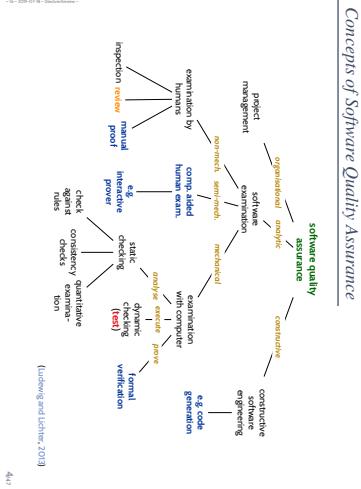


Softwaretechnik / Software-Engineering

Lecture 16: Program Verification

2019-07-18

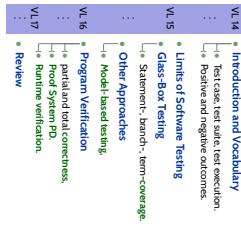
Prof. Dr. Andreas Podelski, Dr. Bernd Westphal
Albert-Ludwigs-Universität Freiburg, Germany



Lüding and Löhr, 2013

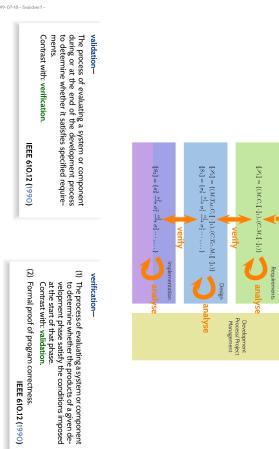
4-17

Topic Area Code Quality Assurance: Content



2-1

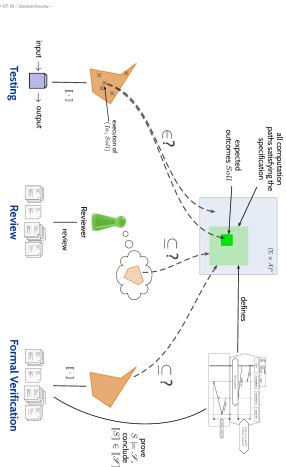
Formal Methods in the Software Development Process



2-1

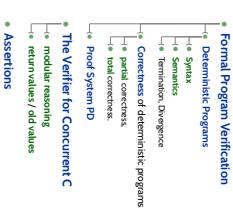
Topic Area Code Quality Assurance: Content

Testing, Review, Verification Illustrated



Lüding and Löhr, 2013

Content



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Deterministic Programs

Syntax:

$$S ::= \text{skip} \mid u := t \mid S_1; S_2 \mid \text{if } B \text{ then } S \text{ fi} \mid \text{while } B \text{ do } S \text{ od}$$

where $u \in V$ is a variable, t is a type-compatible expression, B is a Boolean expression.

Sequential, Deterministic While-Programs

Semantics: It is induced by the following transition relation – $\sigma : V \rightarrow D(V)$

$$\begin{array}{l} \text{(i) } (\text{skip}, \sigma) \xrightarrow{\quad} (E, \sigma) \\ \text{(ii) } (u := t, \sigma) \xrightarrow{\quad} (E, \sigma[u := t]) \\ \text{(iii) } (S_1; S_2, \sigma) \xrightarrow{\quad} (S_2, \tau) \\ \text{(iv) } (\text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma) \xrightarrow{\quad} (S_1, \sigma) \text{ if } \sigma \models B \\ \text{(v) } (\text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma) \xrightarrow{\quad} (S_2, \sigma) \text{ if } \sigma \not\models B \\ \text{(vi) } (\text{while } B \text{ do } S \text{ od}, \sigma) \xrightarrow{\quad} (E, \sigma[B \not\models B]) \\ \text{(vii) } (\text{while } B \text{ do } S \text{ od}, \sigma) \xrightarrow{\quad} (E, \sigma[B \models B]) \end{array}$$

Notes: the first component of (S, σ) is a program (structural/operational semantics) (SOS).

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Deterministic Programs

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where $u \in V$ is a variable, t is a type-compatible expression, B is a Boolean expression.

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Another Example



Consider program
and a state σ with $\sigma \models x = 3$.

$S_1 \equiv y := x; y = (x - 1) - x = y$

$(S_1, \sigma) \xrightarrow{\langle \text{if } (x \neq 0) \text{ then } S_2 \text{ else } S_3, \sigma \rangle} (E, \{x \mapsto 3, y \mapsto 9\})$

$(E, \{x \mapsto 3, y \mapsto 9\}) \xrightarrow{\langle \text{skip}, \sigma \rangle} (E, \{x \mapsto 3, y \mapsto 9\})$

Consider program
 $S_4 \equiv y := x; y := (x - 1) - x + y$, $\text{while } 1 \text{ do skip od.}$

$(S_4, \sigma) \xrightarrow{\langle \text{if } (x \neq 0) \text{ then } (y := (x - 1) - x + y, \{x \mapsto 3, y \mapsto 3\}) \text{ else } S_4, \sigma \rangle} (E, \{x \mapsto 3, y \mapsto 3\})$

$(E, \{x \mapsto 3, y \mapsto 3\}) \xrightarrow{\langle \text{skip}, \sigma \rangle} (E, \{x \mapsto 3, y \mapsto 3\})$

$(E, \{x \mapsto 3, y \mapsto 3\}) \xrightarrow{\langle \text{skip}, \sigma \rangle} (E, \{x \mapsto 3, y \mapsto 3\})$

\dots

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Computations of Deterministic Programs

Definition. Let S be a deterministic program.
(i) A transition sequence of S starting in σ is a finite or infinite sequence $(S, \sigma) = \langle (S_0, \sigma_0) \xrightarrow{\gamma} (S_1, \sigma_1) \xrightarrow{\gamma} \dots$
(that is, (S_i, σ_i) and (S_{i+1}, σ_{i+1}) are in transition relation for all i).
(ii) A computation of S starting in σ is a maximal transition sequence of S starting in σ , i.e. judgeable or not executable.

(iii) A computation of S is said to
a) terminate Σ and only if it is fine and ends with (E, τ) .
b) diverge if and only if a diverging computation starts in σ .
S diverges from σ if and only if a diverging computation starts in σ .

(iv) We use \rightarrow^* to denote the transitive, reflexive closure of \rightarrow .
Note: $M_{det}[S](\sigma)$ has exactly one element, $M[S](\sigma)$ at most one.

Lemma. For each deterministic program S and state σ ,
there is exactly one computation of S which starts in σ .
(Recall: $S_1; S_2 \equiv x; y := (x - 1) - x + y$)

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Input/Output Semantics of Deterministic Programs

Let S be a deterministic program.
(i) The semantics of partial correctness is the function $M[S]: \Sigma \rightarrow 2^\Sigma$ with $M[S](\sigma) = \{r \mid (S, \sigma) \xrightarrow{*} (E, r)\}$.
(ii) The semantics of total correctness is the function $M_{tot}[S]: \Sigma \rightarrow 2^\Sigma \cup \{\infty\}$ with $M_{tot}[S](\sigma) = M[S](\sigma) \cup \{\infty\}$.
S diverges from σ if and only if a diverging computation starts in σ .
 ∞ is an error state representing divergence.

Note: $M_{tot}[S](\sigma)$ has exactly one element, $M[S](\sigma)$ at most one.
Example: $M[S](\sigma) = M_{tot}[S](\sigma) = \{r \mid \tau(r) = \sigma(x) \wedge \tau(r) = \sigma(x)^2\}, \quad \sigma \in \Sigma$.
(Recall: $S_1; S_2 \equiv x; y := (x - 1) - x + y$)

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Content

Formal Program Verification

- Deterministic Programs
 - Syntax
 - Semantics
 - Correctness of deterministic programs
 - Total correctness.
- Proof System PD

Correctness of While-Programs

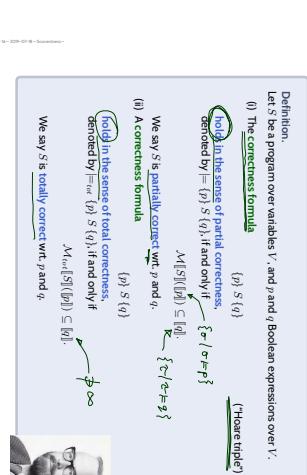
Correctness of Deterministic Programs

Correctness of Deterministic Programs

Definition.
Let S be a program over variables V , and p and q Boolean expressions over V .
(i) The correctness formula $\{p\} S \{q\}$ (Hoare triple)
denoted by $\models (p) S (q)$, and only if $\{ \sigma \mid \sigma \models p \} \subseteq \{ \tau \mid \tau \models q \}$

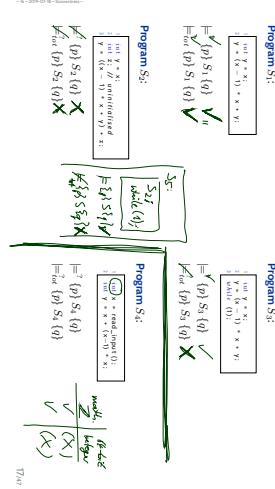
We say S is partially correct wrt. p and q .
 $\{p\} S \{q\}$
(\models) in the sense of total correctness, if and only if $M_{tot}[S](p) \subseteq q$.

- Assertions
 - modular reasoning;
 - return values / odd values
- The Verifier for Concurrent C



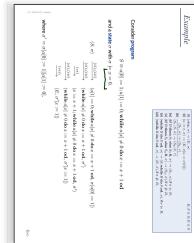
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Example: Computing squares (of numbers 0, ..., 27)



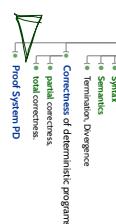
Example: Correctness SSS

- Pre-condition: $p \equiv 0 \leq x \leq 27$.
- Post-condition: $q \equiv y = x^2$.
- By the example, we have shown $\models \{x = 0\} S \{x = 1\}$
- and $\models_{\text{ex}} \{x = 0\} S \{x = 1\}$.
(because we only assumed $\sigma \models x = 0$ for the example, which is exactly the precondition)
- We have also shown (\vdash_{proved} III):
 $\models \{x = 0\} S \{x = 1 \wedge a[i] = 0\}$.
The correctness formula $(x = 2) \wedge S[\text{true}]$ does not hold for S.
(For example, if $a[i] \neq 0$ for all $i > 2$)
- In the sense of partial correctness, $\{x = 2 \wedge \forall i \geq 2 \cdot a[i] = 1\} S[\text{false}]$ also holds.



Content

- Formal Program Verification
- Deterministic Programs
- Syntax
- Semantics
- Termination, Divergence
- Correctness of deterministic programs
- Partial correctness
- Total correctness



- The Verifier for Concurrent C
- module reasoning
- returnvalues/old values
- Assertions

Proof-System PD

Proof-System PD (for sequential, deterministic programs)

- Axiom 1: Skip-Statement
 $\{p\} \text{skip } \{p\}$
- Rule 4: Conditional Statement
 $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$

- Axiom 2: Assignment
 $\frac{\{p[u := t]\} u := t \{p\}}{\{p\}}$
- Rule 5: While-Loop
 $\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$

- Rule 3: Sequential Composition
 $\frac{\{p\} S_1 \{r\} ; S_2 \{q\}}{\{p\} S_1 ; S_2 \{q\}}$

- Rule 6: Consequence
 $\frac{p \rightarrow p, \{p\} S \{q\}, q \rightarrow q}{\{p\} S \{q\}}$

Theorem: PD is correct (sound) and (relatively) complete for partial correctness of deterministic programs, i.e., $\vdash_{\text{PD}} \{p\} S \{q\}$ if and only if $\vdash \{p\} S \{q\}$.

Example Proof

$$\text{DIV} \equiv \overbrace{a := 0, b := x; \text{while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od}}^{(z) S^D}$$

(The first iteratively represented program has been formally verified (Fischer, 1995).)

We can prove: $\models (x \geq 0, y \geq 0) \text{ DIV } (a \cdot y + a = x \cdot b < y)$
by showing: $\vdash_{\text{PDR}} (x \geq 0, y \geq 0) \text{ DIV } (a \cdot y + a = x \cdot b < y)$, i.e., derivability in PDR:

$$\begin{aligned} &= \vdash_{\text{PDR}} \\ &\quad \frac{\text{(1)} \quad \boxed{a := 0, b := x; \text{while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od}}}{\vdash_{\text{PDR}} (x \geq 0, y \geq 0) \text{ DIV } (a \cdot y + a = x \cdot b < y)} \end{aligned}$$

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Proof of (1)

$$\begin{aligned} &\text{(A1) } p \cdot \text{skip } p \\ &\text{(B1) } p \cdot (b := 0) \vdash p \\ &\text{(C1) } p \cdot (b := 0) \vdash p \end{aligned}$$

(2.2)

Proof of (1)

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(2.2)

- (1) claims: $\vdash_{\text{PDR}} (x \geq 0 \wedge y \geq 0) \cdot a := 0, b := x \cdot (P)$
where $P \equiv a \cdot y + b = x \wedge b \geq 0$.

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• $\vdash_{P\Delta} (0 \cdot y + x = x \wedge x \geq 0) \ a := 0 \{a \cdot y + x = x \wedge x \geq 0\}$ by (R2). $\vdash_{P\Delta} (a \cdot y + x = x \wedge x \geq 0) \ b := x \{a \cdot y + b = x \wedge b \geq 0\}$ by (R2).

- thus, $\vdash_{P\Delta} (0 \cdot y + x = x \wedge x \geq 0) \ a := 0; b := x \{P\}$ by (R3).

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• thus, $\vdash_{P\Delta} (0 \cdot y + x = x \wedge x \geq 0) \ a := 0; b := x \{P\}$ by (R3).

• using $x \geq 0 \wedge y \geq 0 \rightarrow 0 = y + x = x \wedge x \geq 0$ and $P \rightarrow P$, we obtain

- $\vdash_{P\Delta} (x \geq 0 \wedge y \geq 0) \ a := 0; b := x \{P\}$ by (R6).

2.4(c)

Substitution

The rule Assignment uses (syntactical) substitution: $\{t[u := t]\} u := t \{p\}$ (In formula p , replace all free occurrences of program or logical variable u by term t) Defined as usual, only indexed and bound variables need to be treated specially:
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□

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Proof of (2)

(A) $\{P\} \Delta y \{P\}$	(B) $\{L^{\omega}(P), S_1(a), L^{\omega}(P), S_2(b)\}$
#(A) $\{y := 0\} \vdash \{y\}$ (B) $\{y = 0\}$ $\{y = 0\} \Delta y \{y\}$ (B) $\{y = 0\}$ $\{y = 0\} \Delta y \{y\}$ (B) $\{y = 0\}$	$\frac{\{y = 0\} \Delta y \{y\}}{\{y = 0\} \Delta y \{y\}}$ (B) $\{y = 0\}$
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- (2) claims: $\vdash_{D^V} (P \wedge \lambda a \geq y) \cdot b := b - y; a := a + 1 \{P\}$

where $P \equiv a \cdot y + b = x \wedge b \geq 0$.

$\vdash_{D^V} P \equiv a \cdot y + b = x \wedge b \geq 0$.

- $\vdash_{D^V} ((a+1) \cdot y + (b-y) = x \wedge (b-y) \geq 0) \cdot b := b - y \{(a+1) \cdot y + b = x \wedge b \geq 0\}$

by (A2).

- $\vdash_{D^V} ((a+1) \cdot y + (b-y) = x \wedge (b-y) \geq 0) \cdot a := a + 1 \{a \cdot y + b = x \wedge b \geq 0\}$

using $P \wedge b \geq y \rightarrow (a+1) \cdot y + (b-y) = x \wedge (b-y) \geq 0$ and $P \rightarrow$ (we obtain,

$$\vdash_{D^V} (P \wedge b \geq y) \cdot b := b - y; a := a + 1 \{P\}$$

by (B2).

□

Example Proof, Cont'd

(A) $\{P\} \Delta y \{P\}$	(B) $\{P, \exists x. (x \geq 0 \wedge y \geq 0) \rightarrow a \cdot y + b = x \wedge b < y\}$
#(A) $\{y := 0\} \vdash \{y\}$ (B) $\{y = 0\}$ $\{y = 0\} \Delta y \{y\}$ (B) $\{y = 0\}$ $\{y = 0\} \Delta y \{y\}$ (B) $\{y = 0\}$	$\frac{\{y = 0\} \Delta y \{y\}}{\{y = 0\} \Delta y \{y\}}$ (B) $\{y = 0\}$
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- (2) claims: $\vdash_{D^V} (x \geq 0 \wedge y \geq 0) \rightarrow a \cdot y + b = x \wedge b < y$

In the following, we show

- (1) $\vdash_{D^V} (x \geq 0 \wedge y \geq 0) \rightarrow a \cdot y + b = x \wedge b < y$

- (2) $\vdash_{D^V} (P \wedge \neg(b \geq y)) \rightarrow a \cdot y + b = x \wedge b < y$

As (loop invariant, we choose (creative act!):

$$P \equiv a \cdot y + b = x \wedge b \geq 0$$

(A) $\{P\} \Delta y \{P\}$	(B) $\{P, \exists x. (x \geq 0 \wedge y \geq 0) \rightarrow a \cdot y + b = x \wedge b < y\}$
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□

Proof of (3)

(A) $\{P\} \Delta y \{P\}$	(B) $\{P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y\}$
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- (3) claims: $\vdash_{D^V} P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y$

where $P \equiv a \cdot y + b = x \wedge b < y$.

Proof easy.

□

Back to the Example Proof

We have shown:

- (1) $\vdash_{D^V} (P \wedge \lambda a \geq y) \cdot b := b - y; a := a + 1 \{P\}$
- (2) $\vdash_{D^V} (P \wedge \neg(b \geq y)) \rightarrow a \cdot y + b = x \wedge b < y$
- (3) $\vdash_{D^V} P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y$

Once Again

(A) $\{P\} \Delta y \{P\}$	(B) $\{P, \exists x. (x \geq 0 \wedge y \geq 0) \rightarrow a \cdot y + b = x \wedge b < y\}$
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Literature Recommendation

Once Again

(A) $\{P\} \Delta y \{P\}$	(B) $\{P, \exists x. (x \geq 0 \wedge y \geq 0) \rightarrow a \cdot y + b = x \wedge b < y\}$
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- $\vdash_{D^V} (P \wedge \lambda a \geq y) \cdot b := b - y; a := a + 1 \{P\}$
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 - $\vdash_{D^V} P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y$
- Now whenever DIV is called with $a \neq 0$ and $y \neq 0$, then if DIV terminates, $x = y + b \wedge z \wedge b < y$.

- pre-condition: $a \geq 0 \wedge y \geq 0$
- post-condition: $a < 0 \wedge b = x \wedge z < y$
- $\text{ord} \{P\} = \{P \wedge \{b \geq y\}\}$
- $\{P \wedge \{b \geq y\}\} \Delta y \{P\}$
- $\{P \wedge \{b \geq y\}\} \Delta b \{P\}$
- $\{P \wedge \{b \geq y\}\} \Delta z \{P\}$
- $\{P \wedge \{b \geq y\}\} \Delta a \{P\}$
- $\{P \wedge \{b \geq y\}\} \Delta x \{P\}$
- $\{P \wedge \{b \geq y\}\} \Delta \text{ord} \{P\}$
- $\{P \wedge \{b \geq y\}\} \Delta \text{post} \{P\}$

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- Formal Program Verification
 - Deterministic Programs
 - Syntax
 - Semantics
 - Termination/Divergence
 - Correctness of deterministic programs
 - partial correctness
 - total correctness

Proof System PD

- The Verifier for Concurrent C
 - modular reasoning
 - return values/ old values
 - Assertions

23(a)

VCC Syntax Example

```

procedure vcc_ls
  var a, b;
  void (ref a, ref b, ref y)
  {
    a = 0;
    b = 0;
    y = 0;
    a >= 0 && b >= 0 && y <= 0;
    a = a + 1;
    b = b + 1;
    y = a + b;
    a >= 0 && b >= 0 && y <= 0;
    a = a - 1;
    b = b - 1;
    y = a + b;
  }
}

DIV ≡ a := 0; b := x; while b ≥ 0 do b := b - 1; a := a + 1 end
{ x ≥ 0 ∧ y ≥ 0 } DIV { x ≥ 0 ∧ y ≥ 0 }
  
```

`3.0(a)`

`3.0(b)`

- The Verifier for Concurrent C (VCC) basically implements Hoare-style reasoning
- Special syntax
 - `!local var <vcc_id>`
 - `(ensures q) -> post-condition, q is (basically) a C expression`
 - `(invariant e) -> loop invariant, e is (basically) a C expression`
 - `(assert p) -> intermediate invariant, p is (basically) a C expression`
 - `\result -> VCC considers concurrent C programs; we need to declare for each procedure which global variables is allowed to write to later checked by VCC`

- Special expression
 - `!writes(x) -> no other threads writes to variable x in pre-conditions`
 - `!old(d) -> the value of x when procedure was called (useful for post-conditions)`
 - `\result -> return value of procedure (useful for post-conditions)`

34(a)

`3.0(a)`

`3.0(b)`



`3.0(a)`

`3.0(b)`

- VCC result: "verification succeeded"

- VCC result: "verification failed"

- Other cases: "timeout" etc.

35(a)

`3.0(a)`

`3.0(b)`

Interpretation of Results

- VCC result: "verification succeeded"
 - We can **only** conclude that the tool – under its interpretation of the C-standard, under its platform assumptions [32-bis], etc. – claims that there is a proof for $\models (\beta) D[V](\eta)$.
 - May be due to an error in the tool (That's a **false negative** then)
Yet we can ask for a **printout** of the proof and check it manually
 - Note: $\models \{\text{false}\} f(\cdot)$ always holds.
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38/i

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VCC Features

- For the exercises, we use VCC only for **sequential, single-thread programs**.
- VCC checks a number of **implicit assertions**:

 - no arithmetic overflow in expressions (according to C-standard),
 - array-out-of-bounds access,
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- For the exercises, we use VCC only for **sequential, single-thread programs**.
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 - and many more.

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- The backend SMT-solver may not be able to discharge proof-obligations (in particular non-linear multiplication and division are challenging).
- In many cases, we need to provide **loop invariants** manually.
- VCC also supports:

 - concurrency**: different threads may write to shared global variables; VCC can check whether concurrent access to shared variables is properly managed;
 - data structure invariants**: we may declare invariants that have to hold for e.g. records (e.g. the length field *l* is always equal to the length of the string field *s[i]*); these invariants may **temporally** be violated when updating the data structure;
 - and much more.

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Modular Reasoning

We can add another rule for calls of functions $f : F$ (simplest case: only global variables):

$$(R7) \quad \frac{\{p\} F, q}{(p) f(t_1)}$$

"If we have": $\{p\} F, q$ for the implementation of function f ,

then if t_1 is called in a state satisfying p , the state after return of f will satisfy q .

p is called **pre-condition** and q is called **post-condition** of f .

Example: if we have

- $\{x \geq 0\} \text{ read_number } r \leq \text{read_number} < 10^8\}$
- $\{r \leq x \wedge 0 \leq y\} \text{ add } ((\text{old}(x) + \text{old}(y)) < 10^8 \wedge \text{result} = \text{old}(x) + \text{old}(y)) \vee \text{result} < 0\}$
- $\{(r \geq 0) \text{ ds_display } ((0 \leq \text{old_num}) \wedge (\text{add_num} < 0) \implies \text{''}=\text{x}\text{''})\}$

we may be able to prove our pocket calculator correct.

state	x	y	r	old_num	add_num	result
1	7	8	9	0	0	15
2	5	6	9	0	0	11
3	1	2	3	0	0	3
4						

Return Values and Old Values

- For **modular reasoning** it's often useful to refer in the post-condition to
- the **return-value** as result ,
- the values of variable x at **calling time** as $\text{old}(x)$.

- Can be defined using **auxiliary variables**:

Transform function

(over variables $V = \{v_1, \dots, v_n\}$, where $\text{result}, v_i^{\text{old}} \notin V$) into

```
T.F() { ...; return expr; }
```

```
{ vold := v1; ...; voldn := vn;
    ...;
    result := expr;
    return result;
}
```

- $\text{over } V' = V \cup \{v^{\text{old}} \mid v \in V\} \cup \{\text{result}\}$,
- Then $\text{old}(x)$ is just an abbreviation for x^{old} .

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Tell Them What You've Told Them...

- Formal Verification:
 - Program verification is another approach to software quality assurance.
 - Proof System PD can be used
 - to prove
 - that given program is correct wrt its specification.

- Assertions
 - Extend the syntax of deterministic programs by $S ::= \dots \mid \text{assert}(B)$
 - and the semantics by rule $\langle \text{assert}(B), \sigma \rangle \rightarrow \langle B, \sigma \rangle \text{ if } \sigma \models B.$
 - If the asserted boolean expression B does not hold at state σ , the empty program is not reached; otherwise the assertion remains in the first component (normal program termination).

Extend PD by axiom:

$$\langle A \rangle(p) \text{ assert}(p) \langle p \rangle$$

- That is, if p holds before the assertion, then we can continue with the derivation in PD. If p does not hold we "get stuck" (and cannot complete the derivation).
- So we **cannot** derive $\langle \text{true} \rangle x := 0 \cdot \text{assert}(x = 2) \cdot \langle \text{true} \rangle$ in PD.

4.3(i)

4.4(i)

7.1(i)

4.5(i)

• Tools like VCC implement this approach.

The approach considers **all inputs** inside the specification!

-
- References
 - Hoare, C. A. R. (1969). An axiomatic basis for computer programming. *Commun. ACM*, 12(10), 576–580.
 - IEEE (1990). IEEE Standard Glossary of Software Engineering Terminology. Std 1012-1990.
 - Lüdke, J. and Lüttner, H. (2013). *Software Engineering & Object-Oriented*, 3. edition.

References

4.5(i)

4.6(i)