

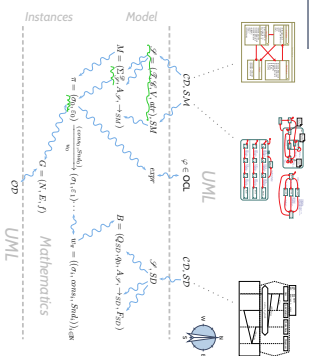
Software Design, Modelling and Analysis in UML

Lecture 2: Semantical Model

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Course Map



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Content

- Basic Object System Signature
 - (label) types, classes
 - typed attributes
 - attribute mapping
- Basic Object System Structure
 - objects / object identities
 - domains of base and derived types
- System State
 - concrete and symbolic
 - changing references
- A Complete Example

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Semantical Foundation

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Basic Object System Signature

Definition. A (Basic) Object System Signature is a quadruple $\mathcal{S} = (\mathcal{T}, \mathcal{K}, \mathcal{V}, \text{atr})$ where

- \mathcal{T} is a set of (basic) types
- \mathcal{K} is a finite set of classes
- \mathcal{V} is a finite set of typed attributes (i.e. each $v \in \mathcal{V}$ has a type $\tau \in \mathcal{T}$ or $\tau \in \mathcal{K}$ or $\tau \in \mathcal{C}$, where $\mathcal{C} \subseteq \mathcal{K}$)
- Written $v : \tau$ or $v : C_1$ or $v : C_2$

Handwritten notes: C_1, C_2 are classes; \mathcal{V} is the *domain of V*; atr maps each class to its set of attributes.

Note inspired by OCL 2.0 standard OMG (2006), Annex A

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Basic Object System Signature Example

$\mathcal{S} = (\mathcal{T}, \mathcal{K}, \mathcal{V}, \text{atr})$ where

- Basic types \mathcal{T} and classes \mathcal{K} (both finite)
- Typed attributes \mathcal{V}, τ from \mathcal{T} or \mathcal{C}_1 or \mathcal{C}_2 for some $C \in \mathcal{K}$
- $\text{atr} : \mathcal{K} \rightarrow 2^{\mathcal{V}}$ mapping classes to attributes

Example

$\mathcal{S} = (\{Int, \mathbb{R}\}, \{C, D\}, \{x : Int, y : C_1, z : C_2 \rightarrow \{0, 1\}, D \rightarrow \{x\}\})$

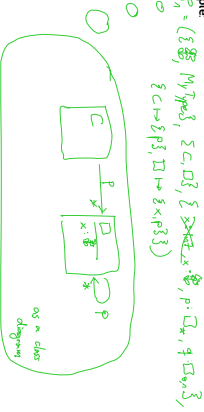
Handwritten notes: \mathcal{T} set of basic types: Int, \mathbb{R} ; \mathcal{K} set of classes: C, D; \mathcal{V} set of typed attributes: x, y, z; atr mapping classes to attributes: $\text{atr}(C) = \{y, z\}$, $\text{atr}(D) = \{x\}$.

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Basic Object System Signature Another Example

- $\mathcal{S} = (\mathcal{O}, \mathcal{V}, \text{attr})$ where
 - (boxed) types, \mathcal{S} and classes, \mathcal{C} (both finite)
 - typed attributes $V_i \rightarrow \mathcal{V}$ from \mathcal{S} or $C_{i,1}$ or $C_{i,2}$ for some $C \in \mathcal{C}$
 - $\text{attr}: \mathcal{V} \rightarrow 2^{\mathcal{V}}$ mapping classes to attributes

Example



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Basic Object System Structure

- Definition: A Basic Object System Structure of $\mathcal{S} = (\mathcal{O}, \mathcal{V}, \text{attr})$ is a domain function \mathcal{D} which assigns to each type a domain, i.e.
 - $\tau \in \mathcal{S}$ is mapped to $\mathcal{D}(\tau)$
 - $\mathcal{D}(\tau)$ is a set
 - $C \in \mathcal{C}$ is mapped to an finite set $\mathcal{D}(C)$ of (object) identities.

Note: Object identities only have the "=" operation.

Set of object identities for different classes are disjoint, i.e.

$$\forall C, D \in \mathcal{C} : C \neq D \Rightarrow \mathcal{D}(C) \cap \mathcal{D}(D) = \emptyset$$

C_1 and $C_{i,1}$, for $C \in \mathcal{C}$ are mapped to $2^{\mathcal{O}(C)}$.

$$\mathcal{D}(C_1) = \mathcal{D}(C_2) = \mathcal{D}(C_3) = \mathcal{D}(C_4) = 2^{\mathcal{O}(C)}$$

$$\mathcal{D}(C_1) = \bigcup_{C \in \mathcal{C}} \mathcal{D}(C)$$

We use $\mathcal{D}(\mathcal{O})$ to denote $\bigcup_{C \in \mathcal{C}} \mathcal{D}(C)$; analogously $\mathcal{D}(\mathcal{V})$ for $\mathcal{D}(V_i)$.

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Basic Object System Structure Example

Wanted a structure for signature

$$\mathcal{S}_0 = (\{int\}, \{C, D\}, \{a : int, p : C_{i,1}, w : C_1\}, \{C \mapsto \{m, n\}, D \mapsto \{a\}\})$$

\mathcal{S} needs to map:

- $\tau \in \mathcal{S}$ to some $\mathcal{D}(\tau)$
- $C \in \mathcal{C}$ to some set of identities $\mathcal{D}(C)$ (finite, disjoint for different classes)
- C_1 and $C_{i,1}$, for $C \in \mathcal{C}$ always mapped to $\mathcal{D}(C) = \mathcal{D}(C_{i,1}) = 2^{\mathcal{O}(C)}$

$$\begin{aligned} \mathcal{D}(int) &= \mathbb{Z} \\ \mathcal{D}(C) &= \mathbb{N} \times \{1, 2, 3, \dots\} \\ \mathcal{D}(D) &= \mathbb{N} \times \{1, 2, 3, \dots\} \\ \mathcal{D}(C_{i,1}) &= \mathcal{D}(C) = 2^{\mathcal{O}(C)} \\ \mathcal{D}(D_{i,1}) &= \mathcal{D}(D) = 2^{\mathcal{O}(D)} \end{aligned}$$

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System State

Definition: Let \mathcal{S} be a structure of $\mathcal{S} = (\mathcal{O}, \mathcal{V}, \text{attr})$. A system state of \mathcal{S} wrt. \mathcal{S} is a **finite** mapping

$$\sigma : \mathcal{O} \rightarrow \bigcup_{\tau \in \mathcal{S}} (V_i \rightarrow \mathcal{D}(\tau)) \cup \mathcal{D}(\mathcal{O})$$

finite means: union of all domains $\mathcal{D}(\tau)$ and all values of typed attributes

That is for each $v \in \mathcal{O}(C)$, $C \in \mathcal{C}$, if $v \in \text{dom}(\sigma)$

- $\text{dom}(\sigma(v)) = \text{attr}(C)$
- $\sigma(v)(v) \in \mathcal{D}(V_i)$ if $v : \tau \in \mathcal{S}$
- $\sigma(v)(v) \in \mathcal{D}(D)$ if $v : D_{i,1}$ or $v : D$, with $D \in \mathcal{C}$

We call $v \in \mathcal{O}(\mathcal{S})$ alive in σ if and only if $v \in \text{dom}(\sigma)$.

We use $2_{\mathcal{S}}$ to denote the set of all system states of \mathcal{S} wrt. \mathcal{S} .

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System State Example

$$\begin{aligned} \mathcal{S}_0 &= (\{int\}, \{C, D\}, \{a : int, p : C_{i,1}, w : C_1\}, \{C \mapsto \{m, n\}, D \mapsto \{a\}\}) \\ \mathcal{D}(int) &= \mathbb{Z}, \mathcal{D}(C) = \{1, 2, 3, \dots\}, \mathcal{D}(D) = \{1, 2, 3, \dots\} \end{aligned}$$

Wanted $\sigma : \mathcal{O}(\mathcal{S}) \rightarrow (V_i \rightarrow \mathcal{D}(\tau)) \cup \mathcal{D}(\mathcal{O})$ such that $\text{dom}(\sigma(v)) = \text{attr}(C)$ and $\sigma(v)(v) \in \mathcal{D}(V_i)$ if $v : \tau \in \mathcal{S}$, $\sigma(v)(v) \in \mathcal{D}(C)$ if $v : D$, with $D \in \mathcal{C}$.

$$\begin{aligned} \sigma_1 &= \emptyset \text{ ("empty" function)} \\ \text{alive } \sigma_1 &= \emptyset \\ \sigma_2 &= \{1, 2, 3, \dots\} \mapsto \{1, 2, 3, \dots\} \\ \sigma_3 &= \{1, 2, 3, \dots\} \mapsto \{1, 2, 3, \dots\} \end{aligned}$$

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System State Example

$$\begin{aligned} \mathcal{S}_0 &= (\{int\}, \{C, D\}, \{a : int, p : C_{i,1}, w : C_1\}, \{C \mapsto \{m, n\}, D \mapsto \{a\}\}) \\ \mathcal{D}(int) &= \mathbb{Z}, \mathcal{D}(C) = \{1, 2, 3, \dots\}, \mathcal{D}(D) = \{1, 2, 3, \dots\} \end{aligned}$$

Wanted $\sigma : \mathcal{O}(\mathcal{S}) \rightarrow (V_i \rightarrow \mathcal{D}(\tau)) \cup \mathcal{D}(\mathcal{O})$ such that $\text{dom}(\sigma(v)) = \text{attr}(C)$ and $\sigma(v)(v) \in \mathcal{D}(V_i)$ if $v : \tau \in \mathcal{S}$, $\sigma(v)(v) \in \mathcal{D}(C)$ if $v : D$, with $D \in \mathcal{C}$.

Two options:

- Concrete, explicit identities
- Alternative: symbolic system state

$$\begin{aligned} \sigma &= \{1, 2, 3, \dots\} \mapsto \{1, 2, 3, \dots\} \\ \sigma &= \{1, 2, 3, \dots\} \mapsto \{1, 2, 3, \dots\} \end{aligned}$$

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System State: Spot the 10 (?) Mistakes

$$\mathcal{S}_A = \{(M), (C,D); (x: int, p: C_{0,1}, n: C); (C \rightarrow \{n,n\}, D \rightarrow \{x\})\}$$

$$\mathcal{S}(M) = \mathcal{Z}, \quad \mathcal{S}(C) = \{1, 2, 3, \dots\}, \quad \mathcal{S}(D) = \{1, 2, 3, 5, \dots\}$$

Warning: $\sigma: \mathcal{S}(C) \rightarrow C = (\mathcal{S}(C) \cup \mathcal{S}(C))$ such that $\text{dom}(\sigma) = \text{dom}(C)$ and $\{\sigma(c) \in C \mid c \in \mathcal{S}(C)\} \cap \mathcal{S} = \emptyset$. $\{\sigma(c) \in \mathcal{S}(C) \mid c \in \mathcal{S}(C)\} \cap \mathcal{S} = \text{dom}(C)$, with $D \in \mathcal{C}$.

- $\sigma = \{(C \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}), \{c \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}, 1 \rightarrow \{x \rightarrow 23\}\}$
- $\sigma = \{(C \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}), \{c \rightarrow \{p \rightarrow \{c, \theta\}, n \rightarrow \{c\}\}, \{p \rightarrow \{x \rightarrow 23\}\}$
- $\sigma = \{(C \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}), \{c \rightarrow \{p \rightarrow \theta, n \rightarrow \theta\}, 1 \rightarrow \{x \rightarrow 23\}\}$
- $\sigma = \{(C \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}), \{c \rightarrow \{p \rightarrow \theta\}, 1 \rightarrow \{x \rightarrow 23\}\}$
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- $\sigma = \{(C \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}), \{c \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}, \{c \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\}\}$

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Dangling References

Definition: Let $\sigma \in \Sigma_{\mathcal{S}}$ be a system state. We say attribute $a \in M_{\mathcal{S}}$, i.e. $a: C_{0,1}$ or $a: C_{1,1}$ in object $u \in \text{dom}(C)$ has a dangling reference if and only if the address value $\sigma(u.a)$ is not alive in σ , i.e. $\sigma(u.a) \notin \text{dom}(\sigma)$. We call σ closed if and only if no attribute has a dangling reference in any object alive in σ .

- Example**
- $\sigma = \{(C \rightarrow \{p \rightarrow \theta, n \rightarrow \{c\}\})\}$

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A Complete Example: Venturing Machine Structure



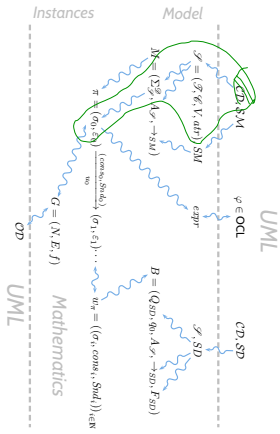
$\mathcal{S} = \{ \{ \text{int}, \text{Bool} \}, \{ \text{VM}, \text{CP}, \text{DD} \}, \{ \text{cp} : \text{CP} \rightarrow \text{dd} : \text{DD}, \text{vm} : \text{VM} \rightarrow \text{vm} : \text{Bool} \}, \{ \text{VM} \rightarrow \{ \text{cp}, \text{dd} \}, \{ \text{CP} \rightarrow \{ \text{vm} \}, \{ \text{DD} \rightarrow \{ \text{vm} \} \} \}$

$\text{dom}(\text{VM}) = \{ \text{VM}, \text{VM} \}$
 $\text{dom}(\text{CP}) = \{ \text{CP} \}$
 $\text{dom}(\text{DD}) = \{ \text{DD} \}$

$\sigma = \{ \{ \text{VM} \rightarrow \{ \text{vm} \}, \text{CP} \rightarrow \{ \text{cp} \}, \text{DD} \rightarrow \{ \text{dd} \}, \text{vm} \rightarrow \{ \text{vm} \}, \text{cp} \rightarrow \{ \text{cp} \}, \text{dd} \rightarrow \{ \text{dd} \} \}$

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Course Map



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Tell Them What You've Told Them...

- We can directly use object system signatures to notate the structure of systems. \rightarrow We don't need diagrams, they will be more pleasant to read.
- We introduce
 - basic types and classes,
 - basic type and derived type attributes, and
 - assign to each class a set of attributes.
- Object system structures provide domains for base and derived types.
- An object system signature \mathcal{S} and an object system structure σ uniquely define the set $\Sigma_{\mathcal{S}}$ of system states.
- Outlook:**
 - Object system signatures will be used to capture the abstract syntax of class diagrams.
 - OCL expressions will be evaluated on system states.
 - State machines will define sequences of system configurations (consisting of a system state and an theta).

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You Are Here

References

- OMG Z006, Object Constraint Language version 2.0, Technical Report Formal/06-05-01
- OMG Z014, Unified modeling language: Infrastructure, version 2.4.1, Technical Report Formal/Z014-08-05
- OMG Z018, Unified modeling language: Superstructure, version 2.4.1, Technical Report Formal/Z018-08-06

References

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