Real-Time Systems

Lecture 18: Automatic Verification of DC Properties for TA II

2013-07-10

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Contents & Goals

Last Lecture:

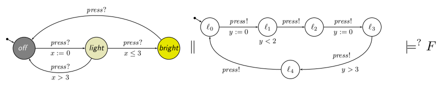
- Completed Undecidability Results for TBA
- Started to relate TA and DC

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
  - How can we relate TA and DC formulae? What's a bit tricky about that?
  - Can we use Uppaal to check whether a TA satisfies a DC formula?
- **Content:**
  - An evolution-of-observables semantics of TA
  - A satisfaction relation between TA and DC
  - Model-checking DC properties with Uppaal

Observing Timed Automata

DC Properties of Timed Automata



Wanted: A satisfaction relation between networks of timed automata and DC formulae, a notion of $\mathcal{N}$ **satisfies** F, denoted by $\mathcal{N} \models F$.

Plan:

- Consider network $\mathcal{N}$ consisting of TA

$$\mathcal{A}_{e,i} = (L_i, C_i, B_i, U_i, X_i, V_i, I_i, E_i, \ell_{ini,i})$$

- Define observables $\mathrm{Obs}(\mathcal{N})$ of $\mathcal{N}$.
- Define evolution $\mathcal{I}_\xi$ of $\mathrm{Obs}(\mathcal{N})$ induced by computation path $\xi \in CompPaths(\mathcal{N})$ of $\mathcal{N}$,
  $CompPaths(\mathcal{N}) = \{\xi \mid \xi$ is a computation path of $\mathcal{N}\}$
- Say $\mathcal{N} \models F$ if and only if $\forall\, \xi \in CompPaths(\mathcal{N}) : \mathcal{I}_\xi \models_0 F$.

Observables of TA Network

Let $\mathcal{N}$ be a network of n extended timed automata

$$\mathcal{A}_{e,i} = (L_i, C_i, B_i, U_i, X_i, V_i, I_i, E_i, \ell_{ini,i})$$

For simplicity: assume that the L_i and X_i are pairwise disjoint and that each V_i is pairwise disjoint to every L_i and X_i (otherwise rename).

- **Definition:** The observables $\mathrm{Obs}(\mathcal{N})$ of $\mathcal{N}$ are

$$\{\ell_1, \dots, \ell_n\} \cup \bigcup_{1 \le i \le n} V_i$$

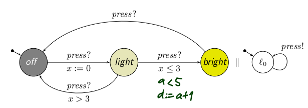
current location of $A_{e,1}$

with
  - $\mathcal{D}(\ell_i) = L_i$,
  - $\mathcal{D}(v)$ as given, $v \in V_i$.

Observables of TA Network: Example

$\mathcal{A}_{e,i} = (L_i, C_i, B_i, U_i, X_i, V_i, I_i, E_i, \ell_{ini,i})$.

The observables $\mathrm{Obs}(\mathcal{N})$ of $\mathcal{N}$ are $\{\ell_1, \dots, \ell_n\} \cup \bigcup_{1 \le i \le n} V_i$ with
- $\mathcal{D}(\ell_i) = L_i$,
- $\mathcal{D}(v)$ as given, $v \in V_i$.



$\mathrm{Obs}(\mathcal{N}) = \{\ell_1, \ell_2\} \cup \{a\}$

$\mathcal{D}(\ell_1) = \{$off, light, bright$\}$

$\mathcal{D}(\ell_2) = \{\ell_0\}$

$\mathcal{D}(a) = \{0, \dots, 5\}$

Evolutions of TA Network

Recall: computation path

$$\xi = \langle \vec{\ell}_0, \nu_0 \rangle, t_0 \xrightarrow{\lambda_1} \langle \vec{\ell}_1, \nu_1 \rangle, t_1 \xrightarrow{\lambda_2} \langle \vec{\ell}_2, \nu_2 \rangle, t_2 \xrightarrow{\lambda_3} \dots$$

of $\mathcal{N}$, $\vec{\ell}_j$ denotes a tuple $\langle \ell_j^1, \dots, \ell_j^n \rangle \in L_1 \times \dots \times L_n$.

Recall: Given ξ and $t \in$ Time, we use $\xi(t)$ to denote the set

$$\{\langle \vec{\ell}, \nu \rangle \mid \exists i \in \mathbb{N}_0 : t_i \le t \le t_{i+1} \wedge \vec{\ell} = \vec{\ell}_i \wedge \nu = \nu_i + t - t_i\}.$$

of **configurations at time** t.

"pick the configuration with the biggest index"

New: $\bar{\xi}(t)$ denotes $\langle \vec{\ell}_j, \nu_j + t - t_j \rangle$ where $j = \max\{i \in \mathbb{N}_0 \mid t_i \le t \cancel{\wedge \vec{\ell} = \vec{\ell}_i}\}$.

Our choice:

- **Ignore** configurations assumed for 0-time only.
- **Extend** finite computation paths to infinite length, staying in last configuration.
  Yet clocks advance – see later. (Assume no timelock.)

Evolutions of TA Network: Example

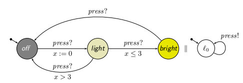
$\bar{\xi}(t)$ denotes $\langle \vec{\ell}_j, \nu_j + t - t_j \rangle$ where $j = \max\{i \in \mathbb{N}_0 \mid t_i \le t \cancel{\wedge \vec{\ell} = \vec{\ell}_i}\}$.

Example:

$$\xi = \langle {\text{off} \atop 0} \rangle, \underbrace{0}_{t_0} \xrightarrow{2.5} \langle {\text{off} \atop 2.5} \rangle, \underbrace{2.5}_{t_1} \xrightarrow{\tau} \langle {\text{light} \atop 0} \rangle, \underbrace{2.5}_{t_2} \xrightarrow{\tau} \langle {\text{bright} \atop 0} \rangle, \underbrace{2.5}_{t_3} \xrightarrow{\tau} \langle {\text{off} \atop 0} \rangle, \underbrace{2.5}_{t_4} \xrightarrow{1.0} \langle {\text{off} \atop 1} \rangle, \underbrace{3.5}_{t_5} \xrightarrow{\tau} \dots$$

- $\bar{\xi}(0) = \langle \text{off}, x=0 \rangle$
- $\bar{\xi}(1.0) = \langle \text{off}, x = 0 + (1.0 - 0) \rangle$
- $\bar{\xi}(2.5) = \langle \text{off}, x = 2.5 \rangle$

$\{i \mid t_i \le 2.5\} = \{4, 3, 2, 1\}$



Evolutions of TA Network Cont'd

$\bar{\xi}$ **induces** the unique interpretation

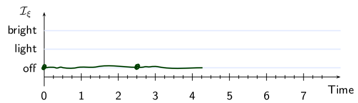
$$\mathcal{I}_\xi : \text{Obs}(\mathcal{N}) \to (\text{Time} \to \mathcal{D})$$

of Obs($\mathcal{N}$) defined pointwise as follows:

$$\mathcal{I}_\xi(a)(t) = \begin{cases} \ell^i & \text{, if } a = \ell_i, \bar{\xi}(t) = \langle \langle \ell^1, \dots \ell^i \dots, \ell^n \rangle, \nu \rangle \\ \nu(a) & \text{, if } a \in V_i, \bar{\xi}(t) = \langle \vec{\ell}, \nu \rangle \end{cases}$$

Example: $\mathcal{D}(\ell_1) = \{\text{off}, \text{light}, \text{bright}\}$

$$\xi = \langle {\text{off} \atop 0} \rangle, 0 \xrightarrow{2.5} \langle {\text{off} \atop 2.5} \rangle, 2.5 \xrightarrow{\tau} \langle {\text{light} \atop 0} \rangle, 2.5 \xrightarrow{\tau} \langle {\text{bright} \atop 0} \rangle, 2.5 \xrightarrow{\tau} \langle {\text{off} \atop 0} \rangle, 2.5 \xrightarrow{1.0} \langle {\text{off} \atop 1} \rangle, 3.5 \xrightarrow{\tau} \dots$$



Evolutions of TA Network Cont'd

$$\xi = \langle {\text{off} \atop 0} \rangle, 0 \xrightarrow{2.5} \langle {\text{off} \atop 2.5} \rangle, 2.5 \xrightarrow{\tau} \langle {\text{light} \atop 0} \rangle, 2.5 \xrightarrow{\tau} \langle {\text{bright} \atop 0} \rangle, 2.5 \xrightarrow{\tau} \langle {\text{off} \atop 0} \rangle, 2.5 \xrightarrow{1.0} \langle {\text{off} \atop 1} \rangle, 3.5 \xrightarrow{\tau} \dots$$

Abbreviations as usual:

- $\mathcal{I}_\xi(\ell_1)(0) =$ off
- $\mathcal{I}(\ell_1 = \text{off})(0) = 1$ iff $\mathcal{I}_\xi(\ell_1)(0) = \mathcal{I}(\text{off}) = \text{off}$
- $\mathcal{I}(\text{off})(1.0) = \mathcal{I}(\ell_1 = \text{off})(1.0)$
  if L_i pairwise disjoint.

state assertion

Evolutions of TA Network Cont'd

- But **what about clocks**? Why not $x \in \text{Obs}(\mathcal{N})$ for $x \in X_i$?
- We would know how to define $\mathcal{I}_\xi(x)(t)$, namely

$$\mathcal{I}_\xi(x)(t) = \nu_{\boxed{j}}(x) + (t - t_{\boxed{j}}). \qquad j = \max\{\dots\}$$

- But... $\mathcal{I}_\xi(x)(t)$ changes too often.

simple clock constraints

Better (if wanted):

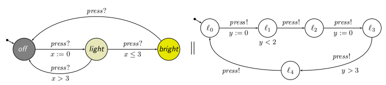
- add $\Phi(X_1 \cup \dots \cup X_i)$ to Obs($\mathcal{N}$),
  with $\mathcal{D}(\varphi) = \{0, 1\}$ for $\varphi \in \Phi(X_1 \cup \dots \cup X_i)$.
- set

$$\mathcal{I}_\xi(\varphi)(t) = \begin{cases} 1, \text{ if } \nu(x) \models \varphi, \bar{\xi}(t) = \langle \vec{\ell}, \nu \rangle \\ 0, \text{ otherwise} \end{cases}$$

The truth value of constraint φ can endure over non-point intervals.

Some Checkable Properties

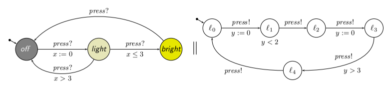
Model-Checking DC Properties with Uppaal



$\models^? F$

- **First Answer**: $\mathcal{N} \models F$ if and only if $\forall \xi \in CompPaths(\mathcal{N}) : \mathcal{I}_\xi \models_0 F$.
- **Second Question**: what kinds of DC formulae can we check with Uppaal?
  - **Clear**: Not every DC formula.
    (Otherwise contradicting undecidability results.)
  - **Quite clear**: $F = \Box\lceil \text{off} \rceil$ or $F = \neg\Diamond\lceil \text{light} \rceil$
    (Use Uppaal's fragment of TCTL, something like $\forall\Box$ off,
    but not exactly ~~(see later)~~.)
  - **Maybe**: $F = \ell > 5 \implies \Diamond\lceil \text{off} \rceil^5$
  - **Not so clear**: $F = \neg\Diamond(\lceil \text{bright} \rceil ; \lceil \text{light} \rceil)$

Model-Checking DC Properties with Uppaal



$\models^? F$

- **Second Question**: what kinds of DC formulae can we check with Uppaal?

Wanted:

- a function f mapping DC formulae to Uppaal ~~DC formulae~~ queries and
- a transformation $\widetilde{\cdot}$ of networks of TA

such that

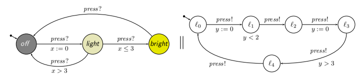
$$\widetilde{\mathcal{N}} \models_{\mathsf{Uppaal}} f(F) \iff \mathcal{N} \models F \; (\Leftrightarrow \forall \xi \in Comp(\mathcal{N}) \bullet \mathcal{I}_\xi \models F)$$

One step more general: an additional **observer** construction $\mathcal{O}(\cdot)$ such that

$$\widetilde{\mathcal{N}} \parallel \mathcal{O}(F) \models_{\mathsf{Uppaal}} f_{\mathcal{O}}(F) \iff \mathcal{N} \models F$$

may use components of the observer

Model-Checking Invariants with Uppaal



$\models^? F$

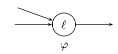
- **Quite clear**: $F = \Box\lceil P \rceil$.
  - Unfortunately, we have in general not

    $$\mathcal{N} \models \Box\lceil P \rceil \not\Longrightarrow \mathcal{N} \models_{up} \forall\Box P,$$

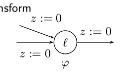
    but ~~in general not~~

    $$\mathcal{N} \models_{up} \forall\Box P \implies \mathcal{N} \models \Box\lceil P \rceil$$

    because Uppaal also considers P without duration.
  - Possible fix: measure duration explicitly, transform

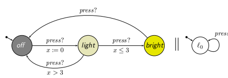
    to

    Then check for $\mathcal{N} \models \forall\Box(P \wedge z > 0)$. if $P \equiv \ell$.

Testable DC Properties

A More Systematic Approach



$\models^? F$

- We have seen $f_{\mathcal{O}}$, $\widetilde{\cdot}$, and $\mathcal{O}(\cdot)$ with

$$\widetilde{\mathcal{N}} \parallel \mathcal{O}(F) \models_{\mathsf{Uppaal}} f_{\mathcal{O}}(F) \iff \mathcal{N} \models F \qquad (*)$$

for **some particular** F. **Tedious**: always have to prove $(*)$.

- **Better**:
  - characterise a subset of DC,
  - give procedures to construct $f_{\mathcal{O}}(\cdot)$, $\widetilde{\cdot}$, and $\mathcal{O}(\cdot)$
  - prove once and for all that, if F is in this fragment, then

$$\widetilde{\mathcal{N}} \parallel \mathcal{O}(F) \models_{\mathsf{Uppaal}} f_{\mathcal{O}}(F) \iff \mathcal{N} \models F$$

- **Even better**: exact (syntactic) characterisation of the DC fragment that is testable (not in the lecture).

Testability

some modification

Definition 6.1. A DC formula F is called **testable** if an observer (or test automaton (or monitor)) $\mathcal{A}_F$ exists such that for all networks $\mathcal{N} = \mathcal{C}(\mathcal{A}_1, \dots, \mathcal{A}_n)$ it holds that

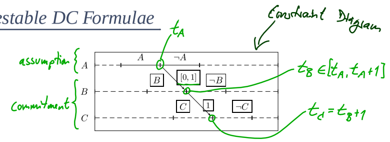
$$\mathcal{N} \models F \quad \text{iff} \quad \mathcal{C}(\mathcal{A}'_1, \dots, \mathcal{A}'_n, \mathcal{A}_F) \models \forall\Box\neg(\mathcal{A}_F.q_{bad})$$

Otherwise it's called **untestable**.

Proposition 6.3. There exist untestable DC formulae.

Theorem 6.4. DC implementables are testable.

Untestable DC Formulae



"Whenever we observe a change from A to $\neg A$ at time t_A, the system has to produce a change from B to $\neg B$ at some time $t_B \in [t_A, t_A + 1]$ and a change from C to $\neg C$ at time $t_B + 1$.

Sketch of Proof: Assume there is $\mathcal{A}_F$ such that, for all networks $\mathcal{N}$, we have

$$\mathcal{N} \models F \quad \text{iff} \quad \mathcal{C}(\mathcal{A}_1', \dots, \mathcal{A}_n', \mathcal{A}_F) \models \forall\Box\neg(\mathcal{A}_F.q_{bad})$$

Assume the number of clocks in $\mathcal{A}_F$ is $n \in \mathbb{N}_0$.

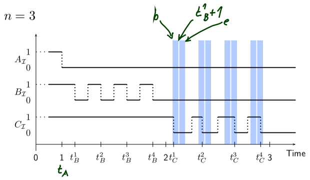
Untestable DC Formulae Cont'd

Consider the following time points:

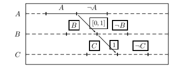
- $t_A := 1$
- $t_B^i := t_A + \frac{2i-1}{2(n+1)}$ for $i = 1, \dots, n+1$
- $t_C^i \in \left]t_B^i + 1 - \frac{1}{4(n+1)}, t_B^i + 1 + \frac{1}{4(n+1)}\right[$ for $i = 1, \dots, n+1$

  with $t_C^i - t_B^i \neq 1$ for $1 \leq i \leq n+1$.

Example: $n = 3$



Untestable DC Formulae Cont'd



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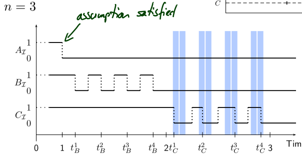
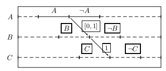
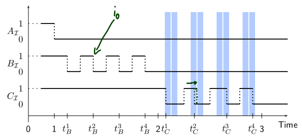


- The shown interpretation $\mathcal{I}$ satisfies **assumption** of property.
- It has $n + 1$ candidates to satisfy **commitment**.
- By choice of t_C^i, the commitment is not satisfied; so F not satisfied.
- Because $\mathcal{A}_F$ is a test automaton for F, is has a computation path to q_{bad}.
- Because $n = 3$, $\mathcal{A}_F$ can not save all $n+1$ time points t_B^i.
- Thus there is $1 \leq i_0 \leq n$ such that all clocks of $\mathcal{A}_F$ have a valuation which is not in $2 - t_B^{i_0} + (-\frac{1}{4(n+1)}, \frac{1}{4(n+1)})$

Untestable DC Formulae Cont'd



Example: $n = 3$



- Because $\mathcal{A}_F$ is a test automaton for F, is has a computation path to q_{bad}.
- Thus there is $1 \leq i_0 \leq n$ such that all clocks of $\mathcal{A}_F$ have a valuation which is not in $2 - t_B^{i_0} + (-\frac{1}{4(n+1)}, \frac{1}{4(n+1)})$
- Modify the computation to $\mathcal{I}'$ such that $t_C^{i_0} := t_B^{i_0} + 1$.
- Then $\mathcal{I}' \models F$, but $\mathcal{A}_F$ reaches q_{bad} via the same path.
- That is: $\mathcal{A}_F$ claims $\mathcal{I}' \not\models F$.
- Thus $\mathcal{A}_F$ is not a test automaton. **Contradiction**.

Testable DC Formulae

> **Theorem 6.4.** DC implementables are testable.

- **Initialisation**: $\lceil\rceil \vee \lceil\pi\rceil \,;\, true$
- **Sequencing**: $\lceil\pi\rceil \longrightarrow \lceil\pi \vee \pi_1 \vee \cdots \vee \pi_n\rceil$
- **Progress**: $\lceil\pi\rceil \xrightarrow{\theta} \lceil\neg\pi\rceil$
- **Synchronisation**: $\lceil\pi \wedge \varphi\rceil \xrightarrow{\theta} \lceil\neg\pi\rceil$
- **Bounded Stability**: $\lceil\neg\pi\rceil \,;\, \lceil\pi \wedge \varphi\rceil \xrightarrow{\leq\theta} \lceil\pi \vee \pi_1 \vee \cdots \vee \pi_n\rceil$
- **Unbounded Stability**: $\lceil\neg\pi\rceil \,;\, \lceil\pi \wedge \varphi\rceil \longrightarrow \lceil\pi \vee \pi_1 \vee \cdots \vee \pi_n\rceil$
- **Bounded initial stability**: $\lceil\pi \wedge \varphi\rceil \xrightarrow{\leq\theta}_0 \lceil\pi \vee \pi_1 \vee \cdots \vee \pi_n\rceil$
- **Unbounded initial stability**: $\lceil\pi \wedge \varphi\rceil \longrightarrow_0 \lceil\pi \vee \pi_1 \vee \cdots \vee \pi_n\rceil$

Proof Sketch:

- For each implementable F, construct $\mathcal{A}_F$.
- Prove that $\mathcal{A}_F$ is a test automaton.

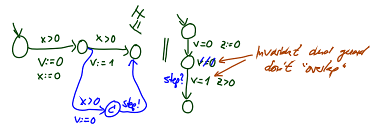
Proof of Theorem 6.4: Preliminaries

- **Note**: DC does not refer to communication between TA in the network, but only to data variables and locations.

  Example:

  $$F = \Diamond(\lceil v = 0\rceil \,;\, \lceil v = 1\rceil)$$

- **Recall**: transitions of TA are only triggered by syncronisation, not by changes of data-variables.



Proof of Theorem 6.4: Preliminaries

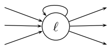
- **Note**: DC does not refer to communication between TA in the network, but only to data variables and locations.

  Example:

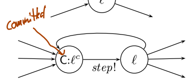
  $$\Diamond(\lceil v = 0 \rceil \,;\, \lceil v = 1 \rceil)$$

- **Recall**: transitions of TA are only triggered by syncronisation, not by changes of data-variables.
- **Approach**: have auxiliary $step$ action.

  Technically, replace each

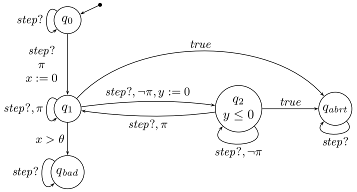
  by

  Note: the observer sees the data variables **after** the update.

Proof of Theorem 6.4: Sketch

- Example: $\lceil \pi \rceil \xrightarrow{\theta} \lceil \neg\pi \rceil$



Counterexample Formulae

Definition 6.5.

- A **counterexample formula** (CE for short) is a DC formula of the form:

  $$true \,;\, (\lceil \pi_1 \rceil \wedge \ell \in I_1) \,;\, \dots \,;\, (\lceil \pi_k \rceil \wedge \ell \in I_k) \,;\, true$$

  where for $1 \leq i \leq k$,
  - π_i are state assertions,
  - I_i are non-empty, and open, half-open, or closed time intervals of the form
    - (b, e) or $[b, e)$ with $b \in \mathbb{Q}_0^+$ and $e \in \mathbb{Q}_0^+ \dot\cup \{\infty\}$,
    - $(b, e]$ or $[b, e]$ with $b, e \in \mathbb{Q}_0^+$.

    (b, ∞) and $[b, \infty)$ denote unbounded sets.
- Let F be a DC formula. A DC formula F_{CE} is called **counterexample formula for** F if $\models F \iff \neg(F_{CE})$ holds.

Theorem 6.7. CE formulae are testable.

References

References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.