Real-Time Systems

Lecture 06: DC Properties I

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Contents & Goals

Last Lecture:

- DC Syntax and Semantics: Abbreviations ("almost everywhere")
- Satisfiable/Realisable/Valid (from 0)
- Semantical Correctness Proof

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
  - What are obstacles on proving a design correct in the real-world, and how to overcome them?
  - Facts: decidability properties.
  - What's the idea of the considered (un)decidability proofs?

- **Content:**
  - (Un-)Decidable problems of DC variants in discrete and continuous time
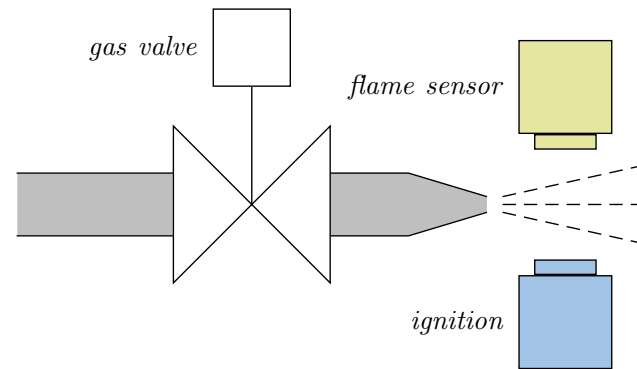
Specification and Semantics-based Correctness Proofs of Real-Time Systems with DC

Methodology: Ideal World...

(i) Choose a collection of **observables** 'Obs'.

(ii) Provide the **requirement**/**specification** 'Spec'
as a conjunction of DC formulae (over 'Obs').

(iii) Provide a description 'Ctrl'
of the **controller** in form of a DC formula (over 'Obs').

(iv) We say 'Ctrl' is **correct** (wrt. 'Spec') iff

$$\models_0 \text{Ctrl} \implies \text{Spec}.$$

Gas Burner Revisited

gas valve

flame sensor

ignition

(i) Choose **observables**:

- two boolean observables G and F
  (i.e. $\mathrm{Obs} = \{G, F\}$, $\mathcal{D}(G) = \mathcal{D}(F) = \{0, 1\}$)
- $G = 1$: gas valve open   (output)
- $F = 1$: have flame   (input)
- define $L := G \wedge \neg F$ (leakage)

(ii) Provide the **requirement**:

$$\mathrm{Req} : \iff \Box(\ell \geq 60 \implies 20 \cdot \smallint L \leq \ell)$$

Gas Burner Revisited

(iii) Provide a description 'Ctrl'
of the **controller** in form of a DC formula (over 'Obs').
Here, firstly consider a **design**:

- Des-1 : $\iff \square(\lceil L \rceil \implies \ell \leq 1)$ *"phases of leakage have length at most 1"*

- Des-2 : $\iff \square(\lceil L \rceil ; \lceil \neg L \rceil ; \lceil L \rceil \implies \ell > 30)$ *"intervals where L_I looks*
    like ⌐:____:⌐ should
    L $\neg L$ L
    length bigger than 30"

(iv) Prove **correctness**:
- We want (or do we want $\models_0$...?):

$$\models (\text{Des-1} \wedge \text{Des-2} \implies \text{Req}) \qquad (\text{Thm. 2.16})$$

Gas Burner Revisited

(iii) Provide a description 'Ctrl'
of the **controller** in form of a DC formula (over 'Obs').
Here, firstly consider a **design**:

- Des-1 : $\iff \Box(\lceil L \rceil \implies \ell \le 1)$

- Des-2 : $\iff \Box(\lceil L \rceil ; \lceil \neg L \rceil ; \lceil L \rceil \implies \ell > 30)$

(iv) Prove **correctness**:

- We want (or do we want $\models_0$...?):

$$\models (\text{Des-1} \wedge \text{Des-2} \implies \text{Req}) \qquad \text{(Thm. 2.16)}$$

- We do show

$$\models \text{Req-1} \implies \text{Req} \qquad \text{(Lem. 2.17)}$$

with the simplified requirement

$$\text{Req-1} := \Box(\ell \le 30 \implies \int L \le 1),$$

- and we show

$$\models (\text{Des-1} \wedge \text{Des-2}) \implies \text{Req-1}. \qquad \text{(Lem. 2.19)}$$

Gas Burner Revisited: Lemma 2.17

Claim: ... *for all $\mathcal{I}, V, [b,e]$*

$$\models \underbrace{\Box(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}} \implies \underbrace{\Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)}_{\text{Req}}$$

Proof:

- Assume 'Req-1'.

- Let $L_{\mathcal{I}}$ be any interpretation of L, and $[b, e]$ an interval with $e - b \geq 60$, *let V a valuation.*

- Show "$20 \cdot \int L \leq \ell$", i.e.

$$\mathcal{I}[\![20 \cdot \int L \leq \ell]\!](V, [b,e]) = tt$$

i.e.

$$20 \cdot \int_b^e L_{\mathcal{I}}(t)\, dt \stackrel{!}{\leq} (e - b)$$

$$\models \underbrace{\Box(\ell \le 30 \implies \int L \le 1)}_{\text{Req-1}}$$

$$\implies \Box(\ell \ge 60 \implies 20 \cdot \int L \le \ell)$$

- Set $n := \lceil \frac{e-b}{30} \rceil$, i.e. $n \in \mathbb{N}$ with $n - 1 < \frac{e-b}{30} \le n$, and split the interval

$$b + 30 \qquad b + 60 \qquad b + 30(n-2) \quad b + 30(n-1) \qquad b + 30n$$

b $\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad$ e

may be shorter than 60

$$20 \cdot \int_b^e L_{\mathcal{I}}(t)\, dt$$

$$= 20 \cdot \left(\sum_{i=0}^{n-2} \int_{b+30i}^{b+30(i+1)} L_{\mathcal{I}}(t)\, dt + \int_{b+30(n-1)}^{e} L_{\mathcal{I}}(t)\, dt \right)$$

$$\{\text{Req-1}\} \le 20 \cdot \sum_{i=0}^{n-2} 1 + 20 \cdot 1$$

$$= 20 \cdot n$$

$$\{n-1 < \tfrac{e-b}{30}\} < 20 \left(\frac{e-b}{30} + 1 \right)$$

$$= \tfrac{2}{3}(e-b) + 20$$

$$\le e-b$$

$$\begin{cases} e-b \ge 60 \\ \hookrightarrow \\ 20 \le \tfrac{1}{3}(e-b) \end{cases}$$

Theorem 2.18

For all state assertions P and all real numbers $r_1, r_2 \in \mathbb{R}$,

(i) $\models \int P \leq \ell$,

(ii) $\models \big((\int P = r_1)\,;\,(\int P = r_2)\big) \Longrightarrow \big(\int P = r_1 + r_2,\big)$

(iii) $\models \lceil \neg P \rceil \Longrightarrow \int P = 0$,

(iv) $\models \lceil\,\rceil \Longrightarrow \int P = 0$.

(i) $\models \int P \le \ell,$ (iv) $\models \lceil\top\rceil \implies \int P = 0.$
(ii) $\models (\int P = r_1)\,;\,(\int P = r_2)$
$\implies \int P = r_1 + r_2,$
(iii) $\models \lceil \neg P \rceil \implies \int P = 0,$

Claim:

$$\models (\Box(\lceil L \rceil \implies \ell \le 1) \land \Box(\lceil L \rceil\,;\,\lceil \neg L \rceil\,;\,\lceil L \rceil \implies \ell > 30)) \implies \Box(\ell \le 30 \implies \int L \le 1)$$

$\underbrace{}_{\text{Des-1}}$ $\underbrace{}_{\text{Des-2}}$ $\underbrace{}_{\text{Req-1}}$

Proof:

$\ell \le 30$

$\{\text{finite}\atop\text{variability}\} \implies \lceil\top\rceil$
$\lor \lceil L \rceil\,;\,(\lceil\top\rceil \lor \lceil\neg L\rceil)$ $\Big\}$ (*)
$\lor \lceil\neg L\rceil\,;\,(\lceil\top\rceil \lor \lceil L\rceil)$
$\lor \lceil\neg L\rceil\,;\,\lceil L\rceil\,;\,\lceil\neg L\rceil$
$\lor \ell \le 30 \land \Diamond(\lceil L\rceil\,;\,\lceil\neg L\rceil\,;\,\lceil L\rceil) \}$ Des-2

$\{\text{Des-2}\} \implies (*)$
$\{\text{Des-1}\} \implies \lceil\top\rceil$
$\lor (\ell \le 1)\,;\,(\lceil\top\rceil \lor \lceil\neg L\rceil)$
$\lor \lceil\neg L\rceil\,;\,(\lceil\top\rceil \lor \ell \le 1)$
$\lor \lceil\neg L\rceil\,;\,\ell \le 1\,;\,\lceil\neg L\rceil$

$\{;\!1\} \implies \lceil\top\rceil$
$\lor (\int L \le 1)\,;\,(\lceil\top\rceil \lor \lceil\neg L\rceil)$
$\lor \lceil\neg L\rceil\,;\,(\lceil\top\rceil \lor \int L \le 1)$
$\lor \lceil\neg L\rceil\,;\,\int L \le 1\,;\,\lceil\neg L\rceil$

$\{(iv),\atop (iii)\} \implies \int L = 0$
$\lor (\int L \le 1)\,;\,(\int L = 0 \lor \int L = 0)$
$\lor \int L = 0\,;\,(\int L = 0 \lor \int L \le 1)$
$\lor \int L = 0\,;\,\int L \le 1\,;\,\int L = 0$

$\{(i;\!)\} \implies \int L = 0$
$\lor \int L \le 1 + 0$
$\lor \int L \le 0 + 1$
$\lor \int L \le 0 + 1 + 0$
$\implies \int L \le 1$

Obstacles in Non-Ideal World

Methodology: The World is Not Ideal...

 (i) Choose a collection of **observables** 'Obs'.

 (ii) Provide **specification** 'Spec' (conjunction of DC formulae (over 'Obs')).

(iii) Provide a description 'Ctrl' of the **controller** (DC formula (over 'Obs')).

(iv) Prove 'Ctrl' is **correct** (wrt. 'Spec').

That looks **too simple to be practical**. Typical **obstacles**:

 (i) It may be impossible to realise 'Spec'
      if it doesn't consider properties of **the plant**.

 (ii) There are typically intermediate **design levels** between 'Spec' and 'Ctrl'.

(iii) 'Spec' and 'Ctrl' may use **different observables**.

(iv) **Proving** validity of the implication is not trivial.

- Often the controller will (or can) operate correctly only under some **assumptions**.

- For instance, with a level crossing
  - we may assume an upper bound on the speed of approaching trains, (otherwise we'd need to close the gates arbitrarily fast)
  - we may assume that trains are not arbitrarily slow in the crossing, (otherwise we can't make promises to the road traffic)

- We shall specify such assumptions as a DC formula 'Asm' on the **input observables** and verify correctness of 'Ctrl' wrt. 'Spec' by proving validity (from 0) of
$$\text{Ctrl} \wedge \text{Asm} \implies \text{Spec}$$

- Shall we **care** whether 'Asm' is satisfiable?

$$\text{Ctrl} \wedge \text{false} \implies \text{Spec} \quad \text{if Asm not satisfiable}$$

Obstacle (ii): Intermediate Design Levels

- A top-down development approach may involve
  - Spec — specification/requirements
  - Des — design
  - Ctrl — implementation
- Then correctness is established by proving validity of

$$\text{Ctrl} \implies \text{Des} \tag{1}$$

and

$$\text{Des} \implies \text{Spec} \tag{2}$$

(then concluding Ctrl $\implies$ Spec by transitivity)
- Any preference on the order?

Obstacle (iii): Different Observables

- Assume, 'Spec' uses more abstract observables Obs_A and 'Ctrl' more concrete ones Obs_C.

- For instance:
  - in Obs_A: only consider gas valve open or closed $(\mathcal{D}(G) = \{0, 1\})$
  - in Obs_C: may control two valves and care for intermediate positions, for instance, to react to different heating requests
    $(\mathcal{D}(G_1) = \{0, 1, 2, 3\}, \mathcal{D}(G_2) = \{0, 1, 2, 3\})$

- To prove correctness, we need information how the observables are related — an **invariant** which **links** the data values of Obs_A and Obs_C.

- **If** we're given the linking invariant as a DC formula, say '$\text{Link}_{C,A}$', **then** proving correctness of 'Ctrl' wrt. 'Spec' amounts to proving validity (from 0) of

$$\text{Ctrl} \wedge \underbrace{\text{Link}_{C,A}} \implies \text{Spec}.$$

- For instance,

$$\text{Link}_{C,A} = \square \lceil G \Leftrightarrow (G_1 + G_2 > 0) \rceil$$
$$\bigcirc \lceil \neg G \Leftrightarrow (G_1 = 0 \wedge G_2 = 0) \rceil$$

- by hand on the basis of DC semantics,

- maybe supported by proof rules,

- sometimes a general theorem may fit (e.g. cycle times of PLC automata),

- algorithms as in Uppaal.

DC Properties

Decidability Results: Motivation

- Recall:

  Given **assumptions** as a DC formula 'Asm' on the input observables, verifying **correctness** of 'Ctrl' wrt. 'Spec' amounts to proving

  $$\models_0 \text{Ctrl} \wedge \text{Asm} \implies \text{Spec} \tag{1}$$

- If 'Asm' is **not satisfiable** then (1) is trivially valid, and thus each 'Ctrl' correct wrt. 'Spec'.

- So: strong interest in assessing the **satisfiability** of DC formulae.

- Question: is there an automatic procedure to help us out? (a.k.a.: is it **decidable** whether a given DC formula is satisfiable?)

- More interesting for 'Spec': is it **realisable** (from 0)?

- Question: is it **decidable** whether a given DC formula is realisable?

restricted DC

Fragment	Discrete Time	Continous Time
RDC	decidable	decidable
RDC $+\, \ell = r$	decidable for $r \in \mathbb{N}$	undecidable for $r \in \mathbb{R}^+$
RDC $+ \int P_1 = \int P_2$	undecidable	undecidable
RDC $+\, \ell = x, \forall\, x$	undecidable	undecidable
DC	undecidable	undecidable

RDC in Discrete Time

Restricted DC (RDC)

$$0 \mid \neg \neg X = 0 \mid X = 1 \mid \neg P \mid P_1 \vee P_2$$

$$F ::= \lceil P \rceil \mid \neg F_1 \mid F_1 \vee F_2 \mid F_1 \; ; \; F_2$$

where P is a state assertion, but with **boolean** observables **only**.

Note:

- No global variables, thus don't need $\mathcal{V}$.
- chop is there
- no $\int_1$ no ℓ (in general)
- no predicate, no function symbols
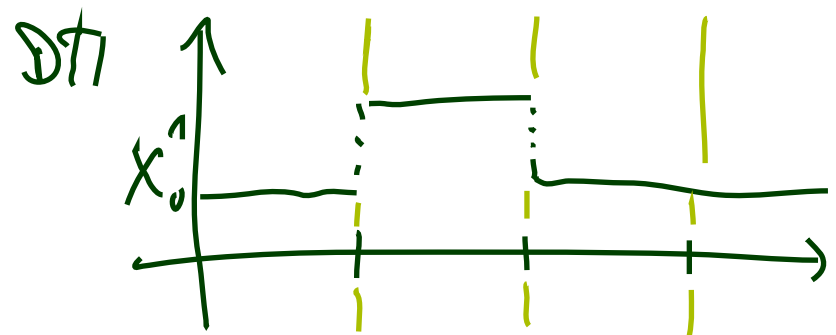- $\Diamond F \dots$?
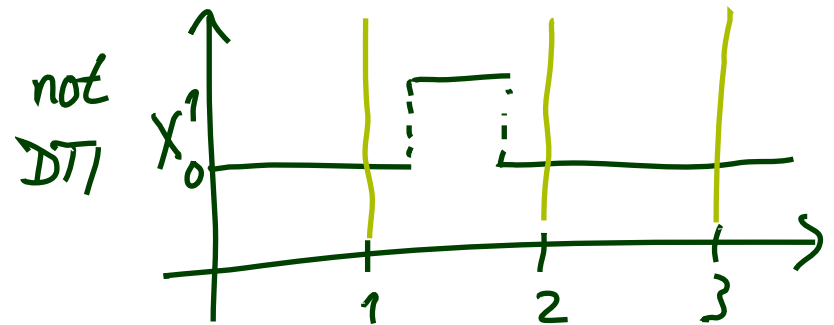- $\lceil 1 \rceil \dots$?

Discrete Time Interpretations

- An interpretation $\mathcal{I}$ is called **discrete time interpretation** if and only if, for each state variable X,

$$X_{\mathcal{I}} : \mathsf{Time} \to \mathcal{D}(X)$$

with

- $\mathsf{Time} = \mathbb{R}_0^+$,
- all discontinuities are in $\mathbb{N}_0$.

Discrete Time Interpretations

- An interpretation $\mathcal{I}$ is called **discrete time interpretation** if and only if, for each state variable X,

$$X_{\mathcal{I}} : \text{Time} \to \mathcal{D}(X)$$

  with

  - $\text{Time} = \mathbb{R}_0^+$,
  - all discontinuities are in $\mathbb{N}_0$.

- we say $\mathcal{I}, [b,e] \models \lceil P \rceil$

  iff

  $$\int_b^e P_{\mathcal{I}}(t)\, dt = (e-b)$$
  $$\wedge\ (e-b) > 0$$

- An interval $[b, e] \subset \text{Intv}$ is called **discrete** if and only if $b, e \in \mathbb{N}_0$.

- We say (for a discrete time interpretation $\mathcal{I}$ and a discrete interval $[b, e]$)
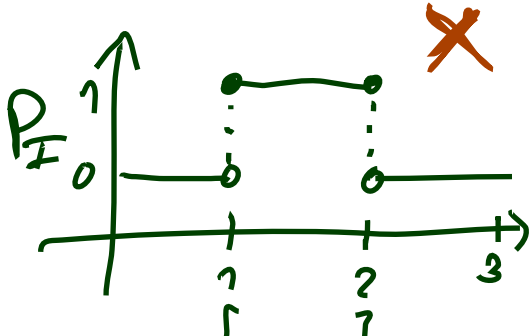
$$\mathcal{I}, [b, e] \models F_1\ ;\ F_2$$

  if and only if there exists $m \in [b, e] \cap \mathbb{N}_0$ such that

$$\mathcal{I}, [b, m] \models F_1 \qquad \text{and} \qquad \mathcal{I}, [m, e] \models F_2$$

- Let P be a state assertion.

	Continuous Time	Discrete Time
$\models^? (\lceil P \rceil \,;\, \lceil P \rceil)$ $\implies \lceil P \rceil$	✓	✓
$\models^? \lceil P \rceil \implies$ $(\lceil P \rceil \,;\, \lceil P \rceil)$	✓	

- Let P be a state assertion.

	Continuous Time	Discrete Time
$\models^? (\lceil P \rceil \,;\, \lceil P \rceil)$ $\implies \lceil P \rceil$	✔	✔
$\models^? \lceil P \rceil \implies$ $(\lceil P \rceil \,;\, \lceil P \rceil)$	✔	✘

- In particular: $\ell = 1 \iff (\lceil 1 \rceil \wedge \neg(\lceil 1 \rceil \,;\, \lceil 1 \rceil))$ (in discrete time).

Expressiveness of RDC

- $\ell = 1$ $:\Longleftrightarrow$ $\lceil 1 \rceil \wedge \neg(\lceil 1 \rceil \,;\, \lceil 1 \rceil)$

- $\ell = 0$ $:\Longleftrightarrow$ $\neg \lceil 1 \rceil$

- $true$ $:\Longleftrightarrow$ $\ell = 0 \vee \neg(\ell = 0)$

- $\int P = 0$ $:\Longleftrightarrow$ $\lceil \neg P \rceil \vee \ell = 0$

- $\int P = 1$ $\Longleftrightarrow$ $(\int P = 0) \,;\, (\lceil P \rceil \wedge \ell = 1) \,;\, \int P = 0$

- $\int P = k+1$ $\Longleftrightarrow$ $(\int P = k) \,;\, (\int P = 1)$

- $\int P \geq k$ $\Longleftrightarrow$ $(\int P = k) \,;\, true$

- $\int P > k$ $\Longleftrightarrow$ $\int P \geq k+1$

- $\int P \leq k$ $\Longleftrightarrow$ $\neg(\int P > k)$

- $\int P < k$ $\Longleftrightarrow$ $\int P \leq k-1$

where $k \in \mathbb{N}$.

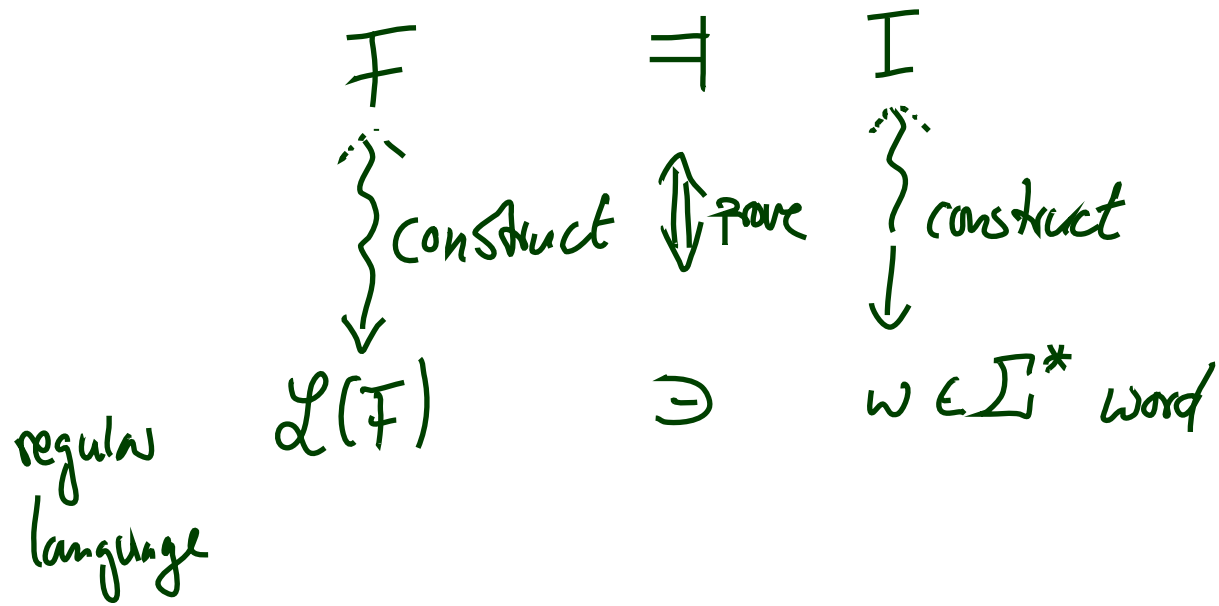still
$\Diamond F := true \,;\, F \,;\, true$
in RDC

Theorem 3.6.

The satisfiability problem for RDC with discrete time is decidable.

Theorem 3.9.

The realisability problem for RDC with discrete time is decidable.

RDC formula F, DTI I.

$$F \qquad \models \qquad I$$

$\left\{ \text{construct} \right.$ $\Uparrow$ prove $\left. \right\} \text{construct}$

$$\mathcal{L}(F) \qquad \supseteq \qquad w \in \Sigma_i^* \text{ word}$$

regular
language

- give a procedure to construct, given a formula F, a **regular** language $\mathcal{L}(F)$ such that

$$\mathcal{I}, [0, n] \models F \text{ if and only if } w \in \mathcal{L}(F)$$

  where word w describes $\mathcal{I}$ on $[0, n]$
  (suitability of the procedure: **Lemma 3.4**)

- then F is satisfiable in discrete time if and only if $\mathcal{L}(F)$ is not empty
  (**Lemma 3.5**)

- Theorem 3.6 follows because
  - $\mathcal{L}(F)$ can **effectively** be constructed,
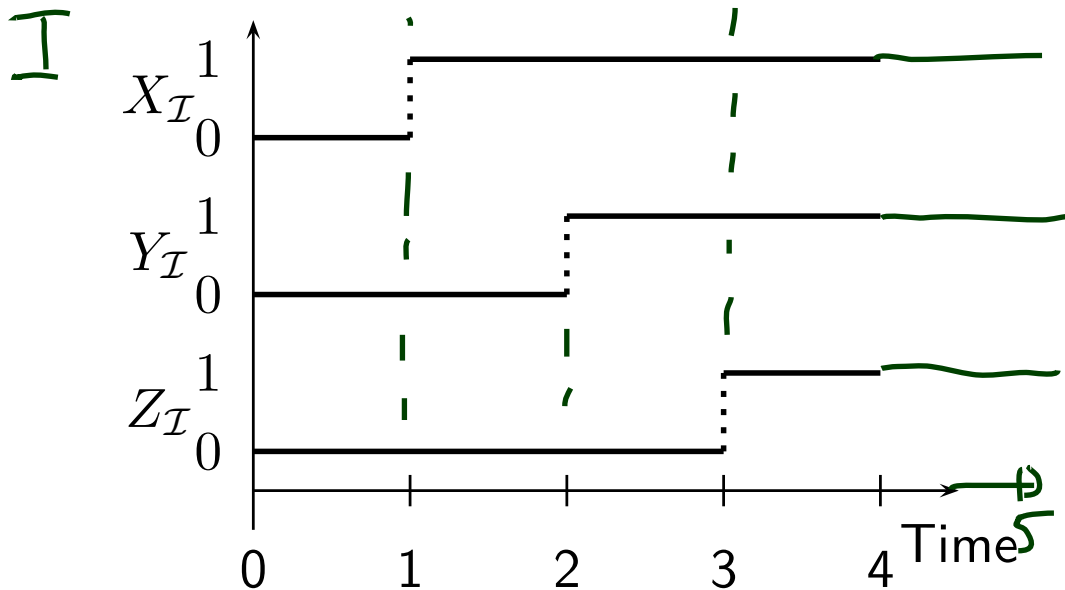 - the emptyness problem is **decidable** for regular languages.

- **Idea:**
    - alphabet $\Sigma(F)$ consists of <u>basic conjuncts</u> of the state variables in F,
    - a letter corresponds to an interpretation on an interval of length 1,
    - a word of length n describes an interpretation on interval $[0, n]$.

- **Example:** Assume F contains exactly state variables X, Y, Z, then

$$\Sigma(F) = \{ \underset{\sim\sim\sim\sim\sim}{X \wedge Y \wedge Z}, X \wedge Y \wedge \neg Z, X \wedge \neg Y \wedge Z, X \wedge \neg Y \wedge \neg Z,$$

$$\neg X \wedge Y \wedge Z, \underline{\neg X \wedge Y \wedge \neg Z}, \neg X \wedge \neg Y \wedge Z, \underline{\neg X \wedge \neg Y \wedge \neg Z} \}.$$

$$w = (\neg X \wedge \neg Y \wedge \neg Z)$$
$$\cdot (X \wedge \neg Y \wedge \neg Z)$$
$$\cdot (X \wedge Y \wedge \neg Z)$$
$$\cdot (X \wedge Y \wedge Z) \in \Sigma(F)^*$$

$$\uparrow \cdot (X \wedge Y \wedge Z)$$
concatenation

Definition 3.2. A word $w = a_1 \ldots a_n \in \Sigma(F)^*$ with $n \geq 0$ **describes** a **discrete** interpretation $\mathcal{I}$ on $[0, n]$ if and only if

$$\forall j \in \{1, \ldots, n\} \; \forall t \in \,]j-1, j[\, : \mathcal{I}[\![a_j]\!](t) = 1.$$

For $n = 0$ we put $w = \varepsilon$.

- Each state assertion P can be transformed into an equivalent **disjunctive normal form** $\bigvee_{i=1}^{m} a_i$ with $a_i \in \Sigma(F)$.
- Set $DNF(P) := \{a_1, \ldots, a_m\} \; (\subseteq \Sigma(F))$. *finite words of length at least one*
- Define $\mathcal{L}(F)$ inductively:

$$\mathcal{L}(\lceil P \rceil) = DNF(P)^+,$$
$$\mathcal{L}(\neg F_1) = \Sigma(F) \setminus \mathcal{L}(F_1),$$
$$\mathcal{L}(F_1 \vee F_2) = \mathcal{L}(F_1) \cup \mathcal{L}(F_2),$$
$$\mathcal{L}(F_1 \, ; F_2) = \mathcal{L}(F_1) \cdot \mathcal{L}(F_2)$$

References

References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.