

Software Design, Modelling and Analysis in UML

Lecture 08: Class Diagrams II

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Contents & Goals

Last Lectures:

- completed class diagrams... except for visibility and associations

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.

- Please explain this class diagram with associations.
- Which annotations of an association arrow are semantically relevant?
- What's a role name? What's it good for?
- What is "multiplicity"? How did we treat them semantically?
- What is "reading direction", "navigability", "ownership", ...?
- What's the difference between "aggregation" and "composition"?

- **Content:**

- Study concrete syntax for "associations".
- (**Temporarily**) extend signature, define mapping from diagram to signature.
- Study effect on OCL.
- Btw.: where do we put OCL constraints?

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Visibility Cont'd

The Intuition by Example

$\mathcal{S} = (\{Int\}, \{C, D\}, \{n : D_{0,1}, m : D_{0,1}, \langle x : Int, \xi, expr_0, \emptyset \rangle\}, \{C \mapsto \{n\}, D \mapsto \{x, m\}\})$

Assume $w_1 : \tau_C$ and $w_2 : \tau_D$ are logical variables. **Which** of the following **syntactically correct** (?) OCL expressions **shall** we consider to be **well-typed**?

ξ of x:	public	private	protected	package
$w_1 . n . x = 0$	✓ I	✓ 0	later	not
$x(n(w_1))$	✗ II	✗ III		
$w_2 . m . x = 0$	✓ III	✓ II	later	not
$x(m(w_2))$	✗ 0	✗ I		
	?	?		

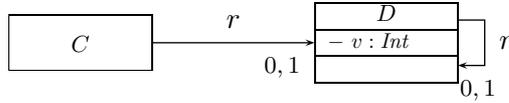
by class - OCL, C++, ...!

by object

Context

$$\mathcal{S} = (\{\text{Int}\}, \{C, D\}, \\ \{r : D_{0,1}, \langle v : \text{Int}, \xi, \star, \emptyset \rangle\}, \\ \{C \mapsto \{r\}, D \mapsto \{v, r\}\})$$

- **Example:**



$$\text{self}_D . v > 0 \quad \checkmark$$

$$\text{self}_D . r . v > 0 \quad \checkmark$$

$$\text{self}_C . r . v > 0 \quad \times$$

- That is, whether an expression involving attributes with visibility is well-typed **depends** on the class of objects for which it is evaluated.

Attribute Access in Context

Recall: attribute access in OCL Expressions, $C, D \in \mathcal{C}$.

$$\begin{aligned} v(\text{expr}_1) & : \tau_C \rightarrow \tau(v) & \bullet v : \tau(v) \in \text{atr}(C), \tau(v) \in \mathcal{T}, \\ r_1(\text{expr}_1) & : \tau_C \rightarrow \tau_D & \bullet r_1 : D_{0,1} \in \text{atr}(C), \\ r_2(\text{expr}_1) & : \tau_C \rightarrow \text{Set}(\tau_D) & \bullet r_2 : D_* \in \text{atr}(C), \end{aligned}$$

New rules:

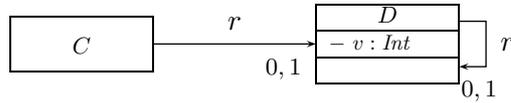
$$\begin{aligned} v(w) & : \tau_C \rightarrow \tau(v) & \langle v : \tau, \xi, \text{expr}_0, P_\xi \rangle \in \text{atr}(C) \\ r_1(w) & : \tau_C \rightarrow \tau_D & \langle r_1 : D_{0,1}, \xi, \text{expr}_0, P_\xi \rangle \in \text{atr}(C) \\ r_2(w) & : \tau_C \rightarrow \text{Set}(\tau_D) & \langle r_1 : D_*, \xi, \text{expr}_0, P_\xi \rangle \in \text{atr}(C) \end{aligned}$$

$$\underbrace{v(\text{expr}_1(w))}_{\tau_{C_2}} : \tau_{C_2} \rightarrow \tau(v) \quad \langle v : \tau, \xi, \text{expr}_0, P_\xi \rangle \in \text{atr}(C), \\ \text{---} \underbrace{\text{expr}_1(w)}_{\tau_{C_1}}, w : \tau_{C_1}, \text{ and } C_1 = C_2 \text{ or } \xi = +$$

$$r_1(\text{expr}_1(w)) : \tau_{C_2} \rightarrow \tau_D \quad \langle v : D_{0,1}, \xi, \text{expr}_0, P_\xi \rangle \in \text{atr}(C), \\ \text{---} \text{expr}_1(w) : \tau_{C_1}, w : \tau_{C_1}, \text{ and } C_1 = C_2 \text{ or } \xi = +$$

Example

①	$v(w)$	$: \tau_C \rightarrow \tau(v)$	$\langle v : \tau, \xi, expr_0, P_\xi \rangle \in atr(C)$
②	$r_1(w)$	$: \tau_C \rightarrow \tau_D$	$\langle r_1 : D_{0,1}, \xi, expr_0, P_\xi \rangle \in atr(C)$
③	$v(expr_1(w))$	$: \tau_{C_2} \rightarrow \tau(v)$	$\langle v : \tau, \xi, expr_0, P_\xi \rangle \in atr(C),$ $expr_1(w) : \tau_{C_2}, w : \tau_{C_1}, \text{ and } C_1 = C_2 \text{ or } \xi = +$
④	$r_1(expr_1(w))$	$: \tau_{C_2} \rightarrow \tau_D$	$\langle v : D_{0,1}, \xi, expr_0, P_\xi \rangle \in atr(C),$ $expr_1(w) : \tau_{C_2}, w : \tau_{C_1}, \text{ and } C_1 = C_2 \text{ or } \xi = +$



- $self_D . v > 0 \rightsquigarrow v(\underline{self_D}) > 0$ ok by ①
 $\tau_{C_2} (= \tau_D)$
- $self_D . r . v > 0 \rightsquigarrow v(r(\underline{self_D})) > 0$
 $r(\underline{self_D})$ ok by ②
 $v(r(\underline{self_D}))$ ok by ③ because $C_2 = D$
 τ_D
- $self_C . r . v > 0 \rightsquigarrow v(r(\underline{self_C})) > 0$
 $v(\underline{self_C})$ ok by ②
 $\tau_{C_2} (= \tau_D)$
 $v(r(\underline{self_C}))$ not ok nil ($C_2 \neq C$) 7/50

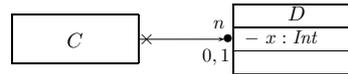
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The Semantics of Visibility

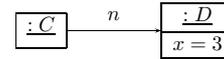
- **Observation:**
 - Whether an expression **does** or **does not** respect visibility is a matter of well-typedness **only**.
 - We only evaluate (= apply I to) **well-typed** expressions.
- We **need not** adjust the interpretation function I to support visibility.

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What is Visibility Good For?



- Visibility is a property of attributes — is it useful to consider it in OCL?
- In other words: given the diagram above, **is it useful** to state the following invariant (even though x is private in D)



context C inv : $n.x > 0$?

It depends.

(cf. [OMG, 2006], Sect. 12 and 9.2.2)

- **Constraints and pre/post conditions:**
 - Visibility is **sometimes not** taken into account. To state “global” requirements, it may be adequate to have a “global view”, be able to look into all objects.
 - But: visibility supports “narrow interfaces”, “information hiding”, and similar good design practices. To be more robust against changes, try to state requirements only in the terms which are visible to a class.

Rule-of-thumb: if attributes are important to state requirements on design models, leave them public or provide get-methods (later).

- **Guards and operation bodies:**
If in doubt, **yes** (= do take visibility into account).

Any so-called **action language** typically takes visibility into account.

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References

____[Oestereich, 2006] Oestereich, B. (2006). *Analyse und Design mit UML 2.1, 8. Auflage*. Oldenbourg, 8. edition.

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[OMG, 2007a] OMG (2007a). Unified modeling language: Infrastructure, version 2.1.2. Technical Report formal/07-11-04.

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