

abstraction of $post$ by $post^\#$

- ▶ instead of iteratively applying $post$, use over-approximation $post^\#$ such that always

$$post(\varphi, \rho) \models post^\#(\varphi, \rho)$$

- ▶ decompose computation of $post^\#$ into two steps: first, apply $post$ and then, over-approximate result
- ▶ define abstraction function α such that always

$$\varphi \models \alpha(\varphi) .$$

- ▶ for a given abstraction function α , define $post^\#$:

$$post^\#(\varphi, \rho) = \alpha(post(\varphi, \rho))$$

abstraction of φ_{reach} by $\varphi_{reach}^\#$

- ▶ instead of computing φ_{reach} , compute over-approximation $\varphi_{reach}^\#$ such that $\varphi_{reach}^\# \supseteq \varphi_{reach}$
- ▶ check whether $\varphi_{reach}^\#$ contains any error states
if $\varphi_{reach}^\# \wedge \varphi_{err} \models false$
then $\varphi_{reach} \wedge \varphi_{err} \models false$, i.e., program is safe
- ▶ compute $\varphi_{reach}^\#$ by applying iteration

$$\begin{aligned}\varphi_{reach}^\# &= \alpha(\varphi_{init}) \vee \\ &\quad post^\#(\alpha(\varphi_{init}), \rho_{\mathcal{R}}) \vee \\ &\quad post^\#(post^\#(\alpha(\varphi_{init}), \rho_{\mathcal{R}}), \rho_{\mathcal{R}}) \vee \dots \\ &= \bigvee_{i \geq 0} (post^\#)^i(\alpha(\varphi_{init}), \rho_{\mathcal{R}})\end{aligned}$$

- ▶ consequence: $\varphi_{reach} \models \varphi_{reach}^\#$

predicate abstraction

- ▶ construct abstraction $\alpha(\varphi)$ using a given set of building blocks, so-called predicates
- ▶ predicate = formula over the program variables V
- ▶ fix finite set of predicates $Preds = \{p_1, \dots, p_n\}$
- ▶ over-approximation of φ by conjunction of predicates in $Preds$

$$\alpha(\varphi) = \bigwedge \{p \in Preds \mid \varphi \models p\}$$

- ▶ computation of $\alpha(\varphi)$ requires n entailment checks ($n =$ number of predicates)

example: compute $\alpha(at_l_2 \wedge y \geq z \wedge x + 1 \leq y)$

► $Preds = \{at_l_1, \dots, at_l_5, y \geq z, x \geq y\}$

1. to compute $\alpha(\varphi)$, check logical consequence between φ and each of the predicates:

	$y \geq z$	$x \geq y$	at_l_1	at_l_2	at_l_3	at_l_4	at_l_5
$at_l_2 \wedge$							
$y \geq z \wedge$	\models	$\not\models$	$\not\models$	\models	$\not\models$	$\not\models$	$\not\models$
$x + 1 \leq y$							

2. result of abstraction = conjunction over entailed predicates

$$\alpha\left(\begin{array}{l} at_l_2 \wedge \\ y \geq z \wedge x + 1 \leq y \end{array} \right) = at_l_2 \wedge y \geq z$$

trivial abstraction $\alpha(\varphi) = true$

- ▶ result of applying predicate abstraction is *true* if none of the predicates is entailed by φ (“predicates are too specific”) . . . always the case if $Preds = \emptyset$

algorithm ABSTREACH

begin

$\alpha := \lambda\varphi . \bigwedge\{p \in \text{Preds} \mid \varphi \models p\}$

$\text{post}^\# := \lambda(\varphi, \rho) . \alpha(\text{post}(\varphi, \rho))$

$\text{ReachStates}^\# := \{\alpha(\varphi_{\text{init}})\}$

$\text{Parent} := \emptyset$

$\text{Worklist} := \text{ReachStates}^\#$

while $\text{Worklist} \neq \emptyset$ **do**

$\varphi := \text{choose from Worklist}$

$\text{Worklist} := \text{Worklist} \setminus \{\varphi\}$

for each $\rho \in \mathcal{R}$ **do**

$\varphi' := \text{post}^\#(\varphi, \rho)$

if $\varphi' \notin \text{ReachStates}^\#$ **then**

$\text{ReachStates}^\# := \{\varphi'\} \cup \text{ReachStates}^\#$

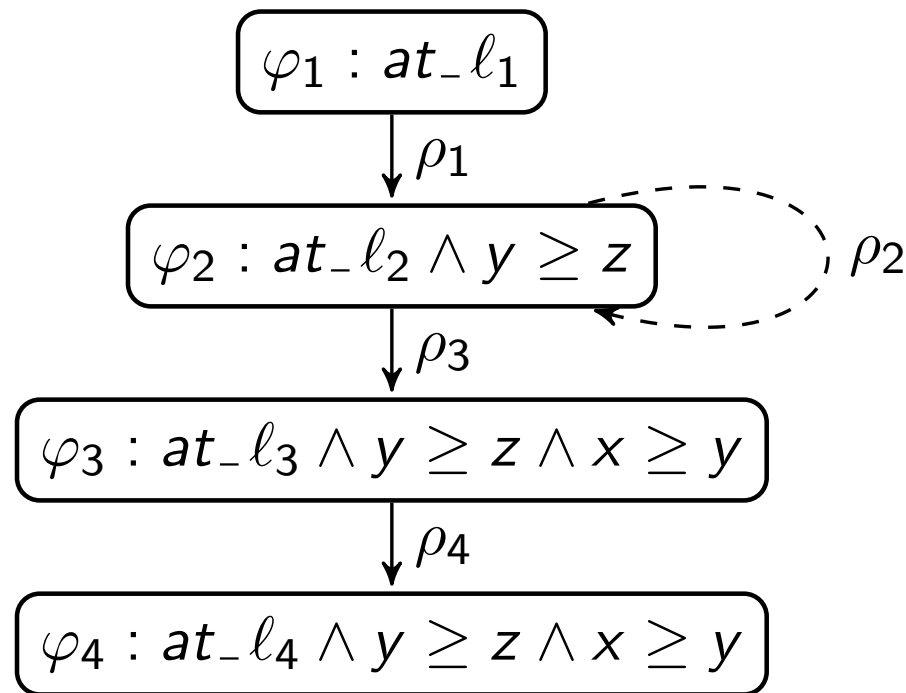
$\text{Parent} := \{(\varphi, \rho, \varphi')\} \cup \text{Parent}$

$\text{Worklist} := \{\varphi'\} \cup \text{Worklist}$

return $(\text{ReachStates}^\#, \text{Parent})$

end

Abstract Reachability Graph



$$\varphi_1 = \alpha(\varphi_{init})$$

$$\varphi_2 = post^\#(\varphi_1, \rho_1)$$

$$post^\#(\varphi_2, \rho_2) \models \varphi_2$$

$$\varphi_3 = post^\#(\varphi_2, \rho_3)$$

$$\varphi_4 = post^\#(\varphi_3, \rho_4)$$

- ▶ $Preds = \{false, at_l_1, \dots, at_l_5, y \geq z, x \geq y\}$
- ▶ nodes $\varphi_1, \dots, \varphi_4 \in ReachStates^\#$
- ▶ labeled edges $\in Parent$
- ▶ dotted edge : entailment relation (here, $post^\#(\varphi_2, \rho_2) \models \varphi_2$)

example: predicate abstraction to compute $\varphi_{reach}^\#$

- ▶ $Preds = \{false, at_l_1, \dots, at_l_5, y \geq z, x \geq y\}$
- ▶ over-approximation of the set of initial states φ_{init} :

$$\varphi_1 = \alpha(at_l_1) = at_l_1$$

- ▶ apply $post^\#$ on φ_1 wrt. each program transition:

$$\varphi_2 = post^\#(\varphi_1, \rho_1) = \alpha(\underbrace{at_l_2 \wedge y \geq z}_{post(\varphi_1, \rho_1)}) = at_l_2 \wedge y \geq z$$

$$post^\#(\varphi_1, \rho_2) = \dots = post^\#(\varphi_1, \rho_5) = \bigwedge \{false, \dots\} = false$$

apply $post^\#$ to $\varphi_2 = (at_l_2 \wedge y \geq z)$

- ▶ application of ρ_1 , ρ_4 , and ρ_5 on φ_2 results in *false* (since ρ_1 , ρ_4 , and ρ_5 are applicable only if either at_l_1 or at_l_3 hold)
- ▶ for ρ_2 we obtain

$$post^\#(\varphi_2, \rho_2) = \alpha(at_l_2 \wedge y \geq z \wedge x \leq y) = at_l_2 \wedge y \geq z$$

result is φ_2 which is already in $ReachStates^\#$: nothing to do

- ▶ for ρ_3 we obtain

$$\begin{aligned} post^\#(\varphi_2, \rho_3) &= \alpha(at_l_3 \wedge y \geq z \wedge x \geq y) \\ &= at_l_3 \wedge y \geq z \wedge x \geq y \\ &= \varphi_3 \end{aligned}$$

new node φ_3 in $ReachStates^\#$, new edge in $Parent$

apply $post^\#$ to $\varphi_3 = (at_l_3 \wedge y \geq z \wedge x \geq y)$

- ▶ application of ρ_1 , ρ_2 , and ρ_3 on φ_3 results in *false*
- ▶ for ρ_4 we obtain:

$$\begin{aligned} post^\#(\varphi_3, \rho_4) &= \alpha(at_l_4 \wedge y \geq z \wedge x \geq y \wedge x \geq z) \\ &= at_l_4 \wedge y \geq z \wedge x \geq y \\ &= \varphi_4 \end{aligned}$$

new node φ_4 in $ReachStates^\#$, new edge in $Parent$

- ▶ for ρ_5 (assertion violation) we obtain:

$$\begin{aligned} post^\#(\varphi_3, \rho_5) &= \alpha(at_l_5 \wedge y \geq z \wedge x \geq y \wedge x + 1 \leq z) \\ &= false \end{aligned}$$

- ▶ any further application of program transitions does not compute any additional reachable states
- ▶ thus, $\varphi_{reach}^\# = \varphi_1 \vee \dots \vee \varphi_4$
- ▶ since $\varphi_{reach}^\# \wedge at_l_5 \models false$, the program is proven safe

abstraction $\alpha(\varphi)$

- ▶ monotonicity

$$\varphi_1 \models \varphi_2 \text{ implies } \alpha(\varphi_1) \models \alpha(\varphi_2)$$

- ▶ idempotency

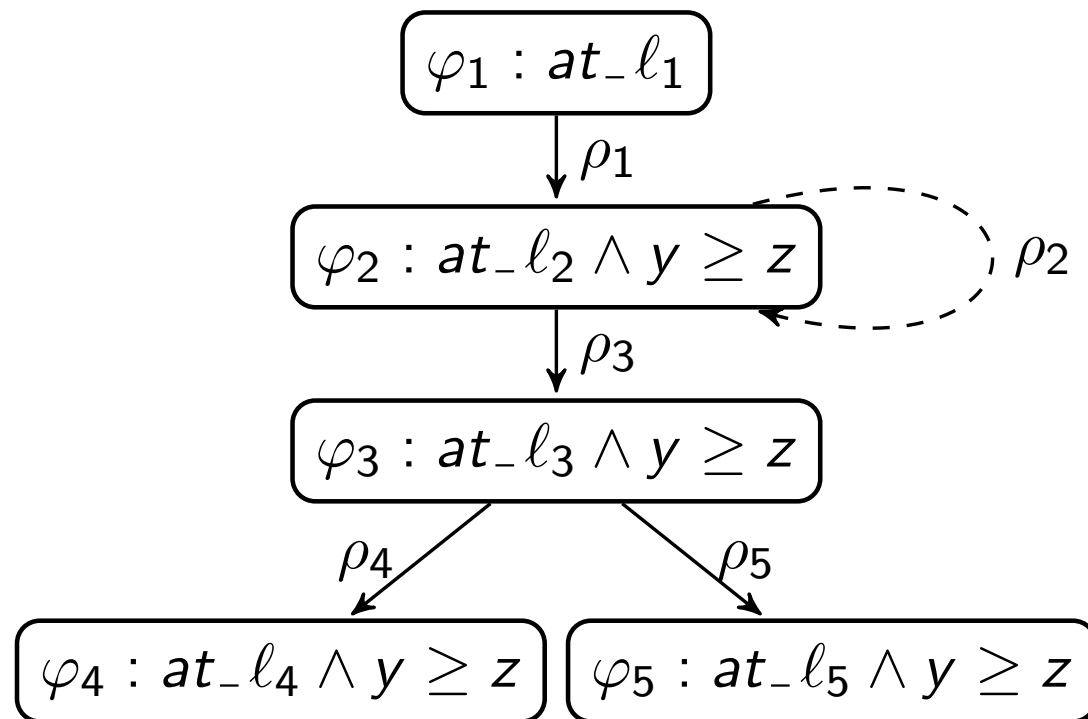
$$\alpha(\alpha(\varphi_1)) = \alpha(\varphi_1)$$

- ▶ extensiveness

$$\varphi_1 \models \alpha(\varphi_1)$$

Abstract reachability computation with

$Preds = \{false, at_l_1, \dots, at_l_5, y \geq z\}$



$$\varphi_1 = \alpha(\varphi_{init})$$

$$\varphi_2 = post^\#(\varphi_1, \rho_1)$$

$$post^\#(\varphi_2, \rho_2) \models \varphi_2$$

$$\varphi_3 = post^\#(\varphi_2, \rho_3)$$

$$\varphi_4 = post^\#(\varphi_3, \rho_4)$$

$$\varphi_5 = post^\#(\varphi_3, \rho_5)$$

- ▶ omitting just one predicate (in the example: $x \geq y$) may lead to an over-approximation $\varphi_{reach}^\#$ such that

$$\varphi_{reach}^\# \wedge \varphi_{err} \not\equiv false$$

that is, `ABSTRACTREACH` without the predicate $x \geq y$ fails to prove safety

counterexample path

- ▶ *Parent* relation records sequence leading to φ_5
 - ▶ apply ρ_1 to φ_1 and obtain φ_2
 - ▶ apply ρ_3 to φ_2 and obtain φ_3
 - ▶ apply ρ_5 to φ_3 and obtain φ_5
- ▶ counterexample path:
sequence of program transitions ρ_1 , ρ_3 , and ρ_5
- ▶ Using this path and the functions α and $post^\#$ corresponding to the current set of predicates we obtain

$$\varphi_5 = post^\#(post^\#(post^\#(\alpha(\varphi_{init}), \rho_1), \rho_3), \rho_5)$$

that is, φ_5 is equal to the over-approximation of the post-condition computed along the counterexample path

analysis of counterexample path

- ▶ check if the counterexample path also leads to the error states when no over-approximation is applied
- ▶ compute

$$\begin{aligned} & post(post(post(\varphi_{init}, \rho_1), \rho_3), \rho_5) \\ &= post(post(at_l_2 \wedge y \geq z, \rho_3), \rho_5) \\ &= post(at_l_3 \wedge y \geq z \wedge x \geq y, \rho_5) \\ &= false . \end{aligned}$$

- ▶ by executing the program transitions ρ_1 , ρ_3 , and ρ_5 is not possible to reach any error
- ▶ conclude that the over-approximation is too coarse when dealing with the above path

need for refinement of abstraction

- ▶ need a more precise over-approximation that will prevent $\varphi_{reach}^{\#}$ from including error states

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- ▶ need a more precise over-approximation that will prevent $\varphi_{reach}^{\#}$ from including error states
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need for refinement of abstraction

- ▶ need a more precise over-approximation that will prevent $\varphi_{reach}^\#$ from including error states
- ▶ need a more precise over-approximation that will prevent α from including states that lead to error states along the path ρ_1 , ρ_3 , and ρ_5
- ▶ need a refined abstraction function α and a corresponding $post^\#$ such that the execution of ABSTRACTREACH along the counterexample path does not compute a set of states that contains some error states

$$post^\#(post^\#(post^\#(\alpha(\varphi_{init}), \rho_1), \rho_3), \rho_5) \wedge \varphi_{err} \models false .$$

over-approximation along counterexample path

- ▶ goal:

$$post^\#(post^\#(post^\#(\alpha(\varphi_{init}), \rho_1), \rho_3), \rho_5) \wedge \varphi_{err} \models false .$$

- ▶ define sets of states ψ_1, \dots, ψ_4 such that

$$\varphi_{init} \models \psi_1$$

$$post(\psi_1, \rho_1) \models \psi_2$$

$$post(\psi_2, \rho_3) \models \psi_3$$

$$post(\psi_3, \rho_5) \models \psi_4$$

$$\psi_4 \wedge \varphi_{err} \models false$$

- ▶ thus, ψ_1, \dots, ψ_4 guarantee that no error state can be reached
may approximate / still allow additional states
- ▶ example choice for ψ_1, \dots, ψ_4

ψ_1	ψ_2	ψ_3	ψ_4
at_l_1	$at_l_2 \wedge y \geq z$	$at_l_3 \wedge x \geq z$	$false$

refinement of predicate abstraction

- ▶ given sets of states ψ_1, \dots, ψ_4 such that

$$\varphi_{init} \models \psi_1$$

$$post(\psi_1, \rho_1) \models \psi_2$$

$$post(\psi_2, \rho_3) \models \psi_3$$

$$post(\psi_3, \rho_5) \models \psi_4$$

$$\psi_4 \wedge \varphi_{err} \models false$$

- ▶ add ψ_1, \dots, ψ_4 to the set of predicates *Preds*
- ▶ formal property (discussed later) guarantees:

$$\alpha(\varphi_{init}) \models \psi_1$$

$$post^\#(\psi_1, \rho_1) \models \psi_2$$

$$post^\#(\psi_2, \rho_3) \models \psi_3$$

$$post^\#(\psi_3, \rho_5) \models \psi_4$$

$$\psi_4 \wedge \varphi_{err} \models false$$

proves: no error state reachable along path $\rho_1, \rho_3,$ and ρ_5

next ...

- ▶ approach for analysing counterexample computed by `ABSTRACTREACH`
- ▶ algorithms `MAKEPATH`, `FEASIBLEPATH`, and `REFINEPATH`

path computation

function MAKEPATH

input

ψ - reachable abstract state

$Parent$ - predecessor relation

begin

1 $path :=$ empty sequence

2 $\varphi' := \psi$

3 **while** exist φ and ρ such that $(\varphi, \rho, \varphi') \in Parent$ **do**

4 $path := \rho . path$

5 $\varphi' := \varphi$

6 **return** $path$

end

path computation

- ▶ input: reachable abstract state ψ + *Parent* relation
- ▶ view *Parent* as a tree where ψ occurs as a node
- ▶ output: sequence of program transitions that labels the tree edges on path from root to ψ
- ▶ sequence is constructed iteratively by a backward traversal starting from the input node
- ▶ variable *path* keeps track of the construction
- ▶ in example, call MAKEPATH(φ_5 , *Parent*)
- ▶ *path*, initially empty, is extended with transitions ρ_5, ρ_3, ρ_1
- ▶ corresponding edges: $(\varphi_3, \rho_5, \varphi_5)$, $(\varphi_2, \rho_3, \varphi_3)$, $(\varphi_1, \rho_1, \varphi_1)$
- ▶ output: $path = \rho_1\rho_3\rho_5$

feasibility of a path

```
function FEASIBLEPATH
input
   $\rho_1 \dots \rho_n$  - path
begin
1    $\varphi := post(\varphi_{init}, \rho_1 \circ \dots \circ \rho_n)$ 
2   if  $\varphi \wedge \varphi_{err} \neq false$  then
3     return true
4   else
5     return false
end
```


feasibility of a path

- ▶ input: sequence of program transitions $\rho_1 \dots \rho_n$
- ▶ checks if there is a computation that produced by this sequence
- ▶ check uses the post-condition function and the relational composition of transition
- ▶ apply FEASIBLEPATH on example path $\rho_1 \rho_3 \rho_5$
- ▶ relational composition of transitions yields

$$\rho_1 \circ \rho_3 \circ \rho_5 = \textit{false} .$$

- ▶ FEASIBLEPATH sets φ to *false* and then returns *false*

counterexample-guided discovery of predicates

function REFINEPATH

input

$\rho_1 \dots \rho_n$ - path

begin

1 $\varphi_0, \dots, \varphi_n :=$ compute such that

2 $(\varphi_{init} \models \varphi_0) \wedge$

3 $(post(\varphi_0, \rho_1) \models \varphi_1) \wedge \dots \wedge (post(\varphi_{n-1}, \rho_n) \models \varphi_n) \wedge$

4 $(\varphi_n \wedge \varphi_{err} \models false)$

5 **return** $\{\varphi_0, \dots, \varphi_n\}$

end

- ▶ omitted: particular algorithm for finding $\varphi_0, \dots, \varphi_n$

counterexample guided discovery of predicates

- ▶ input: sequence of program transitions $\rho_1 \dots \rho_n$
- ▶ output: sets of states $\varphi_0, \dots, \varphi_n$ such that
 - ▶ $\varphi_{init} \models \varphi_0$
 - ▶ $post(\varphi_{i-1}, \rho_i) \models \varphi_i$
 - ▶ $\varphi_n \wedge \varphi_{err} \models false$ for $i \in 1..n$
- ▶ if $\varphi_0, \dots, \varphi_n$ are added to $Preds$ then the resulting α and $post^\#$ guarantee that

$$\alpha(\varphi_{init}) \models \varphi_0$$

$$post^\#(\varphi_0, \rho_1) \models \varphi_1$$

...

$$post^\#(\varphi_{n-1}, \rho_n) \models \varphi_n$$

$$\varphi_n \wedge \varphi_{err} \models false .$$

- ▶ in example, application of `REFINEPATH` on $\rho_1\rho_3\rho_5$ yields sequence of sets of states ψ_1, \dots, ψ_4

next ...

- ▶ algorithm for counterexample-guided abstraction refinement
- ▶ put together all building blocks into an algorithm `ABSTREFINELoop` that verifies safety using predicate abstraction and counterexample guided refinement

predicate abstraction and refinement loop

```
function ABSTREFINELOOP
begin
1   Preds :=  $\emptyset$ 
2   repeat
3     (ReachStates#, Parent) := ABSTREACH(Preds)
4     if exists  $\psi \in \text{ReachStates}^\#$  such that  $\psi \wedge \varphi_{err} \not\equiv \text{false}$ 
5   then
6     path := MAKEPATH( $\psi$ , Parent)
7     if FEASIBLEPATH(path) then
8       return “counterexample path: path ”
9     else
10      Preds := REFINEPATH(path)  $\cup$  Preds
11  else
      return “program is correct”
end.
```

algorithm ABSTREFINELOOP

- ▶ input: program, output: proof or counterexample
- ▶ compute $\varphi_{reach}^{\#}$ using an abstraction defined wrt. set of predicates $Preds$ (initially empty)
- ▶ over-approximation $\varphi_{reach}^{\#}$: set of formulas $ReachStates^{\#}$ where each formula represents a set of states
- ▶ if set of error states disjoint from over-approximation: stop
- ▶ otherwise, consider a formula ψ in $ReachStates^{\#}$ that witnesses overlap with error states
- ▶ refinement is only possible if overlap is caused by imprecision
- ▶ construct $path$, sequence of program transitions leading to ψ
- ▶ analyze $path$ using FEASIBLEPATH
- ▶ if $path$ feasible: stop
- ▶ otherwise ($path$ is not feasible), compute a set of predicates that refines the abstraction function

that's it!