Real-Time Systems

Lecture 05: Duration Calculus III

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Contents & Goals

Last Lecture:

• DC Syntax and Semantics: Formulae

This Lecture:

- Educational Objectives: Capabilities for following tasks/questions.
 - Read (and at best also write) Duration Calculus formulae including abbreviations.
 - What is Validity/Satisfiability/Realisability for DC formulae?
 - How can we prove a design correct?

• Content:

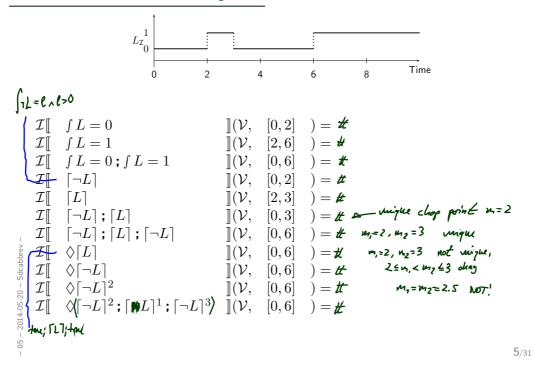
- Duration Calculus Abbreviations
- Basic Properties
- Validity, Satisfiability, Realisability
- Correctness Proofs: Gas Burner

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Duration Calculus Abbreviations

Abbreviations

• $[] := \ell = 0$ (point interval) • $[P] := \ell P \land \ell > 0$ (almost everywhere) • $[P]^t := [P] \land \ell = t$ (for time t) • $[P]^{\leq t} := [P] \land \ell \leq t$ (up to time t) • $\Diamond F := true ; F ; true$ (for some subinterval) • $\Box F := \neg \Diamond \neg F$ (for all subintervals) Abbreviations: Examples

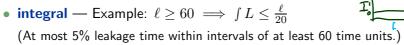


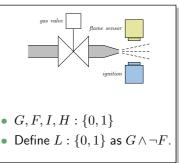
Duration Calculus: Looking Back

- Duration Calculus is an interval logic.
- Formulae are evaluated in an (implicitly given) interval.

Strangest operators:

- almost everywhere Example: [G] (Holds in a given interval [b, e] iff the gas value is open almost everywhere.)
- chop Example: $[(\lceil \neg I \rceil; \lceil I \rceil; \lceil \neg I \rceil) \implies \ell \ge 1)$
 - (Ignition phases last at least one time unit.)





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DC Validity, Satisfiability, Realisability

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Validity, Satisfiability, Realisability

Let ${\mathcal I}$ be an interpretation, ${\mathcal V}$ a valuation, [b,e] an interval, and F a DC formula.

- $\mathcal{I}, \mathcal{V}, [b, e] \models F$ ("F holds in $\mathcal{I}, \mathcal{V}, [b, e]$ ") iff $\mathcal{I}\llbracket F \rrbracket (\mathcal{V}, [b, e]) = \mathsf{tt}.$
- F is called **satisfiable** iff it holds in some \mathcal{I} , \mathcal{V} , [b, e].
- $\mathcal{I}, \mathcal{V} \models F$ (\mathcal{I} and \mathcal{V} realise F") iff $\forall [b, e] \in Intv : \mathcal{I}, \mathcal{V}, [b, e] \models F.$
- F is called **realisable** iff some \mathcal{I} and \mathcal{V} realise F.
- $\mathcal{I} \models F$ (" \mathcal{I} realises F") iff • $\models F$ ("F is valid") iff $\forall \mathcal{V} \in \mathsf{Val} : \mathcal{I}, \mathcal{V} \models F.$ \forall interpretation $\mathcal{I} : \mathcal{I} \models F.$

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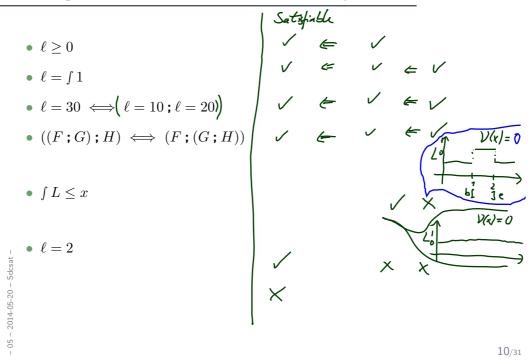
Validity vs. Satisfiability vs. Realisability

Remark 2.13. For all DC formulae F,

- F is satisfiable iff ¬F is not valid, F is valid iff ¬F is not satisfiable.
- If F is valid then F is realisable, but not vice versa.
- If F is realisable then F is satisfiable, but not vice versa.

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Examples: Valid? Realisable? Satisfiable?



Initial Values

• $\mathcal{I}, \mathcal{V} \models_0 F$ (" \mathcal{I} and \mathcal{V} realise F from 0") 'iff

$$\forall t \in \mathsf{Time} : \mathcal{I}, \mathcal{V}, [0, t] \models F.$$

- F is called **realisable from** 0 iff some \mathcal{I} and \mathcal{V} realise F from 0.
- Intervals of the form [0, t] are called **initial intervals**.

• $\mathcal{I} \models_0 F$ (" \mathcal{I} realises F from 0") iff $\forall \mathcal{V} \in \mathsf{Val} : \mathcal{I}, \mathcal{V} \models_0 F$. • $\models_0 F$ ("F is valid from 0") iff \forall interpretation $\mathcal{I} : \mathcal{I} \models_0 F$.

Initial or not Initial...

For all interpretations \mathcal{I} , valuations \mathcal{V} , and DC formulae F,

- (i) $\mathcal{I}, \mathcal{V} \models F$ implies $\mathcal{I}, \mathcal{V} \models_0 F$,
- (ii) if F is realisable then F is realisable from 0, but not vice versa,
- (iii) F is valid iff F is valid from 0.

Specification and Semantics-based Correctness Proofs of Real-Time Systems with DC

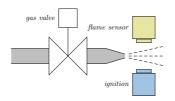
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Methodology: Ideal World...

- (i) Choose a collection of observables 'Obs'.
- (ii) Provide the **requirement**/**specification** 'Spec' as a conjunction of DC formulae (over 'Obs').
- (iii) Provide a description 'Ctrl' of the controller in form of a DC formula (over 'Obs').
- (iv) We say 'Ctrl' is correct (wrt. 'Spec') iff

 $\models_0 \mathsf{Ctrl} \implies \mathsf{Spec.}$

Gas Burner Revisited



(i) Choose **observables**:

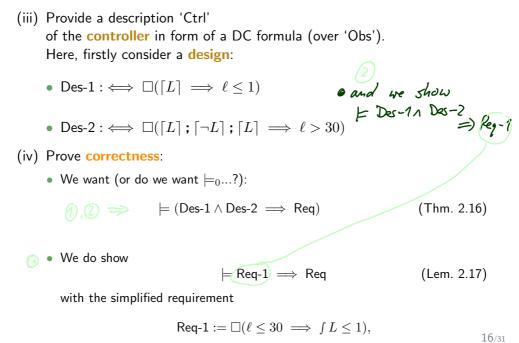
- two boolean observables ${\cal G}$ and ${\cal F}$ (i.e. $Obs = \{G, F\}, \mathcal{D}(G) = \mathcal{D}(F) = \{0, 1\}$) • G = 1: gas valve open now • F = 1: have flame now (output)
- (input)
- define $L := G \land \neg F$ (leakage)
- (ii) Provide the **requirement**:

$$\mathsf{Req}: \iff \Box(\ell \ge 60 \implies 20 \cdot \int L \le \ell)$$

(EX Gas Burner Revisited 2 (iii) Provide a description 'Ctrl' of the controller in form of a DC formula (over 'Obs'). Here, firstly consider a design: • Des-1: $\iff \Box(\lceil L \rceil \implies \ell \le 1)$ "lexkage phases last at most one time unit" • Des-2: $\iff \Box(\lceil L \rceil; \lceil \neg L \rceil; \lceil L \rceil \implies \ell > 30)$ Prove correctness: $\therefore \quad ==t \text{ (or do we want }\models_0...?):$ leaking = line to be twen the operator of the units '(iv) Prove correctness: \models (Des-1 \land Des-2 \implies Req) (Thm. 2.16) - 05 - 2014-05-20 - Sdcgasburner].].].

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Gas Burner Revisited



References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.

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