

Software Design, Modelling and Analysis in UML

Lecture 07: Class Diagrams II

2011-11-30

Prof. Dr. Andreas Podelski, **Dr. Bernd Westphal**

Albert-Ludwigs-Universität Freiburg, Germany

Contents & Goals

Last Lectures:

- VL 05: class diagram — except for associations
- VL 06: semantics of visibility within OCL type system

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.

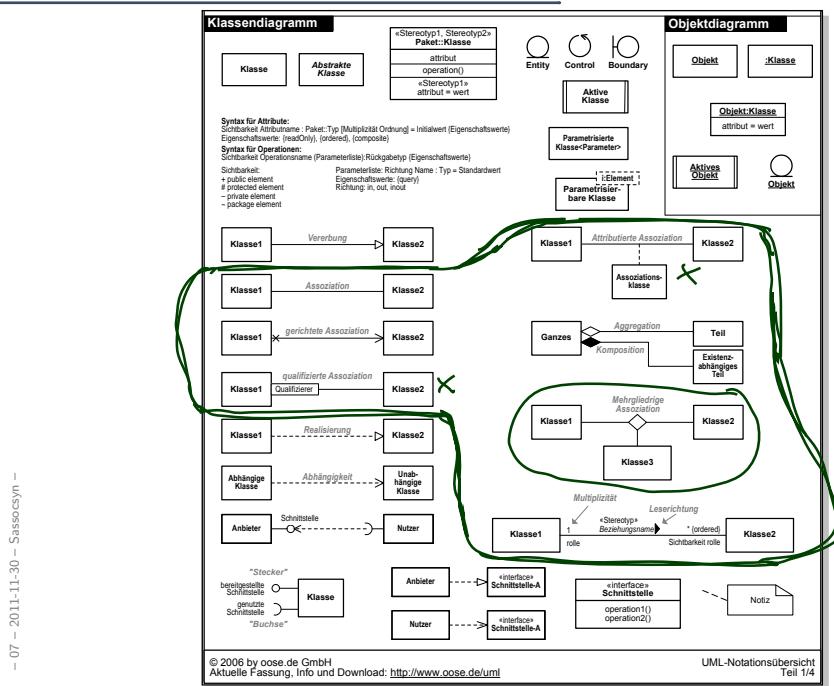
- Please explain this class diagram with associations.
- Which annotations of an association arrow are semantically relevant?
- What's a role name? What's it good for?
- What's "multiplicity"? How did we treat them semantically?
- What is "reading direction", "navigability", "ownership", ... ?
- What's the difference between "aggregation" and "composition"?

- **Content:**

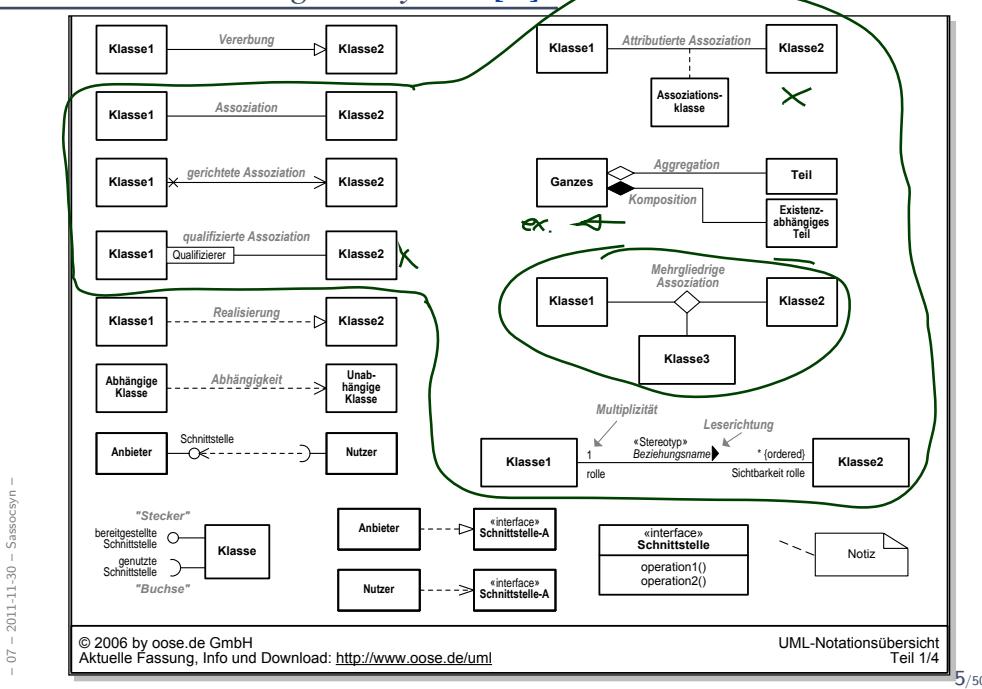
- Study concrete syntax for "associations".
- (**Temporarily**) extend signature, define mapping from diagram to signature.
- Study effect on OCL.
- Where do we put OCL constraints?

Associations: Syntax

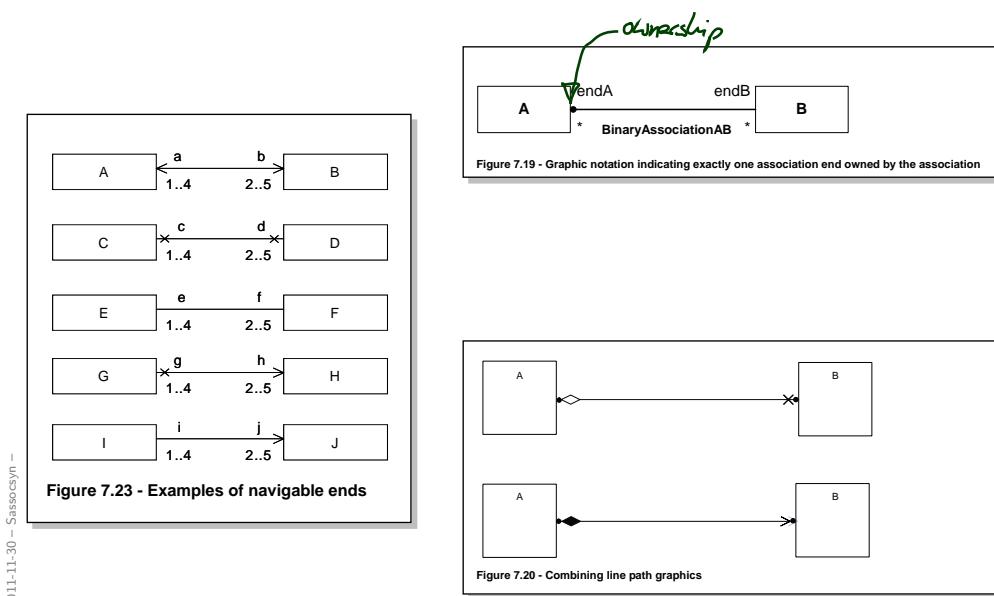
UML Class Diagram Syntax [?]



UML Class Diagram Syntax [?]



UML Class Diagram Syntax [?, 61;43]



What Do We (Have to) Cover?

An **association** has

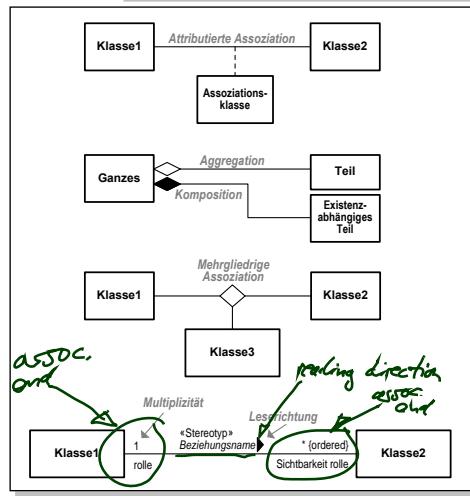
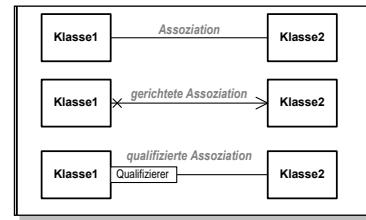
- a **name**,
 - a **reading direction**, and
 - at least two **ends**.
- (association)*

Each **end** has

- a **role name**,
- a **multiplicity**,
- a set of **properties**, such as **unique**, **ordered**, etc.
- a **qualifier**, (we will not treat)
- a **visibility**,
- a **navigability**,
- an **ownership**,
- and possibly a **diamond**. (exercises)

Wanted: places in the signature to represent the information from the picture.

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(Temporarily) Extend Signature: Associations

Only for the course of Lectures 07/08 we assume that each attribute in V

- **either** is $\langle v : \tau, \xi, \text{expr}_0, P_v \rangle$ with $\tau \in \mathcal{T}$ (as before),
- **or** is an **association** of the form

$$\begin{aligned} & \langle r : \langle \text{role}_1 : C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle \rangle, \\ & \quad \text{Association :} \\ & \quad \text{name} \quad \langle \text{role}_n : C_n, \mu_n, P_n, \xi_n, \nu_n, o_n \rangle \rangle \end{aligned}$$

where

- $n \geq 2$ (at least two ends),
- r, role_i are just **names**, $C_i \in \mathcal{C}$, $1 \leq i \leq n$,
- the **multiplicity** μ_i is an expression of the form

$$\mu ::= * \mid N \mid N..M \mid N..* \mid \mu, \mu \quad (N, M \in \mathbb{N})$$

- P_i is a set of **properties** (as before),
- $\xi \in \{+, -, \#, \sim\}$ (as before),
- $\nu_i \in \{\times, -, >\}$ is the **navigability**,
- $o_i \in \mathbb{B}$ is the **ownership**.

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(Temporarily) Extend Signature: Associations

Only for the course of Lectures 07/08 we assume that each attribute in V

- **either** is $\langle v : \tau, \xi, expr_0, P_v \rangle$ with $\tau \in \mathcal{T}$ (as before),
- **or** is an **association** of the form

$$\langle r : \langle role_1 : C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle \rangle,$$

Alternative syntax for multiplicities:

$$\mu ::= N..M \mid N..* \mid \mu, \mu \quad (N, M \in \mathbb{N} \cup \{*\})$$

and define $*$ and N as abbreviations.

Note: N could abbreviate $0..N$, $1..N$, or $N..N$. We use last one.

- $r, role_i$ are just **names**, $\cup_i \in \sigma$, $1 \leq i \leq n$,
- the **multiplicity** μ_i is an expression of the form

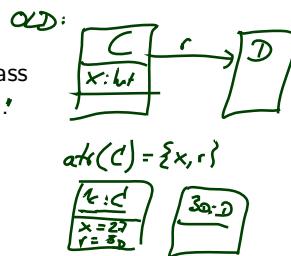
$$\mu ::= * \mid N \mid N..M \mid N..* \mid \mu, \mu \quad (N, M \in \mathbb{N})$$

- P_i is a set of **properties** (as before),
- $\xi \in \{+, -, \#, \sim\}$ (as before),
- $\nu_i \in \{\times, -, >\}$ is the **navigability**,
- $o_i \in \mathbb{B}$ is the **ownership**.

(Temporarily) Extend Signature: Basic Type Attributes

Also only for the course of ~~07/08~~ lectures ~~07/08~~

- we only consider **basic type attributes** to "belong" to a class C (to appear in $atr(C)$),
- **associations** are not "owned" by a particular class (do not appear in $atr(C)$), but live on their own!



Formally: we only call

$$(\mathcal{T}, \mathcal{C}, V, atr)$$

a **signature (extended for associations)** if

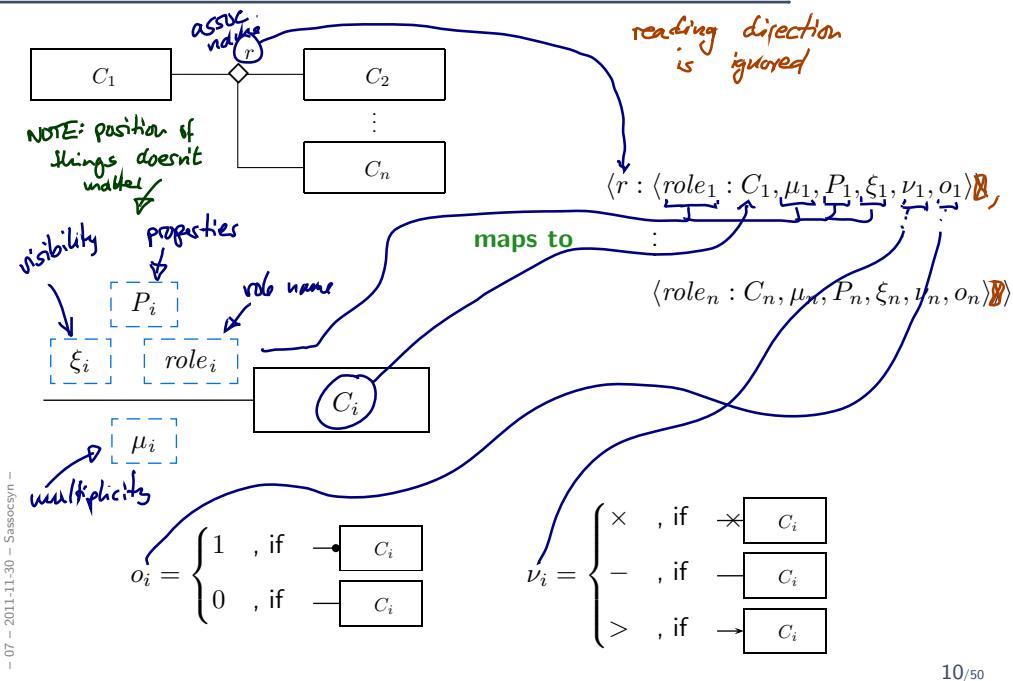
$$atr : \mathcal{C} \rightarrow 2^{\{v \in V \mid v : \tau, \tau \in \mathcal{T}\}}.$$

NOW: $V = \{ \ldots, \tau : D_0, \ldots \}$
NOT: $atr(C) = \{ \ldots, r, \ldots \}$

because
is not of basic type

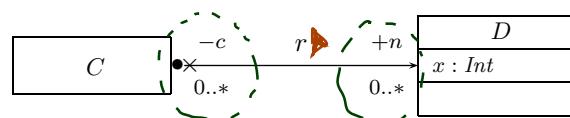
07/08:
if: $\begin{cases} \{x: C\} \\ x = 23 \end{cases}$ $\{y: D\}$
 $r : (x, y)$

From Association Lines to Extended Signatures



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Association Example $\langle role_i : C_i, \mu_i, P_i, \xi_i, \nu_i, o_i \rangle$



Signature:

$$\mathcal{S} = (\{\text{Int}\}, \{C, D\}, x : \text{Int}, \langle r : \langle \langle c : C, 0..*, \emptyset, -, x, 1 \rangle, \langle n : D, 0..*, \emptyset, +, x, 0 \rangle \rangle \}, \{C \{ C \mapsto \{ \}, \{x\} \}, D \mapsto \{x\} \})$$

now: only basic type attr.
are assigned by attr.

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What If Things Are Missing?

Most components of associations or association end may be omitted.

For instance [?, 17], Section 6.4.2, proposes the following rules:

- **Name:** Use

$$A \langle C_1 \rangle \cdots \langle C_n \rangle$$

if the name is missing.

Example:



- **Reading Direction:** no default.

- **Role Name:** use the class name at that end in lower-case letters

Example:

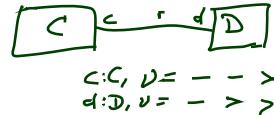


Other convention: (used e.g. by modelling tool Rhapsody)



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What If Things Are Missing?



- **Multiplicity:** 1

In my opinion, it's safer to assume 0..1 or * if there are no fixed, written, agreed conventions ("expect the worst").

- **Properties:** \emptyset

- **Visibility:** public

- **Navigability and Ownership:** not so easy. [?, 43]

"Various options may be chosen for showing navigation arrows on a diagram."

In practice, it is often convenient to suppress some of the arrows and crosses and just show exceptional situations:

- Show all arrows and x's. Navigation and its absence are made completely explicit.
- Suppress all arrows and x's. No inference can be drawn about navigation. This is similar to any situation in which information is suppressed from a view.
- Suppress arrows for associations with navigability in both directions, and show arrows only for associations with one-way navigability.

In this case, the two-way navigability cannot be distinguished from situations where there is no navigation at all; however, the latter case occurs rarely in practice."

Wait, If Omitting Things...

- ...is causing so much trouble (e.g. leading to misunderstanding), why does the standard say “**In practice, it is often convenient...**”?

Is it a good idea to trade **convenience** for **precision/unambiguity**?

It depends.

- Convenience as such is a legitimate goal.
- In UML-As-Sketch mode, precision “doesn’t matter”, so convenience (for writer) can even be a primary goal.
- In UML-As-Blueprint mode, **precision** is the **primary goal**. And misunderstandings are in most cases annoying.

But: (even in UML-As-Blueprint mode)

If all associations in your model have multiplicity *, then it’s probably a good idea not to write all these *’s.

So: tell the reader about it and leave out the *’s.

Association Semantics

Overview

What's left? **Named** association with at least two typed **ends**, each having

- a **role name**,
- a set of **properties**,
- a **navigability**, and
- a **multiplicity**,
- a **visibility**,
- an **ownership**.

The Plan:

- Extend **system states**, introduce so-called **links** as instances of associations — depends on **name** and on **type** and **number** of ends.
- Integrate **role name** and **multiplicity** into **OCL syntax/semantics**.
- Extend **typing rules** to care for **visibility** and **navigability**
- Consider **multiplicity** also as part of the **constraints** set $Inv(\mathcal{CD})$.
- **Properties**: for now assume $P_v = \{\text{unique}\}$.
- **Properties** (in general) and **ownership**: later.

Association Semantics: The System State Aspect

Associations in General

Recall: We consider associations of the following form:

$$\langle r : \langle role_1 : C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle, \dots, \langle role_n : C_n, \mu_n, P_n, \xi_n, \nu_n, o_n \rangle \rangle$$

Only these parts are relevant for extended system states:

$$\langle r : \langle role_1 : C_1, \rightarrow P_1, \dashv, \rightarrow, \dashv \rangle, \dots, \langle role_n : C_n, \rightarrow P_n, \dashv, \rightarrow, \dashv \rangle \rangle$$

(recall: we assume $P_1 = P_n = \{\text{unique}\}$).

The UML standard thinks of associations as **n-ary relations** which “**live on their own**” in a system state.

That is, **links** (= association instances)

- do **not** belong (in general) to certain objects (in contrast to pointers, e.g.)
- are “first-class citizens” **next to objects**,
- are (in general) **not** directed (in contrast to pointers).

Links in System States

$$\langle r : \langle role_1 : C_1, \rightarrow, P_1, \dashv, \rightarrow, \dashv \rangle, \dots, \langle role_n : C_n, \rightarrow, P_n, \dashv, \rightarrow, \dashv \rangle \rangle$$

Only for the course of lectures 07/08 we change the definition of system states:

Definition. Let \mathcal{D} be a structure of the (extended) signature $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$.

A **system state** of \mathcal{S} wrt. \mathcal{D} is a pair (σ, λ) consisting of

- a type-consistent mapping

$$\sigma : \mathcal{D}(\mathcal{C}) \rightarrow (atr(\mathcal{C}) \leftrightarrow \mathcal{D}(\mathcal{T})),$$

- a mapping λ which assigns each association

$$\langle r : \langle role_1 : C_1 \rangle, \dots, \langle role_n : C_n \rangle \rangle \in V \text{ a relation}$$

$$\lambda(r) \subseteq \mathcal{D}(C_1) \times \dots \times \mathcal{D}(C_n)$$

(i.e. a set of type-consistent n -tuples of identities).

Association/Link Example



Signature:

$$\mathcal{S} = (\{ \text{Int} \}, \{ C, D \}, \{ x : \text{Int},$$

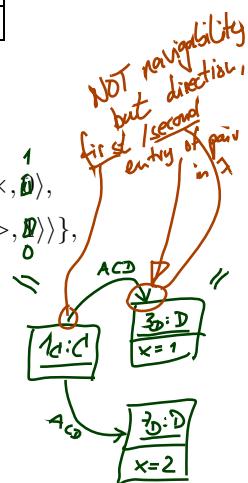
$$\quad \langle A_C_D : \langle c : D, 0..*, \{\text{unique}\}, \times, \emptyset \rangle, \quad 1 \\ \quad \langle n : D, 0..*, \{\text{unique}\}, >, \emptyset \rangle \}, \quad 0 \\ \quad \{ C \mapsto \emptyset, D \mapsto \{x\} \})$$

one instance of class C

A **system state** of \mathcal{S} (some reasonable \mathcal{D}) is (σ, λ) with:

$$\sigma = \{ 1_C \mapsto \emptyset, 3_D \mapsto \{x \mapsto 1\}, 7_D \mapsto \{x \mapsto 2\} \}$$

$$\lambda = \{ A_C_D \mapsto \{(1_C, 3_D), (1_C, 7_D)\} \}$$

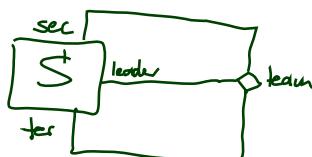


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The order does matter...

if:



$\leftarrow \text{team} : \langle \text{ter}: \text{S}, \dots \rangle$
 $\leftarrow \text{sec}: \text{S}, \dots \rangle$
 $\leftarrow \text{ter}: \text{S}, \dots \rangle \rangle$

$$\sigma = \{ 1_s \mapsto \emptyset, 2_s \mapsto \emptyset, 5_s \mapsto \emptyset, 7_s \mapsto \emptyset \}$$

$$\lambda(A) = \{ (5_s, 2_s, 1_s), (1_s, 7_s, 5_s), (7_s, 7_s, 7_s) \}$$

$$D(S) \times D(S) \times D(S)$$

OBJECT DIAGRAM WOULD NEED HYPEREDGES:



WE WILL NOT FORMALLY DEFINE THAT!

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Extended System States and Object Diagrams

Legitimate question: how do we represent system states such as

$$\sigma = \{1_C \mapsto \emptyset, 3_D \mapsto \{x \mapsto 1\}, 7_D \mapsto \{x \mapsto 2\}\}$$
$$\lambda = \{A _ C _ D \mapsto \{(1_C, 3_D), (1_C, 7_D)\}\}$$

as **object diagram**?

- see page 20
- see page 20a

Associations and OCL

OCL and Associations: Syntax

Recall: OCL syntax as introduced in Lecture 03, interesting part:

$$\begin{aligned} \text{expr} ::= \dots & | r_1(\text{expr}_1) : \tau_C \rightarrow \tau_D & r_1 : D_{0,1} \in \text{atr}(C) \\ & | r_2(\text{expr}_1) : \tau_C \rightarrow \text{Set}(\tau_D) & r_2 : D_* \in \text{atr}(C) \end{aligned}$$

Now becomes

$$\begin{aligned} \text{expr} ::= \dots & | \text{role(expr}_1) : \tau_C \rightarrow \tau_D & \mu = 0..1 \text{ or } \mu = 1 \\ & | \text{role(expr}_1) : \tau_C \rightarrow \text{Set}(\tau_D) & \text{otherwise} \end{aligned}$$

if

$$\langle r : \dots, \langle \text{role} : D, \mu, _, _, _, _ \rangle, \dots, \langle \text{role}' : C, _, _, _, _, _ \rangle, \dots \rangle \in V \text{ or} \\ \langle r : \dots, \langle \text{role}' : C, _, _, _, _, _ \rangle, \dots, \langle \text{role} : D, \mu, _, _, _, _ \rangle, \dots \rangle \in V, \text{role} \neq \text{role}'.$$

Note:

- Association name as such doesn't occur in OCL syntax, role names do.
- expr_1 has to denote an object of a class which "participates" in the association.

References

