

# *Software Design, Modelling and Analysis in UML*

## *Lecture 21: Model-based Software Development*

2017-02-06

Prof. Dr. Andreas Podelski, Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

-21-2017-02-06-main-

### Content

- **Live Sequence Charts**
  - **Semantics**
    - **Full LSCs**
      - **Existential and Universal**
      - **Pre-Charts**
      - **Forbidden Scenarios**
    - **LSCs and Tests**
  
- **Model-Based/-Driven Software Engineering**
  - **Model Element Coverage** of test cases
  - **Model-based Testing**

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## Live Sequence Charts — Full LSC Semantics

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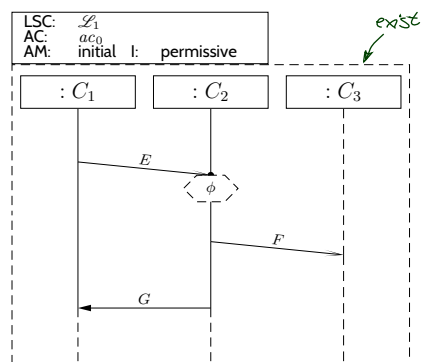
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### Full LSCs

A **full LSC**  $\mathcal{L} = (((L, \preceq, \sim), \mathcal{I}, \text{Msg}, \text{Cond}, \text{LocInv}, \Theta), ac_0, am, \Theta_{\mathcal{L}})$  consists of

- **body**  $((L, \preceq, \sim), \mathcal{I}, \text{Msg}, \text{Cond}, \text{LocInv}, \Theta)$ ,
- **activation condition**  $ac_0 \in \text{Expr}_{\mathcal{L}}$ ,
- **strictness flag**  $strict$  (if  $false$ ,  $\mathcal{L}$  is called **permissive**)
- **activation mode**  $am \in \{\text{initial}, \text{invariant}\}$ ,
- **chart mode** **existential** ( $\Theta_{\mathcal{L}} = \text{cold}$ ) or **universal** ( $\Theta_{\mathcal{L}} = \text{hot}$ ).

**Concrete syntax:**



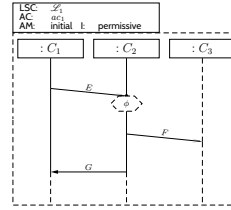
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# Full LSCs

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A set of words  $W \subseteq (\text{Expr}_{\mathcal{B}} \rightarrow \mathbb{B})^{\omega}$  is **accepted** by  $\mathcal{L}$  if and only if

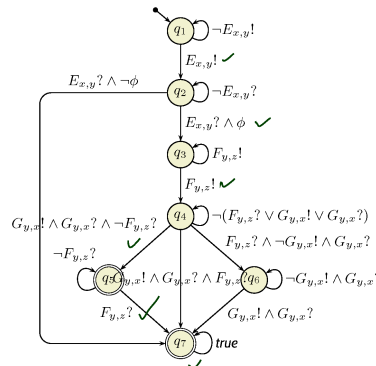
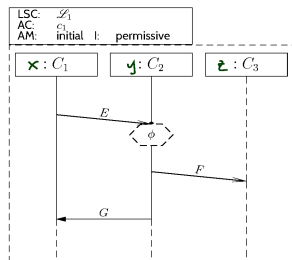
$\Theta_{\mathcal{L}}$	$am = \text{initial}$	$am = \text{invariant}$
<b>cold</b>	$\exists \beta \exists w \in W \bullet w^0 \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0)$ $\wedge w^0 \models_{\beta} \psi_{\text{prog}}(\emptyset, C_0) \wedge w/1 \in \mathcal{L}_{\beta}(\mathcal{B}(\mathcal{L}))$	$\exists \beta \exists w \in W \exists k \in \mathbb{N}_0 \bullet w^k \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0)$ $\wedge w^k \models_{\beta} \psi_{\text{prog}}(\emptyset, C_0) \wedge w/k+1 \in \mathcal{L}_{\beta}(\mathcal{B}(\mathcal{L}))$
<b>hot</b>	$\forall \beta \forall w \in W \bullet w^0 \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0)$ $\implies w^0 \models_{\beta} \psi_{\text{prog}}(\emptyset, C_0) \wedge w/1 \in \mathcal{L}_{\beta}(\mathcal{B}(\mathcal{L}))$	$\forall \beta \forall w \in W \forall k \in \mathbb{N}_0 \bullet w^k \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0)$ $\implies w^k \models_{\beta} \psi_{\text{hot}}^{\text{Cond}}(\emptyset, C_0) \wedge w/k+1 \in \mathcal{L}_{\beta}(\mathcal{B}(\mathcal{L}))$

*suffixes of w starting at index 1*

where  $C_0$  is the minimal (or **instance heads**) cut.

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## Full LSC Semantics: Example

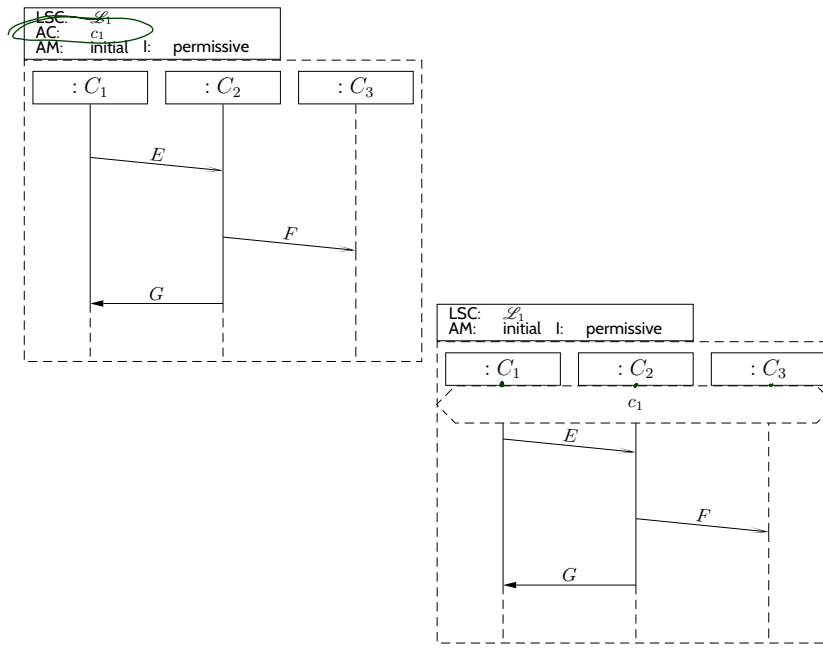


$$\begin{aligned}
 w: & (\sigma, \varepsilon) \xrightarrow{\text{cons}, \text{Snd}} \dots \rightarrow (\sigma_0, \varepsilon_0) \xrightarrow{\text{cons}_0, \text{Snd}_0} (\sigma_1, \varepsilon_1) \xrightarrow{\text{cons}_1, \{(:E, c_2)\}} (\sigma_2, \varepsilon_2) \xrightarrow{\{(:E), \text{Snd}_2\}} \\
 & (\sigma_3, \varepsilon_3) \xrightarrow{\text{cons}_3, \{(:F, c_3)\}} (\sigma_4, \varepsilon_4) \xrightarrow{\text{cons}_4, \{(:G), c_1\}} (\sigma_5, \varepsilon_5) \xrightarrow{\{(:F), \text{Snd}_5\}} (\sigma_6, \varepsilon_6) \rightarrow \dots \\
 \beta & = \{x \mapsto c_1, y \mapsto c_2, z \mapsto c_3\}
 \end{aligned}$$

$\hookrightarrow w$  is accepted by  $\mathcal{L}_1$

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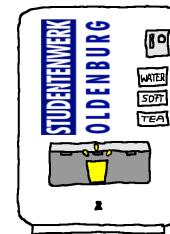
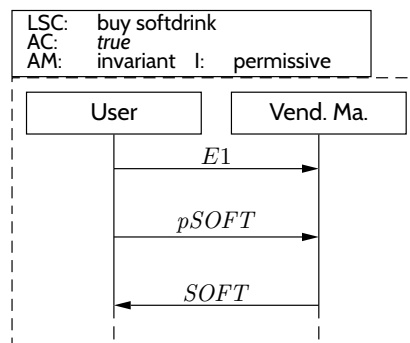
## Note: Activation Condition



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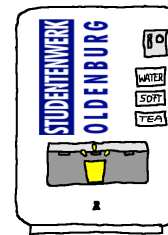
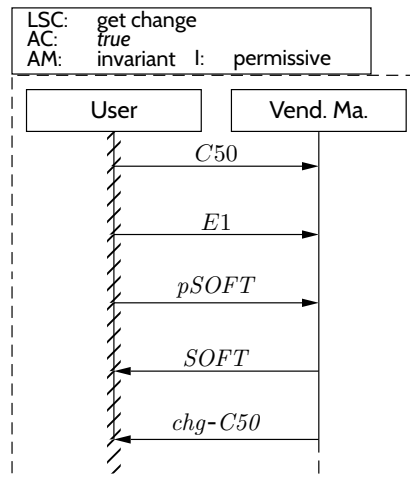
## Existential LSC Example: Buy A Softdrink



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# Existential LSC Example: Get Change



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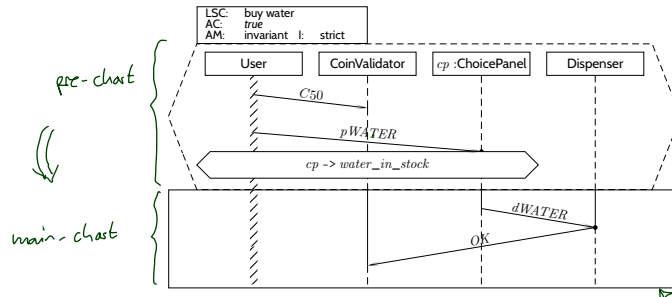
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## Live Sequence Charts — Precharts

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# Pre-Charts

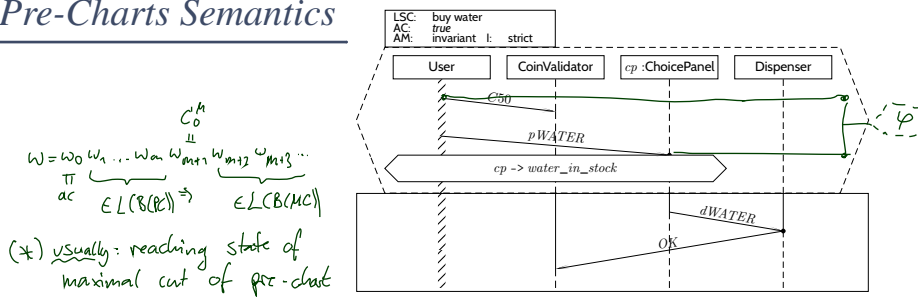


A full LSC  $\mathcal{L} = (PC, MC, ac_0, am, \Theta_{\mathcal{L}})$  actually consist of *(temperature of main-chart)*

- **pre-chart**  $PC = ((L_P, \preceq_P, \sim_P), \mathcal{I}_P, \mathcal{S}, \text{Msg}_P, \text{Cond}_P, \text{Loclnv}_P, \Theta_P)$  (possibly empty),
- **main-chart**  $MC = ((L_M, \preceq_M, \sim_M), \mathcal{I}_M, \mathcal{S}, \text{Msg}_M, \text{Cond}_M, \text{Loclnv}_M, \Theta_M)$  (non-empty),
- **activation condition**  $ac_0 : \text{Bool} \in \text{Expr}_{\mathcal{L}}$ ,
- **strictness flag** *strict* (otherwise called **permissive**)
- **activation mode**  $am \in \{\text{initial}, \text{invariant}\}$ ,
- **chart mode** **existential** ( $\Theta_{\mathcal{L}} = \text{cold}$ ) or **universal** ( $\Theta_{\mathcal{L}} = \text{hot}$ ).

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# Pre-Charts Semantics

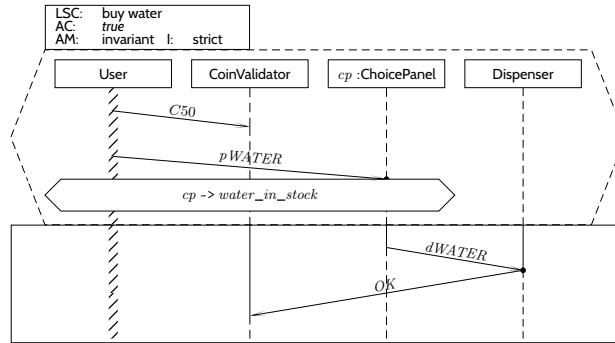
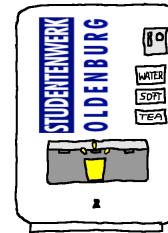
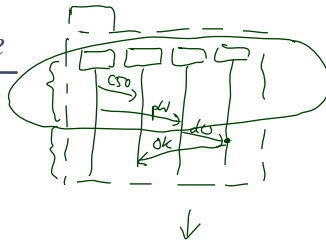


(\*) usually: reading state of maximal cut of pre-chart

	$am = \text{initial}$	$am = \text{invariant}$
$\Theta_{\mathcal{L}} = \text{cold}$	$\exists \beta \exists w \in W \exists m \in \mathbb{N}_0 \bullet$ $\wedge w^0 \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0^P) \wedge \psi_{\text{prog}}(\emptyset, C_0^P)$ $\wedge w^1, \dots, w^m \in \mathcal{L}_{\beta}(\mathcal{B}(PC))$ $\wedge w^{m+1} \models_{\beta} \neg \psi_{\text{exit}}(C_0^M)$ $\wedge w^{m+1} \models_{\beta} \psi_{\text{prog}}(\emptyset, C_0^M)$ $\wedge w/m + 2 \in \mathcal{L}_{\beta}(\mathcal{B}(MC))$	$\exists \beta \exists w \in W \exists k < m \in \mathbb{N}_0 \bullet$ $\wedge w^k \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0^P) \wedge \psi_{\text{prog}}(\emptyset, C_0^P)$ $\wedge w^{k+1}, \dots, w^m \in \mathcal{L}_{\beta}(\mathcal{B}(PC))$ $\wedge w^{m+1} \models_{\beta} \neg \psi_{\text{exit}}(C_0^M)$ $\wedge w^{m+1} \models_{\beta} \psi_{\text{prog}}(\emptyset, C_0^M)$ $\wedge w/m + 2 \in \mathcal{L}_{\beta}(\mathcal{B}(MC))$
$\Theta_{\mathcal{L}} = \text{hot}$	$\forall \beta \forall w \in W \forall m \in \mathbb{N}_0 \bullet$ $\left\{ \begin{array}{l} \wedge w^0 \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0^P) \wedge \psi_{\text{prog}}(\emptyset, C_0^P) \\ \wedge w^1, \dots, w^m \in \mathcal{L}_{\beta}(\mathcal{B}(PC)) \quad (*) \\ \wedge w^{m+1} \models_{\beta} \neg \psi_{\text{exit}}(C_0^M) \end{array} \right.$ $\implies \left\{ \begin{array}{l} w^{m+1} \models_{\beta} \psi_{\text{prog}}(\emptyset, C_0^M) \\ \wedge w/m + 2 \in \mathcal{L}_{\beta}(\mathcal{B}(MC)) \end{array} \right.$	$\forall \beta \forall w \in W \forall k \leq m \in \mathbb{N}_0 \bullet$ $\wedge w^k \models_{\beta} ac \wedge \neg \psi_{\text{exit}}(C_0^P) \wedge \psi_{\text{prog}}(\emptyset, C_0^P)$ $\wedge w^{k+1}, \dots, w^m \in \mathcal{L}_{\beta}(\mathcal{B}(PC))$ $\wedge w^{m+1} \models_{\beta} \neg \psi_{\text{exit}}(C_0^M)$ $\implies \left\{ \begin{array}{l} w^{m+1} \models_{\beta} \psi_{\text{prog}}(\emptyset, C_0^M) \\ \wedge w/m + 2 \in \mathcal{L}_{\beta}(\mathcal{B}(MC)) \end{array} \right.$

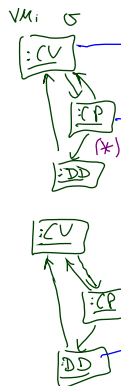
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# Universal LSC: Example

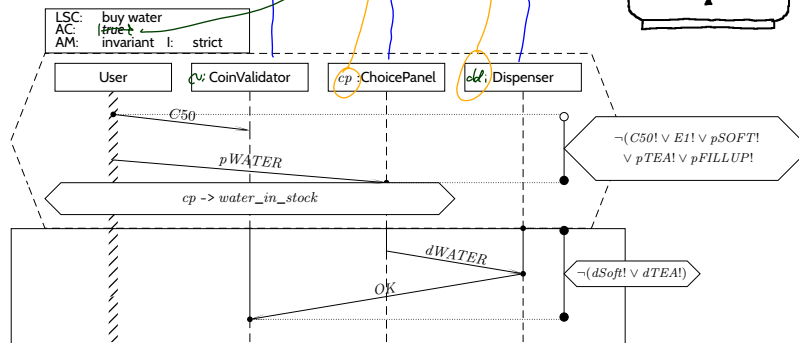
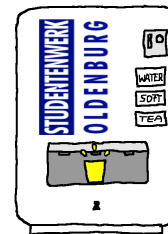


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# Universal LSC: Example

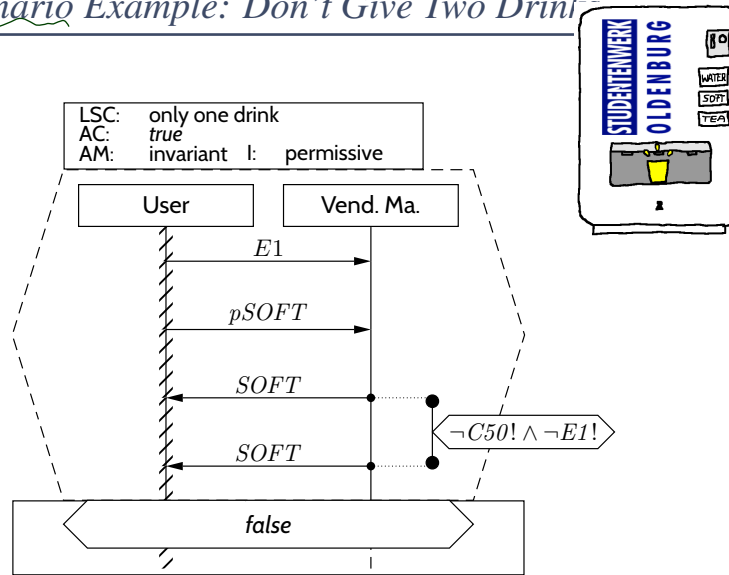


cv. Its cp = cp  
 ^ cp. Its CV = cv  
 ^ dd. Its CV = cv  
 ^ cp. Its DD = dd



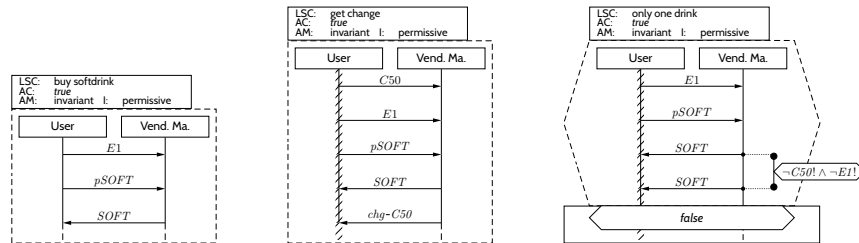
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# Forbidden Scenario Example: Don't Give Two Drinks



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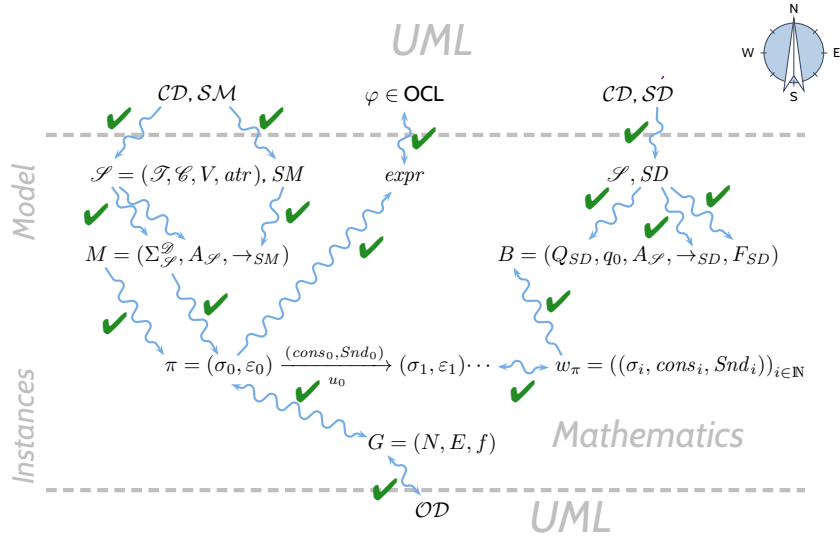
## Note: Sequence Diagrams and (Acceptance) Test



- **Existential** LSCs\* may hint at **test-cases** for the **acceptance test!**  
(\*: as well as (positive) scenarios in general, like use-cases)
- **Universal** LSCs (and negative/anti-scenarios) in general need **exhaustive analysis!**  
(Because they require that the software **never ever** exhibits the unwanted behaviour.)

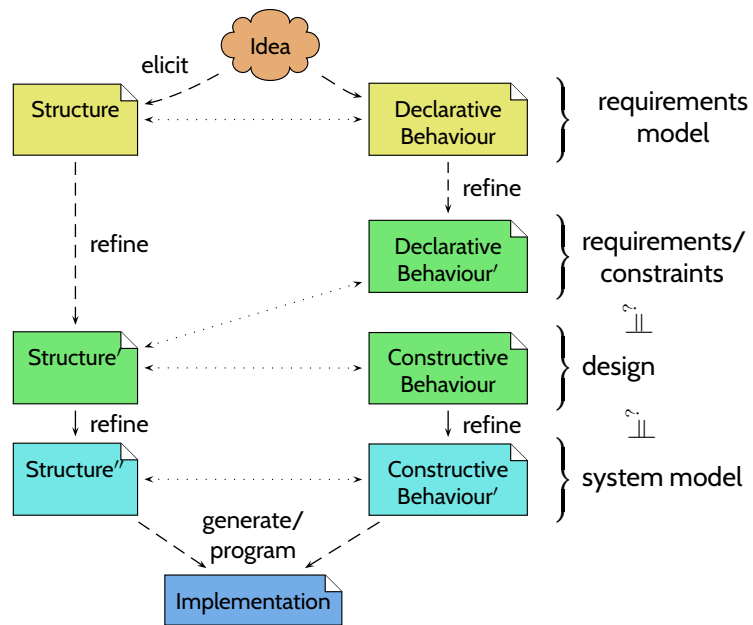
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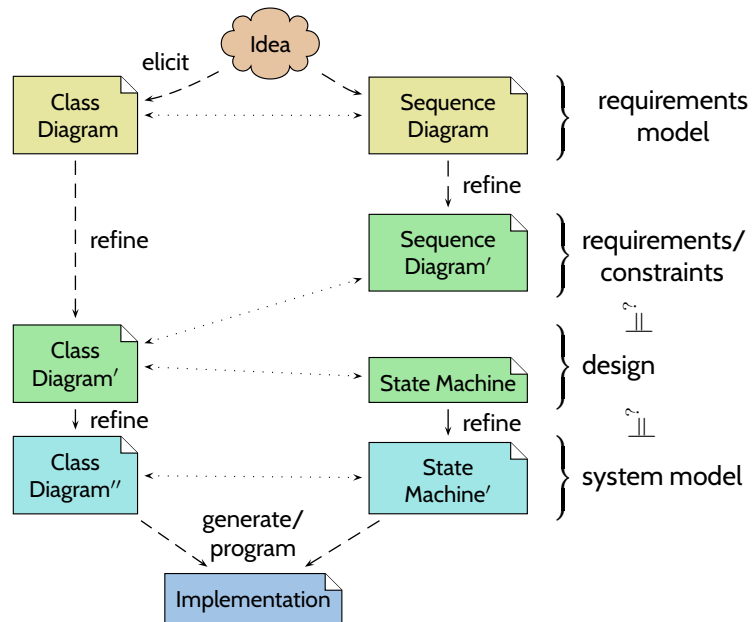
Model-Based/-Driven Software Engineering

# Model-Driven Software Engineering

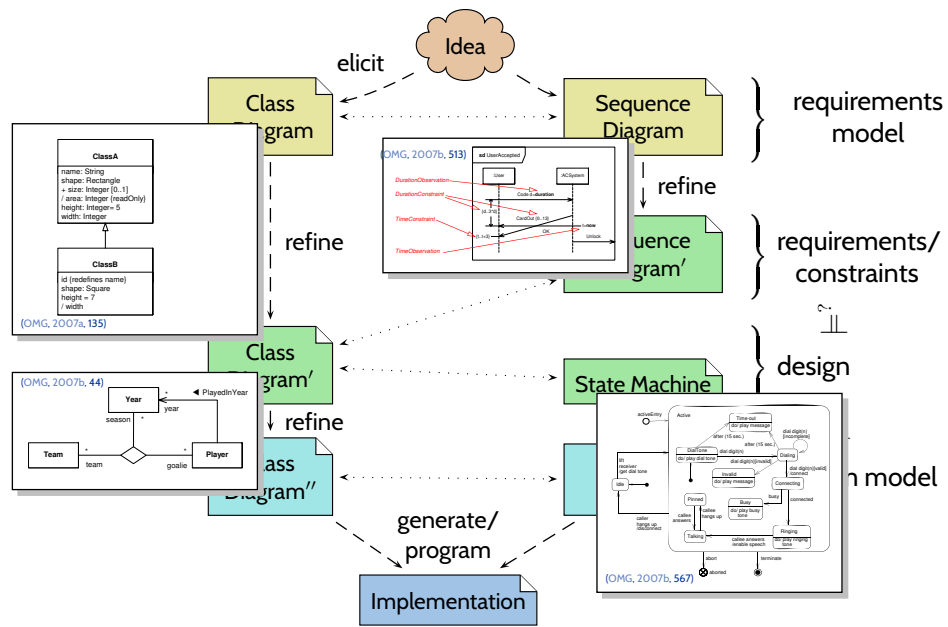


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# Model-Driven Software Engineering with UML



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## Model-Based Testing

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## Recall: Test Case

**Definition.** A **test case**  $T$  is a pair  $(In, Soll)$  consisting of

- a description  $In$  of sets of finite **input sequences**,
- a description  $Soll$  of **expected outcomes**,

and an interpretation  $\llbracket \cdot \rrbracket$  of these descriptions.

A **test execution**  $\pi$ , i.e.  $((\pi^0, \dots, \pi^n) \downarrow \Sigma_{in}) \in In$  for some  $n \in \mathbb{N}_0$ , is called

- **successful** (or **positive**)

if it discovered an error,  
i.e., if  $\pi \notin \llbracket Soll \rrbracket$ .

(Alternative: test item  $S$  **failed to pass test**; confusing: "test failed")

- **unsuccessful** (or **negative**)

if it did not discover an error,  
i.e., if  $\pi \in \llbracket Soll \rrbracket$ .

(Alternative: test item  $S$  **passed test**; okay: "test passed")

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## Glass-Box Testing: Coverage

- **Coverage** is a property of **test cases** and **test suites**.
- Execution  $\pi$  of test case  $T$  achieves  $p\%$  **statement coverage** if and only if

$$p = cov_{stm}(\pi) := \frac{|\bigcup_{i \in \mathbb{N}_0} stm(\sigma_i)|}{|Stm_S|}, |Stm_S| \neq 0.$$

Test case  $T$  achieves  $p\%$  **statement coverage** if and only if  $p = \min_{\pi \text{ execution of } T} cov_{stm}(\pi)$ .

- Execution  $\pi$  of  $T$  achieves  $p\%$  **branch coverage** if and only if

$$p = cov_{cnd}(\pi) := \frac{|\bigcup_{i \in \mathbb{N}_0} cnd(\sigma_i)|}{|Cnd_S|}, |Cnd_S| \neq 0.$$

Test case  $T$  achieves  $p\%$  **branch coverage** if and only if  $p = \min_{\pi \text{ execution of } T} cov_{cnd}(\pi)$ .

- **Define:**  $p = 100$  for empty program.
- Statement/branch coverage canonically extends to test suite  $\mathcal{T} = \{T_1, \dots, T_n\}$ ,  
e.g. given executions  $\pi_1, \dots, \pi_n$ ,  $\mathcal{T}$  achieves

$$p = \frac{|\bigcup_{1 \leq j \leq n} \bigcup_{i \in \mathbb{N}_0} stm(\pi_j^i)|}{|Stm_S|}, |Stm_S| \neq 0, \text{ **statement coverage** .}$$

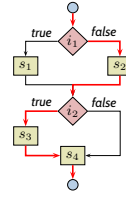
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## Coverage Example

```

int f(int x, int y, int z)
{
  i1: if (x > 100 & y > 10)
  s1: z = z * 2;
  else
  s2: z = z / 2;
  i2: if (x > 500 ∨ y > 50)
  s3: z = z * 5;
  s4: ;
}
    
```



- **Requirement:**  $\{true\} f \{true\}$  (no abnormal termination), i.e.  $Soll = \Sigma^* \cup \Sigma^\omega$ .

test suite coverage

In	$i_1/t$	$i_1/f$	$s_1$	$s_2$	$i_2/t$	$i_2/f$	$c_1$	$c_2$	$s_3$	$s_4$	% stm	% cnd	$i_2/\%$ term
501, 11, 0	✓		✓		✓		✓		✓	✓	75	50	25
501, 0, 0		✓		✓	✓		✓		✓	✓	100	75	25
0, 0, 0		✓		✓		✓				✓	100	100	75
0, 51, 0		✓		✓	✓		✓			✓	100	100	100

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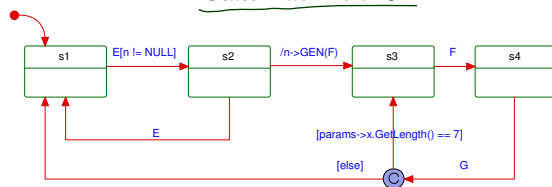
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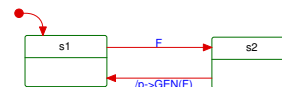
## Model-Element Coverage



State machine of C:



State machine of D:



**100 % Element coverage** of C's state machine:

- a set of test cases (e.g. **Sequence Diagrams**) such that
- when conducting these test cases
  - each state of C is reached at least once,
  - each transition of C is taken at least once.

(state coverage)  
(transition coverage)

In general: **State coverage of a set of test cases**

- number-of-states reached / number-of-states in state machine.

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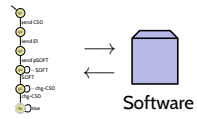
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## *Excursion: Automatic Test Generation*

### *Model-based Testing*

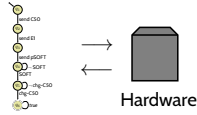
- Given a **set of test cases** passing for the model,
- and an **implementation of the model** (maybe hand-written).
  
- **Execute the test cases on the implementation** (or the final system).  
This may need an appropriate **interpretation**. For example, if the test case says
  - send “C50” to the CoinValidator,
  - rather insert a 50 Cent coin into the vending machine.
  
- If the vending machine **does not behave** according to the test,
  - then **there's something wrong** (wrong test conduction, wrong implementation, etc.).
  
- If the vending machine **does behave** according to the test,
  - then we know that **this scenario works** – not more.

## Vocabulary



- **Software-in-the-loop:**

The final implementation is examined using a separate computer to simulate other system components.



- **Hardware-in-the-loop:**

The final implementation is running on (prototype) hardware which is connected by its standard input/output interface (e.g. CAN-bus) to a separate computer which simulates other system components.

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## References

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## *References*

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