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for larger and larger program fragments
- ▶ verification condition:  
strongest postcondition of  $\phi$  under  $C$  entails  $\psi$   
(+ special treatment of while)

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 $\text{post}(C_1, b \wedge \phi) \vee \text{post}(C_2, \neg b \wedge \phi)$
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## strongest postcondition $\text{post}(C, \psi)$

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- ▶  $\text{post}(\mathbf{while } b \mathbf{ do } \{ \theta \} C_0, \phi) \equiv \theta \wedge \neg b$
  
- ▶ next:  
static analysis constructs candidate for  $\theta$  via forward analysis  
“reachability analysis”

## program code for specifications

validity of Hoare triple:

```
{y >= z}
while (x < y) {
  x++;
}
{x >= z}
```

≡ safety of program:

```
assume(y >= z);
while (x < y) {
  x++;
}
assert(x >= z);
```

program with **assume** () and **assert** ()

▶ **assume** ( $e$ )  $\equiv$  **if**  $e$  **then skip else halt**

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$$\{\phi\} C \{\psi\}$$

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- ▶ generalize *partial correctness*:  
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$$\{\phi\} C \{\psi\}$$

$\equiv$  *safety* of program: **assume** ( $\phi$ ) ;  $C$  ; **assert** ( $\psi$ )

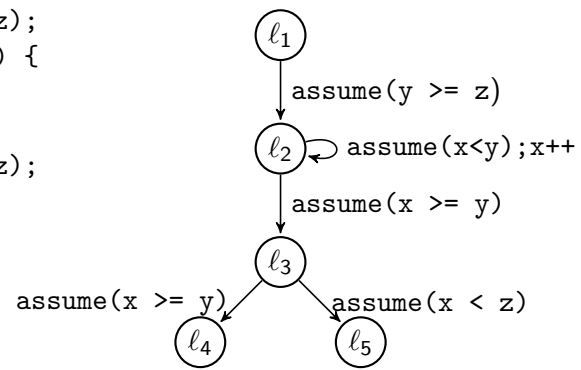
- ▶ safety = non-reachability of **error**  
(no execution of **error** branch)

## control flow graph

source code

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1: assume(y >= z);  
2: while (x < y) {  
    x++;  
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3: assert(x >= z);  
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control flow graph

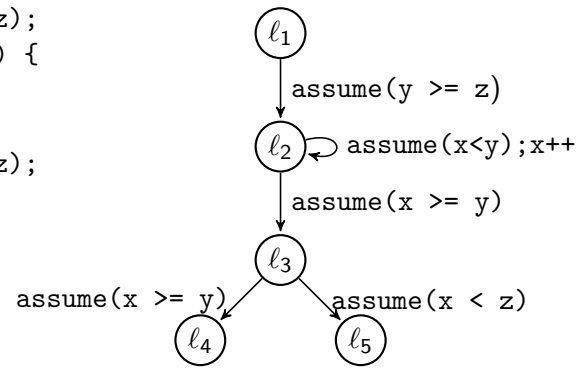


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encode transition as logical formula

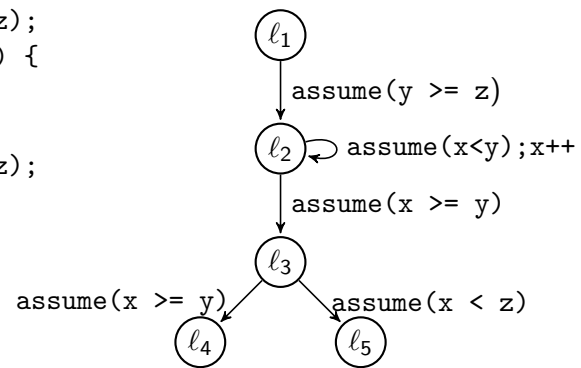
$\text{assume}(y \geq z) \rightsquigarrow$

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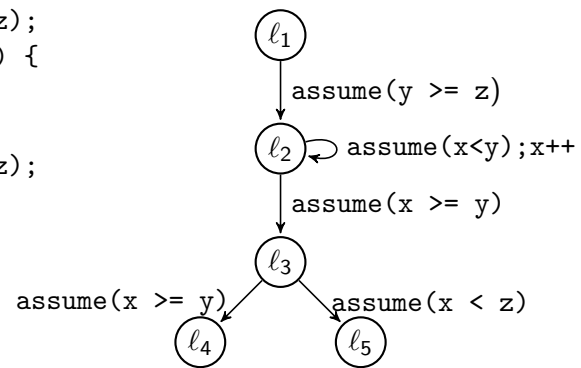
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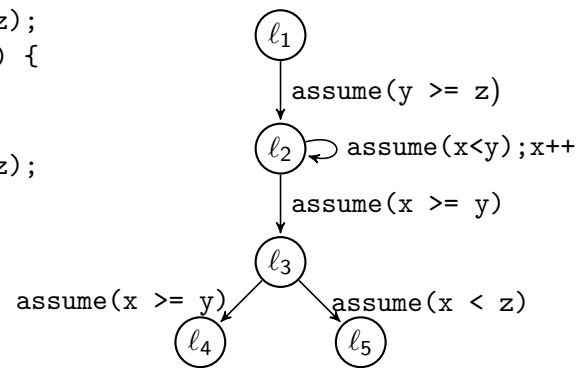
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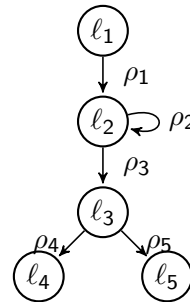
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```
assume( y >= z)  ⇔  y >= z  
x++           ⇔  x'=x+1
```

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$$\rho_1 = (\text{move}(l_1, l_2) \wedge y \geq z \wedge \text{skip}(x, y, z))$$

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transition relation  $\rho$  expressed by logica formula

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abbreviations:

$$\text{move}(\ell, \ell') \equiv (pc = \ell \wedge pc' = \ell')$$

$$\text{skip}(v_1, \dots, v_n) \equiv (v'_1 = v_1 \wedge \dots \wedge v'_n = v_n)$$



program  $\mathbf{P} = (V, pc, \varphi_{init}, \mathcal{R}, \varphi_{err})$

- ▶  $V$  - finite tuple of *program variables*
- ▶  $pc$  - *program counter variable* ( $pc$  included in  $V$ )
- ▶  $\varphi_{init}$  - *initiation condition* given by formula over  $V$
- ▶  $\mathcal{R}$  - a finite set of *transition relations*
- ▶  $\varphi_{err}$  - an *error condition* given by a formula over  $V$
  
- ▶ transition relation  $\rho \in \mathcal{R}$  given by  
formula over the variables  $V$  and their primed versions  $V'$

## states, sets, and relations

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- ▶ identify the satisfaction relation  $\models$  between valuations and formulas, with the membership relation  $\in$

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- ▶ if program state  $s$  assigns 1, 3, 2, and  $\ell_1$   
to program variables  $x$ ,  $y$ ,  $z$ , and  $pc$ , respectively,  
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- ▶ logical consequence:  $y \geq z \models y + 1 \geq z$

example program  $\mathbf{P} = (V, pc, \varphi_{init}, \mathcal{R}, \varphi_{err})$

- ▶ program variables  $V = (pc, x, y, z)$
- ▶ program counter  $pc$
- ▶ program variables  $x$ ,  $y$ , and  $z$  range over integers
- ▶ set of control locations  $\mathcal{L} = \{\ell_1, \dots, \ell_5\}$
- ▶ initiation condition  $\varphi_{init} = (pc = pc = \ell_1)$
- ▶ error condition  $\varphi_{err} = (pc = pc = \ell_5)$
- ▶ program transitions  $\mathcal{R} = \{\rho_1, \rho_2, \rho_3, \rho_4, \rho_5\}$

$$\rho_1 = (\text{move}(\ell_1, \ell_2) \wedge y \geq z \wedge \text{skip}(x, y, z))$$

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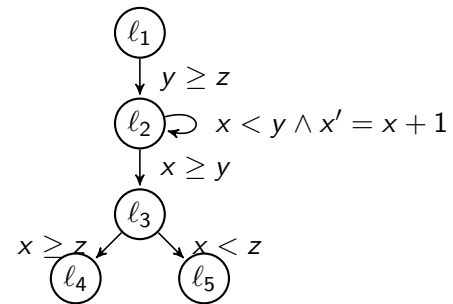
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## initial state, error state, transition relation $\mathcal{R}$

- ▶ each state that satisfies the initiation condition  $\varphi_{init}$  is called an *initial* state
- ▶ each state that satisfies the error condition  $\varphi_{err}$  is called an *error* state
- ▶ program transition relation  $\rho_{\mathcal{R}}$  is the union of the “single-statement” transition relations, i.e.,

$$\rho_{\mathcal{R}} = \bigvee_{\rho \in \mathcal{R}} \rho .$$

- ▶ the state  $s$  has a transition to the state  $s'$  if the pair of states  $(s, s')$  lies in the program transition relation  $\rho_{\mathcal{R}}$ , i.e., if  $(s, s') \models \rho_{\mathcal{R}}$



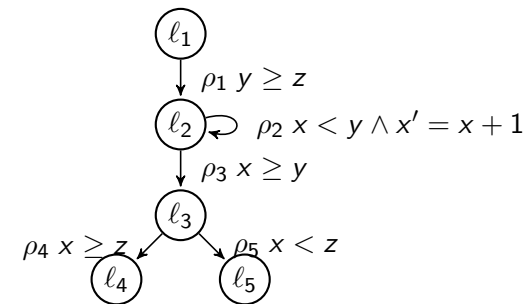
program computation  $s_1, s_2, \dots$

- ▶ the first element is an initial state, i.e.,  $s_1 \models \varphi_{init}$
- ▶ each pair of consecutive states  $(s_i, s_{i+1})$  is connected by a program transition, i.e.,  $(s_i, s_{i+1}) \models \rho_{\mathcal{R}}$
- ▶ if the sequence is finite  
then the last element does not have any successors  
i.e., if the last element is  $s_n$ ,  
then there is no state  $s$  such that  $(s_n, s) \models \rho_{\mathcal{R}}$

```

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      x++;
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example of a computation:

$(l_1, 1, 3, 2), (l_2, 1, 3, 2), (l_2, 2, 3, 2), (l_2, 3, 3, 2), (l_3, 3, 3, 2), (l_4, 3, 3, 2)$

- ▶ sequence of transitions  $\rho_1, \rho_2, \rho_2, \rho_3, \rho_4$
- ▶ state = tuple of values of program variables  $\rho c, x, y,$  and  $z$
- ▶ last program state does not any successors

## Correctness: Safety

- ▶ a state is *reachable* if it occurs in some program computation
- ▶ a program is *safe* if no error state is reachable
- ▶ ... if and only if no error state lies in  $\varphi_{reach}$ ,

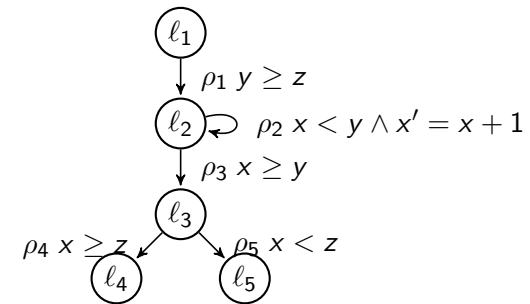
$$\varphi_{err} \wedge \varphi_{reach} \models \text{false} .$$

where  $\varphi_{reach}$  = set of reachable program states

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set of reachable states:

$$\begin{aligned}
\varphi_{reach} = & (pc = l_1 \vee \\
& pc = l_2 \wedge y \geq z \vee \\
& pc = l_3 \wedge y \geq z \wedge x \geq y \vee \\
& pc = l_4 \wedge y \geq z \wedge x \geq y)
\end{aligned}$$

## post operator

- ▶ let  $\varphi$  be a formula over  $V$
- ▶ let  $\rho$  be a formula over  $V$  and  $V'$
- ▶ define a *post-condition* function *post* by:

$$post(\varphi, \rho) = \exists V'' : \varphi[V''/V] \wedge \rho[V''/V][V/V']$$

an application  $post(\varphi, \rho)$  computes the image of the set  $\varphi$  under the relation  $\rho$

- ▶ *post* distributes over disjunction wrt. each argument:

$$post(\varphi, \rho_1 \vee \rho_2) = (post(\varphi, \rho_1) \vee post(\varphi, \rho_2))$$

$$post(\varphi_1 \vee \varphi_2, \rho) = (post(\varphi_1, \rho) \vee post(\varphi_2, \rho))$$