

Software Design, Modelling and Analysis in UML
Lecture 18: Hierarchical State Machines II

2015-01-22

Prof. Dr. Andreas Podelski, **Dr. Bernd Westphal**

Albert-Ludwigs-Universität Freiburg, Germany

– 18 – 2015-01-22 – main –

Contents & Goals

Last Lecture:

- Hierarchical State Machine Syntax
- Entry/Exit Actions

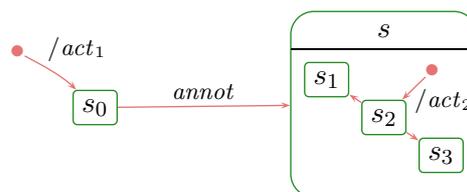
This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What does this State Machine mean? What happens if I inject this event?
 - Can you please model the following behaviour.
 - What does this **hierarchical** State Machine mean? What **may happen** if I inject this event?
 - What is: AND-State, OR-State, pseudo-state, entry/exit/do, final state, . . .
- **Content:**
 - Initial and Final State
 - Composite State Semantics
 - The Rest

– 18 – 2015-01-22 – Prelim –

Initial Pseudostates and Final States

Initial Pseudostate



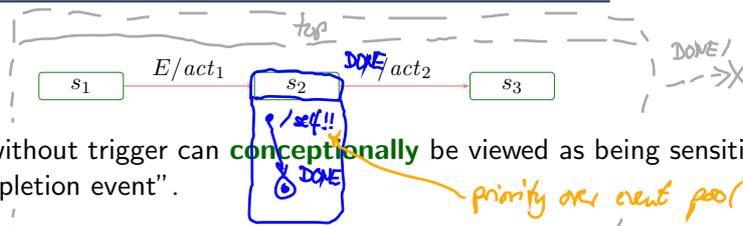
Principle:

- when entering a region **without** a specific destination state,
- then go to a state which is destination of an initiation transition,
- execute the action of the chosen initiation transitions **between** exit and entry actions.

Special case: the region of *top*.

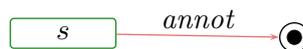
- If class C has a state-machine, then “create- C transformer” is the concatenation of
 - the transformer of the “constructor” of C (here not introduced explicitly) and
 - a transformer corresponding to one initiation transition of the top region.

Towards Final States: Completion of States



- Transitions without trigger can **conceptionally** be viewed as being sensitive for the “completion event”.
- Dispatching (here: E) **can then alternatively** be **viewed** as
 - (i) fetch event (here: E) from the ether,
 - (ii) take an enabled transition (here: to s_2),
 - (iii) remove event from the ether,
 - (iv) after having finished entry and do action of current state (here: s_2) — the state is then called **completed** —,
 - (v) raise a **completion event** — with strict priority over events from ether!
 - (vi) if there is a transition enabled which is sensitive for the completion event,
 - then take it (here: (s_2, s_3)).
 - otherwise become stable.

Final States



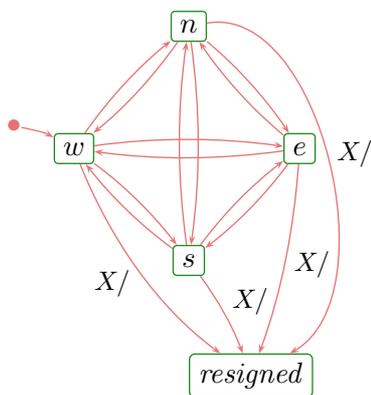
- If
 - a step of object u moves u into a final state (s, fin) , and
 - all sibling regions are in a final state,
 then (conceptionally) a completion event for the current composite state s is raised.
- If there is a transition of a **parent state** (i.e., inverse of $child$) of s enabled which is sensitive for the completion event,
 - then take that transition,
 - otherwise kill u \rightsquigarrow adjust (2.) and (3.) in the semantics accordingly
- **One consequence:**
 u never “survives” reaching a state (s, fin) with $s \in child(top)$.

Composite States

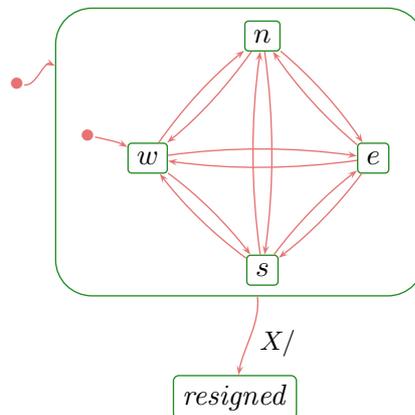
(formalisation follows [Damm et al., 2003])

Composite States

- In a sense, composite states are about **abbreviation**, **structuring**, and **avoiding redundancy**.
- Idea: in Tron, for the Player's Statemachine, instead of

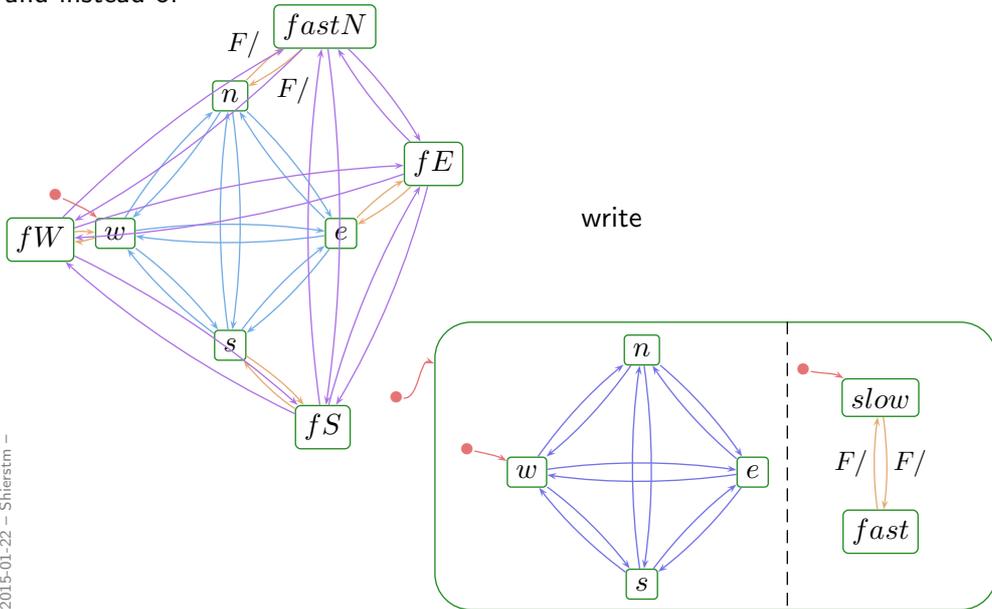


write



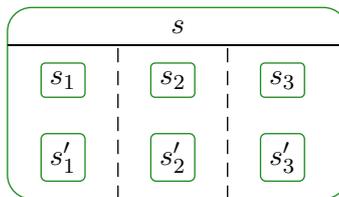
Composite States

and instead of



– 18 – 2015-01-22 – Shierstm –

Recall: Syntax



translates to

$$\underbrace{\{(top, st), (s, st), (s_1, st)(s'_1, st)(s_2, st)(s'_2, st)(s_3, st)(s'_3, st)\}}_{S, kind},$$

$$\underbrace{\{top \mapsto \{s\}, s \mapsto \{\{s_1, s'_1\}, \{s_2, s'_2\}, \{s_3, s'_3\}\}, s_1 \mapsto \emptyset, s'_1 \mapsto \emptyset, \dots\}}_{region}$$

$$\rightarrow, \psi, annot)$$

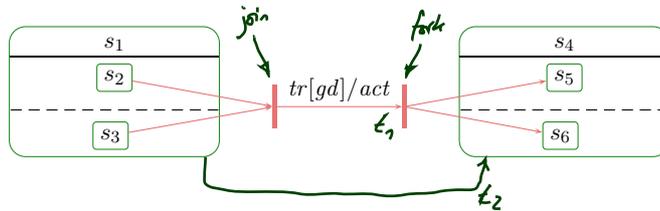
– 18 – 2015-01-22 – Shierstm –

Syntax: Fork/Join

- For brevity, we always consider transitions with (possibly) multiple sources and targets, i.e.

$$\psi : (\rightarrow) \rightarrow (2^S \setminus \emptyset) \times (2^S \setminus \emptyset)$$

- For instance,

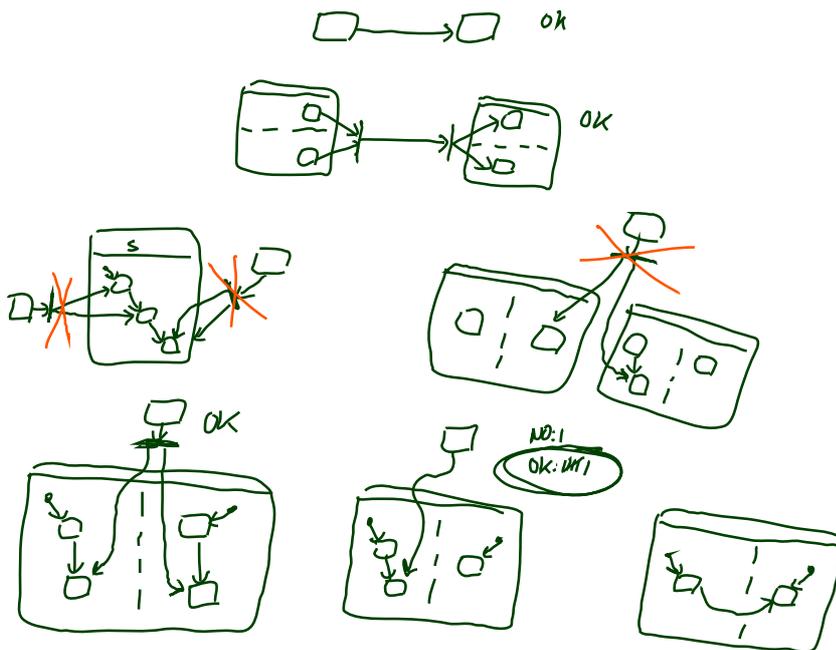


translates to

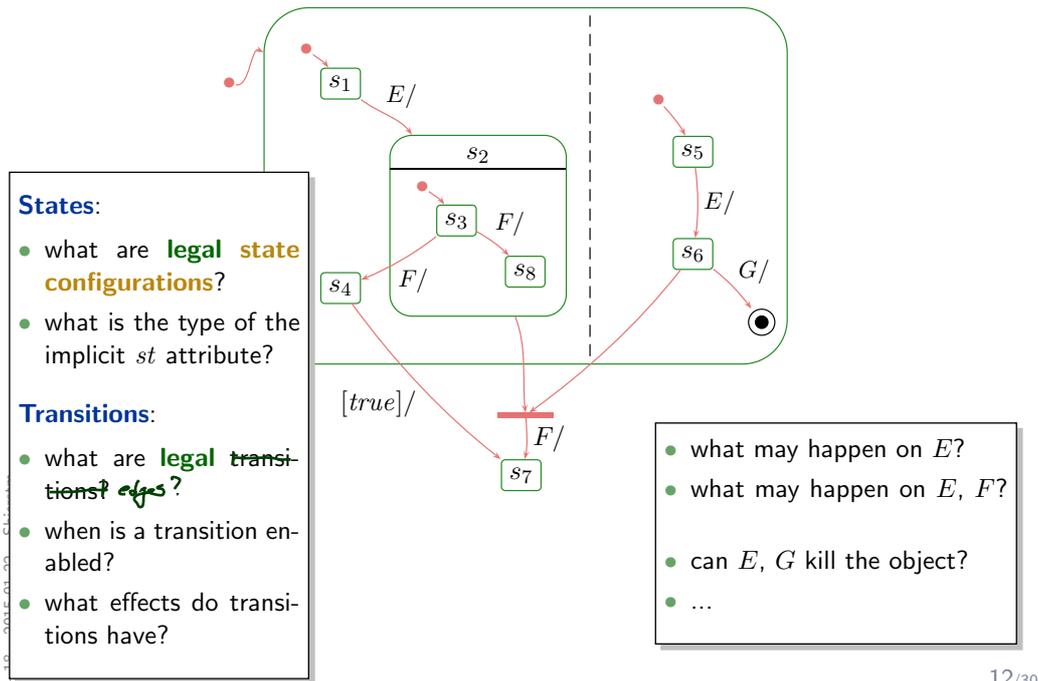
$$(S, \text{kind}, \text{region}, \underbrace{\{t_1\}}_{\tau_2}, \underbrace{\{t_1 \mapsto (\{s_2, s_3\}, \{s_5, s_6\})\}}_{\psi}, \underbrace{\{t_1 \mapsto (tr, gd, act)\}}_{\text{annot}})$$

$$\rightarrow \tau_2 \mapsto (\{s_i\}, \{s_j\})$$

- Naming convention: $\psi(t) = (\text{source}(t), \text{target}(t))$.



Composite States: Blessing or Curse?



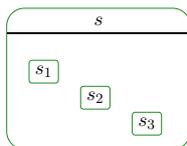
12/30

State Configuration

- The type of *st* is from now on a **set of states**, i.e. $st : 2^S$
- A set $S_1 \subseteq S$ is called (**legal**) **state configurations** if and only if
 - $top \in S_1$, and
 - for each state $s \in S_1$, for each non-empty region $\emptyset \neq R \in region(s)$, exactly one (non pseudo-state) child of s (from R) is in S_1 , i.e.

$$|\{s_0 \in R \mid kind(s_0) \in \{st, fin\}\} \cap S_1| = 1.$$

- **Examples:**



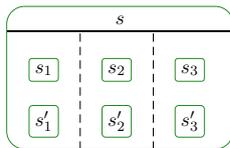
$S = \{s_2\}$ X (top missing)
 $S = \{s_2, top\}$ X (no child of top's region)
 $S = \{top, s, s_2\}$ ✓

State Configuration

- The type of st is from now on a **set of states**, i.e. $st : 2^S$
- A set $S_1 \subseteq S$ is called (**legal**) **state configurations** if and only if
 - $top \in S_1$, and
 - for each state $s \in S_1$, for each non-empty region $\emptyset \neq R \in region(s)$, exactly one (non pseudo-state) child of s (from R) is in S_1 , i.e.

$$|\{s_0 \in R \mid kind(s_0) \in \{st, fin\}\} \cap S_1| = 1.$$

- **Examples:**



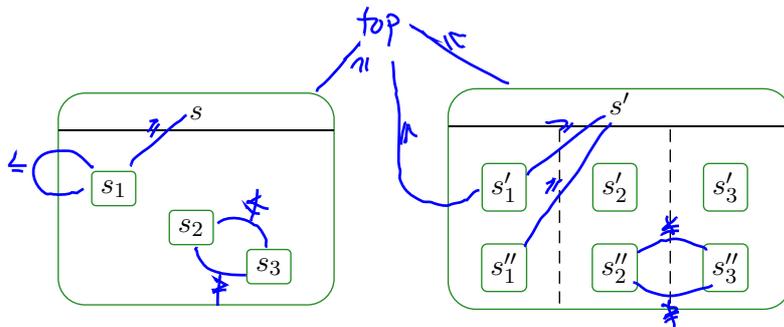
$$S = \{top, s, s_1, s_2, s_3\} \checkmark$$

NOTE: S can be abbreviated as $\{s_1, s_2, s_3\}$

A Partial Order on States

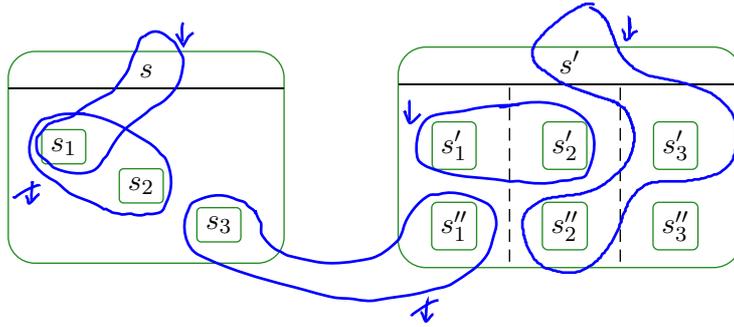
The substate- (or **child-**) relation **induces a partial order on states:**

- $top \leq s$, for all $s \in S$,
- $s \leq s'$, for all $s' \in child(s)$,
- transitive, reflexive, antisymmetric,
- $s' \leq s$ and $s'' \leq s$ implies $s' \leq s''$ or $s'' \leq s'$.



Least Common Ancestor and Ting

- A set of states $S_1 \subseteq S$ is called **consistent**, denoted by $\downarrow S_1$, if and only if for each $s, s' \in S_1$,
 - $s \leq s'$, or
 - $s' \leq s$, or
 - $s \perp s'$.



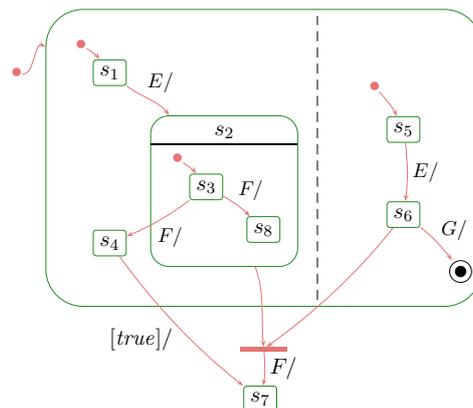
Legal Transitions (Edg)

A hierarchical state-machine $(S, kind, region, \rightarrow, \psi, annot)$ is called **well-formed** if and only if for all transitions $t \in \rightarrow$,

- (i) source and destination are consistent, i.e. $\downarrow source(t)$ and $\downarrow target(t)$,
- (ii) source (and destination) states are pairwise orthogonal, i.e.
 - for all $s \neq s' \in source(t)$ ($\in target(t)$), $s \perp s'$,
- (iii) the top state is neither source nor destination, i.e.
 - $top \notin source(t) \cup target(t)$.

- Recall: final states are not sources of transitions.

Example:



References

- [Crane and Dingel, 2007] Crane, M. L. and Dingel, J. (2007). UML vs. classical vs. rhapsody statecharts: not all models are created equal. *Software and Systems Modeling*, 6(4):415–435.
- [Damm et al., 2003] Damm, W., Josko, B., Votintseva, A., and Pnueli, A. (2003). A formal semantics for a UML kernel language 1.2. IST/33522/WP 1.1/D1.1.2-Part1, Version 1.2.
- [Fecher and Schönborn, 2007] Fecher, H. and Schönborn, J. (2007). UML 2.0 state machines: Complete formal semantics via core state machines. In Brim, L., Haverkort, B. R., Leucker, M., and van de Pol, J., editors, *FMICS/PDMC*, volume 4346 of *LNCS*, pages 244–260. Springer.
- [Harel and Kugler, 2004] Harel, D. and Kugler, H. (2004). The rhapsody semantics of statecharts. In Ehrig, H., Damm, W., Große-Rhode, M., Reif, W., Schnieder, E., and Westkämper, E., editors, *Integration of Software Specification Techniques for Applications in Engineering*, number 3147 in *LNCS*, pages 325–354. Springer-Verlag.
- [OMG, 2007] OMG (2007). Unified modeling language: Superstructure, version 2.1.2. Technical Report formal/07-11-02.