

# *Software Design, Modelling and Analysis in UML*

## *Lecture 7: Class Diagrams II*

2016-11-17

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-7-2016-11-17-main-

### Content

- **Rhapsody Demo I: Class Diagrams**
- **Visibility**
  - **Intuition**
  - **Context**, OCL with Visibility
  - What is Visibility **Good For**?
- **Associations**
  - Overview & Plan
  - (Temporarily) **Extend Signature**
  - From **Diagrams** to Signatures
    - What if Things are Missing?

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## *Rhapsody Demo I: Class Diagrams*

RECALL, SENDS US YOUR POOL-ACCOUNT NAME  
(myself, NOT: mp124 (RZ))

## *Class Diagram Semantics Cont'd*

## Semantical Relevance

- The **semantics** (or meaning) of an extended object system signature  $\mathcal{S}$  wrt. a structure  $\mathcal{D}$  is **the set of system states**  $\Sigma_{\mathcal{D}}^{\mathcal{S}}$ .
- The **semantics** (or meaning) of an extended object system signature  $\mathcal{S}$  is **the set of sets of system states** wrt. some structure of  $\mathcal{S}$ , i.e. the set

$$\{\Sigma_{\mathcal{D}}^{\mathcal{S}} \mid \mathcal{D} \text{ is structure of } \mathcal{S}\}.$$

$\mathcal{S}_1: \langle C, \emptyset, \emptyset, \emptyset \rangle$   
 $\Sigma_{\mathcal{D}_1}^{\mathcal{S}_1} = \dots$   
 $\mathcal{S}_2: \langle C, \emptyset, \emptyset, \tau \rangle$   
 $\Sigma_{\mathcal{D}_2}^{\mathcal{S}_2} = \dots$   
*(only difference is  $\mathcal{S}_1, \mathcal{S}_2$  is activities of  $C$ )*

Which of the following aspects is **semantically relevant**, i.e. **does contribute** to the constitution of system states?

### A class

- has a set of **stereotypes**, ✗
- has a **name**, ✓
- belongs to a **package**, ✓
- can be **abstract**, ✓
- can be **active**, ✗
- has a set of **attributes**, ✓
- has a set of **operations** (later), ✓

### Each attribute has

- a **visibility**, ✗
- a **name**, a **type**, ✓
- a **multiplicity**, an **order**, ✗
- an **initial value**, and ✗
- a set of **properties**, (✗) such as **readOnly**, **ordered**, etc.

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## What About The Rest?

- Classes:**
  - Stereotypes:** Lecture 6
  - Active:** not represented in  $\sigma$ .  
**Later:** relevant for behaviour, i.e., how system states evolve over time.
- Attributes:**
  - Initial value expression:** not represented in  $\sigma$ .  
**Later:** provides an initial value as effect of "creation action".
  - Visibility:** not represented in  $\sigma$ .  
**Later:** viewed as additional **typing information** for well-formedness of OCL expressions and actions. *- typeness*
  - Properties:** such as `readOnly`, `ordered`, `composite` (**Deprecated** in the standard.)
    - `readOnly` – can be treated **similar to visibility**.
    - `ordered` – not considered in our UML fragment ( $\rightarrow$  sets vs. sequences).
    - `composite` – cf. lecture on associations.

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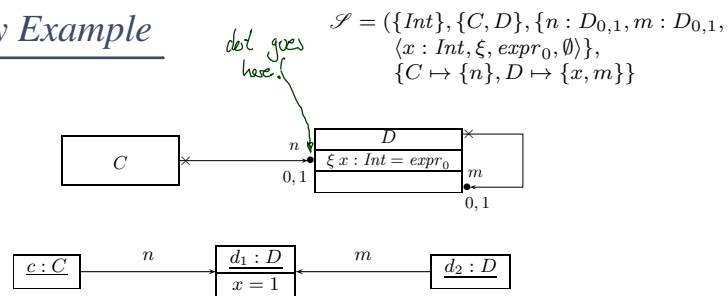
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# Visibility

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## The Intuition by Example



Which of the following two **syntactically correct** (?) OCL expressions should we consider to be **well-typed**?

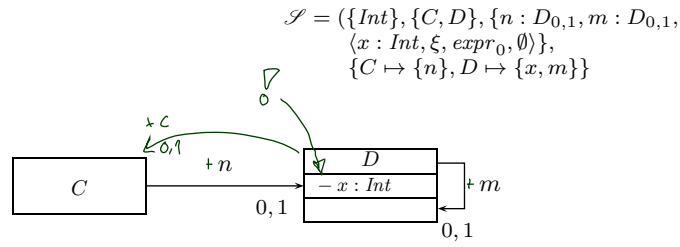
	$\xi = \text{public}$	$\xi = \text{private}$	$\xi = \text{protected}$	$\xi = \text{package}$
$self_C . n . x = 0$	✓ $\llcorner \llcorner \llcorner \llcorner$ ✗ - ?	✓ - ✗ $\llcorner \llcorner \llcorner \llcorner$ ?	later	not in lect. by class (C++, Java, ...)
$self_D . m . x = 0$	✓ $\llcorner \llcorner \llcorner \llcorner$ ✗ - ?	✓ $\llcorner \llcorner \llcorner \llcorner$ ✗    ?	later	not in lect. by object

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## Context

- By example:



$$\frac{}{\tau_D} \text{self}_D . x > 0 \quad \checkmark$$

$$\frac{}{\tau_D} \text{self}_D . m . x > 0 \quad \checkmark$$

$$\frac{}{\tau_C} \text{self}_C . n . x > 0 \quad \times$$

- That is, whether an expression involving attributes with visibility is well-typed **depends** on the class of the object which "tries to read out the value".
- Visibility is 'by class' – **not** 'by object'.

$$\frac{}{\tau_D} \text{self}_D . c . n . x > 0 \quad \checkmark$$

$$\frac{}{\tau_C} \text{self}_C . n . c . n . x > 0 \quad \times$$

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## Attribute Access in Context

**Recall:** attribute access in OCL Expressions,  $C, D \in \mathcal{C}$ .

$v(expr_1) : \tau_C \rightarrow \tau(v)$	$v : T \in atr(C), T \in \mathcal{T}$
$r_1(expr_1) : \tau_C \rightarrow \tau_D$	$r_1 : D_{0,1} \in atr(C)$
$r_2(expr_1) : \tau_C \rightarrow Set(\tau_D)$	$r_2 : D_* \in atr(C)$

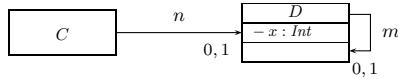
### New rules for well-typedness considering visibility:

- $v(w) : \tau_C \rightarrow T$   $w : \tau_C, v : T \in atr(C), T \in \mathcal{T}$
- $r_1(w) : \tau_C \rightarrow \tau_D$   $w : \tau_C, r_1 : D_{0,1} \in atr(C)$
- $r_2(w) : \tau_C \rightarrow Set(\tau_D)$   $w : \tau_C, r_1 : D_* \in atr(C)$
  
- $v(\underbrace{expr_1(w)}_{\underbrace{\omega_1(\dots(\omega_n(w))\dots)}}) : \tau_C \rightarrow T$   $\langle v : T, \xi, expr_0, P \rangle \in atr(C), T \in \mathcal{T},$   
 $expr_1(w) : \tau_C, w : \tau_{C_1}$  and  $C_1 = C,$  or  $\xi = +$
- $r_1(\underbrace{expr_1(w)}_{\underbrace{\omega_1(\dots(\omega_n(w))\dots)}}) : \tau_C \rightarrow \tau_D$   $\langle r_1 : D_{0,1}, \xi, expr_0, P \rangle \in atr(C),$   
 $expr_1(w) : \tau_C, w : \tau_{C_1}$  and  $C_1 = C,$  or  $\xi = +$
- $r_2(\underbrace{expr_1(w)}_{\underbrace{\omega_1(\dots(\omega_n(w))\dots)}}) : \tau_C \rightarrow Set(\tau_D)$   $\langle r_2 : D_*, \xi, expr_0, P \rangle \in atr(C),$   
 $expr_1(w) : \tau_C, w : \tau_{C_1}$  and  $C_1 = C,$  or  $\xi = +$

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## Example

(i) $v(w)$	$: \tau_C \rightarrow T$	$w : \tau_C, v : T \in \text{atr}(C), T \in \mathcal{T}$
(ii) $r_1(w)$	$: \tau_C \rightarrow \tau_D$	$w : \tau_C, r_1 : D_{0,1} \in \text{atr}(C)$
(iii) $v(\text{expr}_1(w))$	$: \tau_C \rightarrow T$	$\langle v : T, \xi, \text{expr}_0, P \rangle \in \text{atr}(C), T \in \mathcal{T},$ $\text{expr}_1(w) : \tau_C, w : \tau_{C_1}$ and $C_1 = C$ , or $\xi = +$
(iv) $r_1(\text{expr}_1(w))$	$: \tau_C \rightarrow \tau_D$	$\langle r_1 : D_{0,1}, \xi, \text{expr}_0, P \rangle \in \text{atr}(C),$ $\text{expr}_1(w) : \tau_C, w : \tau_{C_1}$ and $C_1 = C$ , or $\xi = +$



- $\text{self}_D . x > 0 \rightsquigarrow x(\text{self}_D) > 0$  OK, by (i)
- $\text{self}_D . m . x > 0 \rightsquigarrow x(\underbrace{u(\text{self}_D)}_{\substack{:\tau_C \\ \tau_D}}) > 0$  OK, by (iii)
- $\text{self}_C . n . x > 0 \rightsquigarrow x(\underbrace{u(\text{self}_C)}_{\substack{:\tau_C \\ \tau_D}}) > 0$  NOT OK

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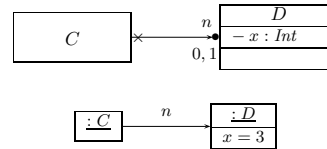
## The Semantics of Visibility

- **Observation:**
  - Whether an expression **does** or **does not** respect visibility is **a matter of well-typedness only**.
  - We only evaluate (= apply  $I$  to) **well-typed** expressions.
- We **need not** adjust the interpretation function  $I$  to support visibility.  
 Just decide: should we take visibility into account yes / no, and check well-typedness by the new / old rules.

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## What is Visibility Good For?



- Visibility is a property of attributes – is it useful to consider it in OCL?
- In other words: given the diagram above, **is it useful** to state the following invariant (even though  $x$  is private in  $D$ )

context  $C$  inv :  $n.x > 0$  ?

(cf. [OMG \(2006\)](#), Sect. 12 and 9.2.2)

### It depends.

- **Constraints and pre/post conditions:**

- Visibility is **sometimes not** taken into account. To state “global” requirements, it may be adequate to have a “global view”, i.e. be able to “look into” all objects.
- But: visibility supports “narrow interfaces”, “information hiding”, and similar **good design practices**. To be more robust against changes, try to state requirements only in the terms which are visible to a class.

**Rule-of-thumb:** if attributes are important to state requirements on design models, leave them public or provide get-methods (later).

- **Guards and operation bodies:**

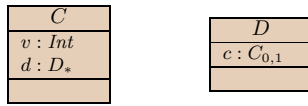
- If in doubt, **yes** (= do take visibility into account).

Any so-called **action language** typically takes visibility into account.

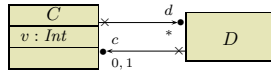
## Associations

# Overview

- **Class diagram:**



- **Alternative presentation:**



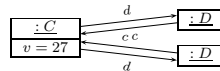
- **Signature:**

$$\mathcal{S} = (\{Int\}, \{C, D\}, \{v : Int, d : D^*, c : C_{0,1}\}, \{C \mapsto \{v, d\}, D \mapsto \{c\}\})$$

- **Example system state:**

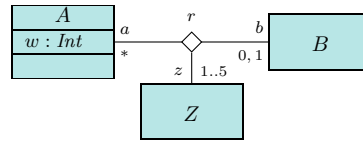
$$\sigma = \{1_C \mapsto \{v \mapsto 27, d \mapsto \{5_D, 7_D\}\}, 5_D \mapsto \{c \mapsto \{1_C\}\}, 7_D \mapsto \{c \mapsto \{1_C\}\}\}$$

- **Object diagram:**



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- **Class diagram (with ternary association):**



- **Signature:** extend again to represent

- **association**  $r$  with
- **association ends**  $a, b,$  and  $z$  (each with multiplicity, visibility, etc.)

- **Example system state:**  $(\sigma, \lambda)$

$$\sigma = \{1_A \mapsto \{w \mapsto 13\}, 1_B \mapsto \emptyset, 1_Z \mapsto \emptyset\}$$

$$\lambda = \{r \mapsto \{(1_A, 1_B, 1_Z), (1_A, 1_B, 2_Z)\}\}$$



- **Object diagram:** No...

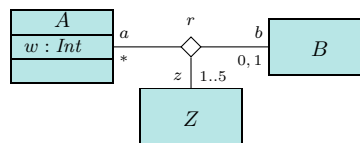
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# Plan

- Study association **syntax**.
- Extend **signature** accordingly.
- Define  $(\sigma, \lambda)$  **system states** with
  - **objects** in  $\sigma$  (instances of classes),
  - **links** in  $\lambda$  (instances of associations).
- Change **syntax** of OCL to refer to **association ends**.
- Adjust **interpretation**  $I$  accordingly.
- ... go back to the special case of  $C_{0,1}$  and  $C_*$  attributes.

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- **Class diagram (with ternary association):**



- **Signature:** extend again to represent

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- **Example system state:**

$$\sigma = \{1_A \mapsto \{w \mapsto 13\}, 1_B \mapsto \emptyset, 1_Z \mapsto \emptyset\}$$

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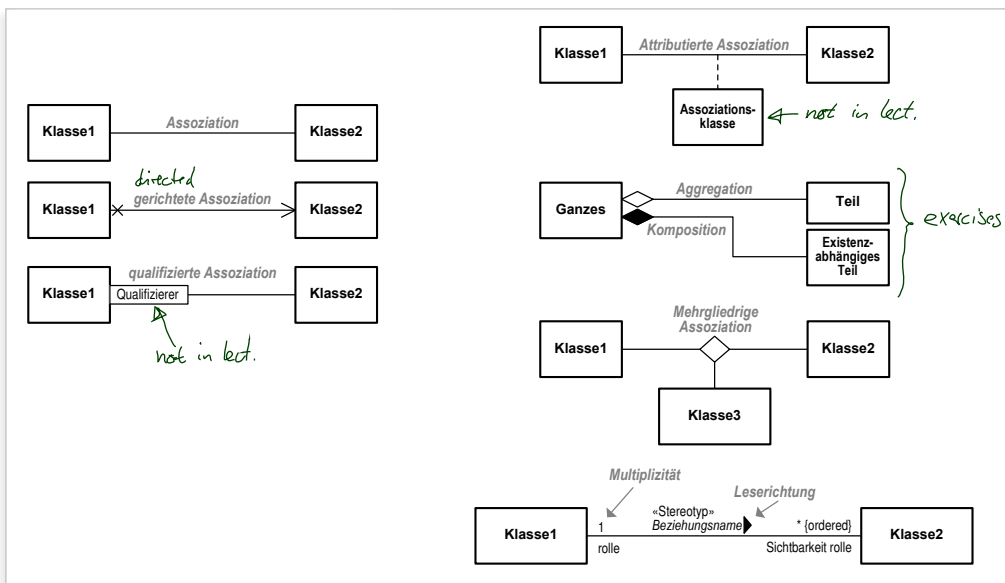
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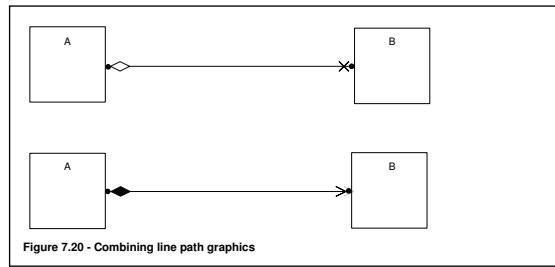
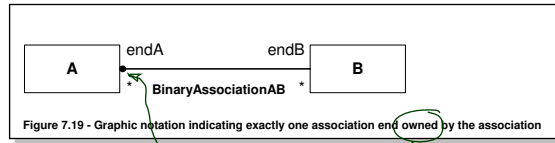
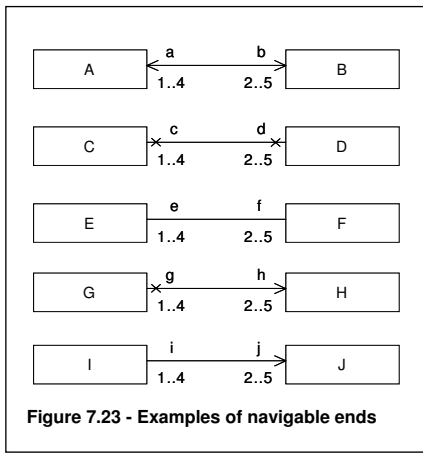
# Associations: Syntax

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## UML Association Syntax Oestereich (2006)



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### So, What Do We (Have to) Cover?

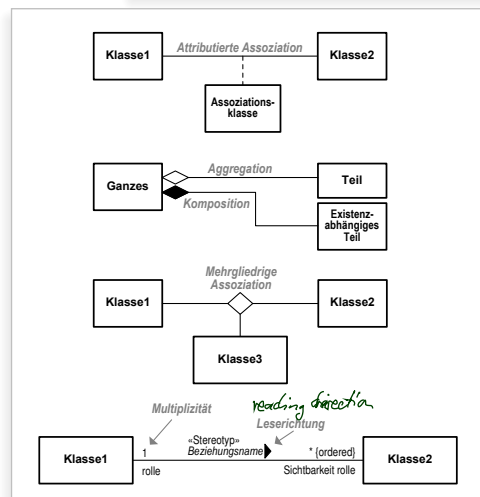
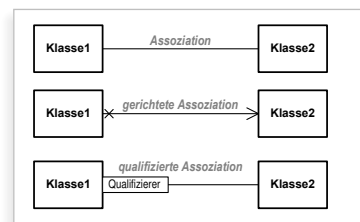
An **association** has

- a **name**,
- a **reading direction**, and
- at least two **ends**.

Each **end** has

- a **role name**,
- a **multiplicity**,
- a set of **properties**, such as **unique**, **ordered**, etc.
- a **qualifier**, (not in lect.)
- a **visibility**,
- a **navigability**,
- an **ownership**,
- and possibly a **diamond**.

**Wanted:** places in the signature to represent the information from the picture.



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## (Temporarily) Extend Signature: Associations

Only for the course of Lectures 7 – 9 we assume that each element in  $V$  is

- either a **basic type attribute**  $\langle v : T, \xi, expr_0, P_v \rangle$  with  $T \in \mathcal{T}$  (as before),
- or an **association** of the form

$$\langle r : \begin{array}{l} \langle role_1 : C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle, \\ \vdots \\ \langle role_n : C_n, \mu_n, P_n, \xi_n, \nu_n, o_n \rangle \end{array} \rangle$$

- $n \geq 2$  (at least two ends),
- $r, role_i$  are just **names**,  $C_i \in \mathcal{C}, 1 \leq i \leq n$ ,
- the **multiplicity**  $\mu_i$  is an expression of the form

$$\mu ::= N..M \mid N..* \mid \mu, \mu \quad (N, M \in \mathbb{N})$$

$\begin{array}{l} 0..1 \checkmark \\ 10..27, 30..31 \checkmark \\ 3..3 \checkmark \\ 0..* \checkmark \end{array}$

- $P_i$  is a set of **properties** (as before),
- $\xi \in \{+, -, \#, \sim\}$  (as before),
- $\nu_i \in \{\times, -, >\}$  is the **navigability**,
- $o_i \in \mathbb{B}$  is the **ownership**.

- $N$  for  $N..N$ ,
- $*$  for  $0..*$  (use with care!)

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## (Temporarily) Extend Signature: Associations

Only for the course of Lectures 7 – 9 we assume that each element in  $V$  is

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- $n \geq 2$  (at least two ends),
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$$\mu ::= N..M \mid N..* \mid \mu, \mu \quad (N, M \in \mathbb{N})$$

- $P_i$  is a set of **properties** (as before),
- $\xi \in \{+, -, \#, \sim\}$  (as before),
- $\nu_i \in \{\times, -, >\}$  is the **navigability**,
- $o_i \in \mathbb{B}$  is the **ownership**.

### Multiplicity abbreviations:

- $N$  for  $N..N$ , e.g. 3 for 3..3
- $*$  for  $0..*$  (use with care!)

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## Temporarily (Lecture 7 – 9) Extended Signature

**Definition.** An (Extended) Object System **Signature** (with Associations) is a quadruple  $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$  where

- ...
- each element of  $V$  is
  - either a **basic type attribute**  $\langle v : T, \xi, expr_0, P_v \rangle$  with  $T \in \mathcal{T}$
  - or an **association** of the form
$$\langle r : \begin{array}{l} \langle role_1 : C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle, \\ \vdots \\ \langle role_n : C_n, \mu_n, P_n, \xi_n, \nu_n, o_n \rangle \end{array} \rangle$$
(ends with multiplicity  $\mu_i$ , properties  $P_i$ , visibility  $\xi_i$ , navigability  $\nu_i$ , ownership  $o_i$ ,  $1 \leq i \leq n$ )
- ...
- $atr : \mathcal{C} \rightarrow 2^{\{v \in V \mid v:T, T \in \mathcal{T}\}}$  maps classes to **basic type (!)** attributes.

In other words:

- only **basic type attributes** “belong” to a class (may appear in  $atr(C)$ ),
- **associations** are not “owned” by a class (not in any  $atr(C)$ ), but “live on their own”.

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## Tell Them What You've Told Them...

- Class Diagrams in the **Rhapsody** Tool
- **Visibility** of attributes contributes to the well-typedness of (among others) OCL expressions.
  - Well-typedness depends on the **context**.
  - We only interpret (= apply  $I$  to) **well-typed** OCL constraints.
  - Sometimes we **consider** visibility, sometimes we don't.
- **Associations** can have any number ( $\geq 2$ ) of **Association Ends**.

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## *References*

## *References*

Oestereich, B. (2006). *Analyse und Design mit UML 2.1, 8. Auflage*. Oldenbourg, 8. edition.

OMG (2006). Object Constraint Language, version 2.0. Technical Report formal/06-05-01.

OMG (2011a). Unified modeling language: Infrastructure, version 2.4.1. Technical Report formal/2011-08-05.

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