

# *Real-Time Systems*

## *Lecture 08: DC Implementables*

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### *Contents & Goals*

#### **Last Lectures:**

- (Un)decidability results for fragments of DC in discrete and continuous time.

#### **This Lecture:**

- **Educational Objectives:** Capabilities for following tasks/questions.
  - What does this standard forms mean? Give a satisfying interpretation.
  - What are implementables? What is a control automaton?
  - Please specify (and prove correct) a controller which satisfies this requirement.
- **Content:**
  - DC Standard Forms
  - Control Automata
  - DC Implementables
  - Example

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## DC Implementables

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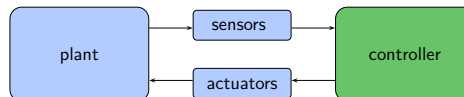
### Requirements vs. Implementations

- **Problem:** in general, a DC requirement doesn't tell **how** to achieve it, how to build a controller/write a program which ensures it.

- What a controller (clearly) can do is:

- consider inputs now,
- change (local) state, or
- wait,
- set outputs now.

(But not, e.g., consider future inputs now.)



- So, if we have
  - a DC requirement 'Req',
  - a description 'Impl' in DC, which "uses" **just these** operations,

then

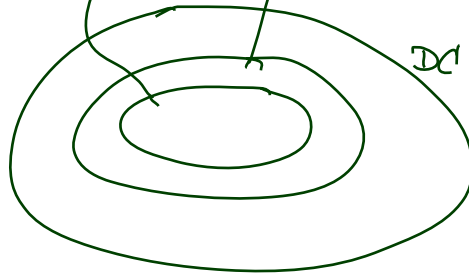
- proving correctness amounts to proving  $\models_0 \text{Impl} \implies \text{Req}$  (in DC)
- and we (more or less) know how to program (the correct) 'Impl' in a PLC language, or in C on a real-time OS, or or...

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Plan:

- Introduce **DC Standard Forms**
- Introduce **Control Automata**
- Introduce **DC Implementables** as subset of **DC Standard Forms**
- Example: a correct controller design for the notorious Gas Burner



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DC Standard Forms: Followed-by

no P, no P

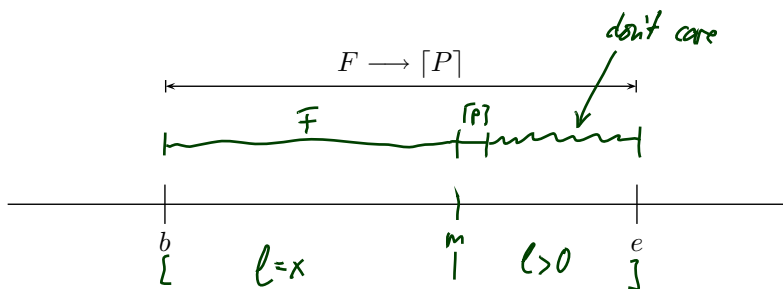
In the following:  $F$  is a DC formula,  $P$  a state assertion,  $\theta$  a rigid term.

- **Followed-by:**

$$F \rightarrow [P] : \Leftrightarrow \neg \diamond (F ; [\neg P]) \Leftrightarrow \Box \neg (F ; [\neg P])$$

in other symbols

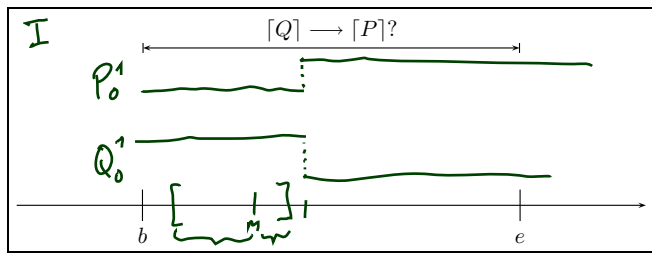
$$\forall x \bullet \Box ((F \wedge \ell = x) ; \ell > 0 \implies (F \wedge \ell = x) ; [P] ; true)$$



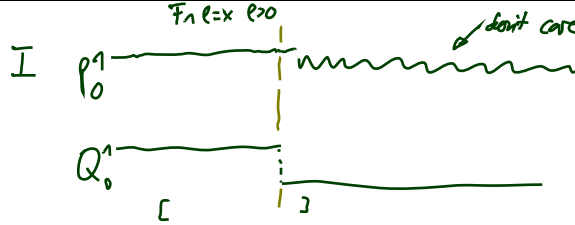
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## DC Standard Forms: Followed-by Examples

$$\forall x \bullet \Box((F \wedge \ell = x); \ell > 0 \implies (F \wedge \ell = x); [P]; true)$$



*I on  $[b, e]$   
does not  
satisfy  
 $\neg Q \rightarrow \neg P$*

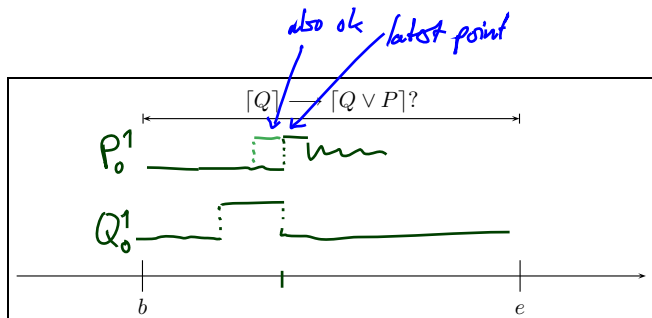


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## DC Standard Forms: Followed-by Examples

$$\forall x \bullet \Box((F \wedge \ell = x); \ell > 0 \implies (F \wedge \ell = x); [P]; true)$$

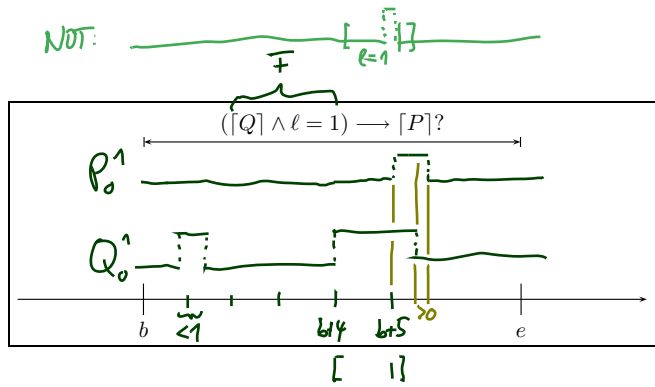


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## DC Standard Forms: Followed-by Examples

$$\forall x \bullet \Box((F \wedge \ell = x); \ell > 0 \implies (F \wedge \ell = x); [P]; true)$$



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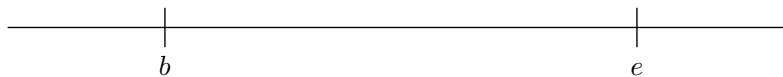
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## DC Standard Forms: (Timed) leads-to

- (Timed) leads-to:

$$F \xrightarrow{\theta} [P] : \iff (F \wedge \ell = \theta) \rightarrow [P]$$

$$\xleftarrow{F \xrightarrow{\theta} [P]} \xrightarrow{\hspace{10em}}$$



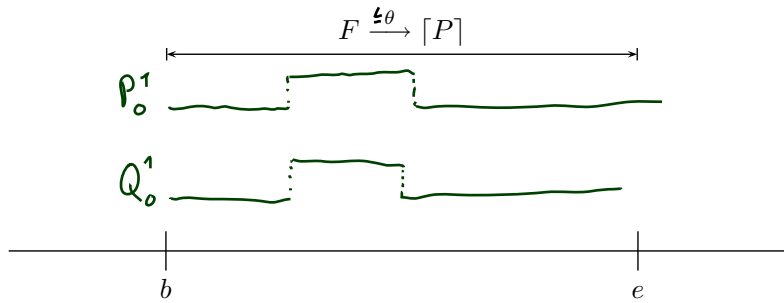
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## DC Standard Forms: (Timed) up-to

- (Timed) up-to:

$$F \xrightarrow{\leq \theta} [P] :\iff (F \wedge \ell \leq \theta) \longrightarrow [P]$$



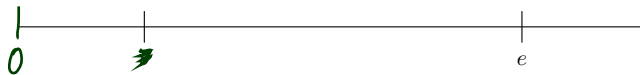
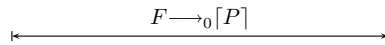
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## DC Standard Forms: Initialisation

- Followed-by-initially:

$$F \longrightarrow_0 [P] :\iff \neg(F ; [\neg P])$$



- (Timed) up-to-initially:

$$F \xrightarrow{\leq \theta}_0 [P] :\iff (F \wedge \ell \leq \theta) \longrightarrow_0 [P]$$

- Initialisation:

$$\square \vee ([P] ; true)$$

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## Control Automata

- Let  $X_1, \dots, X_k$  be  $k$  state variables ranging over **finite** domains  $\mathcal{D}(X_1), \dots, \mathcal{D}(X_k)$ .
- With a DC formula 'Impl' ranging over  $X_1, \dots, X_k$  we have a **system of  $k$  control automata**.
- 'Impl' is typically a conjunction of **DC implementables**.
- A state assertion of the form

$$X_i = d_i, \quad d_i \in \mathcal{D}(X_i),$$

which constrains the values of  $X_i$ , is called **basic phase** of  $X_i$ .

- A **phase** of  $X_i$  is a Boolean combination of basic phases of  $X_i$ .
- Abbreviations:**
  - Write  $X_i$  instead of  $X_i = 1$ , if  $X_i$  is Boolean.
  - Write  $d_i$  instead of  $X_i = d_i$ , if  $\mathcal{D}(X_i)$  is disjoint from  $\mathcal{D}(X_j)$ ,  $i \neq j$ .

## Control Automata: Example

Model of Gas Burner controller as a system of four control automata:

- $H$  Boolean, representing **heat request**, (input)
  - $F$  Boolean, representing **flame**, (input)
  - $C$  with  $\mathcal{D}(C) = \{\text{idle, purge, ignite, burn}\}$ , representing the (status of the) **controller**, (local)
  - $G$  Boolean, representing **gas valve**. (output)
- 

- Basic phase** of  $C$ :

$$C = \text{purge} \quad (\text{or only: } \text{purge})$$

- Phase** of  $C$ :

$$\text{purge} \vee \text{idle}$$

## DC Implementables

- DC Implementables are special patterns of DC Standard Forms (due to A.P. Ravn).
- Within one pattern,
  - $\pi, \pi_1, \dots, \pi_n, n \geq 0$ , denote **phases** of the same state variable  $X_i$ ,
  - $\varphi$  denotes a state assertion not depending on  $X_i$ .
- $\theta$  denotes a **rigid** term.

- **Initialisation:**

$$[\ ] \vee [\pi] ; true$$

- **Sequencing:**

$$[\pi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$

- **Progress:**

$$[\pi] \xrightarrow{\theta} [\neg\pi]$$

- **Synchronisation:**

$$[\pi \wedge \varphi] \xrightarrow{\theta} [\neg\pi]$$

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## DC Implementables Cont'd

- **Bounded Stability:**

$$\underbrace{([\neg\pi] ; [\pi \wedge \varphi])}_{\mathcal{F}} \xrightarrow{\leq \theta} \underbrace{[\pi \vee \pi_1 \vee \dots \vee \pi_n]}_{\mathcal{P}}$$

- **Unbounded Stability:**

$$[\neg\pi] ; [\pi \wedge \varphi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$

- **Bounded initial stability:**

$$[\pi \wedge \varphi] \xrightarrow{\leq \theta}_0 [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$

- **Unbounded initial stability:**

$$[\pi \wedge \varphi] \longrightarrow_0 [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$

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## Specification by DC Implementables

- Let  $X_1, \dots, X_k$  be a system of  $k$  control automata.
- Let 'Impl' be a conjunction of **DC implementables**.
- Then 'Impl' **specifies** all interpretations  $\mathcal{I}$  of  $X_1, \dots, X_k$  and all valuations  $\mathcal{V}$  such that

$$\mathcal{I}, \mathcal{V} \models_0 \text{Impl}$$

- Hmm: And what does this have to do with controllers...?

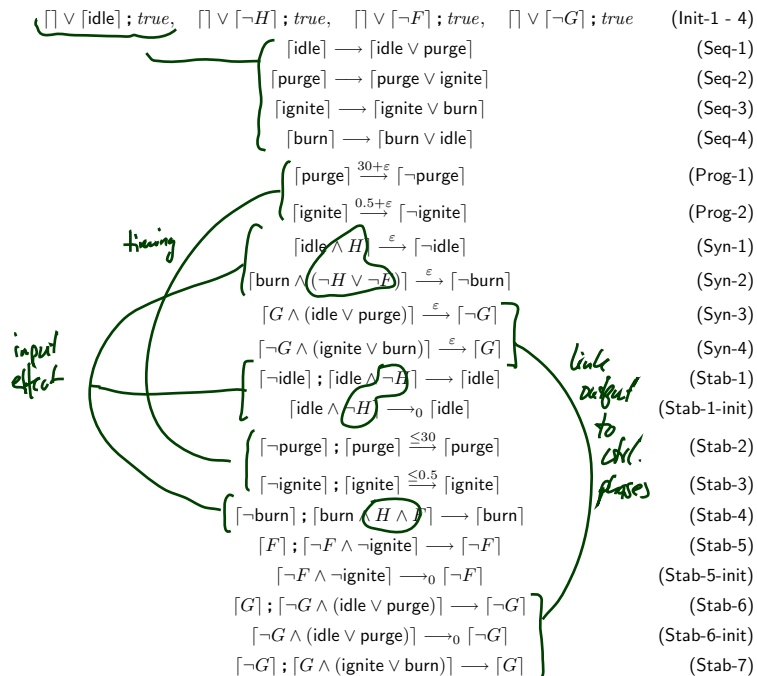
### *Example: Gas Burner*

## Recall: Control Automata

Model of Gas Burner controller as a system of four control automata:

- $H$  : Boolean, representing **heat request**, (input)
- $F$  : Boolean, representing **flame**, (input)
- $C$  with  $\mathcal{D}(C) = \{\text{idle, purge, ignite, burn}\}$ , representing the **controller**, (local)
- $G$  : Boolean, representing **gas valve**. (output)

## Gas Burner Controller Specification



## Gas Burner Controller Specification: Untimed

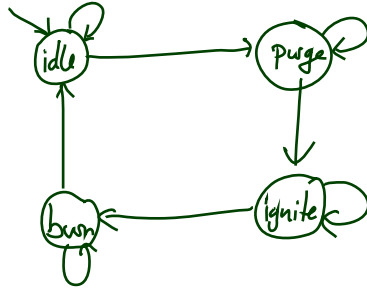
$\lceil \rceil \vee \lceil \text{idle} \rceil ; \text{true}$  (Init-1)

$\lceil \text{idle} \rceil \longrightarrow \lceil \text{idle} \vee \text{purge} \rceil$  (Seq-1)

$\lceil \text{purge} \rceil \longrightarrow \lceil \text{purge} \vee \text{ignite} \rceil$  (Seq-2)

$\lceil \text{ignite} \rceil \longrightarrow \lceil \text{ignite} \vee \text{burn} \rceil$  (Seq-3)

$\lceil \text{burn} \rceil \longrightarrow \lceil \text{burn} \vee \text{idle} \rceil$  (Seq-4)



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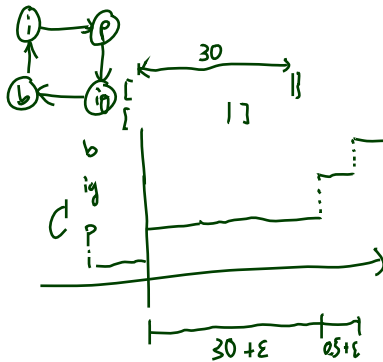
## Gas Burner Controller Specification: Timing

$\lceil \text{purge} \rceil \xrightarrow{30+\epsilon} \lceil \neg \text{purge} \rceil$  (Prog-1)

$\lceil \text{ignite} \rceil \xrightarrow{0.5+\epsilon} \lceil \neg \text{ignite} \rceil$  (Prog-2)

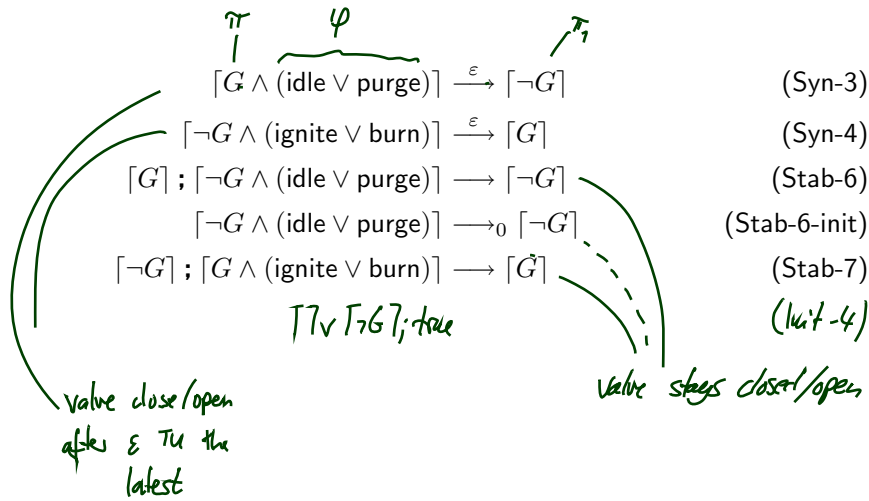
$\lceil \neg \text{purge} \rceil ; \lceil \text{purge} \rceil \xrightarrow{\leq 30} \lceil \text{purge} \rceil$  (Stab-2)

$\lceil \neg \text{ignite} \rceil ; \lceil \text{ignite} \rceil \xrightarrow{\leq 0.5} \lceil \text{ignite} \rceil$  (Stab-3)

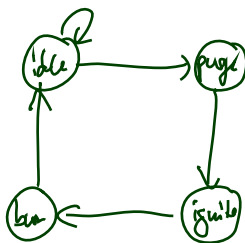
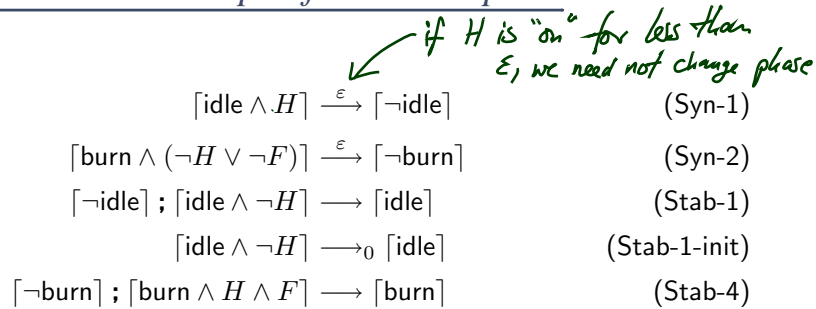


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## Gas Burner Controller Specification: Outputs



## Gas Burner Controller Specification: Inputs



## Gas Burner Controller Specification: Assumptions

$$\begin{array}{ll}
 \Box \vee [\neg H] ; true & \text{(Init-2)} \\
 \Box \vee [\neg F] ; true & \text{(Init-3)} \\
 \Box \vee [\neg G] ; true & \text{(Init-4)} \\
 [F] ; [\neg F \wedge \neg \text{ignite}] \longrightarrow [\neg F] & \text{(Stab-5)} \\
 [\neg F \wedge \neg \text{ignite}] \longrightarrow_0 [\neg F] & \text{(Stab-5-init)}
 \end{array}$$

*no spontaneous flame*

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## Gas Burner Controller Correctness Proof

$$\text{GB-Ctrl} := \text{Init-1} \wedge \dots \wedge \text{Stab-7} \wedge \varepsilon > 0$$

### Recall:

$$\text{Req} := \iff \Box(\ell \geq 60 \implies 20 \cdot \int L \leq \ell)$$

and (cf. [Olderog and Dierks, 2008])

$$\models \text{Req-1} \implies \text{Req}$$

for the **simplified**

$$\text{Req-1} := \Box(\ell \leq 30 \implies \int L \leq 1).$$

Here we show

$$\models \text{GB-Ctrl} \wedge A(\varepsilon) \implies \text{Req-1}.$$

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### Lemma 3.15

$$\models_{\mathcal{I}, \mathcal{V}, [c, d]} \text{GB-Ctrl} \implies \Box \left( \begin{array}{l} ([\text{idle}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{purge}] \implies \int G \leq \varepsilon) \\ \wedge ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ \wedge ([\text{burn}] \implies \int \neg F \leq 2\varepsilon) \end{array} \right) \quad (*)$$

**Proof:** Let  $\mathcal{I}$  be an interpretation,  $\mathcal{V}$  a valuation, and  $[c, d]$  an interval with  $\mathcal{I}, \mathcal{V}, [c, d] \models \text{GB-Ctrl}$ . Let  $[b, e] \subseteq [c, d]$ .

- Case 1:  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{idle}]$

$$\begin{array}{ll} [G \wedge (\text{idle} \vee \text{purge})] \xrightarrow{\varepsilon} [\neg G] & (\text{Syn-3}) \\ [G]; [\neg G \wedge (\text{idle} \vee \text{purge})] \longrightarrow [\neg G] & (\text{Stab-6}) \end{array}$$

*conclude*

$$\mathcal{I}, \mathcal{V}, [b, e] \models \Box([G] \implies \ell \leq \varepsilon) \wedge \neg \Diamond([G]; [\neg G]; [G])$$

*(\*)*

*gas valve doesn't open up again in idle phase*

- Case 2:  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{purge}]$  Analogously to case 1.

### Lemma 3.15 Cont'd

$$\begin{array}{l} ([\text{idle}] \implies \int G \leq \varepsilon) \\ ([\text{purge}] \implies \int G \leq \varepsilon) \\ ([\text{ignite}] \implies \ell \leq 0.5 + \varepsilon) \\ ([\text{burn}] \implies \int \neg F \leq 2\varepsilon) \end{array} \quad (**)$$

- Case 3:  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{ignite}]$

$$[\text{ignite}] \xrightarrow{0.5+\varepsilon} [\neg \text{ignite}] \quad (\text{Prog-2})$$

*conclude*

$$\mathcal{I}, \mathcal{V}, [b, e] \models \ell \leq 0.5 + \varepsilon$$

- Case 4:  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{burn}]$

$$[\text{burn} \wedge (\neg H \vee \neg F)] \xrightarrow{\varepsilon} [\neg \text{burn}] \quad (\text{Syn-2})$$

$$[F]; [\neg F \wedge \neg \text{ignite}] \longrightarrow [\neg F] \quad (\text{Stab-5})$$

*conclude*

$$\mathcal{I}, \mathcal{V}, [b, e] \models \Box([\neg F] \implies \ell \leq \varepsilon) \wedge \neg \Diamond([F]; [\neg F]; [F])$$

*(\*)*

*[F]  
[F]; [¬F]  
[¬F]; [F]; [¬F]  
[¬F]; [F]*

### Lemma 3.16

$$\models \exists \epsilon \bullet \text{GB-Ctrl} \implies \underbrace{\square(\ell \leq 30 \implies \int L \leq 1)}_{\text{Req-1}}$$

#### Proof Sketch

Choose  $\mathcal{I}, \mathcal{V}, [b, e]$  s.t.  $\mathcal{I}, \mathcal{V}, [b, e] \models \text{GB-Ctrl} \wedge \ell \leq 30$

Distinguish 5 cases:

- $\mathcal{I}, \mathcal{V}, [b, e] \models \perp$  (0)
- $\forall (\ulcorner \text{idle} \urcorner; \text{true} \wedge \ell \leq 30)$  (1)
- $\forall (\ulcorner \text{purge} \urcorner; \text{true} \wedge \ell \leq 30)$  (2)
- $\forall (\ulcorner \text{ignite} \urcorner; \text{true} \wedge \ell \leq 30)$  (3)
- $\forall (\ulcorner \text{boom} \urcorner; \text{true} \wedge \ell \leq 30)$  (4)

### Lemma 3.16 Cont'd

- Case 0:  $\mathcal{I}, \mathcal{V}, [b, e] \models \perp$  ✓
- Case 1:  $\mathcal{I}, \mathcal{V}, [b, e] \models \ulcorner \text{idle} \urcorner; \text{true} \wedge \ell \leq 30$

$$\ulcorner \text{idle} \urcorner \longrightarrow \ulcorner \text{idle} \vee \text{purge} \urcorner \quad (\text{Seq-1})$$

$$\ulcorner \neg \text{purge} \urcorner; \ulcorner \text{purge} \urcorner \stackrel{\leq 30}{\longrightarrow} \ulcorner \text{purge} \urcorner \quad (\text{Stab-2})$$

$$\hookrightarrow \mathcal{I}, \mathcal{V}, [b, e] \models \ulcorner \text{idle} \urcorner \vee \ulcorner \text{idle} \urcorner; \ulcorner \text{purge} \urcorner$$

$$\stackrel{3.15}{\hookrightarrow} \mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq \epsilon \vee \int L \leq \epsilon; \int L \leq \epsilon$$

$$\hookrightarrow \mathcal{I}, \mathcal{V}, [b, e] \models \int L \leq 2\epsilon$$

Thus  $\boxed{\epsilon \leq 0.5}$  is sufficient for Req-1 in this case.

### Lemma 3.16 Cont'd

- Case 2:  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{burn}] ; \text{true} \wedge \ell \leq 30$

$$[\text{burn}] \longrightarrow [\text{burn} \vee \text{idle}] \quad (\text{Seq-4})$$

$$\begin{aligned} & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models ([\text{burn}] \vee [\text{burn}]; [\text{idle}]; \text{true}) \wedge \ell \leq 30 \\ 3.15, (1) & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models (\mathcal{J}L \leq 2\varepsilon \vee \mathcal{J}L \leq 2\varepsilon; \mathcal{J}L \leq 2\varepsilon) \wedge \ell \leq 30 \\ & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models \mathcal{J}L \leq 4\varepsilon \end{aligned}$$

Thus  $\boxed{\varepsilon \leq 0.25}$  sufficient for Req-1.

### Lemma 3.16 Cont'd

- Case 3:  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{ignite}] ; \text{true} \wedge \ell \leq 30$

$$[\text{ignite}] \longrightarrow [\text{ignite} \vee \text{burn}] \quad (\text{Seq-3})$$

$$\begin{aligned} & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models ([\text{ignite}] \vee [\text{ignite}]; [\text{burn}]; \text{true}) \wedge \ell \leq 30 \\ 3.5, (2) & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models \mathcal{J}L \leq 0.5 + \varepsilon \vee (\mathcal{J}L \leq 0.5 + \varepsilon; \mathcal{J}L \leq 4\varepsilon) \wedge \ell \leq 30 \\ & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models \mathcal{J}L \leq 0.5 + 5\varepsilon \end{aligned}$$

So  $\boxed{\varepsilon \leq 0.1}$  is sufficient for Req-1.



## Lemma 3.16 Cont'd

- Case 4:  $\mathcal{I}, \mathcal{V}, [b, e] \models [\text{purge}] ; \text{true} \wedge \ell \leq 30$

$$[\text{purge}] \longrightarrow [\text{purge} \vee \text{ignite}] \quad (\text{Seq-2})$$

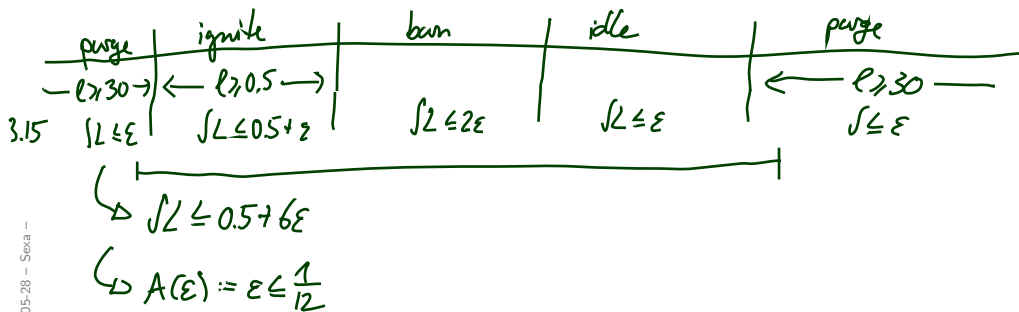
$$\begin{aligned} & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models ([\text{purge}] \vee [\text{ignite}]); [\text{ignite}]; \text{true} \wedge \ell \leq 30 \\ 3.15, (3) & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models \sqrt{L} \leq \varepsilon \vee (\sqrt{L} \leq \varepsilon; \sqrt{L} \leq 0.5 + \varepsilon) \\ & \hookrightarrow \mathcal{I}, \mathcal{U}, [b, e] \models \sqrt{L} \leq 0.5 + 6\varepsilon \end{aligned}$$

Thus  $\boxed{\varepsilon \leq \frac{1}{12}}$  is sufficient for Req-1 in this case.

## Correctness Result

### Theorem 3.17.

$$\models \left( \text{GB-Ctrl} \wedge \varepsilon \leq \frac{1}{12} \right) \implies \text{Req}$$



## Discussion

- We used only

'Seq-1', 'Seq-2', 'Seq-3', 'Seq-4',  
'Prog-2', 'Syn-2', 'Syn-3',  
'Stab-2', 'Stab-5', 'Stab-6'.

What about

$$\text{Prog-1} = [\text{purge}] \xrightarrow{30+\epsilon} [\neg\text{purge}]$$

for instance?

*Wijya, there is the requirement (not noted down)  
that the system does something finally,  
e.g. get the heating going on request.*

## References

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## References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.