Software Design, Modelling and Analysis in UML

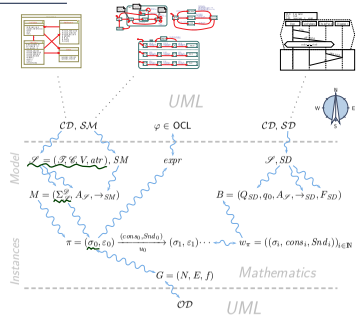
Lecture 2: Semantical Model

2015-10-22

Prof. Dr. Andreas Podelski, **Dr. Bernd Westphal**

Albert-Ludwigs-Universität Freiburg, Germany

Course Map



Contents & Goals

Last Lecture:

- Introduction: Motivation, Content, Formalia

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
  - What is a signature, an object, a system state, etc.?
  - What is the purpose of signature, object, etc. in the course?
  - How do Basic Object System Signatures relate to UML class diagrams?
- **Content:**
  - Basic Object System Signatures
  - Structures
  - System States

Semantical Foundation

Basic Object System Signature

Definition. A (Basic) Object System Signature is a quadruple

$$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$$

could have chosen alt.
C_* C_b
C_1 $C_\square$

where

- $\mathscr{T}$ is a set of (basic) types,
- $\mathscr{C}$ is a finite set of classes,
- V is a finite set of typed attributes, i.e., each $v \in V$ has a type
  - $\tau \in \mathscr{T}$, or
  - $C_{0,1}$ or C_*, where $C \in \mathscr{C}$

  (written $v : \tau$ or $v : C_{0,1}$ or $v : C_*$),
- $atr : \mathscr{C} \to 2^V$ maps each class to its set of attributes.

total function powerset of V

Note: Inspired by OCL 2.0 standard OMG (2006), Annex A.

Basic Object System Signature Example

$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$ where

- (basic) types $\mathscr{T}$ and classes $\mathscr{C}$ (both finite),
- typed attributes V, τ from $\mathscr{T}$, or $C_{0,1}$ or C_*, for some $C \in \mathscr{C}$,
- $atr : \mathscr{C} \to 2^V$ mapping classes to attributes.

Example: set of basic types $\mathscr{T}$ set of classes $\mathscr{C}$ attributes V attributes mapping atr

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{\underbrace{x : Int}_{\text{attribute } x \text{ has (basic) type Int}}, p : C_{0,1}, \underbrace{n : C_*}_{\text{attribute } n \text{ has (desired) type } C_*}\}, \{\underbrace{C \mapsto \{p, n\}}_{C \text{ has attributes } p \text{ and } n}, D \mapsto \{x\}\})$$

"maps to"

$atr(C) = \{p, n\}$
$atr(D) = \{x\}$

Basic Object System Signature Another Example

$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$ where

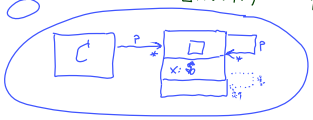
- (basic) types $\mathscr{T}$ and classes $\mathscr{C}$ (both finite),
- typed attributes V, τ from $\mathscr{T}$, or $C_{0,1}$ or C_*, for some $C \in \mathscr{C}$,
- $atr : \mathscr{C} \to 2^V$ mapping classes to attributes.

Example:

no, Int ∉ T of $\mathcal{S}_1$

$\mathcal{S}_1 = (\{\$, MyType\}, \{C, \square\}, \{\cancel{x:\$}, x:\$, p:\square_*, q:\square_{0,1}\},$
$\{C \mapsto \{p\},$
$\square \mapsto \{x, p\}\})$

name not be used (if not used, may be omitted)



looks like a class diagram...

Basic Object System Structure

Definition. A Basic Object System Structure of $\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$ is a domain function $\mathscr{D}$ which assigns to each type a domain, i.e.

- $\tau \in \mathscr{T}$ is mapped to $\mathscr{D}(\tau)$,
- $C \in \mathscr{C}$ is mapped to an infinite set $\mathscr{D}(C)$ of (object) identities.
  Note: Object identities only have the "=" operation.
- Sets of object identities for different classes are disjoint, i.e.
  $$\forall C, D \in \mathscr{C} : C \neq D \to \mathscr{D}(C) \cap \mathscr{D}(D) = \emptyset.$$
- C_* **and** $C_{0,1}$ for $C \in \mathscr{C}$ are mapped to $2^{\mathscr{D}(C)}$.

We use $\mathscr{D}(\mathscr{C})$ to denote $\bigcup_{C \in \mathscr{C}} \mathscr{D}(C)$; analogously $\mathscr{D}(\mathscr{C}_*)$.

Note: We identify objects and object identities, because both uniquely determine each other (cf. OCL 2.0 standard).

Basic Object System Structure Example

Wanted: a structure for signature

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

$\mathscr{D}$ needs to map:

- $\tau \in \mathscr{T}$ to **some** $\mathscr{D}(\tau)$,
- $C \in \mathscr{C}$ to **some** set of identities $\mathscr{D}(C)$ (infinite, disjoint for different classes),
- C_* and $C_{0,1}$ for $C \in \mathscr{C}$: always mapped to $\mathscr{D}(C_*) = \mathscr{D}(C_{0,1}) = 2^{\mathscr{D}(C)}$.

$$\begin{aligned}
\mathscr{D}(Int) &= \mathbb{Z} \\
\mathscr{D}(C) &= \mathbb{N}^+ \times \{C\} \cong \{1_C, 2_C, 3_C, \dots\} \\
\mathscr{D}(D) &= \mathbb{N}^+ \times \{D\} \cong \{1_D, 2_D, 3_D, \dots\} \\
\mathscr{D}(C_{0,1}) = \mathscr{D}(C_*) &= 2^{\mathscr{D}(C)} \\
\mathscr{D}(D_{0,1}) = \mathscr{D}(D_*) &= 2^{\mathscr{D}(D)}
\end{aligned}$$

$\mathscr{D}(Int) = \{-2, -1, 0, 1, 2\}$
$\mathscr{D}_1(C) = \{n, nn, nnn, \dots\}$
$\mathscr{D}_1(D) = \{u, uu, uuu, \dots\}$
$= 2^{\mathscr{D}_1(C)}$
$= 2^{\mathscr{D}_1(D)}$

System State

set of all object identities in $\mathscr{D}$

partial function mapping attributes (for V) to values (from $\mathscr{D}(\mathscr{T})$ and $\mathscr{D}(\mathscr{C}_*)$)

Definition. Let $\mathscr{D}$ be a structure of $\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$.

A system state of $\mathscr{S}$ wrt. $\mathscr{D}$ is a type-consistent mapping

partial function

$$\sigma : \mathscr{D}(\mathscr{C}) \nrightarrow (V \nrightarrow (\mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*))).$$

set of attributes — set of all values in $\mathscr{D}$

That is, for each $u \in \mathscr{D}(C)$, $C \in \mathscr{C}$, if $u \in \mathrm{dom}(\sigma)$

- $\mathrm{dom}(\sigma(u)) = atr(C)$
- $(\sigma(u))(v) \in \mathscr{D}(\tau)$ if $v : \tau, \tau \in \mathscr{T}$
- $(\sigma(u))(v) \in \mathscr{D}(D_*)$ if $v : D_{0,1}$ or $v : D_*$ with $D \in \mathscr{C}$
  $: V \nrightarrow \mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*)$

We call $u \in \mathscr{D}(\mathscr{C})$ alive in σ if and only if $u \in \mathrm{dom}(\sigma)$.

We use $\Sigma^{\mathscr{D}}_{\mathscr{S}}$ to denote the set of all system states of $\mathscr{S}$ wrt. $\mathscr{D}$.

System State Example

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$
$$\mathscr{D}(Int) = \mathbb{Z}, \quad \mathscr{D}(C) = \{1_C, 2_C, 3_C, \dots\}, \quad \mathscr{D}(D) = \{1_D, 2_D, 3_D, \dots\}$$

Wanted: $\sigma : \mathscr{D}(\mathscr{C}) \nrightarrow (V \nrightarrow (\mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*)))$ such that (i) $\mathrm{dom}(\sigma(u)) = atr(C)$, and (ii) $\sigma(u)(v) \in \mathscr{D}(\tau)$ if $v : \tau, \tau \in \mathscr{T}$, (iii) $\sigma(u)(v) \in \mathscr{D}(C_*)$ if $v : D_*$ with $D \in \mathscr{C}$.

$\sigma = \emptyset$ ("empty function")
alive in σ_1: none

$\sigma_2 = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{1_C, 5_C\}\}, 5_C \mapsto \{p \mapsto \{1_C\}, n \mapsto \emptyset\}, 3_D \mapsto \{x \mapsto 3\}\}$

alive in σ_2: $1_C, 5_C, 3_D$
not alive: everybody else

$\sigma(1_D) = \{x \mapsto 0\}$
$\sigma(1_D)(x) = 0$

$\sigma_3 = \{1_D \mapsto \{x \mapsto 2\}, 2_D \mapsto \{x \mapsto 2\}, 1_D \mapsto \{x \mapsto 0\}\}$

alive objects in σ_3: $1_D, 2_D, 1_D$

System State Example

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$
$$\mathscr{D}(Int) = \mathbb{Z}, \quad \mathscr{D}(C) = \{1_C, 2_C, 3_C, \dots\}, \quad \mathscr{D}(D) = \{1_D, 2_D, 3_D, \dots\}$$

Wanted: $\sigma : \mathscr{D}(\mathscr{C}) \nrightarrow (V \nrightarrow (\mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*)))$ such that (i) $\mathrm{dom}(\sigma(u)) = atr(C)$, and (ii) $\sigma(u)(v) \in \mathscr{D}(\tau)$ if $v : \tau, \tau \in \mathscr{T}$, (iii) $\sigma(u)(v) \in \mathscr{D}(C_*)$ if $v : D_*$ with $D \in \mathscr{C}$.

Two options:

- **Concrete, explicit** identities:
  $$\sigma_2 = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}.$$
- **Alternative**: **symbolic** system state.
  $$\sigma_3 = \{c_1 \mapsto \{p \mapsto \emptyset, n \mapsto \{c_2\}\}, c_2 \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, d \mapsto \{x \mapsto 23\}\}$$
  assuming $c_1, c_2 \in \mathscr{D}(C)$, $d \in \mathscr{D}(D)$, $c_1 \neq c_2$.

System State: Spot the 10 (?) Mistakes

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$
$$\mathscr{D}(Int) = \mathbb{Z}, \quad \mathscr{D}(C) = \{1_C, 2_C, 3_C, ...\}, \quad \mathscr{D}(D) = \{1_D, 2_D, 3_D, ...\}$$

Wanted: $\sigma : \mathscr{D}(\mathscr{C}) \nrightarrow (V \nrightarrow (\mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*)))$ such that (i) $\mathrm{dom}(\sigma(u)) = atr(C)$, and (ii) $\sigma(u)(v) \in \mathscr{D}(\tau)$ if $v : \tau, \tau \in \mathscr{T}$, (iii) $\sigma(u)(v) \in \mathscr{D}(C_*)$ if $v : D_*$ with $D \in \mathscr{C}$.

- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, \quad 5_C \mapsto \{p \mapsto \emptyset, n \mapsto 1_C\}, \quad 1_D \mapsto \{x \mapsto 23\}\}.$
  empty set $\{\}$; (iii) $1_C \notin 2^{\mathscr{D}(C)}$; (i), $23 \notin \mathscr{D}(Int)$
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, \quad 5_C \mapsto \{p \mapsto 1_C, n \mapsto \emptyset\}, \quad 1_D \mapsto \{x \mapsto 23\}\}.$
  (i)
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{1_D\}\}, \quad 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, \quad 1_D \mapsto \{x \mapsto 22\}\}.$
  (ii) $\notin 2^{\mathscr{D}(C)}$
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, \quad 5_C \mapsto \{n \mapsto \emptyset\}, \quad 1_D \mapsto \{x \mapsto 1, p \mapsto \{1_C\}\}\}.$
  (i) peak(C)!; (i), pk ∉ atr(D)
- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, \quad 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \{9_C\}\}\}$

Dangling References

Definition. Let $\sigma \in \Sigma_{\mathscr{S}}^{\mathscr{D}}$ be a system state.
We say attribute $v \in V_{0,1,*}$, i.e. $v : C_{0,1}$ or $v : C_*$, in object $u \in \mathrm{dom}(\sigma)$ has a dangling reference if and only if the attribute's value comprises an object which is not alive in σ, i.e. if
$$(\sigma(u))(v) \not\subset \mathrm{dom}(\sigma).$$
alive objects
We call σ closed if and only if no attribute has a dangling reference in any object alive in σ.

Example:

- $\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}\}$
  $(\sigma(1_C))(n) = \{5_C\} \not\subset \{1_C\} = dom(\sigma)$

A Complete Example: Vending Machine

$\mathcal{S} = (\{Bool, Nat\},$
$\{VM, CP, DD\},$
$\{cp : CP_*, dd : DD_{0,1}, wen : Bool, win : Nat\},$
$\{VM \mapsto \{cp, dd\}, CP \mapsto \{wen\}, DD \mapsto \{win, wen\}\})$

$\mathscr{D}(Bool) = \{true, false\}$
$\mathscr{D}(Nat) = \mathbb{N}$
$\mathscr{D}(VM) = \{1_{vm}, 2_{vm}, ...\}$
$\mathscr{D}(DD) = \{1_{DD}, ...\}$
$\mathscr{D}(CP) = \{1_{CP}, ...\}$

$\mathscr{D}(DD_{0,*}) = 2^{\mathscr{D}(DD)} = 2^{\{1_{DD}, 2_{DD}, ...\}}$

context DD inv:
wen implies win > 0

$\sigma = \{1_{vm} \mapsto \{dd \mapsto \{1_{DD}\}, cp \mapsto \{3_{CP}, 5_{CP}\}\},$
$1_{DD} \mapsto \{win \mapsto 13, wen \mapsto true\},$
$3_{CP} \mapsto \{wen \mapsto true\},$
$5_{CP} \mapsto \{wen \mapsto false\}\}$

References

——. OMG (2006). Object Constraint Language, version 2.0. Technical Report formal/06-05-01.

OMG (2011a). Unified modeling language: Infrastructure, version 2.4.1. Technical Report formal/2011-08-05.

OMG (2011b). Unified modeling language: Superstructure, version 2.4.1. Technical Report formal/2011-08-06.