

Lecture 20: Live Sequence Charts

2015-02-03

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Contents & Goals

Last Lecture:

- Hierarchical State Machines completed
- Behavioural feature (aka. methods)

This Lecture:

Educational Objectives: Capabilities for following tasks/questions.

- What does this LSC mean?
- Are this UML model's state machines consistent with the interactions?
- Please provide a UML model which is consistent with this LSC.
- What is: activation, hot/cold condition, pre-chart, etc.?

Content:

- Reflective description of behaviour.
- LSC concrete and abstract syntax.
- LSC semantics.

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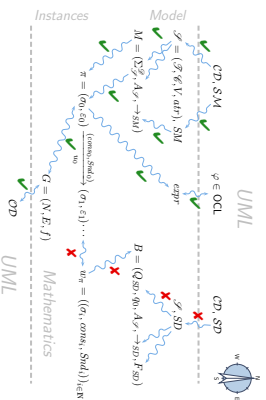
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- LSC semantics.

Course Map



Motivation: Reflective, Dynamic Descriptions of Behaviour

Recall: Constructive vs. Reflective Descriptions

- [Harel, 1997] proposes to distinguish constructive and reflective descriptions:
 - "A language is **constructive**, if it contributes to the dynamic semantics of the model. That is, its constructs contain information needed in executing the model or in translating it into executable code.
 - A constructive description tells **how** things are computed (which can then be desired or undesired).
- "Other languages are **reflective** or **assertive**, and can be used by the system modeller to capture parts of the thinking that go into building the model – behavior included –, to derive and present views of the model statically or during execution, or to set constraints on behavior in preparation for verification."

A reflective description tells **what** shall or shall not be computed.

Note: No sharp boundaries!

You are here.

Recall: What is a Requirement?

- Recall:
 - The semantics of the UML model $\mathcal{M} = (\mathcal{G}, \mathcal{J}, \mathcal{K}, \mathcal{O}, \mathcal{D})$ is the transition system $(S \rightarrow S_0)$ constructed according to discard/dispatch/commence-rules.
 - The computations of \mathcal{M} , denoted by $[[\mathcal{M}]]$, are the computations of $(S \rightarrow S_0)$.

Now:

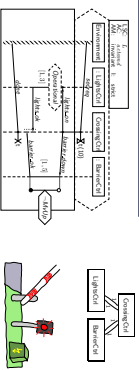
A reflective description tells what shall or shall not be computed.

More formally: a requirement ψ is a property of computations, something which is either satisfied or not satisfied by a computation

$$\pi = (o_0, e_0) \xrightarrow{(Comm, Start)} (o_1, e_1) \xrightarrow{(Comm, Start)} \dots \in [[\mathcal{M}]]$$

denoted by $\pi \models \psi$ and $\pi \not\models \psi$, resp.
Simplest case: OCL constraint.

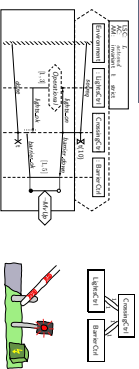
Example: What Is Required?



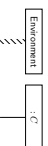
- Whenever the CrossingCtrl has consumed a 'secret' event
- then it shall finally send 'lightOn' and 'barrierDown' to LightCtrl and BarrierCtrl.
- If LightCtrl is not 'operational' when receiving that event, the rest of this scenario doesn't apply; maybe there's another LSC for that case.
- If LightCtrl is 'operational' when receiving that event, it shall reply with 'lightAck' within 1-3 time units.
- the BarrierCtrl shall reply with 'barrierAck' within 1-5 time units, during this time (dispatch time not included) it shall not be in state 'Multiply'.
- 'lightAck' and 'barrierAck' may occur in any order.
- After having consumed both, CrossingCtrl may reply with 'done' to the environment.

Live Sequence Charts — Concrete Syntax

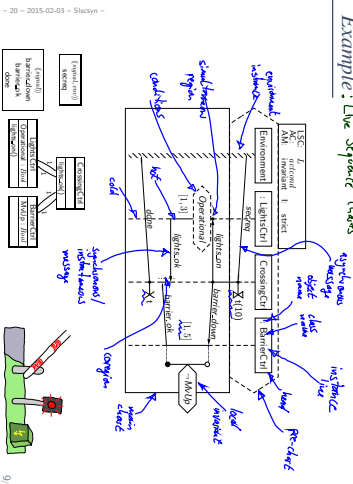
Building Blocks



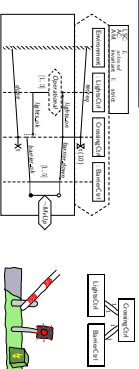
- Instance Lines:



Example: Live Sequence Charts

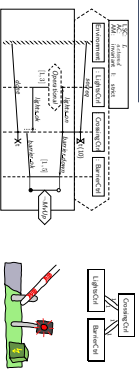


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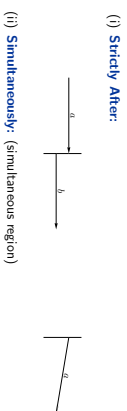


- Messages: (asynchronous or synchronous/instantaneous)

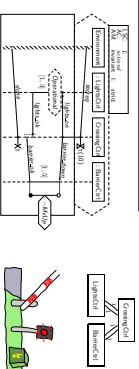




- Conditions and Local Invariants: ($expr_1, expr_2, expr_3 \in Expr_{\mathcal{P}}$)



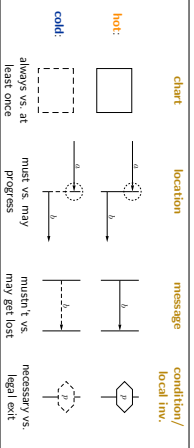
- (iii) Explicitly Unordered: (co-region)



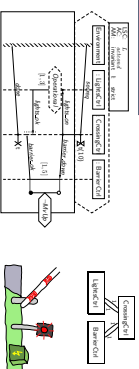
- Whenever the CrossingCrl has consumed a secret event
- then it shall finally send 'lights-on' and 'barrier-down' to LightScrl and BarrierCrl
- if LightCrl is not operational when receiving that event, the rest of this scenario doesn't apply; maybe there's another LSC for that case.
- if LightCrl is operational when receiving that event, it shall reply with 'lights-ack' within 1-3 time units.
- the BarrierCrl shall reply with 'barrier-ack' within 1-5 time units during this time (dispatch time not included) it shall not be in state 'MvUp'.
- 'lights-ack' and 'barrier-ack' may occur in any order.
- After having consumed both, CrossingCrl may reply with 'done' to the environment.

LSC Specialty: Modes

- With LSCs,
 - whole charts,
 - locations, and
 - elements
 have a **mode** — one of **hot** or **cold** (graphically indicated by outline).



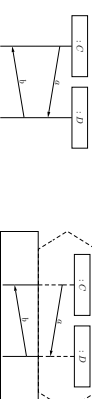
Example: Modes



- Whenever the CrossingCrl has consumed a secret event
- then it shall finally send 'lights-on' and 'barrier-down' to LightScrl and BarrierCrl
- if LightScrl is not operational when receiving that event, the rest of this scenario doesn't apply; maybe there's another LSC for that case.
- if LightScrl is operational when receiving that event, it shall reply with 'lights-ack' within 1-3 time units.
- the BarrierCrl shall reply with 'barrier-ack' within 1-5 time units during this time (dispatch time not included) it shall not be in state 'MvUp'.
- 'lights-ack' and 'barrier-ack' may occur in any order.
- After having consumed both, CrossingCrl may reply with 'done' to the environment.

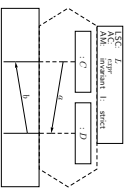
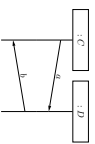
LSC Specialty: Activation

- One **major defect** of MSCs and SDs: they don't say **when** the scenario has activation mode ($AM \in \{init, inv\}$) to may be observed.
- LSCs: Activation condition ($AC \in Expr_{\mathcal{P}}$), activation mode ($AM \in \{init, inv\}$), and pre-chart.



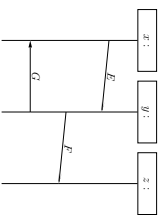
LSC Specialty: Activation

One major defect of MSCs and SDs: they don't say when the scenario has activation mode (AM ∈ {init, run}) and pre-chart.

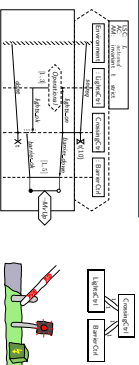


- Intuition: (universal case)
 - given a computation π , whenever expr holds in a configuration (σ_i, ξ_i) of ξ (AM = Initial)
 - which is initial, i.e. $k = 0$, or
 - whose k is not further restricted, (AM = Invariant)
- and if the pre-chart is observed from k to $k+n$, then the main-chart has to follow from $k+n+1$.

Restricted Syntax

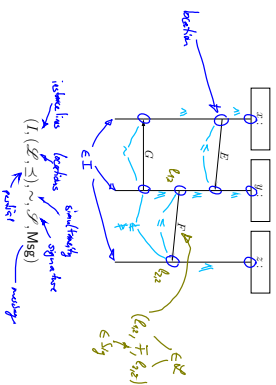


Example: What Is Required?

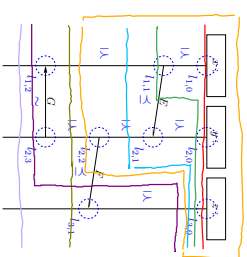


- Whenever the CrossingCrl has consumed a 'secret' event
- then it shall finally send 'lights-on' and 'barrier-down' to LightCrl and BarrierCrl.
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- If LightCrl is 'operational' when receiving that event, it shall reply with 'lightsack' within 1-3 time units.
- the BarrierCrl shall reply with 'barriersack' within 1-3 time units, during this time (dispatch time not included) it shall not be in state 'WVLP'.
- 'lightsack' and 'barriersack' may occur in any order.
- After having consumed both, CrossingCrl may reply with 'done' to the environment.

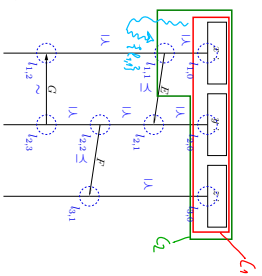
Restricted Abstract Syntax



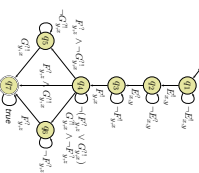
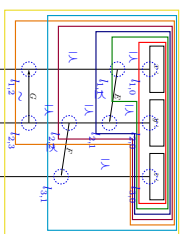
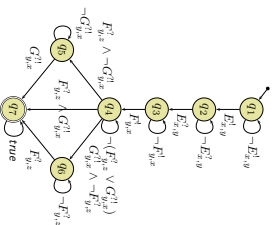
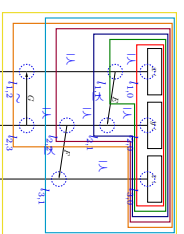
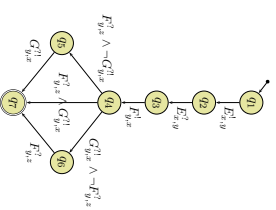
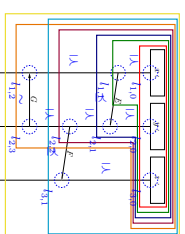
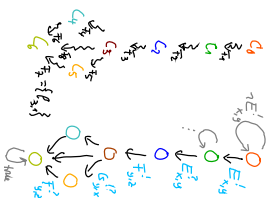
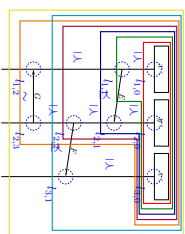
Live Sequence Charts — Semantics in a Mashell



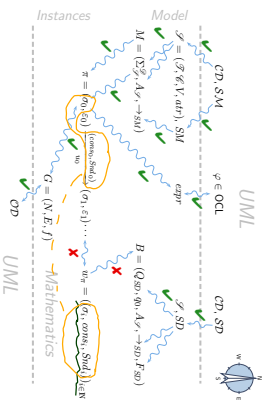
- A set $C \subseteq \mathcal{C}$ is called cset iff
 - downward closed cset s
 - closed cset ~
 - at least one loc. per instance loc. (if more than one, then unordered)



- $C \neq \emptyset$
- $C \setminus C = F$
- for all $c \in C$ symbols in F the symbols are in d
- final decision: $\forall e \in F \exists c \in C \cdot e \leq c$
- $\forall e \in C \cdot e \leq c \Rightarrow e \leq c'$



You are here



Language of a Model

Definition. Let $\mathcal{S} = (\mathcal{S}, \mathcal{K}, V, att, \delta)$ be a signature and \mathcal{D} a structure of \mathcal{S} . A **word over \mathcal{S}** and \mathcal{D} is an infinite sequence $(\sigma_1, cons_1, Snd_1)_{i \in \mathbb{N}_0} \in (\Sigma_{\mathcal{S}}^{\mathcal{D}} \times \mathcal{D}^{|\mathcal{K}|} \times \text{Bool}(\mathcal{D}) \times \mathcal{D}^{|\mathcal{V}|})^{\omega}$.

The Language of a Model

Recall: A UML model $\mathcal{M} = (\mathcal{S}, \mathcal{D}, \mathcal{M}, \theta, \mathcal{D})$ and a structure \mathcal{D} denotes a set $[M]$ of (initial and consequent) **computations** of the form

$$(\sigma_0, \varepsilon_0) \xrightarrow{msg} (\sigma_1, \varepsilon_1) \xrightarrow{msg} (\sigma_2, \varepsilon_2) \xrightarrow{msg} \dots \text{ where}$$

$$a_i = (cons_i, Snd_i, \eta_i) \in \underbrace{\mathcal{D}^{|\mathcal{K}|} \times \text{Bool}(\mathcal{D}) \times \mathcal{D}^{|\mathcal{V}|}}_{=: A} \times \mathcal{D}^{|\mathcal{K}|} \times \mathcal{D}^{|\mathcal{V}|}$$

For the connection between models and interactions, we **disregard** the configuration of the **ether** and **who** made the step, and define as follows:

Definition. Let $\mathcal{M} = (\mathcal{S}, \mathcal{D}, \mathcal{M}, \theta, \mathcal{D})$ be a UML model and \mathcal{D} a structure. Then $L(\mathcal{M}) := \{(\sigma_1, cons_1, Snd_1)_{i \in \mathbb{N}_0} \in (\Sigma_{\mathcal{S}}^{\mathcal{D}} \times A)^{\omega} \mid \exists (\varepsilon_1, \eta_1)_{i \in \mathbb{N}_0} : (\sigma_0, \varepsilon_0) \xrightarrow{msg} (\sigma_1, \varepsilon_1) \dots \in [M]\}$ is the **language** of \mathcal{M} .

Example: The Language of a Model

$$L(\mathcal{M}) := \{(\sigma_1, cons_1, Snd_1)_{i \in \mathbb{N}_0} \in (\Sigma_{\mathcal{S}}^{\mathcal{D}} \times A)^{\omega} \mid \exists (\varepsilon_1, \eta_1)_{i \in \mathbb{N}_0} : (\sigma_0, \varepsilon_0) \xrightarrow{msg} (\sigma_1, \varepsilon_1) \dots \in [M]\}$$

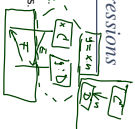
Signal and Attribute Expressions

- Let $\mathcal{S} = (\mathcal{S}, \mathcal{K}, V, att, \delta)$ be a signature and X a set of logical variables.
- The signal and attribute expressions $Expr_{\mathcal{S}}(\mathcal{S}, X)$ are defined by the grammar:

$$\psi ::= true \mid expr \mid E_{\sigma, \theta}^1 \mid E_{\sigma, \theta}^2 \mid \neg \psi \mid \psi_1 \vee \psi_2 \mid E_{\sigma, \theta}^3$$
 where $expr : Bool \in Expr_{\mathcal{S}}, E \in \delta, x, y \in X$.

ψ set of variables

Satisfaction of Signal and Attribute Expressions



- Let $(\sigma, cons, Std) \in \Sigma_{\mathcal{G}} \times \bar{A}$ be a triple consisting of **system state**, **consume set**, and **send set**.
- Let $\beta : X \rightarrow \mathcal{P}(\mathcal{G})$ be a valuation of the logical variables.
- Then
 - $(\sigma, cons, Std) \models_{\beta} true$
 - $(\sigma, cons, Std) \models_{\beta} \neg\psi$ if and only if not $(\sigma, cons, Std) \models_{\beta} \psi$
 - $(\sigma, cons, Std) \models_{\beta} \psi_1 \vee \psi_2$ if and only if $(\sigma, cons, Std) \models_{\beta} \psi_1$ or $(\sigma, cons, Std) \models_{\beta} \psi_2$
 - $(\sigma, cons, Std) \models_{\beta} expr$ if and only if $\llbracket expr \rrbracket(\sigma, \beta) = 1$
 - $(\sigma, cons, Std) \models_{\beta} E_{s,w}^i$ if and only if $\exists \vec{d} \bullet (\beta(\vec{d}), (E, \vec{d}), \beta(\vec{d})) \in Std$
 - $(\sigma, cons, Std) \models_{\beta} E_{r,w}^i$ if and only if $\exists \vec{d} \bullet (\beta(\vec{d}), (E, \vec{d}), \beta(\vec{d})) \in cons$

Observation: semantics of models **keeps track** of sender and receiver at sending and consumption time. We disregard the event identity.
Alternative: keep track of event identities.

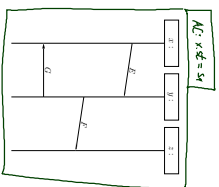
Activation, Chart Mode

TBA over Signature

Definition. A TBA $B = (Expr_g(X), X, Q, g_{init} \rightarrow, Q_f)$ where $Expr_g(X)$ is the set of **signal and attribute expressions** $Expr_{\mathcal{S}}(\mathcal{G}, X)$ over signature \mathcal{S} is called **TBA over** \mathcal{S} .

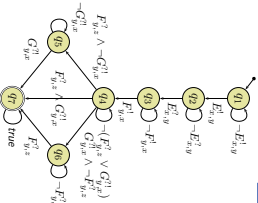
- Any word over \mathcal{S} and \mathcal{G} is then a word for B .
- (By the satisfaction relation defined on the previous slide, $\mathcal{D}(X) = \mathcal{D}(\mathcal{G})$)
- Thus a TBA over \mathcal{S} accepts words of models with signature \mathcal{S} .
- (By the previous definition of TBA)

Activation Condition

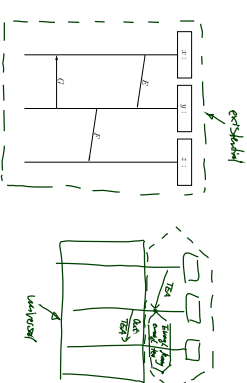


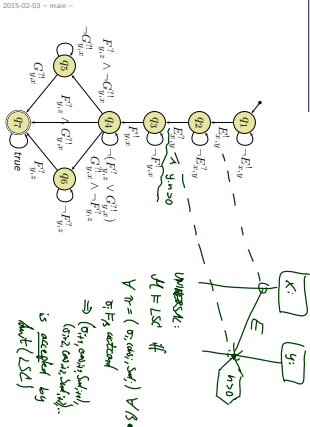
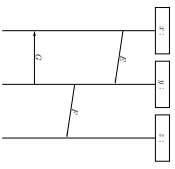
TBA over Signature Example

$(\sigma, cons, Std) \models_{\beta} expr$ iff $\llbracket expr \rrbracket(\sigma, \beta) = 1$:
 $(\sigma, cons, Std) \models_{\beta} E_{s,w}^i$ iff $(\beta(\vec{d}), (E, \vec{d}), \beta(\vec{d})) \in Std$



Universal vs. Existential Charts





Conditions

Model Consistency wrt Interaction

- We assume that the set of interactions \mathcal{I} is partitioned into two (possibly empty) sets of **universal** and **existential** interactions, i.e. $\mathcal{I} = \mathcal{I}_U \cup \mathcal{I}_E$.

Definition. A model $M = (\mathcal{O}, \mathcal{S}, \mathcal{M}, \theta, \mathcal{Q}, \mathcal{I})$ is called **consistent** (more precise: the constructive description of behaviour is consistent with the reflective one) if and only if

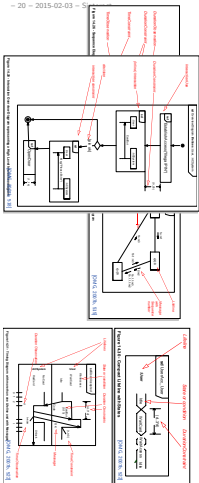
$$\forall I \in \mathcal{I}_E: \mathcal{L}(M) \subseteq \mathcal{L}(I)$$

and

$$\forall I \in \mathcal{I}_U: \mathcal{L}(M) \cap \mathcal{L}(I) \neq \emptyset.$$

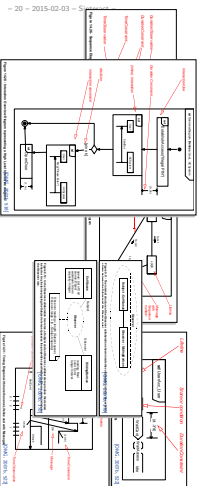
Interactions as Reflective Description

- In UML, reflective (temporal) descriptions are subsumed by **interactions**.
- A UML model $M = (\mathcal{O}, \mathcal{S}, \mathcal{M}, \theta, \mathcal{Q}, \mathcal{I})$ has a set of interactions \mathcal{I} .
- An interaction $I \in \mathcal{I}$ can be (OMG claim: equivalently) diagrammed as
 - sequence diagram**,
 - timing diagram**, or
 - communication diagram** (frequently known as collaboration diagram).



Back to UML: Interactions

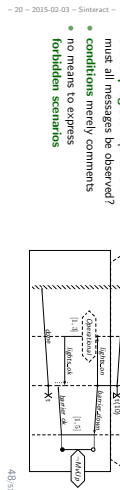
- In UML, reflective (temporal) descriptions are subsumed by **interactions**.
- A UML model $\mathcal{M} = (\mathcal{B}, \mathcal{D}, \mathcal{S}, \mathcal{H}, \theta, \mathcal{I}, \mathcal{J})$ has a set of interactions \mathcal{I} .
- An interaction $I \in \mathcal{I}$ can be (OMG claim: equivalently) **diagrammed** as
 - **sequence diagram**,
 - **sequence diagram**, **timing diagram**, or
 - **communication diagram** (formerly known as collaboration diagram).



- **Most Prominent:** Sequence Diagrams — with **long history**.
- **Message Sequence Charts**, standardized by the ITU in different versions, often accused to lack a formal semantics.
- **Sequence Diagrams** of UML 1.x

Most severe drawbacks of these formalisms:

- unclear interpretation.
- unclear scenario or invariant?
- unclear activation:
 - what triggers the requirement?
 - unclear progress requirement?
 - must all messages be observed?
 - conditions merely comments
 - no means to express forbidden scenarios



- **SDs of UML 2.x** address **some** issues, yet the standard exhibits **uncertainties** and even contradictions [Harel and Maoz, 2007; Störle, 2003]
- For the lecture, we consider **Live Sequence Charts (LSCs)** [Damm and Harel, 2001; Klose, 2003; Harel and Marelli, 2003], who have a common fragment with UML 2.x SDs [Harel and Maoz, 2007]
- **Modeling guideline:** stick to that fragment.

References

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