

Reachability Analysis

Andreas Podelski and Matthias Heizmann

May 31, 2017

program code for specifications

validity of Hoare triple:

```
{y >= z}
while (x < y) {
  x++;
}
{x >= z}
```

≡ safety of program:

```
assume(y >= z);
while (x < y) {
  x++;
}
assert(x >= z);
```

program with **assume** () and **assert** ()

- ▶ **assume** (e) \equiv **if** e **then skip else halt**

program with **assume** () and **assert** ()

- ▶ **assume** (e) \equiv **if** e **then skip else halt**
- ▶ **assert** (e) \equiv **if** e **then skip else error**

program with **assume** () and **assert** ()

- ▶ **assume** (e) \equiv **if** e **then skip else halt**
- ▶ **assert** (e) \equiv **if** e **then skip else error**
- ▶ generalize *partial correctness*:

program with **assume** () and **assert** ()

- ▶ **assume** (e) \equiv **if** e **then skip else halt**
- ▶ **assert** (e) \equiv **if** e **then skip else error**
- ▶ generalize *partial correctness*:
correctness of program wrt. Hoare triple:

$$\{\phi\} C \{\psi\}$$

\equiv

program with **assume** () and **assert** ()

- ▶ **assume** (e) \equiv **if** e **then skip else halt**
- ▶ **assert** (e) \equiv **if** e **then skip else error**
- ▶ generalize *partial correctness*:
correctness of program wrt. Hoare triple:

$$\{\phi\} C \{\psi\}$$

\equiv *safety* of program: **assume** (ϕ) ; C ; **assert** (ψ)

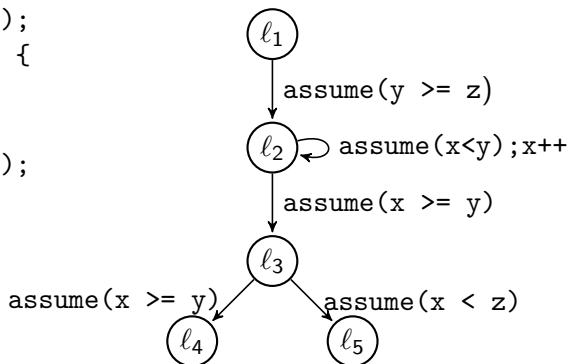
- ▶ *safety* = non-reachability of **error**
(no execution of **error** branch)

control flow graph

source code

```
1:  assume(y >= z);  
2:  while (x < y) {  
    x++;  
  }  
3:  assert(x >= z);  
4:  exit  
5:  error
```

control flow graph

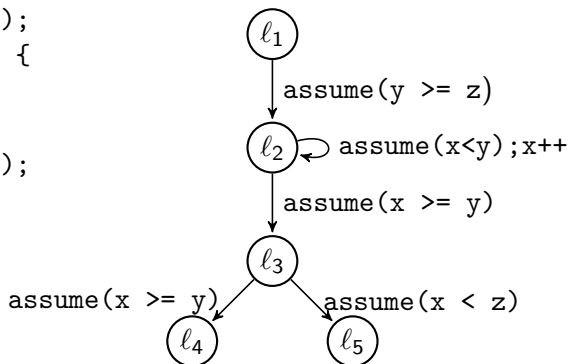


control flow graph

source code

```
1:  assume(y >= z);  
2:  while (x < y) {  
      x++;  
  }  
3:  assert(x >= z);  
4:  exit  
5:  error
```

control flow graph



encode transition as logical formula

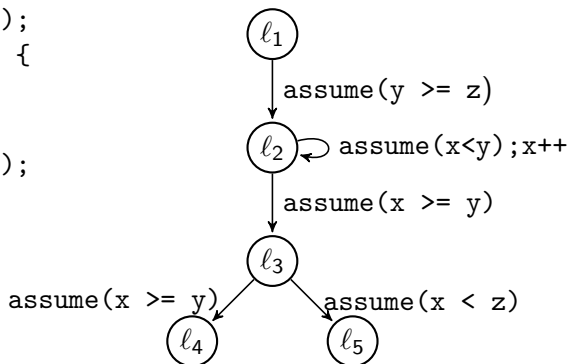
`assume(y >= z) \rightsquigarrow`

control flow graph

source code

```
1:  assume(y >= z);
2:  while (x < y) {
      x++;
    }
3:  assert(x >= z);
4:  exit
5:  error
```

control flow graph



encode transition as logical formula

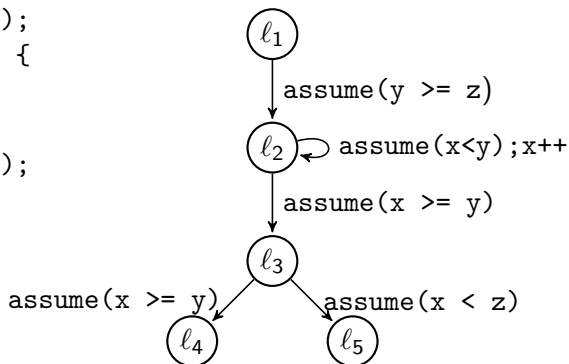
`assume(y >= z) \rightsquigarrow y >= z`

control flow graph

source code

```
1:  assume(y >= z);
2:  while (x < y) {
      x++;
  }
3:  assert(x >= z);
4:  exit
5:  error
```

control flow graph



encode transition as logical formula

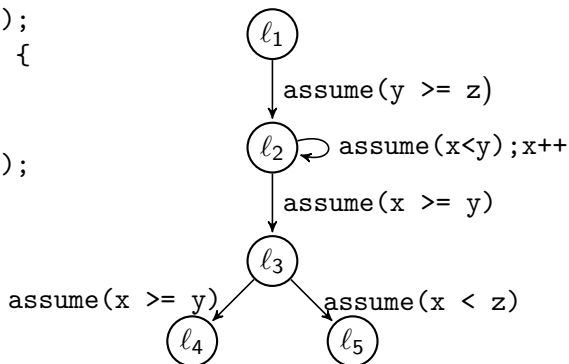
$$\begin{aligned} \text{assume}(y \geq z) &\rightsquigarrow y \geq z \\ x++ &\rightsquigarrow \end{aligned}$$

control flow graph

source code

```
1:  assume(y >= z);
2:  while (x < y) {
      x++;
  }
3:  assert(x >= z);
4:  exit
5:  error
```

control flow graph



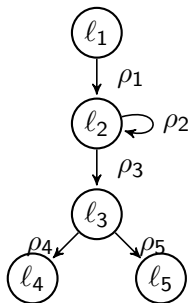
encode transition as logical formula

$$\begin{aligned} \text{assume}(y \geq z) &\rightsquigarrow y \geq z \\ x++ &\rightsquigarrow x' = x + 1 \end{aligned}$$

```

1:  assume(y >= z);
2:  while (x < y) {
      x++;
    }
3:  assert(x >= z);
4:  exit
5:  error

```



$$\rho_1 = (\text{move}(l_1, l_2) \wedge y \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_2 = (\text{move}(l_2, l_2) \wedge x + 1 \leq y \wedge x' = x + 1 \wedge \text{skip}(y, z))$$

$$\rho_3 = (\text{move}(l_2, l_3) \wedge x \geq y \wedge \text{skip}(x, y, z))$$

$$\rho_4 = (\text{move}(l_3, l_4) \wedge x \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_5 = (\text{move}(l_3, l_5) \wedge x + 1 \leq z \wedge \text{skip}(x, y, z))$$

transition relation ρ expressed by logical formula

$$\rho_1 \equiv (\text{move}(\ell_1, \ell_2) \wedge y \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_2 \equiv (\text{move}(\ell_2, \ell_2) \wedge x + 1 \leq y \wedge x' = x + 1 \wedge \text{skip}(y, z))$$

$$\rho_3 \equiv (\text{move}(\ell_2, \ell_3) \wedge x \geq y \wedge \text{skip}(x, y, z))$$

$$\rho_4 \equiv (\text{move}(\ell_3, \ell_4) \wedge x \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_5 \equiv (\text{move}(\ell_3, \ell_5) \wedge x + 1 \leq z \wedge \text{skip}(x, y, z))$$

abbreviations:

$$\text{move}(\ell, \ell') \equiv (pc = \ell \wedge pc' = \ell')$$

$$\text{skip}(v_1, \dots, v_n) \equiv (v'_1 = v_1 \wedge \dots \wedge v'_n = v_n)$$

program $\mathbf{P} = (V, pc, \varphi_{init}, \mathcal{R}, \varphi_{err})$

- ▶ V - finite tuple of *program variables*
- ▶ pc - *program counter variable* (pc included in V)
- ▶ φ_{init} - *initiation condition* given by formula over V
- ▶ \mathcal{R} - a finite set of *transition relations*
- ▶ φ_{err} - an *error condition* given by a formula over V

- ▶ transition relation $\rho \in \mathcal{R}$ given by formula over the variables V and their primed versions V'

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values
- ▶ *program state* = function that assigns each program variable a value from its respective domain

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values
- ▶ *program state* = function that assigns each program variable a value from its respective domain
- ▶ Σ = set of program states

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values
- ▶ *program state* = function that assigns each program variable a value from its respective domain
- ▶ Σ = set of program states
- ▶ formula with free variables in V = set of program states

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values
- ▶ *program state* = function that assigns each program variable a value from its respective domain
- ▶ Σ = set of program states
- ▶ formula with free variables in V = set of program states
- ▶ formula with free variables in V and $V' =$
binary relation over program states
 - ▶ first component of each pair assigns values to V
 - ▶ second component of the pair assigns values to V'

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values
- ▶ *program state* = function that assigns each program variable a value from its respective domain
- ▶ Σ = set of program states
- ▶ formula with free variables in V = set of program states
- ▶ formula with free variables in V and $V' =$
binary relation over program states
 - ▶ first component of each pair assigns values to V
 - ▶ second component of the pair assigns values to V'
- ▶ identify formulas with sets and relations that they represent

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values
- ▶ *program state* = function that assigns each program variable a value from its respective domain
- ▶ Σ = set of program states
- ▶ formula with free variables in V = set of program states
- ▶ formula with free variables in V and $V' =$ binary relation over program states
 - ▶ first component of each pair assigns values to V
 - ▶ second component of the pair assigns values to V'
- ▶ identify formulas with sets and relations that they represent
- ▶ identify the logical consequence relation between formulas \models with set inclusion \subseteq

states, sets, and relations

- ▶ each program variable is assigned a *domain* of values
- ▶ *program state* = function that assigns each program variable a value from its respective domain
- ▶ Σ = set of program states
- ▶ formula with free variables in V = set of program states
- ▶ formula with free variables in V and $V' =$ binary relation over program states
 - ▶ first component of each pair assigns values to V
 - ▶ second component of the pair assigns values to V'
- ▶ identify formulas with sets and relations that they represent
- ▶ identify the logical consequence relation between formulas \models with set inclusion \subseteq
- ▶ identify the satisfaction relation \models between valuations and formulas, with the membership relation \in

example: states, sets, and relations

- ▶ formula $y \geq z$ = set of program states in which the value of the variable y is greater than the value of z

example: states, sets, and relations

- ▶ formula $y \geq z$ = set of program states in which the value of the variable y is greater than the value of z
- ▶ formula $y' \geq z$ = binary relation over program states,
= set of pairs of program states (s_1, s_2) in which the value of the variable y in the second state s_2 is greater than the value of z in the first state s_1

example: states, sets, and relations

- ▶ formula $y \geq z$ = set of program states in which the value of the variable y is greater than the value of z
- ▶ formula $y' \geq z$ = binary relation over program states,
= set of pairs of program states (s_1, s_2) in which the value of the variable y in the second state s_2 is greater than the value of z in the first state s_1
- ▶ if program state s assigns 1, 3, 2, and ℓ_1
to program variables x , y , z , and pc , respectively,
then $s \models y \geq z$

example: states, sets, and relations

- ▶ formula $y \geq z$ = set of program states in which the value of the variable y is greater than the value of z
- ▶ formula $y' \geq z$ = binary relation over program states,
= set of pairs of program states (s_1, s_2) in which the value of the variable y in the second state s_2 is greater than the value of z in the first state s_1
- ▶ if program state s assigns 1, 3, 2, and ℓ_1
to program variables x , y , z , and pc , respectively,
then $s \models y \geq z$
- ▶ logical consequence: $y \geq z \models y + 1 \geq z$

example program $\mathbf{P} = (V, pc, \varphi_{init}, \mathcal{R}, \varphi_{err})$

- ▶ program variables $V = (pc, x, y, z)$
- ▶ program counter pc
- ▶ program variables $x, y,$ and z range over integers
- ▶ set of control locations $\mathcal{L} = \{l_1, \dots, l_5\}$
- ▶ initiation condition $\varphi_{init} = (pc = pc = l_1)$
- ▶ error condition $\varphi_{err} = (pc = pc = l_5)$
- ▶ program transitions $\mathcal{R} = \{\rho_1, \rho_2, \rho_3, \rho_4, \rho_5\}$

$$\rho_1 = (\text{move}(l_1, l_2) \wedge y \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_2 = (\text{move}(l_2, l_2) \wedge x + 1 \leq y \wedge x' = x + 1 \wedge \text{skip}(y, z))$$

$$\rho_3 = (\text{move}(l_2, l_3) \wedge x \geq y \wedge \text{skip}(x, y, z))$$

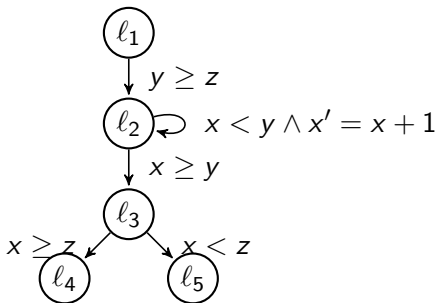
$$\rho_4 = (\text{move}(l_3, l_4) \wedge x \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_5 = (\text{move}(l_3, l_5) \wedge x + 1 \leq z \wedge \text{skip}(x, y, z))$$

```

1:  assume(y >= z);
2:  while (x < y) {
      x++;
    }
3:  assert(x >= z);
4:  exit
5:  error

```



$$\rho_1 = (\text{move}(l_1, l_2) \wedge y \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_2 = (\text{move}(l_2, l_2) \wedge x + 1 \leq y \wedge x' = x + 1 \wedge \text{skip}(y, z))$$

$$\rho_3 = (\text{move}(l_2, l_3) \wedge x \geq y \wedge \text{skip}(x, y, z))$$

$$\rho_4 = (\text{move}(l_3, l_4) \wedge x \geq z \wedge \text{skip}(x, y, z))$$

$$\rho_5 = (\text{move}(l_3, l_5) \wedge x + 1 \leq z \wedge \text{skip}(x, y, z))$$

initial state, error state, transition relation \mathcal{R}

- ▶ each state that satisfies the initiation condition φ_{init} is called an *initial* state
- ▶ each state that satisfies the error condition φ_{err} is called an *error* state
- ▶ program transition relation $\rho_{\mathcal{R}}$ is the union of the “single-statement” transition relations, i.e.,

$$\rho_{\mathcal{R}} = \bigvee_{\rho \in \mathcal{R}} \rho .$$

- ▶ the state s has a transition to the state s' if the pair of states (s, s') lies in the program transition relation $\rho_{\mathcal{R}}$, i.e., if $(s, s') \models \rho_{\mathcal{R}}$

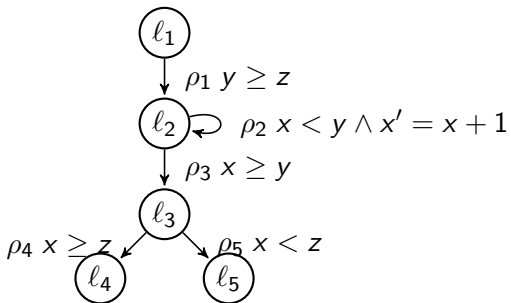
program computation s_1, s_2, \dots

- ▶ the first element is an initial state, i.e., $s_1 \models \varphi_{init}$
- ▶ each pair of consecutive states (s_i, s_{i+1}) is connected by a program transition, i.e., $(s_i, s_{i+1}) \models \rho_{\mathcal{R}}$
- ▶ if the sequence is finite
then the last element does not have any successors
i.e., if the last element is s_n ,
then there is no state s such that $(s_n, s) \models \rho_{\mathcal{R}}$

```

1:  assume(y >= z);
2:  while (x < y) {
      x++;
    }
3:  assert(x >= z);
4:  exit
5:  error

```



example of a computation:

$(l_1, 1, 3, 2), (l_2, 1, 3, 2), (l_2, 2, 3, 2), (l_2, 3, 3, 2), (l_3, 3, 3, 2), (l_4, 3, 3, 2)$

- ▶ sequence of transitions $\rho_1, \rho_2, \rho_2, \rho_3, \rho_4$
- ▶ state = tuple of values of program variables $pc, x, y,$ and z
- ▶ last program state does not any successors

Correctness: Safety

- ▶ a state is *reachable* if it occurs in some program computation
- ▶ a program is *safe* if no error state is reachable
- ▶ ... if and only if no error state lies in φ_{reach} ,

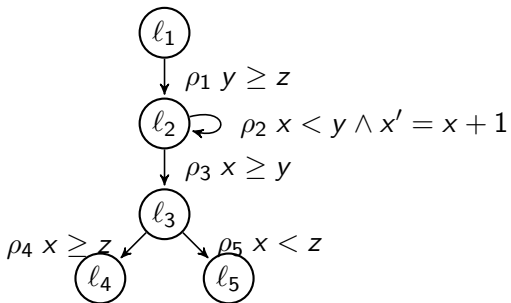
$$\varphi_{err} \wedge \varphi_{reach} \models \text{false} .$$

where φ_{reach} = set of reachable program states

```

1:  assume(y >= z);
2:  while (x < y) {
      x++;
    }
3:  assert(x >= z);
4:  exit
5:  error

```



set of reachable states:

$$\begin{aligned}
\varphi_{reach} = & (pc = l_1 \vee \\
& pc = l_2 \wedge y \geq z \vee \\
& pc = l_3 \wedge y \geq z \wedge x \geq y \vee \\
& pc = l_4 \wedge y \geq z \wedge x \geq y)
\end{aligned}$$

post operator

- ▶ let φ be a formula over V
- ▶ let ρ be a formula over V and V'
- ▶ define a *post-condition* function *post* by:

$$post(\varphi, \rho) = \exists V'' : \varphi[V''/V] \wedge \rho[V''/V][V/V']$$

an application $post(\varphi, \rho)$ computes the image of the set φ under the relation ρ

- ▶ post distributes over disjunction wrt. each argument:

$$post(\varphi, \rho_1 \vee \rho_2) = (post(\varphi, \rho_1) \vee post(\varphi, \rho_2))$$

$$post(\varphi_1 \vee \varphi_2, \rho) = (post(\varphi_1, \rho) \vee post(\varphi_2, \rho))$$