

Antichain algorithms.

Using Antichains to solve reachability problems on non-deterministic finite automata.

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Proseminar on Automata Theory at the chair of Software Engineering.
Supervised by Alexander Nutz.

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Partial orders

- V be a finite set
- \preceq a binary relation $\preceq \subseteq V \times V$
- \preceq reflexive, transitive and anti-symmetric then it is called a partial order
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- $(\subseteq, 2^V)$, subset-inclusion in a powerset.

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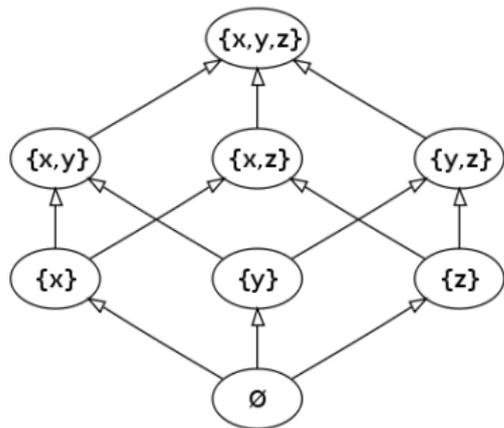
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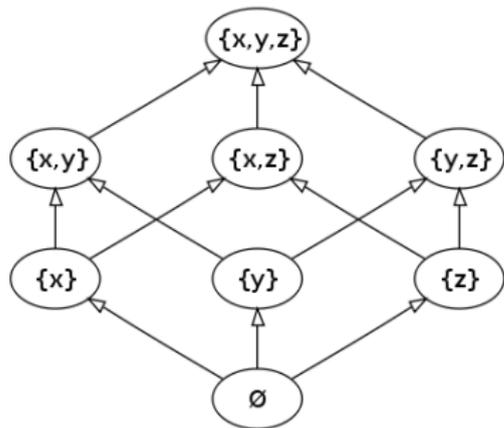


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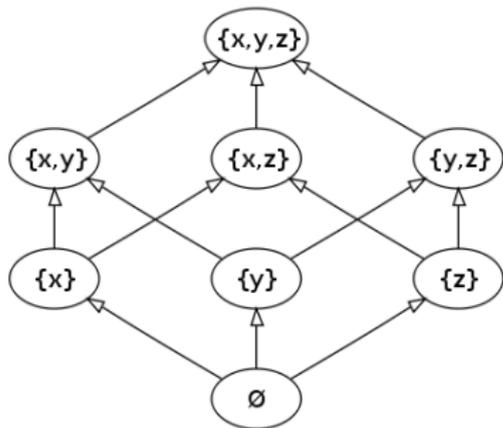


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Downward closure, Maximum of $S \subseteq V$

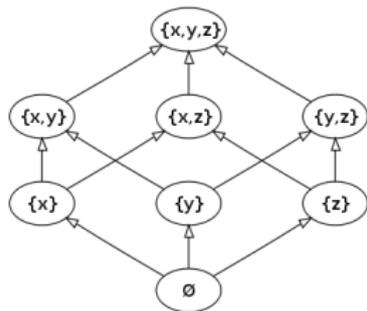
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Examples

■ $\text{Down}(\subseteq, \{x, y\}) = \{\emptyset, \{x\}, \{y\}, \{x, y\}\}$

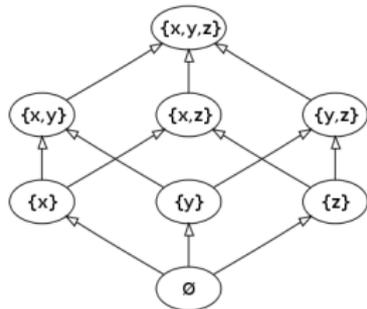
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Examples

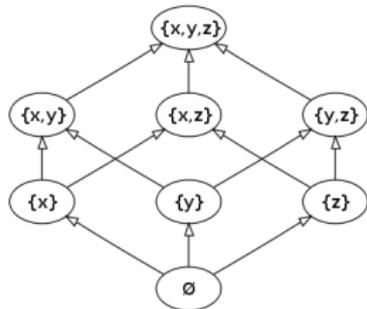
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$$\blacksquare \text{Max}(\subseteq, \{\{x\}, \{x,y\}, \{x,z\}\}) = \{\{x,y\}, \{x,z\}\}$$

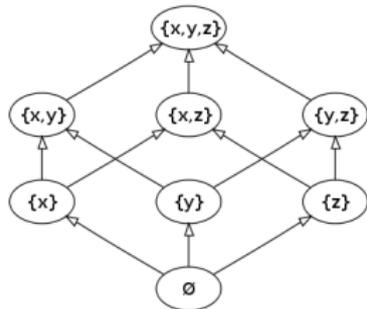
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Examples

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Antichain as a representation for a downward closed set

$S \subseteq V$.

- Use $S' := \text{Max}(\preceq, S)$ to represent S .

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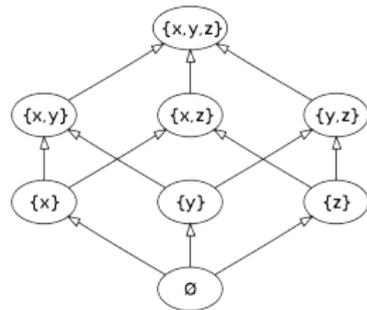
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Example

$S_1 := \{\emptyset, \{x\}, \{y\}\}$ so $S'_1 = \{\{x\}, \{y\}\}$
 $S_2 := \{\emptyset, \{x\}, \{y\}, \{x,y\}\}$ so $S'_2 = \{\{x,y\}\}$



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Powerset determinization of Non-deterministic finite automata

- Let $A := (Loc, Init, Fin, \delta, \Sigma)$ be a finite automaton.
- $G(A) := (V, E, In, \overline{Fin})$ is the corresponding powerset automaton.

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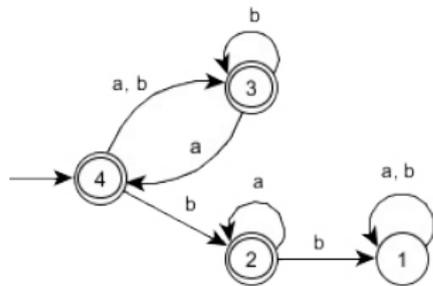
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- $(v_1, v_2) \in E$ iff there exists a $\sigma \in \Sigma$ such that $\bigcup_{q \in v_1} \delta(q, \sigma) = v_2$.

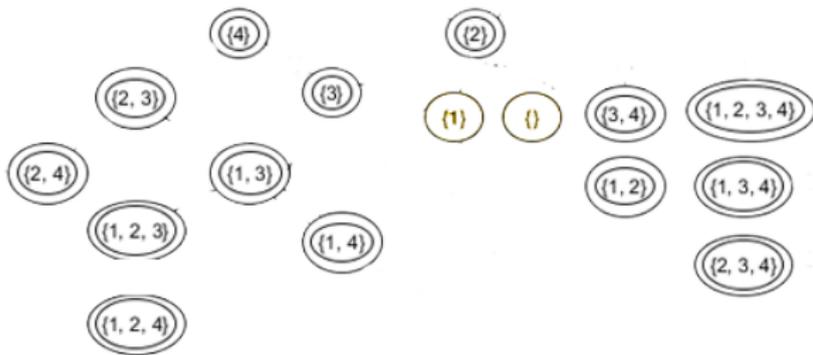
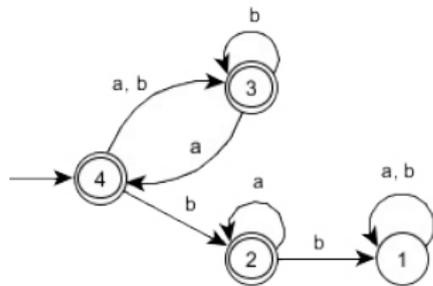
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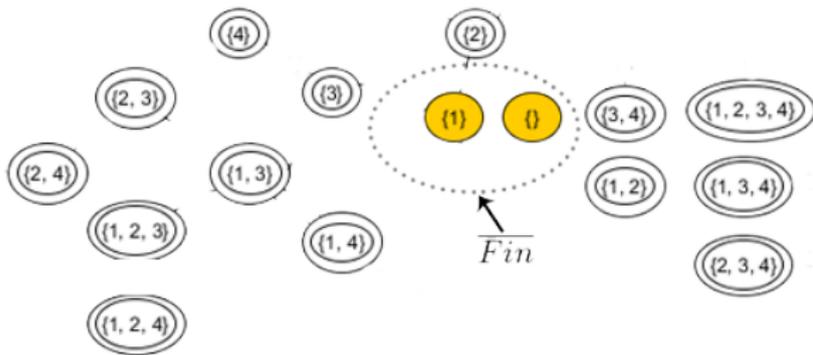
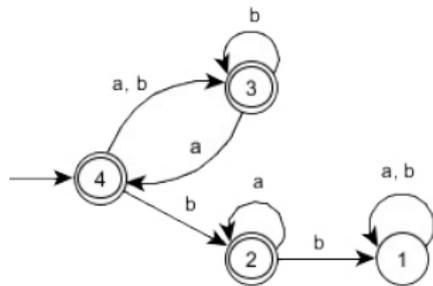
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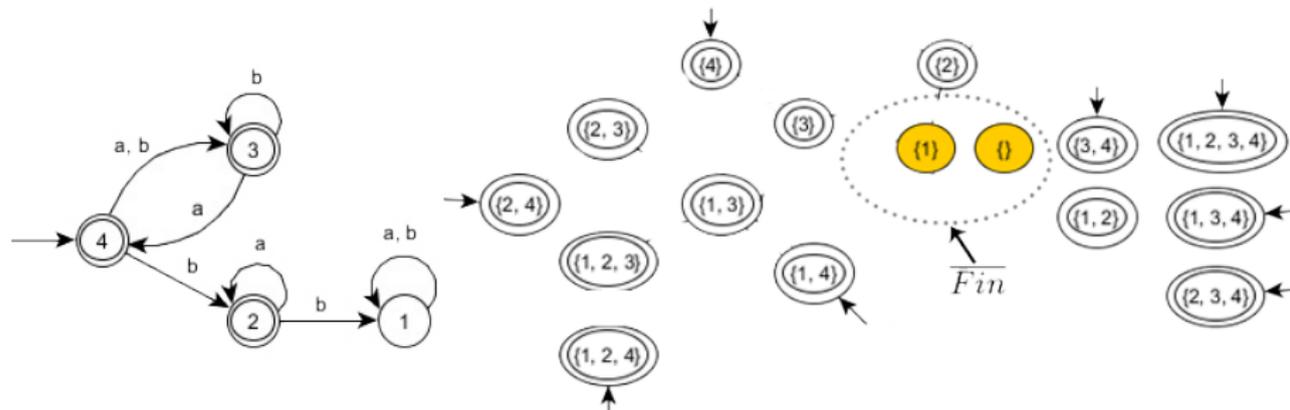
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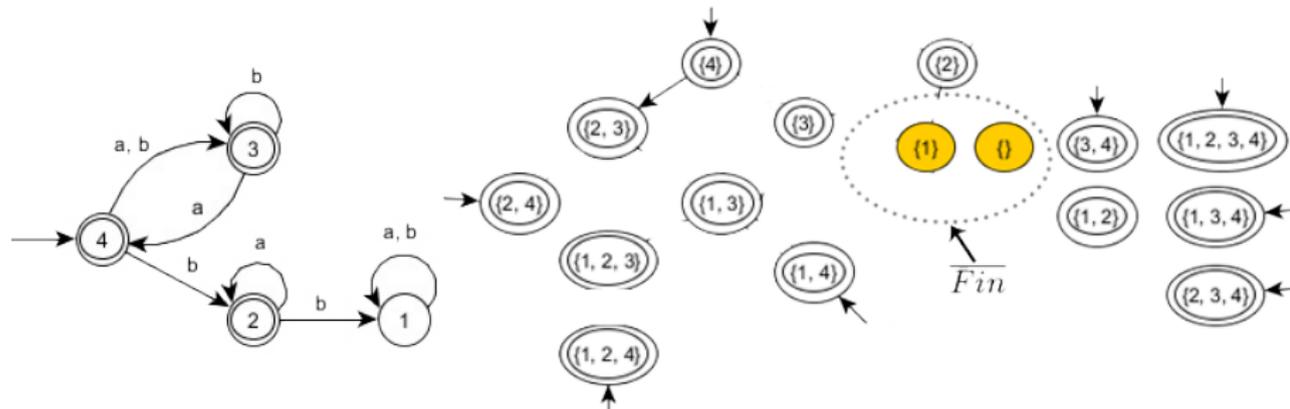
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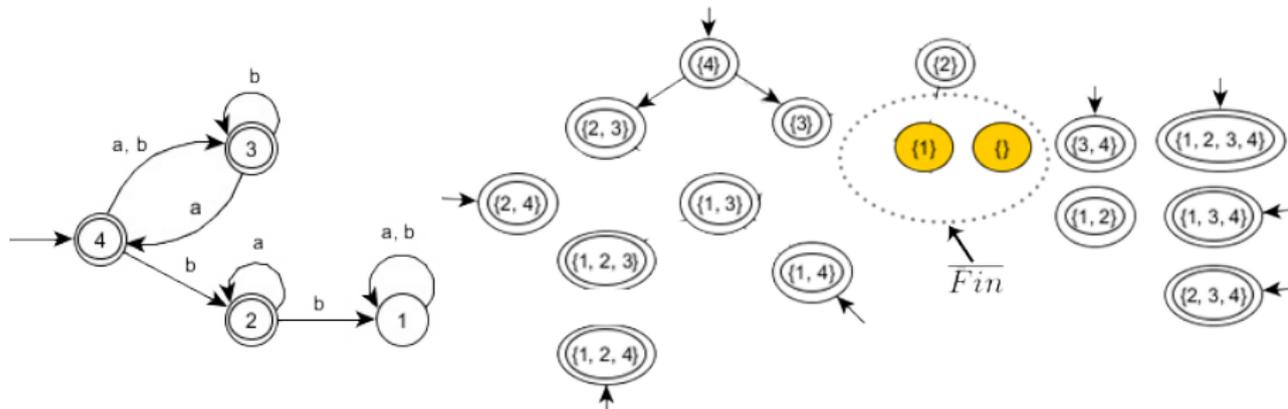
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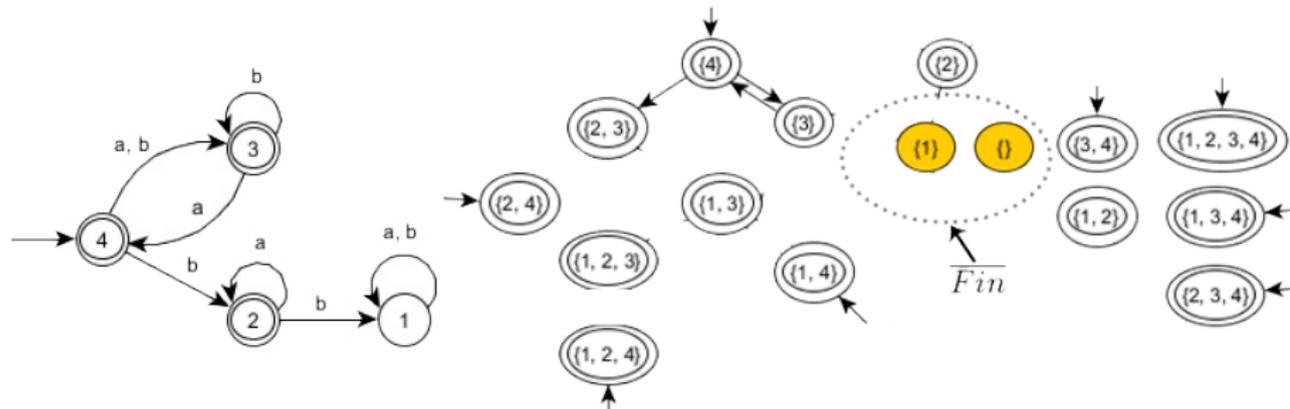
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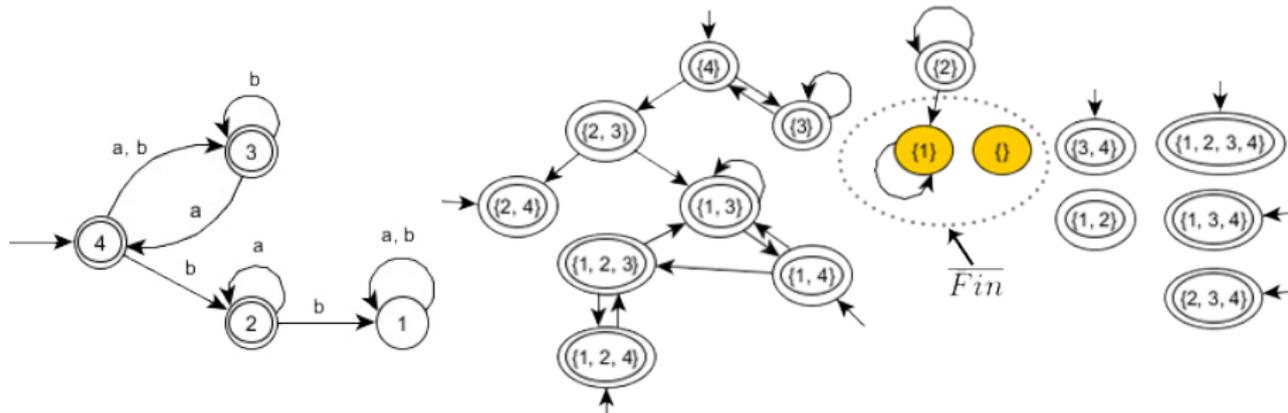
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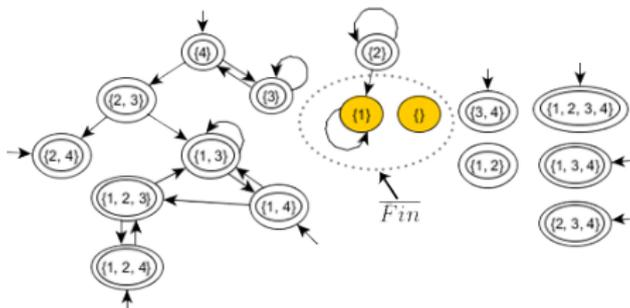
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Reachability problem in $G(A) = (V, E; In, \overline{Fin})$

- Asks if a subset $S \subseteq V$ is reachable from In .
- Where *Reachable* here means there is a *path* from In to S . This is v_1, \dots, v_n such that $(v_i, v_{i+1}) \in E$ for all $0 < i < n$ and $v_1 \in In$ and $v_n \in S$.

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Example

$S := \{\{1\}, \{1, 2, 3\}\}$ is reachable from In .

The predecessors of $S \subseteq V$ in $G(A) = (V, E; In, \overline{Fin})$

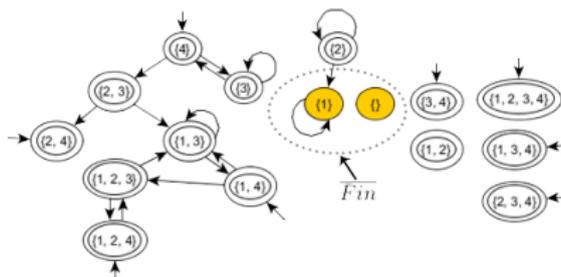
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$$pre(S) := \{v_1 \in V \mid \exists v_2 \in S : (v_1, v_2) \in E\}$$

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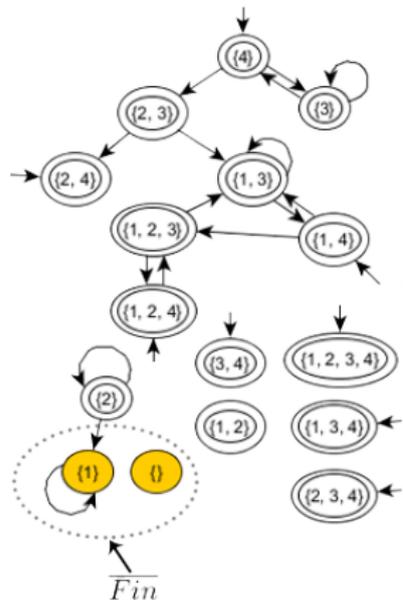
- Solves the reachability problem for $S \subseteq V$ by computing the monotone growing sequence of sets

$$B_0 = S; B_i = B_{i-1} \cup pre(B_{i-1})$$

Backward reachability fixpoint algorithm in $G(A) = (V, E; In, \overline{Fin})$

Example starting with \overline{Fin}

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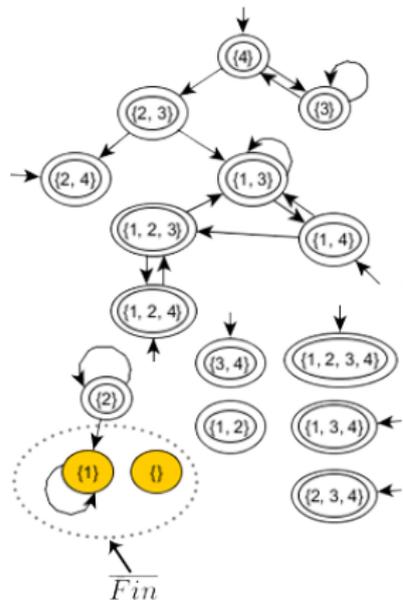


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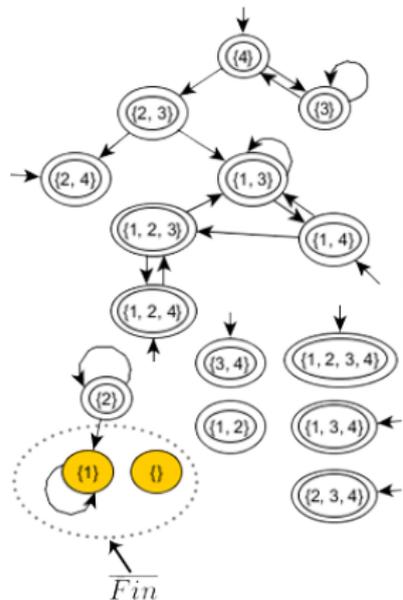
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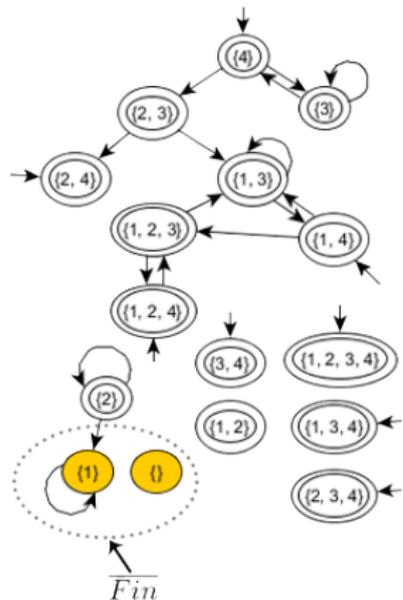
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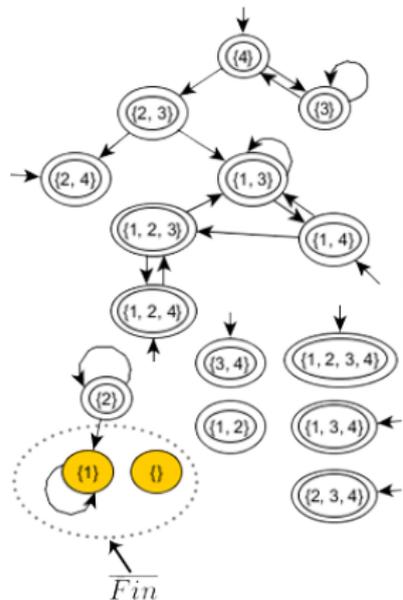
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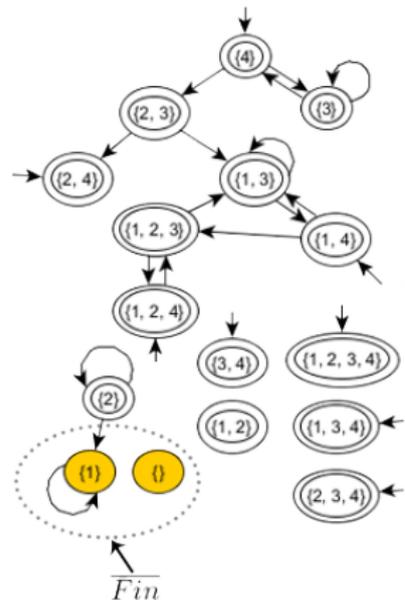
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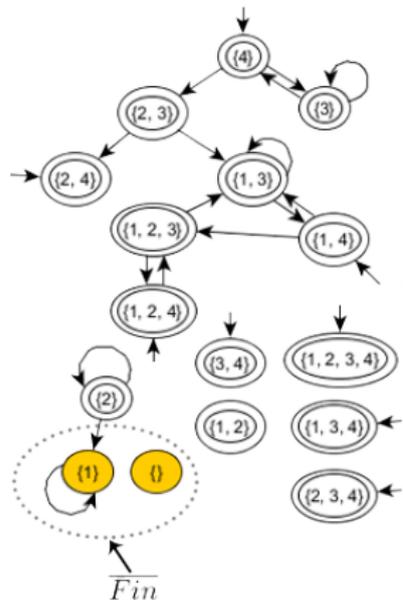
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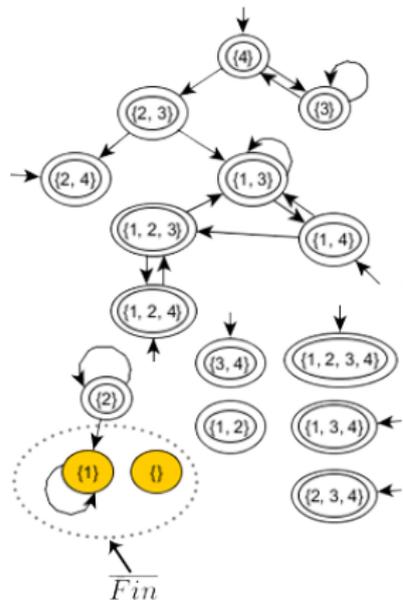
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Lemma 1

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Lemma 1

Given $G = (V, E; In, \overline{Fin})$ then $pre(S)$ is downward closed for all downward closed sets $S \subseteq V$

Lemma 2

\overline{Fin} is downward closed.

Antichain Backward reachability algorithm

Proof for Lemma 1

Proof " $pre(S)$ is downward closed for all downward closed S ."

Antichain Backward reachability algorithm

Proof for Lemma 1

Proof "*pre(S)* is downward closed for all downward closed *S*."

Let $S \subseteq V$ be downward closed. We need to show that

$$v_1 \in \text{pre}(S) \text{ and } v_2 \subseteq v_1 \Rightarrow v_2 \in \text{pre}(S)$$

Antichain Backward reachability algorithm

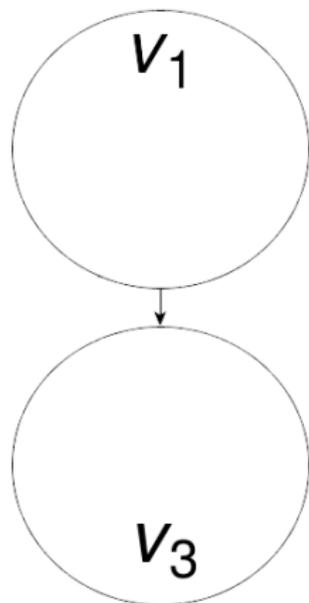
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Let $v_1 \in pre(S)$ this means there exists $v_3 \in S$ where $(v_1, v_3) \in E$ and a $\sigma \in \Sigma$ s.t. $\bigcup_{q \in v_1} \delta(q, \sigma) = v_3$



Antichain Backward reachability algorithm

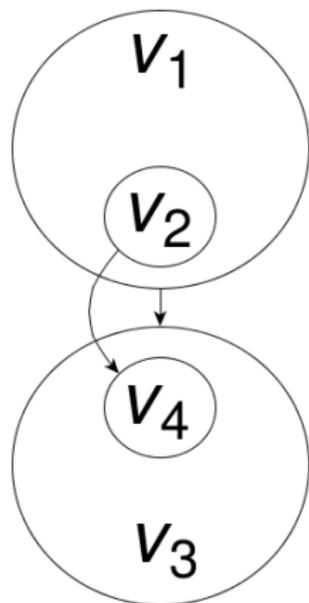
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Antichain Backward reachability algorithm

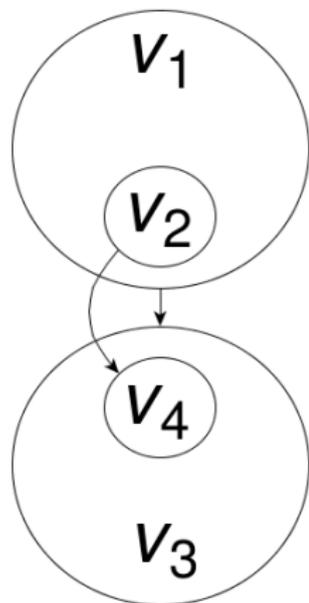
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Looking at $v_2 \subseteq v_1$ we get $\bigcup_{q \in v_2} \delta(q, \sigma) = v_4 \subseteq v_3$
Hence $v_2 \in pre(S)$ \square



Antichain Backward reachability algorithm

Proof for Lemma 2

Recap: Definition of \overline{Fin}

$$\overline{Fin} := \{v \in 2^{Loc} \mid v \subseteq Loc \setminus Fin\}$$

Proof " \overline{Fin} is downward closed."

If $v_1 \in \overline{Fin}$ and $v_2 \subseteq v_1$ then $v_2 \subseteq v_1 \subseteq Loc \setminus Fin$ hence $v_2 \in \overline{Fin}$ □

Antichain Backward reachability algorithm

- We extend the fixpoint algorithm

$$B_0 = S; B_i = B_{i-1} \cup \text{pre}(B_{i-1})$$

to the antichain fixpoint algorithm

$$\tilde{B}_0 = \text{Max}(\subseteq, S); \tilde{B}_i = \text{Max}(\subseteq, \tilde{B}_{i-1} \cup \text{pre}(\text{Down}(\subseteq, \tilde{B}_{i-1})))$$

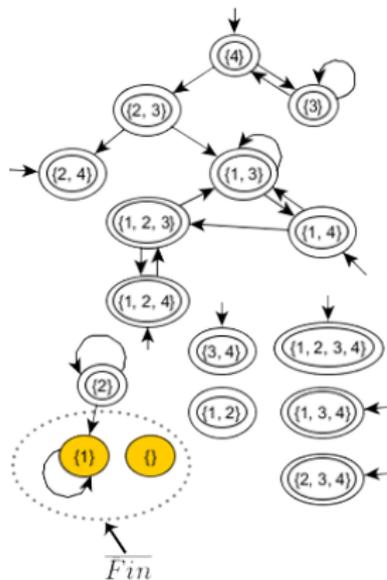
Antichain Backward reachability algorithm. Starting with $S = \overline{Fin} = \{\{\}, \{1\}\}$;

Example starting with \overline{Fin}

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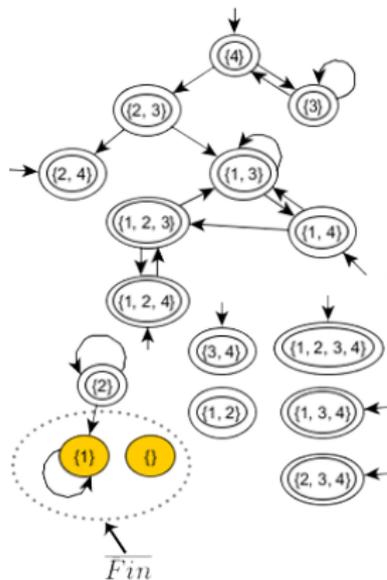
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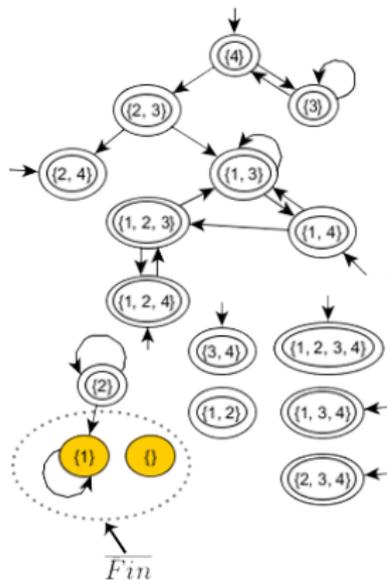
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$$\begin{aligned} \tilde{B}_1 &= \text{Max}(\subseteq, \{1\} \cup \text{pre}(\text{Down}(\subseteq, \{1\}))) \\ &= \text{Max}(\subseteq, \{1\} \cup \text{pre}(\{\{\}, \{1\}\})) \end{aligned}$$



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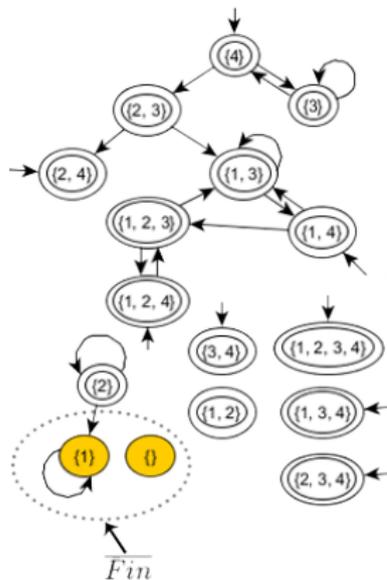
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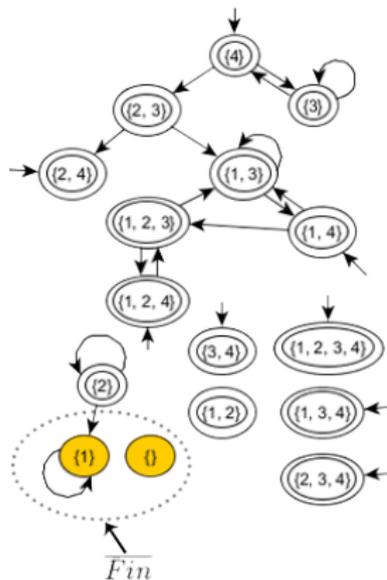
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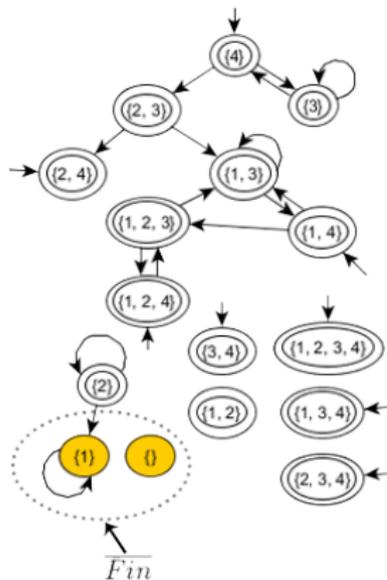
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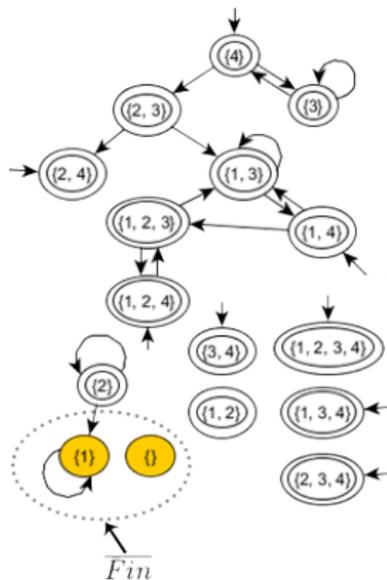
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Content

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Downward closure, Maximum

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Backward reachability fixpoint algorithm

Antichain Backward reachability algorithm

Conclusion

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Conclusion

- Antichains can be used as representations of closed sets.
- In the powerset construction \overline{Fin} is a downward closed set.
- On the powerset automaton $pre(S)$ for closed S is downward closed. Thus we can use antichains in the classic backward reachability algorithm.
- To be efficient, further improvements are possible and will be shown in antichain talk II.

References I

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