Real-Time Systems

Lecture 05: Duration Calculus III

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Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

Contents & Goals

Last Lecture:

• DC Syntax and Semantics: Formulae

This Lecture:

- Educational Objectives: Capabilities for following tasks/questions.
 - Read (and at best also write) Duration Calculus formulae including abbreviations.
 - What is Validity/Satisfiability/Realisability for DC formulae?
 - How can we prove a design correct?

• Content:

- Duration Calculus Abbreviations
- Basic Properties
- Validity, Satisfiability, Realisability
- Correctness Proofs: Gas Burner

Duration Calculus Abbreviations

Abbreviations

- $[] := \ell = 0$
- $\lceil P \rceil := \int P = \ell \land \ell > 0$
- $\lceil P \rceil^t := \lceil P \rceil \land \ell = t$
- $\lceil P \rceil^{\leq t} := \lceil P \rceil \land \ell \leq t$
- $\Diamond F := true$; F ; true
- $\Box F := \neg \Diamond \neg F$

(point interval)
(almost everywhere)
 (for time t)
 (up to time t)

(for all subintervals)

(for some subinterval)

Abbreviations: Examples



Duration Calculus: Looking Back

- Duration Calculus is an interval logic.
- Formulae are evaluated in an (implicitly given) interval.

Strangest operators:

• almost everywhere — Example: $\lceil G \rceil$



(Holds in a given interval [b, e] iff the gas value is open almost everywhere.)

- chop Example: ([¬I]; [I]; [¬I]) ⇒ ℓ ≥ 1 (Ignition phases last at least one time unit.)
- integral Example: $\ell \ge 60 \implies \int L \le \frac{\ell}{20}$

(At most 5% leakage time within intervals of at least 60 time units.)

Let \mathcal{I} be an interpretation, \mathcal{V} a valuation, [b, e] an interval, and F a DC formula.

• $\mathcal{I}, \mathcal{V}, [b, e] \models F$ ("F holds in $\mathcal{I}, \mathcal{V}, [b, e]$ ") iff $\mathcal{I}[\![F]\!](\mathcal{V}, [b, e]) = \mathsf{tt}.$

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- $\mathcal{I}, \mathcal{V} \models F$ (" \mathcal{I} and \mathcal{V} realise F") iff $\forall [b, e] \in \mathsf{Intv} : \mathcal{I}, \mathcal{V}, [b, e] \models F$.

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• $\mathcal{I} \models F$ (" \mathcal{I} realises F") iff $\forall \mathcal{V} \in \mathsf{Val} : \mathcal{I}, \mathcal{V} \models F$.

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- F is called **realisable** iff some \mathcal{I} and \mathcal{V} realise F.

• $\mathcal{I} \models F$ (" \mathcal{I} realises F") iff $\forall \mathcal{V} \in \mathsf{Val} : \mathcal{I}, \mathcal{V} \models F$.

• $\models F$ ("*F* is valid") iff \forall interpretation $\mathcal{I} : \mathcal{I} \models F$.

Validity vs. Satisfiability vs. Realisability

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Remark 2.13. For all DC formulae F,
F is satisfiable iff ¬F is not valid,
F is valid iff ¬F is not satisfiable.
If F is valid then F is realisable, but not vice versa.
If F is realisable then F is satisfiable, but not vice versa.
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Examples: Valid? Realisable? Satisfiable?

- $\ell \ge 0$
- $\ell = \int 1$
- $\ell = 30 \iff \ell = 10$; $\ell = 20$
- $((F;G);H) \iff (F;(G;H))$
- $\int L \leq x$

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• $\mathcal{I}, \mathcal{V} \models_0 F$ (" \mathcal{I} and \mathcal{V} realise F from 0") iff

 $\forall t \in \mathsf{Time} : \mathcal{I}, \mathcal{V}, [0, t] \models F.$

- F is called **realisable from** 0 iff some \mathcal{I} and \mathcal{V} realise F from 0.
- Intervals of the form [0, t] are called **initial intervals**.
- $\mathcal{I} \models_0 F$ (" \mathcal{I} realises F from 0") iff $\forall \mathcal{V} \in \mathsf{Val} : \mathcal{I}, \mathcal{V} \models_0 F$.
- $\models_0 F$ ("*F* is valid from 0") iff

 \forall interpretation $\mathcal{I}: \mathcal{I} \models_0 F$.

Initial or not Initial...

For all interpretations \mathcal{I} , valuations \mathcal{V} , and DC formulae F,

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(i) \mathcal{I}, \mathcal{V} \models F implies \mathcal{I}, \mathcal{V} \models_0 F,
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(ii) if F is realisable then F is realisable from 0, but not vice versa,

(iii) F is valid iff F is valid from 0.

Specification and Semantics-based Correctness Proofs of Real-Time Systems with DC

Methodology: Ideal World...

- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide the **requirement**/**specification** 'Spec' as a conjunction of DC formulae (over 'Obs').
- (iii) Provide a description 'Ctrl' of the controller in form of a DC formula (over 'Obs').
- (iv) We say 'Ctrl' is **correct** (wrt. 'Spec') iff

 $\models_0 \mathsf{Ctrl} \implies \mathsf{Spec.}$

Gas Burner Revisited



(i) Choose **observables**:

- two boolean observables G and F(i.e. Obs = {G, F}, $\mathcal{D}(G) = \mathcal{D}(F) = \{0, 1\}$)
- G = 1: gas valve open
- F = 1: have flame
- define $L := G \land \neg F$ (leakage)

(ii) Provide the **requirement**:

$$\mathsf{Req}: \iff \Box(\ell \ge 60 \implies 20 \cdot \int L \le \ell)$$

Gas Burner Revisited

(iii) Provide a description 'Ctrl'
 of the controller in form of a DC formula (over 'Obs').
 Here, firstly consider a design:

• Des-1 :
$$\iff \Box(\lceil L \rceil \implies \ell \le 1)$$

• Des-2: $\iff \Box(\lceil L \rceil; \lceil \neg L \rceil; \lceil L \rceil \implies \ell > 30)$

(iv) Prove correctness:

• We want (or do we want
$$\models_0 \dots ?$$
):

$$\models (\mathsf{Des-1} \land \mathsf{Des-2} \implies \mathsf{Req}) \tag{Thm. 2.16}$$

Gas Burner Revisited

(iii) Provide a description 'Ctrl' of the controller in form of a DC formula (over 'Obs'). Here, firstly consider a design:

• Des-1 :
$$\iff \Box(\lceil L \rceil \implies \ell \le 1)$$

• Des-2: $\iff \Box(\lceil L \rceil; \lceil \neg L \rceil; \lceil L \rceil \implies \ell > 30)$

(iv) Prove correctness:

• We want (or do we want $\models_0 ... ?$):

$$= (\mathsf{Des-1} \land \mathsf{Des-2} \implies \mathsf{Req}) \tag{Thm. 2.16}$$

• We do show

$$\models \mathsf{Req-1} \implies \mathsf{Req} \qquad (\mathsf{Lem. 2.17})$$

with the simplified requirement

 $\mathsf{Req-1} := \Box(\ell \le 30 \implies \int L \le 1),$

Claim:

$$\models \underbrace{\Box(\ell \le 30 \implies \int L \le 1)}_{\mathsf{Req-1}} \implies \underbrace{\Box(\ell \ge 60 \implies 20 \cdot \int L \le \ell)}_{\mathsf{Req}}$$

Proof:

Claim:

$$\models \underbrace{\Box(\ell \le 30 \implies \int L \le 1)}_{\mathsf{Req-1}} \implies \underbrace{\Box(\ell \ge 60 \implies 20 \cdot \int L \le \ell)}_{\mathsf{Req}}$$

Proof:

• Assume 'Req-1'.

Claim:

$$\models \underbrace{\Box(\ell \le 30 \implies \int L \le 1)}_{\text{Req-1}} \implies \underbrace{\Box(\ell \ge 60 \implies 20 \cdot \int L \le \ell)}_{\text{Req}}$$

Proof:

- Assume 'Req-1'.
- Let $L_{\mathcal{I}}$ be any interpretation of L, and [b, e] an interval with $e b \ge 60$.

Claim:

$$\models \underbrace{\Box(\ell \le 30 \implies \int L \le 1)}_{\text{Req-1}} \implies \underbrace{\Box(\ell \ge 60 \implies 20 \cdot \int L \le \ell)}_{\text{Req}}$$

Proof:

- Assume 'Req-1'.
- Let $L_{\mathcal{I}}$ be any interpretation of L, and [b, e] an interval with $e b \ge 60$.
- Show " $20 \cdot \int L \leq \ell$ ", i.e.

 $\mathcal{I}[\![20 \cdot \int L \leq \ell]\!](\mathcal{V}, [b, e]) = \mathsf{tt}$

i.e.

$$\hat{20} \cdot \int_{b}^{e} L_{\mathcal{I}}(t) \, dt \stackrel{\circ}{\leq} (e-b)$$

Gas Burner Revisited: Lemma 2.17
$$\models \bigcirc (\ell \le 30 \implies \int L \le 1) \\ \underset{\text{Req-1}}{\overset{\text{Req-1}}{\Rightarrow}} \bigcirc (\ell \ge 60 \implies 20 \cdot \int L \le \ell)$$

• Set $n := \lfloor \frac{e-b}{30} \rfloor$, i.e. $n \in \mathbb{N}$ with $n-1 < \frac{e-b}{30} \leq n$, and split the interval



Some Laws of the DC Integral Operator

Theorem 2.18.
For all state assertions
$$P$$
 and all real numbers $r_1, r_2 \in \mathbb{R}$
(i) $\models \int P \leq \ell$,
(ii) $\models (\int P = r_1)$; $(\int P = r_2) \implies \int P = r_1 + r_2$,
(iii) $\models [\neg P] \implies \int P = 0$,
(iv) $\models [\neg \implies \int P = 0$.

Claim:



Proof:



Des-2

Des-1

Proof:

Req-1

Obstacles in Non-Ideal World

Methodology: The World is Not Ideal...

- (i) Choose a collection of **observables** 'Obs'.
- (ii) Provide **specification** 'Spec' (conjunction of DC formulae (over 'Obs')).
- (iii) Provide a description 'Ctrl' of the controller (DC formula (over 'Obs')).
- (iv) Prove 'Ctrl' is **correct** (wrt. 'Spec').

That looks too simple to be practical. Typical obstacles:

- (i) It may be impossible to realise 'Spec' if it doesn't consider properties of the plant.
- (ii) There are typically intermediate design levels between 'Spec' and 'Ctrl'.
- (iii) 'Spec' and 'Ctrl' may use **different observables**.
- (iv) **Proving** validity of the implication is not trivial.

(i) Assumptions As A Form of Plant Model

- Often the controller will (or can) operate correctly only under some assumptions.
- For instance, with a level crossing
 - we may assume an upper bound on the speed of approaching trains, (otherwise we'd need to close the gates arbitrarily fast)
 - we may assume that trains are not arbitrarily slow in the crossing, (otherwise we can't make promises to the road traffic)

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 $\mathsf{Ctrl} \land \mathsf{Asm} \implies \mathsf{Spec}$

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Shall we care whether 'Asm' is satisfiable?

(ii) Intermediate Design Levels

- A top-down development approach may involve
 - Spec specification/requirements
 - Des design
 - Ctrl implementation
- Then correctness is established by proving validity of

$$Ctrl \implies Des$$
 (1)

and

$$Des \implies Spec$$
 (2)

(then concluding Ctrl \implies Spec by transitivity)

Any preference on the order?

(iii): Different Observables

- Assume, 'Spec' uses more abstract observables Obs_A and 'Ctrl' more concrete ones Obs_C.
- For instance:
 - in Obs_A : only consider gas value open or closed $(\mathcal{D}(G) = \{0, 1\})$
 - in Obs_C: may control two valves and care for intermediate positions, for instance, to react to different heating requests
 (D(G) = {0.1.2.3}, D(G) = {0.1.2.3})

(iii): Different Observables

- Assume, 'Spec' uses more abstract observables Obs_A and 'Ctrl' more concrete ones Obs_C.
- For instance:
 - in Obs_A: only consider gas valve open or closed ($\mathcal{D}(G) = \{0, 1\}$)
 - in Obs_C: may control two valves and care for intermediate positions, for instance, to react to different heating requests (D(G₁) = {0, 1, 2, 3}, D(G₂) = {0, 1, 2, 3})
- To prove correctness, we need information how the observables are related

 an invariant which links the data values of Obs_A and Obs_C.
- If we're given the linking invariant as a DC formula, say 'Link_{C,A}', then proving correctness of 'Ctrl' wrt. 'Spec' amounts to proving validity (from 0) of

 $\mathsf{Ctrl} \wedge \mathsf{Link}_{C,A} \implies \mathsf{Spec.}$

• For instance,

Obstacle (iv): How to Prove Correctness?

- by hand on the basis of DC semantics,
- maybe supported by proof rules,
- sometimes a general theorem may fit (e.g. cycle times of PLC automata),
- algorithms as in Uppaal.

Recall: Tying It All Together



References

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). *Real-Time Systems - Formal Specification and Automatic Verification*. Cambridge University Press.