

## inductive invariants for example program

- ▶ weakest inductive invariant:  $true$  (set of all states)  
contains error states
- ▶ strongest inductive invariant (does not contain error states)

$$pc = l_1 \vee$$

$$(pc = l_2 \wedge y \geq z) \vee$$

$$(pc = l_3 \wedge y \geq z \wedge x \geq y) \vee$$

$$(pc = l_4 \wedge y \geq z \wedge x \geq y)$$

- ▶ a slightly weaker inductive invariant also proves the safety of our examples:

$$pc = l_1 \vee$$

$$(pc = l_2 \wedge y \geq z) \vee$$

$$(pc = l_3 \wedge y \geq z \wedge x \geq y) \vee$$

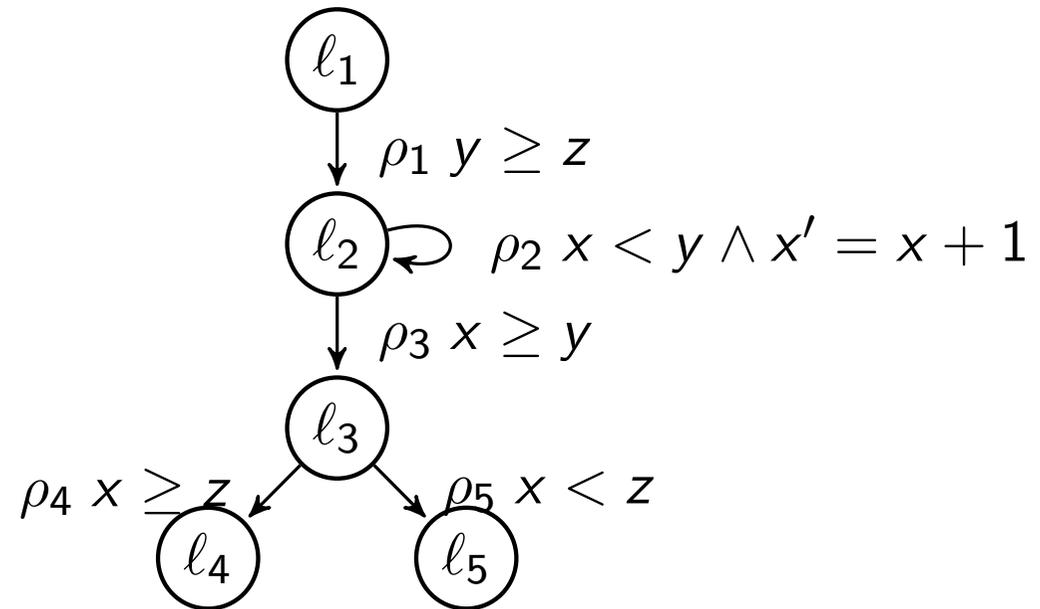
$$pc = l_4$$

- ▶ can we drop another conjunct in one of the disjuncts?

```

1:  assume(y >= z);
2:  while (x < y) {
      x++;
    }
3:  assert(x >= z);
4:  exit
5:  error

```



inductive invariant (strict superset of reachable states):

$$\begin{aligned}
\varphi_{reach} = & (pc = l_1 \vee \\
& pc = l_2 \wedge y \geq z \vee \\
& pc = l_3 \wedge y \geq z \wedge x \geq y \vee \\
& pc = l_4)
\end{aligned}$$

# fixpoint iteration

- ▶ computation of reachable program states =  
iterative application of  $\text{post}$  on initial program states until  
*a fixpoint is reached*  
i.e., no new program states are obtained by applying  $\text{post}$
- ▶ in general, iteration process does not *converge*  
i.e., does not reach fixpoint in finite number of iterations

## example: fixpoint iteration *diverges*

$$\rho_2 \equiv (\text{move}(\ell_2, \ell_2) \wedge x + 1 \leq y \wedge x' = x + 1 \wedge \text{skip}(y, z))$$

$$\text{post}(\text{at\_}\ell_2 \wedge x \leq z, \rho_2) = (\text{at\_}\ell_2 \wedge x - 1 \leq z \wedge x \leq y)$$

$$\text{post}^2(\text{at\_}\ell_2 \wedge x \leq z, \rho_2) = (\text{at\_}\ell_2 \wedge x - 2 \leq z \wedge x \leq y)$$

$$\text{post}^3(\text{at\_}\ell_2 \wedge x \leq z, \rho_2) = (\text{at\_}\ell_2 \wedge x - 3 \leq z \wedge x \leq y)$$

...

$$\text{post}^n(\text{at\_}\ell_2 \wedge x \leq z, \rho_2) = (\text{at\_}\ell_2 \wedge x - n \leq z \wedge x \leq y)$$

example: fixpoint not reached after  $n$  steps,  $n \geq 1$

- ▶ set of states reachable after applying *post* twice not included in the union of previous two sets:

$$(at\_l_2 \wedge x - 2 \leq z \wedge x \leq y) \not\equiv$$

$$at\_l_2 \wedge x \leq z \vee$$

$$at\_l_2 \wedge x - 1 \leq z \wedge x \leq y$$

- ▶ set of states reachable after  $n$ -fold application of *post* still contains previously unreached states:

$$\forall n \geq 1 : (at\_l_2 \wedge x - n \leq z \wedge x \leq y) \not\equiv$$

$$at\_l_2 \wedge x \leq z \vee$$

$$\bigvee_{1 \leq i < n} (at\_l_2 \wedge x - i \leq z \wedge x \leq y)$$

## abstraction of $\varphi_{reach}$ by $\varphi_{reach}^\#$

- ▶ instead of computing  $\varphi_{reach}$ , compute over-approximation  $\varphi_{reach}^\#$  such that  $\varphi_{reach}^\# \supseteq \varphi_{reach}$
- ▶ check whether  $\varphi_{reach}^\#$  contains any error states
- ▶ if  $\varphi_{reach}^\# \wedge \varphi_{err} \models false$  holds then  $\varphi_{reach} \wedge \varphi_{err} \models false$ , and hence the program is safe
- ▶ compute  $\varphi_{reach}^\#$  by applying iteration
- ▶ instead of iteratively applying  $post$ , use over-approximation  $post^\#$  such that always

$$post(\varphi, \rho) \models post^\#(\varphi, \rho)$$

- ▶ decompose computation of  $post^\#$  into two steps:  
first, apply  $post$  and  
then, over-approximate result using a function  $\alpha$  such that

$$\forall \varphi : \varphi \models \alpha(\varphi) .$$

## abstraction of $post$ by $post^\#$

- ▶ given an abstraction function  $\alpha$ , define  $post^\#$ :

$$post^\#(\varphi, \rho) = \alpha(post(\varphi, \rho))$$

- ▶ compute  $\varphi_{reach}^\#$ :

$$\begin{aligned}\varphi_{reach}^\# &= \alpha(\varphi_{init}) \vee \\ &\quad post^\#(\alpha(\varphi_{init}), \rho_{\mathcal{R}}) \vee \\ &\quad post^\#(post^\#(\alpha(\varphi_{init}), \rho_{\mathcal{R}}), \rho_{\mathcal{R}}) \vee \dots \\ &= \bigvee_{i \geq 0} (post^\#)^i(\alpha(\varphi_{init}), \rho_{\mathcal{R}})\end{aligned}$$

- ▶ consequence:  $\varphi_{reach} \models \varphi_{reach}^\#$

# predicate abstraction

- ▶ construct abstraction using a given set of building blocks, so-called predicates
- ▶ predicate = formula over the program variables  $V$
- ▶ fix finite set of predicates  $Preds = \{p_1, \dots, p_n\}$
- ▶ over-approximation of  $\varphi$  by conjunction of predicates in  $Preds$

$$\alpha(\varphi) = \bigwedge \{p \in Preds \mid \varphi \models p\}$$

- ▶ computation requires  $n$  entailment checks  
( $n$  = number of predicates)

example: compute  $\alpha(at\_l_2 \wedge y \geq z \wedge x + 1 \leq y)$

►  $Preds = \{at\_l_1, \dots, at\_l_5, y \geq z, x \geq y\}$

1. check logical consequence between argument to the abstraction function and each of the predicates:

	$y \geq z$	$x \geq y$	$at\_l_1$	$at\_l_2$	$at\_l_3$	$at\_l_4$	$at\_l_5$
$at\_l_2 \wedge$ $y \geq z \wedge$ $x + 1 \leq y$	$\models$	$\not\models$	$\not\models$	$\models$	$\not\models$	$\not\models$	$\not\models$

2. result of abstraction = conjunction over entailed predicates

$$\alpha\left( \begin{array}{l} at\_l_2 \wedge \\ y \geq z \wedge x + 1 \leq y \end{array} \right) = at\_l_2 \wedge y \geq z$$

trivial abstraction  $\alpha(\varphi) = \textit{true}$

- ▶ result of applying predicate abstraction is *true* if

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- ▶ result of applying predicate abstraction is *true* if none of the predicates is entailed by  $\varphi$  (“predicates are too specific”)  
... always the case if  $Preds = \emptyset$

example: predicate abstraction to compute  $\varphi_{reach}^\#$

▶  $Preds = \{false, at\_l_1, \dots, at\_l_5, y \geq z, x \geq y\}$

▶ over-approximation of the set of initial states  $\varphi_{init}$ :

$$\varphi_1 = \alpha(at\_l_1) = at\_l_1$$

▶ apply  $post^\#$  on  $\varphi_1$  wrt. each program transition:

$$\varphi_2 = post^\#(\varphi_1, \rho_1) = \alpha(\underbrace{at\_l_2 \wedge y \geq z}_{post(\varphi_1, \rho_1)}) = at\_l_2 \wedge y \geq z$$

$$post^\#(\varphi_1, \rho_2) = \dots = post^\#(\varphi_1, \rho_5) = \bigwedge \{false, \dots\} = false$$

apply  $post^\#$  to  $\varphi_2 = (at\_l_2 \wedge y \geq z)$

- ▶ application of  $\rho_1$ ,  $\rho_4$ , and  $\rho_5$  on  $\varphi_2$  results in *false* (since  $\rho_1$ ,  $\rho_4$ , and  $\rho_5$  are applicable only if either  $at\_l_1$  or  $at\_l_3$  hold)
- ▶ for  $\rho_2$  we obtain

$$post^\#(\varphi_2, \rho_2) = \alpha(at\_l_2 \wedge y \geq z \wedge x \leq y) = at\_l_2 \wedge y \geq z$$

result is  $\varphi_2$  and, therefore, is discarded

- ▶ for  $\rho_3$  we obtain

$$\begin{aligned} post^\#(\varphi_2, \rho_3) &= \alpha(at\_l_3 \wedge y \geq z \wedge x \geq y) \\ &= at\_l_3 \wedge y \geq z \wedge x \geq y \\ &= \varphi_3 \end{aligned}$$

apply  $post^\#$  to  $\varphi_3 = (at\_l_3 \wedge y \geq z \wedge x \geq y)$

- ▶  $\rho_1, \rho_2$ , and  $\rho_3$ : inconsistency with program counter valuation in  $\varphi_3$
- ▶ for  $\rho_4$  we obtain:

$$\begin{aligned} post^\#(\varphi_3, \rho_4) &= \alpha(at\_l_4 \wedge y \geq z \wedge x \geq y \wedge x \geq z) \\ &= at\_l_4 \wedge y \geq z \wedge x \geq y \\ &= \varphi_4 \end{aligned}$$

- ▶ for  $\rho_5$  (assertion violation) we obtain:

$$\begin{aligned} post^\#(\varphi_3, \rho_5) &= \alpha(at\_l_5 \wedge y \geq z \wedge x \geq y \wedge x + 1 \leq z) \\ &= false \end{aligned}$$

- ▶ any further application of program transitions does not compute any additional reachable states
- ▶ thus,  $\varphi_{reach}^\# = \varphi_1 \vee \dots \vee \varphi_4$
- ▶ since  $\varphi_{reach}^\# \wedge at\_l_5 \models false$ , the program is proven safe

## algorithm ABSTRACTREACH

**begin**

$\alpha := \lambda\varphi . \bigwedge\{p \in \text{Preds} \mid \varphi \models p\}$

$\text{post}^\# := \lambda(\varphi, \rho) . \alpha(\text{post}(\varphi, \rho))$

$\text{ReachStates}^\# := \{\alpha(\varphi_{\text{init}})\}$

$\text{Parent} := \emptyset$

$\text{Worklist} := \text{ReachStates}^\#$

**while**  $\text{Worklist} \neq \emptyset$  **do**

$\varphi := \text{choose from } \text{Worklist}$

$\text{Worklist} := \text{Worklist} \setminus \{\varphi\}$

**for each**  $\rho \in \mathcal{R}$  **do**

$\varphi' := \text{post}^\#(\varphi, \rho)$

**if**  $\varphi' \not\models \bigvee \text{ReachStates}^\#$  **then**

$\text{ReachStates}^\# := \{\varphi'\} \cup \text{ReachStates}^\#$

$\text{Parent} := \{(\varphi, \rho, \varphi')\} \cup \text{Parent}$

$\text{Worklist} := \{\varphi'\} \cup \text{Worklist}$

**return**  $(\text{ReachStates}^\#, \text{Parent})$

**end**