

Real-Time Systems

Lecture 08: DC Implementables

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Contents & Goals

- Last Lectures:**
 - (Un)decidability results for fragments of DC in discrete and continuous time.

This Lecture:

- Educational Objectives:** Capabilities for following tasks/questions:
 - What does this standard forms mean? Give a satisfying interpretation.
 - What are implementables? What is a control automaton?
 - Please specify (and prove correct) a controller which satisfies this requirement.
- Content:**
 - DC Standard Forms
 - Control Automata
 - DC Implementables
 - Example

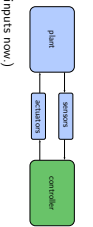
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DC Implementables

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Requirements vs. Implementations

- Problem:** in general, a DC requirement doesn't tell how to achieve it, how to build a controller/write a program which ensures it.
 - What a controller (clearly) can do is:
 - consider inputs now,
 - change (local) state, or
 - wait,
 - set outputs now.
 (But not, e.g., consider future inputs now.)
 - So, if we have
 - a DC requirement 'Req'_{DC}
 - a description 'Impl'_{DC} which 'uses' **just these operations**,
 then
 - proving correctness amounts to proving $\models_{DC} \text{Impl} \Rightarrow \text{Req}$ (in DC)
 - and we (more or less) know how to program (the correct) 'Impl' in a PLC language or in C on a real-time OS, or or...



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Approach: Control Automata and DC Implementables

- Plan:**
 - Introduce **DC Standard Forms**
 - Introduce **Control Automata**
 - Introduce **DC Implementables** as subset of **DC Standard Forms**
 - Example: a correct controller design for the notorious Gas Burner



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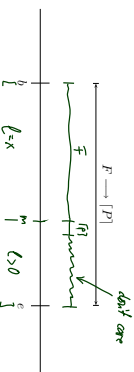
DC Standard Forms: Followed-by

In the following, F is a DC formula, P a state assertion, θ a rigid term.

- Followed-by:**

$$F \rightarrow [P] \iff \neg(\exists F; [-P]) \iff \Box \neg(F; [-P])$$

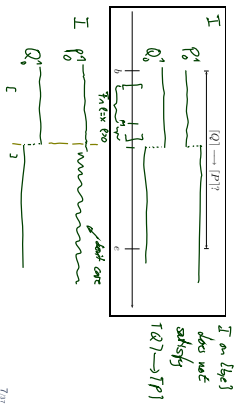
In other symbols
 $\forall x \bullet \Box((F \wedge \ell = x) : \ell > 0 \implies (F \wedge \ell = x) : [P] ; \text{true})$



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DC Standard Forms: Followed-by Examples

$$\forall x \bullet \Box (F \wedge t = x) : t > 0 \implies (F \wedge t = x) : [P] : true$$

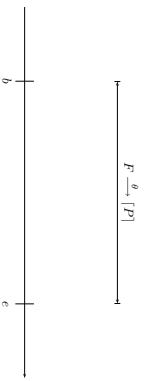


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DC Standard Forms: (Timed) leads-to

- (Timed) leads-to: $\overset{Q \text{ not } \perp!}{\implies}$

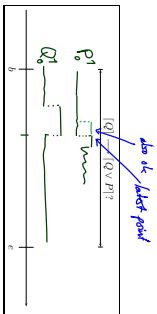
$$F \xrightarrow{\theta} [P] \iff (F \wedge t = \theta) \multimap [P]$$



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DC Standard Forms: Followed-by Examples

$$\forall x \bullet \Box (F \wedge t = x) : t > 0 \implies (F \wedge t = x) : [P] : true$$

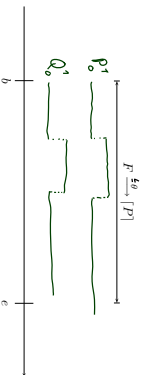


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DC Standard Forms: (Timed) up-to

- (Timed) up-to:

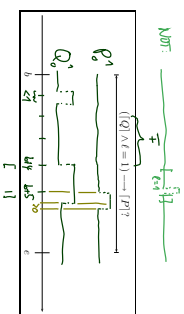
$$F \xrightarrow{\leq \theta} [P] \iff (F \wedge t \leq \theta) \multimap [P]$$



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DC Standard Forms: Followed-by Examples

$$\forall x \bullet \Box (F \wedge t = x) : t > 0 \implies (F \wedge t = x) : [P] : true$$

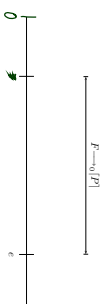


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DC Standard Forms: Initialisation

- Followed-by-initially:

$$F \multimap_0 [P] \iff \neg (F : \neg [P])$$



- (Timed) up-to-initially:

$$F \xrightarrow{\leq \theta}_0 [P] \iff (F \wedge t \leq \theta) \multimap_0 [P]$$

- Initialisation: $\bigcap \vee ([P] : true)$

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- Let X_1, \dots, X_k be k state variables ranging over finite domains $\mathcal{D}(X_1), \dots, \mathcal{D}(X_k)$.
- With a DC formula 'Imp' ranging over X_1, \dots, X_k we have a **system of k control automata**:
- 'Imp' is typically a conjunction of **DC implementables**.
- A state assertion of the form

$$X_i = d_i, \quad d_i \in \mathcal{D}(X_i),$$
 which constrains the values of X_i , is called **basic phase** of X_i .
- A **phase** of X_i is a Boolean combination of basic phases of X_i .
- Abbreviations:**
 - Write X_i instead of $X_i = 1$, if X_i is Boolean.
 - Write d_i instead of $X_i = d_i$, if $\mathcal{D}(X_i)$ is disjoint from $\mathcal{D}(X_j)$, $i \neq j$.

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Model of Gas Burner controller as a system of four control automata:

- H Boolean, representing heat request, (input)
- F Boolean, representing flame, (input)
- C with $\mathcal{D}(C) = \{\text{idle, purge, ignite, burn}\}$, representing the (status of the) controller, (local)
- G Boolean, representing gas valve, (output)

- Basic phase** of C :

$$C = \text{purge} \quad (\text{or only: } \text{purge})$$
- Phase** of C :

$$\text{purge} \vee \text{idle}$$

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- DC Implementables are special patterns of DC Standard Forms (due to A. P. Rayn)
- Within one pattern, $\pi_1, \pi_2, \dots, \pi_n$, $n \geq 0$, denote **phases of the same state variable** X_i .
- φ denotes a state assertion not depending on X_i .
- θ denotes a **rigid** term.

- Initialisation:**

$$\bigwedge \vee [\pi] : \text{true}$$
- Sequencing:**

$$[\pi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$
- Progress:**

$$[\pi] \xrightarrow{\theta} [\pi]$$
- Synchronisation:**

$$[\pi \wedge \varphi] \xrightarrow{\theta} [\pi]$$

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- Bounded Stability:**

$$[\neg\pi] : [\pi \wedge \varphi] \xrightarrow{\theta} [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$
- Unbounded Stability:**

$$[\neg\pi] : [\pi \wedge \varphi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$
- Bounded initial stability:**

$$[\pi \wedge \varphi] \xrightarrow{\theta} [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$
- Unbounded initial stability:**

$$[\pi \wedge \varphi] \longrightarrow [\pi \vee \pi_1 \vee \dots \vee \pi_n]$$

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- Let X_1, \dots, X_k be a system of k control automata.
- Let 'Imp' be a conjunction of **DC implementables**.
- Then 'Imp' specifies all interpretations \mathcal{I} of X_1, \dots, X_k and all valuations γ such that

$$\mathcal{I}\gamma \models_{\text{imp}}$$

- Hmm: And what does this have to do with controllers...?

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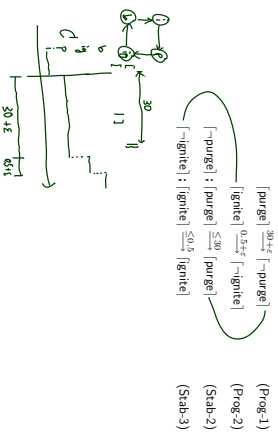
Example: Gas Burner

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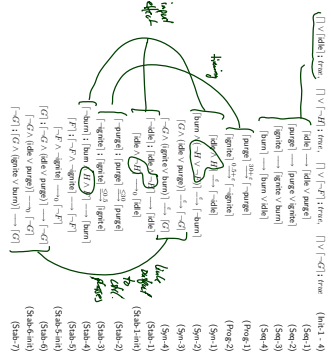
Model of Gas Burner controller as a system of four control automata:

- F : Boolean representing heat request.
- F' : Boolean representing flame.
- C with $D(C) = \{\text{idle, purge, ignite, burn}\}$, representing the controller.
- G : Boolean representing gas valve.

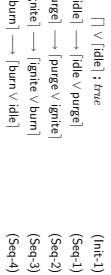
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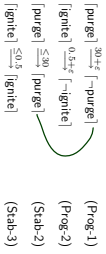
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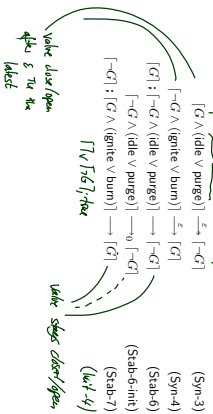
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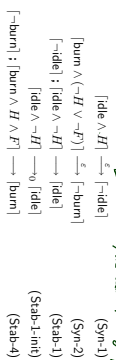
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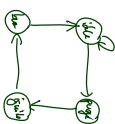
(Prog-1)
(Prog-2)
(Stab-2)
(Stab-3)



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$$\begin{aligned}
 & \Box \vee [-H] : \text{true} & (\text{Init-2}) \\
 & \Box \vee [-F] : \text{true} & (\text{Init-3}) \\
 & \text{---} & \text{---} \\
 & [F] : [-F \wedge \text{ignite}] \xrightarrow{\text{thin-3}} [-F] & (\text{Stab-5}) \\
 & [-F \wedge \text{ignite}] \xrightarrow{\text{no gas/no valve}} [-F] & (\text{Stab-5-init})
 \end{aligned}$$

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$$\begin{aligned}
 \text{GB-Ctrl} & \equiv \text{Init-1} \wedge \dots \wedge \text{Stab-7} \wedge \epsilon > 0 \\
 \text{Recall:} & \text{Req-1} \iff \Box(\epsilon \geq 0) \implies 20 \cdot J_L \leq 0 \\
 & \text{and (cf. [Olderog and Dierks, 2008])} \\
 & \text{Req-1} \implies \text{Req} \\
 \text{for the simplified} & \\
 \text{Req-1} & \equiv \Box(\epsilon \leq 30) \implies J_L \leq 1.
 \end{aligned}$$

Here we show $\models \text{GB-Ctrl} \wedge A(\epsilon) \implies \text{Req-1}$.

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$$\begin{aligned}
 \models \text{GB-Ctrl} & \implies \Box \left(\begin{array}{l} (\text{Idle}) \implies J_G \leq \epsilon \\ \vee (\text{Purge}) \implies J_G \leq \epsilon \\ \vee (\text{Ignite}) \implies \epsilon \leq 0.5 + \epsilon \\ \vee (\text{Burn}) \implies J_{-F} \leq 2\epsilon \end{array} \right) \quad (4)
 \end{aligned}$$

Proof: Let Z be an interpretation, γ a valuation, and $[c, d]$ an interval with $Z, \gamma, [c, d] \models \text{GB-Ctrl}$. Let $\{b, d\} \subseteq [c, d]$.

- Case 1: $Z, \gamma, [b, d] \models \text{Idle}$

$$\begin{aligned}
 & \text{---} & \text{---} \\
 & [G] : [-G \wedge (\text{Idle} \vee \text{Purge})] \xrightarrow{\text{thin-3}} [-G] & (\text{Syn-3}) \\
 & & (\text{Stab-6})
 \end{aligned}$$
- Case 2: $Z, \gamma, [b, d] \models \text{Purge}$ Analogously to case 1.

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$$\begin{aligned}
 (\text{Idle}) & \implies J_G \leq \epsilon \\
 (\text{Purge}) & \implies J_G \leq \epsilon \\
 (\text{Burn}) & \implies J_{-F} \leq 2\epsilon
 \end{aligned} \quad (6)$$

- Case 3: $Z, \gamma, [b, d] \models \text{Ignite}$

$$\begin{aligned}
 & \text{---} & \text{---} \\
 & \text{Ignite} \stackrel{0.5\epsilon}{\implies} \text{Ignite} & (\text{Prog-2}) \\
 & Z, \gamma, [b, d] \models \epsilon \leq 0.5 + \epsilon
 \end{aligned}$$
- Case 4: $Z, \gamma, [b, d] \models \text{Burn}$

$$\begin{aligned}
 & \text{Burn} \wedge (-H \vee -F) \xrightarrow{\text{thin-3}} \text{Burn} \\
 & [F] : [-F \wedge \text{ignite}] \xrightarrow{\text{thin-3}} [-F] & (\text{Syn-2}) \\
 & & (\text{Stab-5})
 \end{aligned}$$

Thus $Z, \gamma, [b, d] \models \Box(\epsilon \leq \epsilon) \wedge \neg \Box([F] : [-F]) \implies [F]$ is satisfied for Req-1 in this case.

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$$\models \exists \epsilon \bullet \text{GB-Ctrl} \implies \underbrace{\Box(\epsilon \leq 30)}_{\text{Req-1}} \implies J_L \leq 1$$

Proof Sketch

Assume $Z, \gamma, [b, d] \models \text{Req-1}$ and $\epsilon \leq 30$.
 Distinguish 5 cases:

- $Z, \gamma, [b, d] \models \neg \Gamma$

$$\begin{aligned}
 & \vee [(\text{Idle} \vee \text{Purge}) \wedge (\epsilon \leq 30)] & (1) \\
 & \vee [(\text{Ignite}) \wedge (\epsilon \leq 30)] & (2) \\
 & \vee [(\text{Burn}) \wedge (\epsilon \leq 30)] & (3) \\
 & \vee [(\text{Burn}) \wedge (\epsilon \leq 30)] & (4)
 \end{aligned}$$

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- Case 0: $Z, \gamma, [b, d] \models \neg \Gamma$ ✓
- Case 1: $Z, \gamma, [b, d] \models \text{Idle}$: true $\wedge \epsilon \leq 30$

$$\begin{aligned}
 & \text{Idle} \xrightarrow{\text{thin-3}} \text{Idle} \vee \text{Purge} & (\text{Seq-1}) \\
 & [-\text{purge}] : \text{Purge} \xrightarrow{\leq 30} \text{Purge} & (\text{Stab-2})
 \end{aligned}$$

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Lemma 3.16 Cont'd

- Case 2: $I, Y, [b, c] \models \text{burn} : \text{true} \wedge t \leq 30$

$$[\text{burn}] \longrightarrow [\text{burn} \vee \text{idle}] \quad (\text{Seq-4})$$

$$\begin{aligned} & \hookrightarrow I, Y, [b, c] \models (\text{burn}) \vee (\text{idle}) \wedge t \leq 30 \\ & \text{3.5 (2)} \hookrightarrow I, Y, [b, c] \models (t \leq 28 \vee t \leq 28 \wedge t \leq 28) \wedge t \leq 30 \\ & \hookrightarrow I, Y, [b, c] \models t \leq 42 \end{aligned}$$

Thus $\boxed{t \leq 0.05}$ sufficient for Req. 1.

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Theorem 3.17.
 $\models (\text{GB-CHI} \wedge t \leq \frac{1}{12}) \Rightarrow \text{Req}$



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Lemma 3.16 Cont'd

- Case 3: $I, Y, [b, c] \models [\text{ignite}] : \text{true} \wedge t \leq 30$

$$[\text{ignite}] \longrightarrow [\text{ignite} \vee \text{burn}] \quad (\text{Seq-3})$$

$$\begin{aligned} & \hookrightarrow I, Y, [b, c] \models ([\text{ignite}] \vee [\text{burn}]) \wedge t \leq 30 \\ & \text{3.5 (2)} \hookrightarrow I, Y, [b, c] \models (t \leq 0.5 + t \vee (t \leq 0.5 + t \wedge t \leq 28)) \wedge t \leq 30 \\ & \hookrightarrow I, Y, [b, c] \models t \leq 0.5 + 5t \end{aligned}$$

So $\boxed{t \leq 0.1}$ is sufficient for Req. 1.

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Discussion

- We used only

Seq-1, Seq-2, Seq-3, Seq-4,
 Prog-2, Spr-2, Spr-3,
 Stab-2, Stab-5, Stab-6.

What about
 for instance?

Why, there is the requirement (not model shown)
 that the system does something finally,
 e.g. get the heating going in request.

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Lemma 3.16 Cont'd

- Case 4: $I, Y, [b, c] \models [\text{purge}] : \text{true} \wedge t \leq 30$

$$[\text{purge}] \longrightarrow [\text{purge} \vee \text{ignite}] \quad (\text{Seq-2})$$

$$\begin{aligned} & \hookrightarrow I, Y, [b, c] \models ([\text{purge}] \vee [\text{ignite}]) \wedge t \leq 30 \\ & \text{3.5 (2)} \hookrightarrow I, Y, [b, c] \models (t \leq t \vee (t \leq t \wedge t \leq 0.5 + t)) \\ & \hookrightarrow I, Y, [b, c] \models t \leq 0.5 + 6t \end{aligned}$$

Thus $\boxed{t \leq \frac{1}{12}}$ is sufficient for Req. 1 in this case.

33.7

References

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References

Oleveg and Dierks. 2008] Oleveg, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.