

Real-Time Systems
Lecture 06: DC Properties I
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Contents & Goals

- DC Syntax and Semantics: Abbreviations ("almost everywhere")
- Satisfiable/Realizable/Valid (from 0)
- Semantical Correctness Proof

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions:
 - What are obstacles on proving a design correct in the realworld, and how to overcome them?
 - Facts: decidability properties
 - What's the idea of the considered (un)decidability proofs?

Content:

- (Un)Decidable problems of DC variants in discrete and continuous time

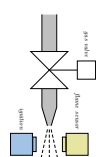
Specification and Semantics-based Correctness Proofs of Real-Time Systems with DC

Methodology: Ideal World...

- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide the **requirement/specification** 'Spec' as a conjunction of DC formulae (over 'Obs').
- (iii) Provide a description 'Ctrl' of the **controller** in form of a DC formula (over 'Obs').
- (iv) We say 'Ctrl' is **correct** (wrt. 'Spec') iff

$$\models_0 \text{Ctrl} \implies \text{Spec}$$

Gas Burner Revisited



- (i) Choose **observables**:
 - two boolean observables G and F (i.e. $\text{Obs} = (G, F)$, $\mathcal{D}(G) = \mathcal{D}(F) = \{0, 1\}$)
 - $G = 1$: gas valve open
 - $F = 1$: have flame
 - define $L := G \wedge \neg F$ (leakage)
- (ii) Provide the **requirement**:

$$\text{Req} := \square (\ell \geq 60 \implies 20 \cdot J \cdot L \leq 0)$$

(output)
(input)

Gas Burner Revisited

- (iii) Provide a description 'Ctrl' of the **controller** in form of a DC formula (over 'Obs')
Here, firstly consider a **design**:
 - $\text{Des-1} := \square (L] \implies \ell \leq 1)$ "places of leakage have length of max 1"
 - $\text{Des-2} := \square ([L] : \neg L] : [L] \implies \ell > 30)$ "shutd where L is false" *the "shutd" where L is false*
- (iv) Prove **correctness**:
 - We want (or do we want $\models_{\text{req}} ?$):

$$\models (\text{Des-1} \wedge \text{Des-2} \implies \text{Req})$$

(Thm. 2.16)
length "higher" than 30

- (iii) Provide a description 'Ctrl' of the controller in form of a DC formula (over 'Obs'). Here, firstly consider a design:
 - Des-1: $\Leftrightarrow \Box([L] \Rightarrow \ell \leq 1)$
 - Des-2: $\Leftrightarrow \Box([L]; [-L]; [L] \Rightarrow \ell > 30)$
- (iv) Prove correctness:
 - We want (or do we want $\models_{0..7}$):
 - Des-1 \wedge Des-2 \Rightarrow Req
 - We do show
 - Req-1 \Rightarrow Req
 - with the simplified requirement
 - Req-1 := $\Box(\ell \leq 30 \Rightarrow \int L \leq 1)$
 - and we show
 - Des-1 \wedge Des-2 \Rightarrow Req-1

(Thm. 2.16)
(Lem. 2.17)
(Lem. 2.19)
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Some Laws of the DC Integral Operator

- Theorem 2.18**
For all state assertions P and all real numbers $r_1, r_2 \in \mathbb{R}$,
- (i) $\models P \leq \ell$
 - (ii) $\models (P = r_1) \wedge (P = r_2) \Rightarrow (P = r_1 + r_2)$
 - (iii) $\models \neg P \Rightarrow \int P = 0$
 - (iv) $\models \Box \Rightarrow \int P = 0$

Gas Burner Revised: Lemma 2.17

Claim: $\models \Box(\ell \leq 30) \Rightarrow \int L \leq 1$

Proof: Assume 'Req-1': Let I, z be any interpretation of L , and $[b, e]$ an interval with $e - b \geq 0$. Show $\int_{b..e} L \leq 1$, i.e.

$\int_{b..e} L \leq \int_{b..e} \ell \leq \int_{b..e} 1 = e - b = \ell$

i.e. $\int_{b..e} L \leq \ell$

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Gas Burner Revised: Lemma 2.18

Claim: $\models \Box(\ell \leq 0) \Rightarrow \int L \leq 0$

Proof: $\ell \leq 0$

$\int_{b..e} L \leq \int_{b..e} \ell \leq \int_{b..e} 0 = 0$

$\int_{b..e} L \leq 0$

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Gas Burner Revised: Lemma 2.17

Set $n := \lfloor \frac{e-b}{\Delta} \rfloor$, i.e. $n \in \mathbb{N}$ with $n - 1 < \frac{e-b}{\Delta} \leq n$, and split the interval

$\int_{b..e} L = \int_{b..b+\Delta} L + \int_{b+\Delta..b+2\Delta} L + \dots + \int_{b+(n-1)\Delta..b+n\Delta} L + \int_{b+n\Delta..e} L$

$\leq \int_{b..b+\Delta} \ell + \int_{b+\Delta..b+2\Delta} \ell + \dots + \int_{b+(n-1)\Delta..b+n\Delta} \ell + \int_{b+n\Delta..e} \ell$

$\leq \int_{b..e} \ell \leq \int_{b..e} 1 = e - b = \ell$

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Obstacles in Non-Ideal World

- (i) Choose a collection of **observables**, 'Obs'.
- (ii) Provide **specification** 'Spec' (conjunction of DC formulae (over 'Obs'))
- (iii) Provide a description 'Ctrl' of the **controller** (DC formula (over 'Obs'))
- (iv) Prove 'Ctrl' is **correct** (wrt. 'Spec')

That looks **too simple to be practical**. Typical **obstacles**:

- (i) It may be impossible to realise 'Spec' if it doesn't consider properties of the **plant**.
- (ii) There are typically **intermediate design levels** between 'Spec' and 'Ctrl'.
- (iii) 'Spec' and 'Ctrl' may use **different observables**.
- (iv) **Proving** validity of the implication is not trivial.

- When the controller will (or can) operate correctly only under some **assumptions**.
- For instance, with a level crossing
 - we may assume an upper bound on the speed of approaching trains, (otherwise we'd need to close the gates arbitrarily fast)
 - we may assume that trains are not arbitrarily slow in the crossing, (otherwise we can't make promises to the road traffic)
- We shall specify such assumptions as a DC formula 'Asm' on the **input observables** and verify correctness of 'Ctrl' wrt. 'Spec' by proving validity (from U) of

$$\text{Ctrl} \wedge \text{Asm} \implies \text{Spec}$$
- Shall we **care** whether 'Asm' is satisfiable?

Ctrl is false \implies Spec is false when not satisfied

- A top-down development approach may involve
 - Spec — specification/requirements
 - Des — design
 - Ctrl — implementation
- Then correctness is established by proving validity of

$$\text{Ctrl} \implies \text{Des} \tag{1}$$
- and

$$\text{Des} \implies \text{Spec} \tag{2}$$
 (then concluding Ctrl \implies Spec by transitivity)
- Any preference on the order?

Obstacle (iii): Different Observables

- Assume, 'Spec' uses more abstract observables Obs_A and 'Ctrl' more concrete ones Obs_C.
- For instance:
 - in Obs_A: only consider gas valve open or closed ($D(G) = \{0, 1\}$)
 - in Obs_C: may control two valves and care for intermediate positions, for instance, to react to different heating requests ($D(G_1) = \{0, 1, 2, 3\}; D(G_2) = \{0, 1, 2, 3\}$)
- To prove correctness, we need information how the observables are related — an **invariant** which links the data values of Obs_A and Obs_C.
- If we're given the linking invariant as a DC formula, say 'Link_{C,A}', then proving correctness of 'Ctrl' wrt. 'Spec' amounts to proving validity (from U) of

$$\text{Ctrl} \wedge \text{Link}_{C,A} \implies \text{Spec}$$

- For instance,

$$\text{Link}_{C,A} = \square [G \wedge (G_1 + G_2 > 0)]$$

$$\square [G \wedge (G_1 = 0 \wedge G_2 = 0) \wedge 1]$$

Obstacle (iv): How to Prove Correctness?

- by hand on the basis of DC semantics,
- maybe supported by proof rules,
- sometimes a general theorem may fit (e.g. cycle times of PLC automata),
- algorithms as in Uppaal

DC Properties

Decidability Results: Motivation

- Recall: Given assumptions as a DC formula 'Asm' on the input observables, verifying **correctness** of 'Ctrl' wrt. 'Spec' amounts to proving

$$\models_{\text{Asm}} \text{Ctrl} \wedge \text{Asm} \implies \text{Spec} \tag{1}$$
- If 'Asm' is **not satisfiable** then (1) is trivially valid, and thus each 'Ctrl' correct wrt. 'Spec'.
- So, strong interest in assessing the **satisfiability** of DC formulae.
- Question: is there an automatic procedure to help us out? (a.k.a.: is it **decidable** whether a given DC formula is satisfiable?)

- More interesting for 'Spec': is it **realisable** (from 0)?
- Question: is it **decidable** whether a given DC formula is realisable?

Decidability Results for Realisability: Overview

restricted DC

Fragment	Discrete Time	Continuous Time
RDC	decidable	decidable
RDC + $\ell = r$	decidable for $r \in \mathbb{N}$	undecidable for $r \in \mathbb{R}^+$
RDC + $fA_1 = fA_2$	undecidable	undecidable
RDC + $\ell = x, \forall x$	undecidable	undecidable
DC	undecidable	undecidable

RDC in Discrete Time

Restricted DC (RDC)

$$F := [P \mid \neg F_1 \mid F_1 \vee F_2 \mid F_1 \wedge F_2]$$

where P is a state assertion, but with **boolean observables only**.

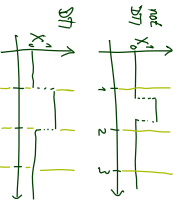
- Note:
- No global variables, thus don't need γ .
 - dup is **static**.
 - no f_1 no ℓ (ℓ is **global**)
 - no **predicate**, no **function symbols**
 - $\exists x \dots ?$
 - $\exists \dots ?$

Discrete Time Interpretations

- An interpretation I is called **discrete time interpretation** if and only if, for each state variable X ,

$$X_I : \text{Time} \rightarrow \mathcal{D}(X)$$

- with
- Time = \mathbb{R}_0^+
 - all discontinuities are in \mathbb{N}_0



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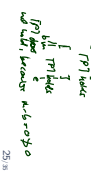
- An interval $[b, c] \subset \text{Intv}$ is called **discrete** if and only if $b, c \in \mathbb{N}_0$.

- We say (for a discrete time interpretation I and a discrete interval $[b, c]$)

$I \upharpoonright [b, c] \models F_1 \wedge F_2$
 if and only if there exists $m \in [b, c] \cap \mathbb{N}_0$ such that
 $I \upharpoonright [b, m] \models F_1$ and $I \upharpoonright [m, c] \models F_2$

Differences between Continuous and Discrete Time

Let P be a state assertion.	Continuous Time	Discrete Time
$\models^c ([P]; [P]) \Rightarrow [P]$	✓	✓
$\models^d ([P]; [P]) \Rightarrow [P]$	✓	✗



Differences between Continuous and Discrete Time

Let P be a state assertion.	Continuous Time	Discrete Time
$\models^c ([P]; [P]) \Rightarrow [P]$	✓	✓
$\models^d ([P]; [P]) \Rightarrow [P]$	✓	✗

In particular: $\ell = 1 \iff ([\top] \wedge \neg([\top]; [\top]))$ (in discrete time)

Expressiveness of RDC

- $\ell = 1 \iff [\top] \wedge \neg([\top]; [\top])$
- $\ell = 0 \iff \neg[\top]$
- $true \iff \ell = 0 \vee \neg(\ell = 0)$
- $J.P = 0 \iff \neg P \vee \ell = 0$
- $J.P = 1 \iff (P = 0) \wedge (\neg P \wedge \ell = 1) \vee P = 0$
- $J.P = k + 1 \iff (P = k) \wedge (P = 1)$
- $J.P \geq k \iff (P = k) \wedge true$
- $J.P > k \iff J.P \geq k + 1$
- $J.P \leq k \iff \neg(J.P > k)$
- $J.P < k \iff J.P \leq k - 1$

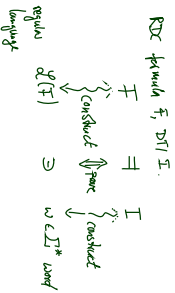
where $k \in \mathbb{N}$.

all $\iff \neg \text{true} = \text{false}$, $\neg true$ is RDC

Decidability of Satisfiability/Realisability from 0

Theorem 3.6. The satisfiability problem for RDC with discrete time is decidable.

Theorem 3.9. The realisability problem for RDC with discrete time is decidable.



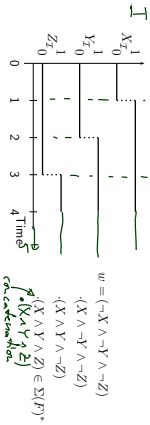
Sketch: Proof of Theorem 3.6

- give a procedure to construct, given a formula F , a regular language $L(F)$ such that $\mathcal{I}. [0, n] \models F$ if and only if $w \in L(F)$ (where word w describes \mathcal{I} on $[0, n]$) (satisfiability of the procedure: Lemma 3.4)
- then F is satisfiable in discrete time if and only if $L(F)$ is not empty (Lemma 3.3)
- Theorem 3.6 follows because
- $L(F)$ can effectively be constructed,
- the emptiness problem is decidable for regular languages.

Construction of $\mathcal{L}(F)$

- Idea:
 - alphabet $\Sigma(F)$ consists of basic conjuncts of the state variables in F ,
 - a letter corresponds to an interpretation on an interval of length 1,
 - a word of length n describes an interpretation on interval $[0, n]$.

• **Example:** Assume F contains exactly state variables X, Y, Z , then
 $\Sigma(F) = \{ \underbrace{X \wedge Y \wedge Z}, \underbrace{X \wedge Y \wedge \neg Z}, \underbrace{X \wedge \neg Y \wedge Z}, \underbrace{X \wedge \neg Y \wedge \neg Z}, \underbrace{\neg X \wedge Y \wedge Z}, \underbrace{\neg X \wedge Y \wedge \neg Z}, \underbrace{\neg X \wedge \neg Y \wedge Z}, \underbrace{\neg X \wedge \neg Y \wedge \neg Z} \}$



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Construction of $\mathcal{L}(F)$ more formally

Definition 3.2. A word $w = a_1 \dots a_n \in \Sigma(F)^*$ with $n \geq 0$ describes a discrete interpretation \mathcal{I} on $[0, n]$ if and only if
 $\forall j \in \{1, \dots, n\} \forall i \in \{j-1, j\} : \mathcal{I}[a_j](i) = 1$
 For $n = 0$ we put $w = \varepsilon$.

- Each state assertion P can be transformed into an equivalent disjunctive normal form $\bigvee_{i=1}^m a_i$ with $a_i \in \Sigma(F)$.
- Set $DNF(P) := \{a_1, \dots, a_m\} \subseteq \Sigma(F)$.
- Define $\mathcal{L}(F)$ inductively:

$$\begin{aligned} \mathcal{L}(\top) &= DNF(\top) \\ \mathcal{L}(\neg \top) &= \Sigma(F) \setminus \mathcal{L}(\top) \\ \mathcal{L}(F_1 \vee F_2) &= \mathcal{L}(F_1) \cup \mathcal{L}(F_2) \\ \mathcal{L}(F_1 \wedge F_2) &= \mathcal{L}(F_1) \cap \mathcal{L}(F_2) \end{aligned}$$

Hand cards of length at least one

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References

[Oderog and Dierks, 2008] Oderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.

References