

Real-Time Systems

Lecture 7: DC Properties II

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Contents & Goals

Last Lecture:

- RDC in discrete time
- Satisfiability and realisability from 0 is decidable for RDC in discrete time

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - Facts: (un)decidability properties of DC in continuous time.
 - What's the idea of the considered (un)decidability proofs?
- **Content:**
 - Undecidable problems of DC in continuous time

(Variants of) RDC in Continuous Time

Recall: Restricted DC (RDC)

$$\ell=1 = \lceil 1 \rceil \wedge \lceil (\lceil 1 \rceil; \lceil 1 \rceil) \rceil$$

$$F ::= \lceil P \rceil \mid \neg F_1 \mid F_1 \vee F_2 \mid F_1 ; F_2$$

where P is a state assertion, but with **boolean** observables **only**.

From now on: “RDC + $\ell = x, \forall x$ ”

$$F ::= \lceil P \rceil \mid \neg F_1 \mid F_1 \vee F_2 \mid F_1 ; F_2 \mid \ell = 1 \mid \ell = x \mid \forall x \bullet F_1$$

Undecidability of Satisfiability/Realisability from 0

Theorem 3.10.

The realisability from 0 problem for DC with **continuous time** is undecidable, not even semi-decidable.

Theorem 3.11.

The satisfiability problem for DC with continuous time is undecidable.

Sketch: Proof of Theorem 3.10

Reduce divergence of **two-counter machines** to realisability from 0:

- Given a two-counter machine \mathcal{M} with final state q_{fin} ,
- construct a DC formula $F(\mathcal{M}) := \text{encoding}(\mathcal{M})$
- such that

\mathcal{M} **diverges** **if and only if** the DC formula

$$F(\mathcal{M}) \wedge \neg \Diamond [q_{fin}]$$

is **realisable from 0**.

- If realisability from 0 was (semi-)decidable, divergence of two-counter machines would be (which it isn't).

Recall: Two-counter machines

A **two-counter** machine is a structure

$$\mathcal{M} = (\mathcal{Q}, q_0, q_{fin}, \text{Prog})$$

where

- \mathcal{Q} is a finite set of **states**,
- comprising the **initial state** q_0 and the **final state** q_{fin}
- Prog is the **machine program**, i.e. a finite set of **commands** of the form

just
syntax

$$q : inc_i : q' \quad \text{and} \quad q : dec_i : q', q'', \quad i \in \{1, 2\}.$$

could
also
be:

$$\begin{aligned} A(q, q') \\ B(q, q') \\ C(q, q', q'') \\ D(q, q', q'') \end{aligned}$$

- We assume **deterministic** 2CM: for each $q \in \mathcal{Q}$, at most one command starts in q , and q_{fin} is the only state where no command starts.

2CM Configurations and Computations

- a **configuration** of \mathcal{M} is a triple $K = (q, n_1, n_2) \in \mathcal{Q} \times \mathbb{N}_0 \times \mathbb{N}_0$.

2CM Configurations and Computations

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- The (!) **computation** of \mathcal{M} is a finite sequence of the form (“ \mathcal{M} **halts**”)

$$K_0 = (q_0, 0, 0) \vdash K_1 \vdash K_2 \vdash \dots \vdash (q_{fin}, n_1, n_2)$$

or an infinite sequence of the form (“ \mathcal{M} **diverges**”)

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2CM Configurations and Computations

- a **configuration** of \mathcal{M} is a triple $K = (q, n_1, n_2) \in Q \times \mathbb{N}_0 \times \mathbb{N}_0$.

- The (!) **computation** of \mathcal{M} is a finite sequence of the form (" \mathcal{M} halts")

$$K_0 = (q_0, 0, 0) \vdash K_1 \vdash K_2 \vdash \dots \vdash (q_{fin}, n_1, n_2)$$

or an infinite sequence of the form $(K_1, K_2) \in \vdash$ (" \mathcal{M} diverges")

$$K_0 = (q_0, 0, 0) \vdash K_1 \vdash K_2 \vdash \dots$$

- The **transition relation** " \vdash " on configurations is defined as follows:

| Command | Semantics: $K \vdash K'$ |
|---|--|
| $q : inc_1 : q'$ $q : dec_1 : q', q''$ | $(q, n_1, n_2) \vdash (q', n_1 + 1, n_2)$ $(q, 0, n_2) \vdash (q', 0, n_2)$ $(q, n_1 + 1, n_2) \vdash (q'', n_1, n_2)$ |
| $q : inc_2 : q'$ $q : dec_2 : q', q''$ | $(q, n_1, n_2) \vdash (q', n_1, n_2 + 1)$ $(q, n_1, 0) \vdash (q', n_1, 0)$ $(q, n_1, n_2 + 1) \vdash (q'', n_1, n_2)$ |

2CM Example

- $\mathcal{M} = (\mathcal{Q}, q_0, q_{fin}, Prog)$
- commands of the form $q : inc_i : q'$ and $q : dec_i : q', q'', i \in \{1, 2\}$
- configuration $K = (q, n_1, n_2) \in \mathcal{Q} \times \mathbb{N}_0 \times \mathbb{N}_0$.

| Command | Semantics: $K \vdash K'$ |
|-----------------------|---|
| $q : inc_1 : q'$ | $(q, n_1, n_2) \vdash (q', n_1 + 1, n_2)$ |
| $q : dec_1 : q', q''$ | $(q, 0, n_2) \vdash (q', 0, n_2)$ $(q, n_1 + 1, n_2) \vdash (q'', n_1, n_2)$ |
| $q : inc_2 : q'$ | $(q, n_1, n_2) \vdash (q', n_1, n_2 + 1)$ |
| $q : dec_2 : q', q''$ | $(q, n_1, 0) \vdash (q', n_1, 0)$ $(q, n_1, n_2 + 1) \vdash (q'', n_1, n_2)$ |

$$\mathcal{Q} = \{q_0, q_1, q_{fin}\}$$

$$Prog = \{q_0 : inc_1 : q_1, \\ q_1 : inc_2 : q_{fin}\}$$

$(q_0, 0, 0)$ ↳ machine halts
 $(q_1, 1, 0)$
 \vdash^T
 $(q_{fin}, 1, 1)$

$$\hat{\mathcal{Q}} = \{ \hat{q}_0, \hat{q}_{fin} \}, \quad \hat{Prog} = \{ \hat{q}_0 : inc_1 : \hat{q}_0 \}$$

$$(\hat{q}_0, 0, 0) \\ (\hat{q}_0, 1, 0) \\ (\hat{q}_0, 2, 0) \\ \vdots$$

↳ machine diverges

Reducing Divergence to DC realisability: Idea In Pictures

$\Sigma(M)$ diverges
iff
exists $\pi: k_0 \vdash k_1 \vdash k_2 \dots$
iff
exist

(I describes π)

and

$$I \models_0 F(M) \wedge \neg \Diamond_{q_{fin}}$$

$F(M)$ intuitively requires:

- $[n \cdot d, (n+1) \cdot d]$ encodes a configuration
- $[n \cdot d, (n+1) \cdot d]$ and $[(n+1) \cdot d, (n+2) \cdot d]$ are in \vdash -relation
- $[0, d]$ encodes $(q_0, \emptyset, \emptyset)$
- if q_{fin} is reached, we stay there

Reducing Divergence to DC realisability: Idea

- A single configuration K of \mathcal{M} can be encoded in an interval of length 4; being an encoding interval can be **characterised** by a DC formula.
- An interpretation on ‘Time’ encodes **the** computation of \mathcal{M} if
 - each interval $[4n, 4(n + 1)]$, $n \in \mathbb{N}_0$, **encodes** a configuration K_n ,
 - each two subsequent intervals $[4n, 4(n + 1)]$ and $[4(n + 1), 4(n + 2)]$, $n \in \mathbb{N}_0$, encode configurations $K_n \vdash K_{n+1}$ **in transition relation**.
- Being encoding of the run can be **characterised** by DC formula $F(\mathcal{M})$.
- Then \mathcal{M} **diverges** if and only if $F(\mathcal{M}) \wedge \neg \Diamond [q_{fin}]$ is realisable from 0.

Encoding Configurations

- We use $\text{Obs} = \{\text{obs}\}$ with
 $\mathcal{D}(\text{obs}) = \mathcal{Q}_M \dot{\cup} \{C_1, C_2, B, X\}$.
 states of M
 disjoint union
 abbreviates $\Gamma_{\text{Obs}} = q_1 \top$

Examples:

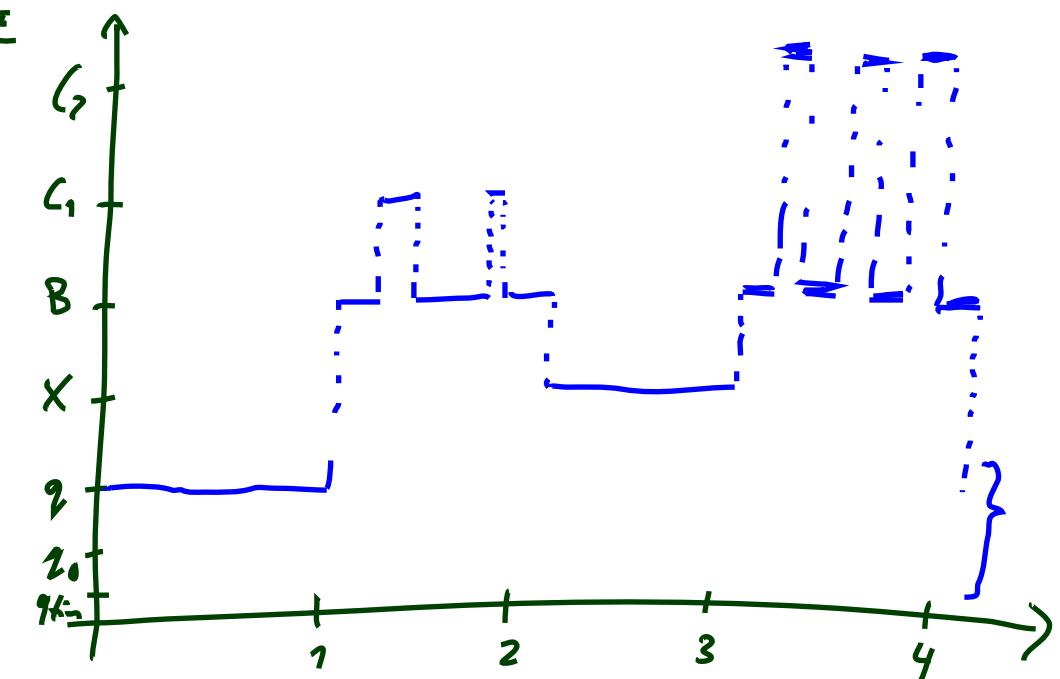
- $K = (q, 2, 3)$

$$\left(\begin{array}{c} [q] \\ \wedge \\ \ell = 1 \end{array} \right); \left(\begin{array}{c} [B]; [C_1]; [B]; [C_1]; [B] \\ \wedge \\ \ell = 1 \end{array} \right); \left(\begin{array}{c} [X] \\ \wedge \\ \ell = 1 \end{array} \right); \left(\begin{array}{c} [B]; [C_2]; [B]; [C_2]; [B]; [C_2]; [B] \\ \wedge \\ \ell = 1 \end{array} \right)$$

- $K_0 = (q_0, 0, 0)$

$$\left(\begin{array}{c} [q_0] \\ \wedge \\ \ell = 1 \end{array} \right); \left(\begin{array}{c} [B] \\ \wedge \\ \ell = 1 \end{array} \right); \left(\begin{array}{c} [X] \\ \wedge \\ \ell = 1 \end{array} \right); \left(\begin{array}{c} [B] \\ \wedge \\ \ell = 1 \end{array} \right)$$

or, using abbreviations, $[q_0]^1; [B]^1; [X]^1; [B]^1$.



Construction of $F(\mathcal{M})$

In the following, we give DC formulae describing

- the initial configuration,
- the general form of configurations,
- the transitions between configurations,
- the handling of the final state.

$F(\mathcal{M})$ is the conjunction of all these formulae.

$$F(\mathcal{M}) = \text{init} \wedge \text{keep} \wedge \dots$$
$$\wedge F(q; \text{inc}; q')$$

$q : \text{inc}; q' \in \text{Reg}_k$

$$\wedge F(q; \text{dec}; q'q'')$$

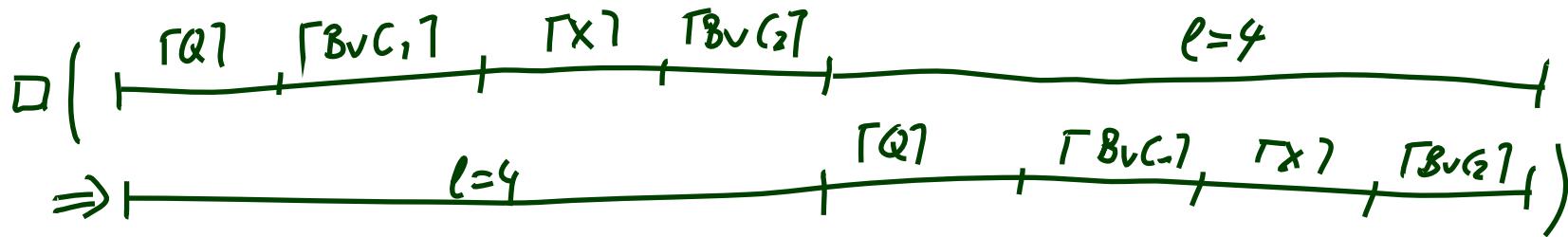
$q : \text{dec}; q'q'' \in \text{Reg}_m$

Initial and General Configurations

$$init : \iff (\ell \geq 4 \implies \lceil q_0 \rceil^1 ; \lceil B \rceil^1 ; \lceil X \rceil^1 ; \lceil B \rceil^1 ; true)$$

$$\begin{aligned} keep : &\iff \square(\lceil Q \rceil^1 ; \lceil B \vee C_1 \rceil^1 ; \lceil X \rceil^1 ; \lceil B \vee C_2 \rceil^1 ; \ell = 4 \\ &\quad \implies \ell = 4 ; \lceil Q \rceil^1 ; \lceil B \vee C_1 \rceil^1 ; \lceil X \rceil^1 ; \lceil B \vee C_2 \rceil^1) \end{aligned}$$

where $Q := \neg(X \vee C_1 \vee C_2 \vee B)$.



Auxiliary Formula Pattern copy

↗ formula
↗ state assertions

$$copy(F, \{P_1, \dots, P_n\}) : \iff$$

$$\forall c, d \bullet \square((F \wedge \ell = c) ; (\lceil P_1 \vee \dots \vee P_n \rceil \wedge \ell = d) ; \lceil P_1 \rceil ; \ell = 4$$

$$\implies \ell = c + d + 4 ; \lceil P_1 \rceil$$

$\wedge \dots$

$$\wedge \forall c, d \bullet \square((F \wedge \ell = c) ; (\lceil P_1 \vee \dots \vee P_n \rceil \wedge \ell = d) ; \lceil P_n \rceil ; \ell = 4$$

$$\implies \ell = c + d + 4 ; \lceil P_n \rceil$$

$$\forall c, d \bullet \square \left(\begin{array}{c} \vdash F \\ \ell = c \end{array} \right) \quad \left(\begin{array}{c} \vdash \lceil P_1 \vee \dots \vee P_n \rceil \\ \ell = d \end{array} \right) \quad \left(\begin{array}{c} \vdash \lceil P_1 \rceil \\ \ell = 4 \end{array} \right)$$

$$\Rightarrow \left(\begin{array}{c} \vdash \ell = c + d + 4 \\ \vdash \lceil P_n \rceil \end{array} \right)$$

$(q) : inc_1 : q' (Increment)$

(i) Change state

$$\square(\lceil q \rceil^1 ; \lceil B \vee C_1 \rceil^1 ; \lceil X \rceil^1 ; \lceil B \vee C_2 \rceil^1 ; \ell = 4 \implies \ell = 4 ; \lceil q' \rceil^1 ; \text{true})$$

$$\models \left(\begin{array}{c} \lceil q \rceil \\ \hline 1 \end{array} \right) \rightarrow \left(\begin{array}{c} \lceil q' \rceil \\ \hline 1 \end{array} \right)$$

$$\Rightarrow \left(\begin{array}{c} \lceil q' \rceil \\ \hline 1 \end{array} \right)$$

(ii) Increment counter

$$\forall d \bullet \square(\lceil q \rceil^1 ; \lceil B \rceil^d ; (\ell = 0 \vee \lceil C_1 \rceil ; \lceil \neg X \rceil) ; \lceil X \rceil^1 ; \lceil B \vee C_2 \rceil^1 ; \ell = 4 \implies \ell = 4 ; \lceil q' \rceil^1 ; (\lceil B \rceil ; \lceil C_1 \rceil ; \lceil B \rceil \wedge \ell = d) ; \text{true})$$

$$\forall d \bullet \square \left(\begin{array}{ccccccccc} \lceil q \rceil & \lceil B \rceil & \lceil C_1 \rceil & \overset{\ell=0}{\lceil \neg X \rceil} & \lceil X \rceil & \lceil B \vee C_2 \rceil & & \\ \hline 1 & d & 1 & 1 & 1 & 1 & 4 & \end{array} \right) \rightarrow \left(\begin{array}{ccccccccc} \lceil q' \rceil & \lceil B \rceil ; \lceil C_1 \rceil ; \lceil B \rceil & & & & & & \\ \hline 1 & d & & & & & & \end{array} \right)$$

$q : inc_1 : q' \text{ (Increment)}$

(i) Keep rest of first counter

$$copy(\lceil q \rceil^1 ; \lceil B \vee C_1 \rceil ; \lceil C_1 \rceil, \{B, C_1\})$$

\mathcal{F}

$\{P_1, P_2\}$

(ii) Leave second counter unchanged

$$copy(\lceil q \rceil^1 ; \lceil B \vee C_1 \rceil ; \lceil X \rceil^1, \{B, C_2\})$$

$q : dec_1 : q', q''$ (Decrement)

(i) If zero

$$\square(\lceil q \rceil^1 ; \lceil B \rceil^1 ; \lceil X \rceil^1 ; \lceil B \vee C_2 \rceil^1 ; \ell = 4 \implies \ell = 4 ; \lceil q' \rceil^1 ; \lceil B \rceil^1 ; \text{true})$$

(ii) Decrement counter

$$\begin{aligned} \forall d \bullet \square(\lceil q \rceil^1 ; (\lceil B \rceil ; \lceil C_1 \rceil \wedge \ell = d) ; \lceil B \rceil ; \lceil B \vee C_1 \rceil ; \lceil X \rceil^1 ; \lceil B \vee C_2 \rceil^1 ; \ell = 4 \\ \implies \ell = 4 ; \lceil q'' \rceil^1 ; \lceil B \rceil^d ; \text{true}) \end{aligned}$$

(iii) Keep rest of first counter

$$copy(\lceil q \rceil^1 ; \lceil B \rceil ; \lceil C_1 \rceil ; \lceil B_1 \rceil, \{B, C_1\})$$

(iv) Leave second counter unchanged

$$copy(\lceil q \rceil^1 ; \lceil B \vee C_1 \rceil ; \lceil X \rceil^1, \{B, C_2\})$$

Final State

$\text{copy}([\lceil q_{fin} \rceil^1 ; \lceil B \vee C_1 \rceil^1 ; \lceil X \rceil ; \lceil B \vee C_2 \rceil^1, \{q_{fin}, B, X, C_1, C_2\})$

Satisfiability

- Following [Chaochen and Hansen, 2004] we can observe that \mathcal{M} **halts if and only if** the DC formula $F(\mathcal{M}) \wedge \Diamond[q_{fin}]$ is **satisfiable**. This yields

Theorem 3.11. The satisfiability problem for DC with continuous time is undecidable.

(It is semi-decidable.)

- Furthermore, by taking the contraposition, we see
 \mathcal{M} **diverges if and only if** \mathcal{M} does not **halt**
if and only if $F(\mathcal{M}) \wedge \neg\Diamond[q_{fin}]$ is **not** satisfiable.
- Thus whether a DC formula is **not satisfiable** is not decidable, not even semi-decidable.

Validity

- By Remark 2.13, F is valid iff $\neg F$ is not satisfiable, so

Corollary 3.12. The validity problem for DC with continuous time is undecidable, not even semi-decidable.

- This provides us with an alternative proof of Theorem 2.23 (“there is no sound and complete proof system for DC”):
 - **Suppose** there were such a calculus \mathcal{C} .
 - By Lemma 2.22 it is semi-decidable whether a given DC formula F is a theorem in \mathcal{C} .
 - By the soundness and completeness of \mathcal{C} , F is a theorem in \mathcal{C} **if and only if** F is valid.
 - Thus it is semi-decidable whether F is valid. **Contradiction.**

Discussion

- Note: the DC fragment defined by the following grammar is **sufficient** for the reduction

$$F ::= [P] \mid \neg F_1 \mid F_1 \vee F_2 \mid F_1 ; F_2 \mid \ell = 1 \mid \ell = x \mid \forall x \bullet F_1,$$

P a state assertion, x a global variable.

- Formulae used in the reduction are abbreviations:

$$\ell = 4 \iff \ell = 1 ; \ell = 1 ; \ell = 1 ; \ell = 1$$

$$\ell \geq 4 \iff \ell = 4 ; \text{true}$$

$$\ell = x + y + 4 \iff \ell = x ; \ell = y ; \ell = 4$$

- Length 1 is not necessary — we can use $\ell = z$ instead, with fresh z .
- This is RDC augmented by “ $\ell = x$ ” and “ $\forall x$ ”, which we denote by **RDC** + $\ell = x, \forall x$.

References

References

- [Chaochen and Hansen, 2004] Chaochen, Z. and Hansen, M. R. (2004). *Duration Calculus: A Formal Approach to Real-Time Systems*. Monographs in Theoretical Computer Science. Springer-Verlag. An EATCS Series.
- [Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.