Real-Time Systems

Lecture 16: The Universality Problem for TBA

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Recall: Testability

Untestable DC Formulae

Definition 6.1. A DC formula F is called testable if an observer (or test automaton (or monitor)) \mathcal{A}_F exists such that for all networks $\mathcal{N}=\mathcal{C}(\mathcal{A}_1,\dots,\mathcal{A}_n)$ it holds that

 $\mathcal{N} \models F \quad \text{iff} \quad \mathcal{C}(\mathcal{A}'_1, \dots, \mathcal{A}'_n, \mathcal{A}_F) \models \forall \Box \neg (\mathcal{A}_F.q_{bad})$

Otherwise it's called untestable.

Proposition 6.3. There exist untestable DC formulae.

Theorem 6.4. DC implementables are testable.

Assume the number of clocks in \mathcal{A}_F is $n \in \mathbb{N}_0$.

Sketch of Proof: Assume there is \mathcal{A}_F such that, for all networks \mathcal{N} , we have

 $\mathcal{N} \models F \quad \text{iff} \quad \mathcal{C}(\mathcal{A}_1', \dots, \mathcal{A}_n', \mathcal{A}_F) \models \forall \Box \neg (\mathcal{A}_F.q_{bol})$

"Whenever we observe a change from A to $\neg A$ at time t_A , the system has to produce a change from B to $\neg B$ at some time $t_B \in [t_A, t_A + 1]$ and a change from C to $\neg C$ at time $t_B + 1$.

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Contents & Goals

- Extended Timed Automata Cont'd
- A Fragment of TCTL

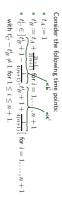
- Testable DC Formulae

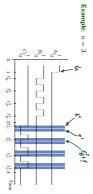
- This Lecture:
- Educational Objectives: Capabilities for following tasks/questions.
- Are all DC formulae testable?
 What's a TBA and what's the difference to (extended) TA?
 What's undecidable for timed (Büchi) automata? Idea of the proof?

- An untestable DC formula.
 Timed Büchi Automata and timed regular languages [Alur and Dill, 1994].
 The University Problem is undecidable for TBA [Alur and Dill, 1994].
 Why this is unfortunate.
- Timed regular languages are not everything.

Untestable DC Formulae

Untestable DC Formulae Cont'd





Untestable DC Formulae Cont'd

Example: n=3



• The shown interpretation $\mathcal I$ satisfies assumption of property. • It has n+1 candidates to satisfy commitment.

 $1 \ t_B^1 = t_B^2 = t_B^3 = t_B^4 \ 2t_C^1$

- By choice of t_{i}^{\prime} , the commitment is not satisfied; so F not satisfied.
 Because A_F is a test automaton for F, is has a computation path to q_{bod} .
- Because n=3, A_P can not save all n+1 time points t_B^p .
 Thus there is $1 \le i_0 \le n$ such that all clocks of A_P have a valuation which is not in $2 t_B^p + (-\frac{1}{4(n+1)}, \frac{1}{4(n+1)})$.

Example: n=3

• Because A_F is a test automaton for F, is has a computation path to q_{0ab} .
• Thus there is $1 \leq i_0 \leq n$ such that all clocks of A_F have a valuation which is not in $2-t_0^B+(-\frac{n}{4(n+1)},\frac{n}{4(n+1)})$

 $1 t_B^1 = t_B^2 = t_B^3 = t_B^4 = 2t_C^4$

- Modify the computation to T' such that t₀^(p) := t₀^(p) + 1.
 Then T' |= F, but A_F reaches q_{bad} via the same path.
 That is: A_F claims T' |≠ F.
 Thus A_F is not a test automaton. Contradiction.

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Untestable DC Formulae Cont'd



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Timed Büchi Automata [Alur and Dill, 1994]

... vs. Timed Automata

 $\xi = \langle off, 0 \rangle, 0 \xrightarrow{1} \langle off, 1 \rangle, 1$ $\frac{press?}{press?} \langle light, 0 \rangle, 1 \xrightarrow{3} \langle light, 3 \rangle, 4$ $\frac{press?}{press?} \langle bright, 3 \rangle, 4 \xrightarrow{\cdots} \dots$ ξ is a computation path and run of \mathcal{A} .

New: acceptance criterion is visiting accepting state infinitely often. does A accept it? New: Given a timed word (a, 1), (b, 2), (a, 3), (b, 4), (a, 5), (b, 6), (b, 6.5)

Timed Büchi Automata not simple!

Definition. The set $\Phi(X)$ of clock constraints over X is defined inductively by where $x \in X$ and $c \in \mathbb{Q}$ is a rational constant. $\delta ::= x \leq c \mid c \leq x \mid \neg \delta \mid \delta_1 \wedge \delta_2$

Definition. A timed Büchi automaton (TBA) $\mathcal A$ is a tuple (Σ,S,S_0,X,E,F) , where

- Σ is an alphabet,
- S is a finite set of states, $S_0 \subseteq S$ is a set of start states, X is a finite set of clocks, and
- * $E\subseteq S\times S\times \Sigma\times \Sigma^{k}\times \Phi(X)$ gives the set of transitions. An edge (s,s',a,λ,δ) represents a transition from state s to state s' on input symbol a. The set $\lambda\in X$ gives the clock to be reset with this transition, and δ is a clock constraint over X.

Timed Languages

Definition. A time sequence $\tau=\tau_1,\tau_2,\ldots$ is an infinite sequence of time values $\tau_i\in\mathbb{R}^+_0$, satisfying the following constraints:

(i) Monotonicity: $\tau \text{ increases strictly monotonically, i.e. } \tau_i < \tau_{i+1} \text{ for all } i \geq 1.$ (ii) Progress: For every $t \in \mathbb{R}_0^+$, there is some $i \geq 1$ such that $\tau_i > t$.

τ is a time sequence.

Definition. A timed language over an alphabet Σ is a set of timed words over $\Sigma.$

Definition. A timed word over an alphabet Σ is a pair (σ,τ) where

• $\sigma=\sigma_1,\sigma_2,\dots\in\Sigma^\omega$ is an infinite word over Σ , and

Example: TBA

 $A = (\Sigma, S, S_0, X, E, F)$ $(s, s', a, \lambda, \delta) \in E$



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Example: Timed Language

Timed word over alphabet Σ : a pair (σ,τ) where $\sigma = \sigma_1, \sigma_2, \dots$ is an infinite word over Σ , and σ is a time sequence (strictly (!) monotonic, non-Zeno).

 $L_{crt} = \{((ab)^{\omega}, \tau) \mid \exists i \ \forall j \geq i : (\tau_{2j} < \tau_{2j-1} + 2)\}$

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(Accepting) TBA Runs

Definition. A run r, denoted by (\overline{s},P) , of a TBA (Σ,S,S_0,X,E,F) over a timed word (σ,τ) is an infinite sequence of the form

 $r: \langle s_0, \nu_0 \rangle \xrightarrow{\sigma_1} \langle s_1, \nu_1 \rangle \xrightarrow{\sigma_2} \langle s_2, \nu_2 \rangle \xrightarrow{\sigma_3} \dots$

with $s_i \in S$ and $\nu_i: X \to \mathbb{R}^+_0$, satisfying the following requirements:

• Initiation: $s_0 \in S_0$ and $\nu(x) = 0$ for all $x \in X$. • Consecution: for all $i \geq 1$, there is an edge in E of the form $(s_{l-1}, s_l; \sigma_{li}, \lambda_l, \delta_l)$ such that

The set $inf(r)\subseteq S$ consists of those states $s\in S$ such that $s=s_i$ for infinitely many $i\ge 0$.

• $\nu_i = (\nu_{i-1} + (\tau_i - \tau_{i-1}))[\lambda_i := 0].$ • $(\nu_{i-1} + (\tau_i - \tau_{i-1}))$ satisfies δ_i and

Definition. A run $r=(\bar{s},\bar{\nu})$ of a TBA over timed word (σ,τ) is called (an) accepting (run) if and only if $inf(r)\cap F\neq\emptyset$.

Example: (Accepting) Runs

 $\begin{array}{ccc} r: (s_0, \nu_0) \stackrel{\alpha_1}{\longrightarrow} (s_1, \nu_1) \stackrel{\alpha_2}{\longrightarrow} (s_2, \nu_2) \stackrel{\alpha_3}{\longrightarrow} \ldots & \text{initial and } (s_{-1}, s_i, \sigma_i, \lambda_i, \delta_i) \in E, \text{ s.t.} \\ (\nu_{-1} + (\tau_1 - \tau_{-1})) \models \delta_i, \nu_i = (\nu_{-1} + (\tau_1 - \tau_{-1})) [\lambda_i := 0]. \text{ Accepting iff } vif(\tau) \cap F \neq \emptyset. \end{array}$



Timed word: $(a, 1), (b, 2), (a, 3), (b, 4), (a, 5), (b, 6), \dots$

- Can we construct any run? Is it accepting? $\langle z_0, x_0 \rangle \xrightarrow{q} \langle s_1, 0 \rangle \xrightarrow{b} \langle s_2, u \rangle \cdots$
- Can we construct a non-run?

• Can we construct a (non-)accepting run? $\langle \lambda_{j}, 0 \rangle \xrightarrow[\tau_{k}]{d} \langle \xi_{k}, n \rangle \xrightarrow[r_{k}]{b} \langle \xi_{k}, n \rangle \xrightarrow[r_{k}]{d} \langle \xi_{k}, n \rangle \xrightarrow[r_{k}]{d} \langle \xi_{k}, n \rangle$

Definition. For a TBA A, the law is defined to be the set For short: L(A) is the language of A. $\{(\sigma,\tau) \mid A \text{ has an accepting run over } (\sigma,\tau)\}.$

 $M \in L(A)$ of timed words it accepts

The Language of a TBA

Definition. A timed language L is a timed regular language if and only if $L=L(\mathcal{A})$ for some TBA \mathcal{A} .

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The Universality Problem is Undecidable for TBA

[Alur and Dill, 1994]

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The Universality Problem

- Given: A TBA $\mathcal A$ over alphabet Σ .
 Question: Does $\mathcal A$ accept all timed words over Σ ?
 In other words: Is $L(\mathcal A)=\{(\sigma,\tau)\mid \sigma\in \Sigma^\omega, \tau \text{ time sequence}\}.$

D={a,b,c} +: 200

Example: Language of a TBA

 $L(\mathcal{A}) = \{(\sigma,\tau) \mid \mathcal{A} \text{ has an accepting run over } (\sigma,\tau)\}.$



 $L(\mathcal{A}) = L_{crt} \ (= \{ ((ab)^{\omega}, \tau) \mid \exists i \ \forall j \ge i : (\tau_{2j} < \tau_{2j-1} + 2) \})$

Question: Is L_{crt} timed regular or not?

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Given: A TBA A over alphabet Σ.

The Universality Problem

- $\bullet \ \, \text{Question: Does \mathcal{A} accept all timed words over Σ?}$ In other words: Is $L(\mathcal{A}) = \{(\sigma,\tau) \mid \sigma \in \Sigma^\omega, \tau \text{ time sequence}\}.$

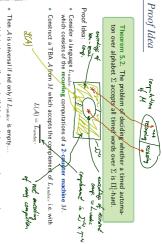
Theorem 5.2. The problem of deciding whether a timed automaton over alphabet Σ accepts all timed words over Σ is $\Pi^1_1\text{-hard}.$

("The class Π_1^1 consists of highly undecidable problems, including some nonarithmetical sets (for an exposition of the analytical hierarchy consult, see for instance [Rogers, 1967].)

Recall: With classical Büchi Automata (untimed), this is different:

Let B be a Büchi Automaton over Σ.
 B is universal if and only if L(B) = ∅.
 B' such that L(B') = L(B) is effectively computable.
 Language emptyness is decidable for Büchi Automata.

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 \dots which is the case if and only if M doesn't have a recurring computation.

Once Again: 2-Counter Mach. (Different Flavour)

A two-counter machine ${\cal M}$

- has two counters C, D and
- a finite program consisting of n instructions.
 An instruction increments or decrements one of the counters, or jumps. here even non-deterministically.
- A configuration of M is a triple ⟨i, c, d⟩:

program counter $i \in \{1, \dots, n\}$, values $c, d \in \mathbb{N}_0$ of C and D.

A computation of M is an infinite consecutive sequence

that is, $\langle i_{j+1}, c_{j+1}, d_{j+1} \rangle$ is a result executing instruction i_j at $\langle i_j, c_j, d_j \rangle$. $\langle 1,0,0\rangle = \langle i_0,c_0,d_0\rangle, \langle i_1,c_1,d_1\rangle, \langle i_2,c_2,d_2\rangle, \dots$

A computation of M is called **recurring** iff $i_j=1$ for infinitely many $j\in\mathbb{N}_0$.

Step 2: Construct "Observer" for \overline{L}_{undec}

Step 1: The Language of Recurring Computations

Let L_{undec} be the set of the timed words (σ, τ) with

• σ is of the form $b_{i_1}a_1^{c_1}a_2^{d_1}b_{i_2}a_1^{c_2}a_2^{d_2}\dots$

• $\langle i_1,c_1,d_1 \rangle, \langle i_2,c_2,d_2 \rangle, \dots$ is a recurring computation of M .

For all $j \in \mathbb{N}_0$,

the time of b_{ij} is j.

• if $c_{j+1}=c_j$: for every a_i at time t in the interval [j,j+1] there is an a_i at time t+1,

• if $c_{j+1}=c_j+1$: for every a_1 at time t in the interval [j+1,j+2], except for the last one, there is an a_1 at time t-1,

i.e., A accepts a timed word (σ, τ) if and only if $(\sigma, \tau) \notin L_{undec}$. Wanted: A TBA A such that $L(A) = \overline{L_{undec}}$

Approach: What are the reasons for a timed word not to be in L_{undec} ?

- **Recall**: (σ, τ) is in L_{undec} if and only if: • $\sigma = b_{i_1} a_1^{c_1} a_2^{a_1} b_{i_2} a_1^{c_2} a_2^{a_2}$
- $\langle i_1, c_1, d_1 \rangle, \langle i_2, c_2, d_2 \rangle, \dots$ is a recurring computation of M.
- the time of b_{ij} is j,
- if $c_{j+1} = c_j$ (= $c_j + 1$, = $c_j 1$): ...
- (i) The b_i at time $j\in \mathbb{N}$ is missing, or there is a spurious b_i at time $t\in]j,j+1[$
- (ii) The prefix of the timed word with times $0 \le t < 1$ doesn't encode $\langle 1, 0, 0 \rangle$.
- (iii) The timed word is not recurring, i.e. it has only finitely many b_i .

• if $c_{j+1}=c_j-1$: for every a_1 at time t in the interval [j,j+1], except for the last one, there is an a_1 at time t+1,

And analogously for the a_2 's.

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(iv) The configuration encoded in [j+1,j+2[doesn't faithfully represent the effect of instruction b_l on the configuration encoded in [j,j+1[.

Step 1: The Language of Recurring Computations

ullet Let M be a 2CM with n instructions

Wanted: A timed language L_{mdec} (over some alphabet) representing exactly the recurring computations of M. (In particular s.t. $L_{undec} = \emptyset$ if and only if M has no recurring computation.)

- Choose $\Sigma = \{b_1, \dots, b_n, a_1, a_2\}$ as alphabet.
- \bullet . We represent a configuration $\langle i,c,d\rangle$ of M by the sequence

 $b_i \underbrace{a_1 \dots a_1}_{c \text{ times}} \underbrace{a_2 \dots a_2}_{d \text{ times}} = b_1 a_1^c a_2^d$

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Step 2: Construct "Observer" for Lundec

Wanted: A TBA A such that $L(A) = \overline{L_{undec}}$,

i.e., \mathcal{A} accepts a timed word (σ,τ) if and only if $(\sigma,\tau) \not\in L_{undec}.$

Approach: What are the reasons for a timed word not to be in L_{undec} ?

- (i) The b_i at time $j \in \mathbb{N}$ is missing, or there is a spurious b_i at time $t \in]j,j+1[$.
- (iii) The timed word is not recurring, i.e. it has only finitely many $b_{\rm f}$. (ii) The prefix of the timed word with times $0 \le t < 1$ doesn't encode $\langle 1, 0, 0 \rangle$.
- (iv) The configuration encoded in [j+1,j+2] doesn't faithfully represent the effect of instruction b_i on the configuration encoded in [j,j+1].

Then set **Plan**: Construct a TBA \mathcal{A}_0 for case (i), a TBA \mathcal{A}_{init} for case (ii), a TBA \mathcal{A}_{resur} for case (iii), and one TBA \mathcal{A}_i for each instruction for case (iv).

 $\mathcal{A} = \mathcal{A}_0 \cup \mathcal{A}_{init} \cup \mathcal{A}_{recur} \cup \bigcup_{1 \leq i \leq n} \mathcal{A}_i$

Step 2.(i): Construct A_0

(i) The b_i at time $j\in\mathbb{N}$ is missing, or there is a spurious b_i at time $t\in]j,j+1[.$

[Alur and Dill, 1994]: "It is easy to construct such a timed automaton."

Step 2.(iv): Construct A_i

(iv) The configuration encoded in [j+1,j+2] doesn't faithfully represent the effect of instruction b_i on the configuration encoded in [j,j+1].

Example: assume instruction 7 is:

Increment counter ${\cal D}$ and jump non-deterministically to instruction 3 or 5.

Once again: stepwise. A_7 is $A_7^1 \cup \cdots \cup A_7^6$.

• A_7^1 accepts words with b_7 at time j but neither b_3 nor b_6 at time j+1. "Easy to construct."

- A_1^2 accepts words which encode unexpected increment of counter C.
 A_2^4,\ldots,A_2^6 accept words with missing decrement of D.

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Step 2.(ii): Construct A_{init}

Step 2.(iii): Construct Arecur

(iii) The timed word is not recurring, i.e. it has only finitely many $b_{i\cdot}$

ullet \mathcal{A}_{recur} accepts words with only finitely many b_i

(ii) The prefix of the timed word with times $0 \le t < 1$ doesn't encode $\langle 1, 0, 0 \rangle$.

 $\{(\sigma_j,\tau_j)_{j\in\mathbb{N}_0}\mid (\sigma_0\neq b_1)\vee (\tau_0\neq 0)\vee (\tau_1\neq 1)\}.$

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Consequences: Language Inclusion

• Given: Two TBAs \mathcal{A}_1 and \mathcal{A}_2 over alphabet B.
• Question: Is $\mathcal{L}(\mathcal{A}_1) \subseteq \mathcal{L}(\mathcal{A}_2)$?

Possible applications of a decision procedure:

Aha, And...?

- Characterise the allowed behaviour as A₂ and model the design as A₁.
 Automatically check whether the behaviour of the design is a subset of the allowed behaviour.

 $\mathcal{L}(\mathcal{A}_{univ}) \subseteq \mathcal{L}(\mathcal{A})$

 \bullet If language inclusion was decidable, then we could use it to decide universality of ${\cal A}$ by checking

where \mathcal{A}_{univ} is any universal TBA (which is easy to construct).

Consequences: Complementation

- Given: A timed regular language W over B (that is, there is a TBA A such that $\mathcal{L}(A)=W$).
 Question: Is \overline{W} timed regular?

- Possible applications of a decision procedure: • Characterise the allowed behaviour as \mathcal{A}_2 and model the design as \mathcal{A}_1 . • Automatically construct \mathcal{A}_3 with $L(\mathcal{A}_3) = L(\mathcal{A}_2)$ and check

$$L(\mathcal{A}_1) \cap L(\mathcal{A}_3) = \emptyset,$$

that is, whether the design has any non-allowed behaviour.

- Taking for granted that:
- The intersection automaton is effectively computable.
 The emptyness problem for Büchi automata is decidable.
 (Proof by construction of region automaton [Alur and Dill, 1994].)

• Given: A timed regular language W over B (that is, there is a TBA A such that $\mathcal{L}(A)=W$).
• Question: Is \overline{W} timed regular?

Consequences: Complementation

If the class of timed regular languages were closed under complementation, "the complement of the inclusion problem is recursively enumerable. This contradicts the II]-hadness of the inclusion problem." [Alur and Dill, 1994]

A non-complementable TBA \mathcal{A} :

$$\mathcal{L}(\mathcal{A}) = \{(a^{a_i}, (t_i)_{i \in \mathbb{N}_0}) \mid \exists i \in \mathbb{N}_0 \exists j > i : (t_j = t_i + 1)\}$$

Complement language:

 $\overline{\mathcal{L}(\mathcal{A})} = \{(a^{\omega}, (t_i)_{i \in \mathbb{N}_0}) \mid \text{no two } a \text{ are separated by distance 1}\}.$

Beyond Timed Regular

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hat's special about PLC?

Beyond Timed Regular

With clock constraints of the form

• There are strictly more timed languages than timed regular languages. • There exists timed languages L such that there exists no $\mathcal A$ with $L(\mathcal A)=L$.

 $\{((abc)^{\omega},\tau)\mid\forall\,j.(\tau_{3j}-\tau_{3j-1})=2(\tau_{3j-1}-\tau_{3j-2})\}$

In other words:

we can describe timed languages which are not timed regular.

 $x+y \leq x'+y'$

hat is a PLC?

microprocessor, memory, timers

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digital (or analog) I/O ports
possibly RS 232.
fieldbuses, networking
obust hardware
reprogrammable
standardised programming
model (IEC 61131-3)

here are PLC employed?



mostly process automatisation production lines packaging lines chemical plants power plants power pomentic or hydraulic cylinders

- not so much: product automatisation, there
 tailored or OTS controller boards
 embedded controllers
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o are PLC programmed?

PLC have in common that they operate in a cyclic manner.



Cyclic operation is repeated until external interruption (such as shutdown or reset).
 Cycle time: typically a few milliseconds. [7]

write outputs

- Programming for PLC means providing the "compute" part.

Input/output values are available via designated local variables.

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[Alur and Dill, 1994] Alur, R. and Dill, D. L. (1994). A theory of timed automata. *Theoretical Computer Science*, 126(2):183–235.

[Olderog and Dierks, 2008] Olderog, E.-R. and Dierks, H. (2008). Real-Time Systems - Formal Specification and Automatic Verification. Cambridge University Press.

References

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hy study PLC?

- Note:
 the discussion here is not limited to PLC and IEC 61131-3 languages.
- Any programming language on an operating system with at least one real-time clock will do.
 (Where a real-time clock is a piece of hardware such that,
 we can program it to wait for it time units,
 we can query whether the set time has elapsed,
 if we program it to wait for it time units,
 if does so with negligible deviation.)
- And strictly speaking, we don't even need "full blown" operating systems.
- PLC are just a formalisation on a good level of abstraction:
- there are inputs somehow available as local variables,
 there are outputs somehow available as local variables,
 somehow, inputs are polled and outputs updated atomically,
 there is some interface to a real-time dock.