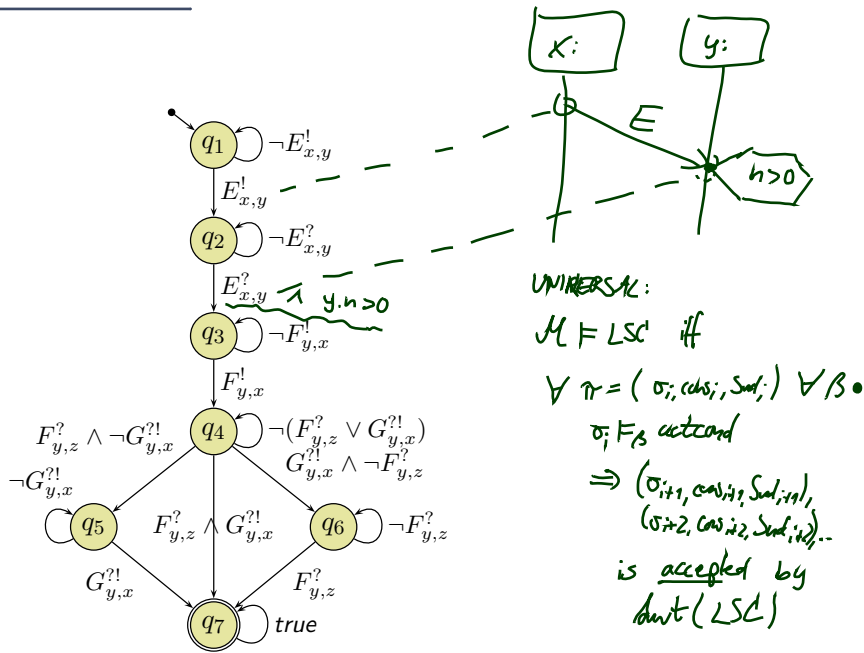
41/51

Prechart



Conditions

Conditions



- 20 - 2015-02-03 - main -

Back to UML: Interactions

- 20 - 2015-02-03 - main -

Model Consistency wrt. Interaction

- We assume that the set of interactions \mathcal{I} is partitioned into two (possibly empty) sets of **universal** and **existential** interactions, i.e.

$$\mathcal{I} = \mathcal{I}_{\forall} \dot{\cup} \mathcal{I}_{\exists}.$$

Definition. A model

$$\mathcal{M} = (\mathcal{CD}, \mathcal{IM}, \mathcal{OD}, \mathcal{I})$$

is called **consistent** (more precise: the constructive description of behaviour is consistent with the reflective one) if and only if

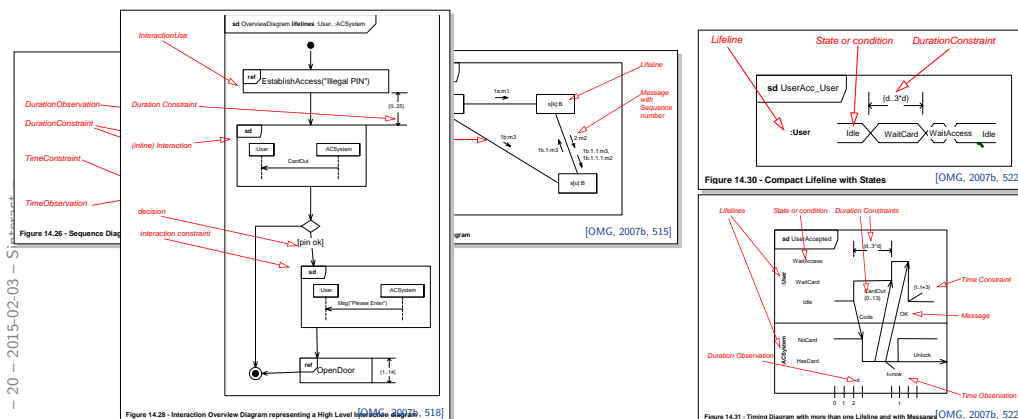
$$\forall I \in \mathcal{I}_{\forall} : \mathcal{L}(\mathcal{M}) \subseteq \mathcal{L}(I)$$

and

$$\forall I \in \mathcal{I}_{\exists} : \mathcal{L}(\mathcal{M}) \cap \mathcal{L}(I) \neq \emptyset.$$

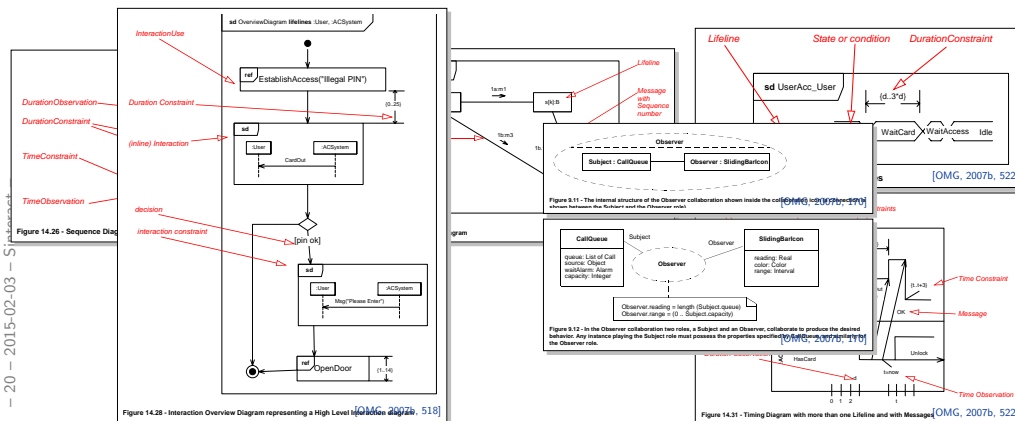
Interactions as Reflective Description

- In UML, reflective (temporal) descriptions are subsumed by **interactions**.
- A UML model $\mathcal{M} = (\mathcal{CD}, \mathcal{IM}, \mathcal{OD}, \mathcal{I})$ has a set of interactions \mathcal{I} .
- An interaction $I \in \mathcal{I}$ can be (OMG claim: equivalently) **diagrammed** as
 - sequence diagram**, **timing diagram**, or
 - communication diagram** (formerly known as collaboration diagram).



Interactions as Reflective Description

- In UML, reflective (temporal) descriptions are subsumed by **interactions**.
- A UML model $\mathcal{M} = (\mathcal{CD}, \mathcal{SM}, \mathcal{OD}, \mathcal{I})$ has a set of interactions \mathcal{I} .
- An interaction $\mathcal{I} \in \mathcal{I}$ can be (OMG claim: equivalently) **diagrammed** as
 - **sequence diagram**, **timing diagram**, or
 - **communication diagram** (formerly known as collaboration diagram).



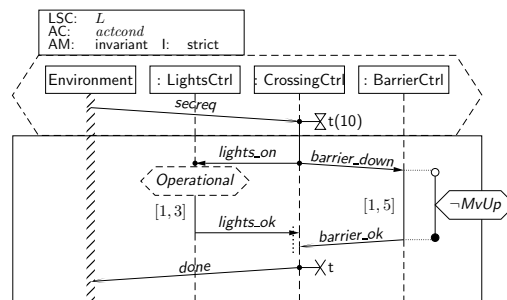
Why Sequence Diagrams?

Most Prominent: Sequence Diagrams — with **long history**:

- **Message Sequence Charts**, standardized by the ITU in different versions, often accused to lack a formal semantics.
- **Sequence Diagrams** of UML 1.x

Most severe **drawbacks** of these formalisms:

- unclear **interpretation**: example scenario or invariant?
- unclear **activation**: what triggers the requirement?
- unclear **progress** requirement: must all messages be observed?
- **conditions** merely comments
- no means to express **forbidden scenarios**



Thus: Live Sequence Charts

- **SDs of UML 2.x** address **some** issues, yet the standard exhibits unclarities and even contradictions [Harel and Maoz, 2007, Störrle, 2003]
- For the lecture, we consider **Live Sequence Charts** (LSCs) [Damm and Harel, 2001, Klose, 2003, Harel and Marelly, 2003], who have a common fragment with UML 2.x SDs [Harel and Maoz, 2007]
- **Modelling guideline**: stick to that fragment.

References

- [Damm and Harel, 2001] Damm, W. and Harel, D. (2001). LSCs: Breathing life into Message Sequence Charts. *Formal Methods in System Design*, 19(1):45–80.
- [Harel, 1997] Harel, D. (1997). Some thoughts on statecharts, 13 years later. In Grumberg, O., editor, *CAV*, volume 1254 of *LNCS*, pages 226–231. Springer-Verlag.
- [Harel and Maoz, 2007] Harel, D. and Maoz, S. (2007). Assert and negate revisited: Modal semantics for UML sequence diagrams. *Software and System Modeling (SoSyM)*. To appear. (Early version in *SCESM'06*, 2006, pp. 13-20).
- [Harel and Marelly, 2003] Harel, D. and Marelly, R. (2003). *Come, Let's Play: Scenario-Based Programming Using LSCs and the Play-Engine*. Springer-Verlag.
- [Klose, 2003] Klose, J. (2003). *LSCs: A Graphical Formalism for the Specification of Communication Behavior*. PhD thesis, Carl von Ossietzky Universität Oldenburg.
- [OMG, 2007a] OMG (2007a). Unified modeling language: Infrastructure, version 2.1.2. Technical Report formal/07-11-04.
- [OMG, 2007b] OMG (2007b). Unified modeling language: Superstructure, version 2.1.2. Technical Report formal/07-11-02.
- [Störrle, 2003] Störrle, H. (2003). Assert, negate and refinement in UML-2 interactions. In Jürjens, J., Rumpe, B., France, R., and Fernandez, E. B., editors, *CSDUML 2003*, number TUM-I0323. Technische Universität München.