Softwaretechnik / Software-Engineering Lecture 7: Decision Tables

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Topic Area Requirements Engineering: Content





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 Decision Tables for Requirements Analysis Completeness, Useless Rules, 	
• Determinism	
Detour: Apropos (Non-)Determinism	
• Domain Modelling	
(● Conflict Axiom,	Logic
-(• Relative Completeness,	Logic
Detour: Apropos Assumptions	
–(• Vacuous Rules,	
 ↓● Conflict Relation 	
Collecting Semantics	
 Consistency 	
Discussion	

Recall: Decision Tables









Decision Tables for Requirements Analysis



Once Again...



Completeness

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Definition. [Completeness] A decision table T is called **complete** if and only if the disjunction of all rules' premises is a tautology, i.e. if

$$\models \bigvee_{r \in T} \mathcal{F}_{pre}(r).$$

Completeness: Example

T: roo	r_1	r_2	r_3	
b	button pressed?	×	×	-
off	ventilation off?	×		*
on	ventilation on?	-	×	*
go	start ventilation	×	-	-
stop	stop ventilation	-	×	-

• Is T complete?

NO: bis the, off the, at the

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Completeness: Example

T: roo	r_1	r_2	r_3	
b	button pressed?	×	×	_
off	ventilation off?	×		*
on	ventilation on?	-	×	*
go	start ventilation	×	_	_
stop	stop ventilation	-	×	-

• Is T complete?

No. (Because there is no rule for, e.g., the case $\sigma(b) = true$, $\sigma(on) = false$, $\sigma(off) = false$).

Recall:

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$$\mathcal{F}(r_1) = c_1 \wedge c_2 \wedge \neg c_3 \wedge a_1 \wedge \neg a_2$$

$$\mathcal{F}(r_2) = c_1 \wedge \neg c_2 \wedge c_3 \wedge \neg a_1 \wedge a_2$$

$$\mathcal{F}(r_3) = \neg c_1 \wedge true \wedge true \wedge \neg a_1 \wedge \neg a_2$$

$$\mathcal{F}_{pre}(r_1) \lor \mathcal{F}_{pre}(r_2) \lor \mathcal{F}_{pre}(r_3) = (c_1 \land c_2 \land \neg c_3) \lor (c_1 \land \neg c_2 \land c_3) \lor (\neg c_1 \land true \land true)$$

is not a tautology.

Requirements Analysis with Decision Tables



• Assume we have formalised requirements as decision table T.



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Requirements Analysis with Decision Tables



• Assume we have formalised requirements as decision table T.

• If T is (formally) incomplete,

- then there is probably a case not yet discussed with the customer, or some misunderstandings.
- If T is (formally) complete,
 - then there still may be misunderstandings. If there are no misunderstandings, then we did discuss all cases.

• Note:

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- Whether T is (formally) complete is decidable.
- Deciding whether T is complete reduces to plain SAT.
- There are efficient tools which decide SAT.
- In addition, decision tables are often much easier to understand than natural language text.

• Syntax:

T: decision table		r_1		r_n	else
c_1	description of condition c_1	$v_{1,1}$	••••	$v_{1,n}$	
:	:	:		:	
c_m	description of condition c_m	$v_{m,1}$	•••	$v_{m,n}$	
a_1	description of action a_1	$w_{1,1}$	•••	$w_{1,n}$	$w_{1,e}$
:		:	÷.,	:	÷
a_k	description of action a_k	$w_{k,1}$		$w_{k,n}$	$w_{k,e}$

• Semantics:

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$$\mathcal{F}(\mathsf{else}) := \neg \left(\bigvee_{r \in T \setminus \{\mathsf{else}\}} \mathcal{F}_{pre}(r) \right) \land F(w_{1,e}, a_1) \land \dots \land F(w_{k,e}, a_k)$$

Proposition. If decision table T has an 'else'-rule, then T is complete.

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Uselessness

Definition. [Uselessness] Let T be a decision table. A rule $r \in T$ is called useless (or: redundant) if and only if there is another (different) rule $r' \in T$ • whose premise is implied by the one of r and • whose effect is the same as r's, i.e. if $\exists r' \neq r \in T \bullet \models (\mathcal{F}_{pre}(r) \implies \mathcal{F}_{pre}(r')) \land (\mathcal{F}_{eff}(r) \iff \mathcal{F}_{eff}(r')).$ r is called subsumed by r'.

• Again: uselessness is decidable; reduces to SAT.

Uselessness: Example

T: roo	r_1	r_2	r_3	r_4	
b	button pressed?	×	×	-	-
off	ventilation off?	×	-	*	-
on	ventilation on?	-	×	*	\times
go	start ventilation	×	-	_	_
stop	stop ventilation	-	×	١	-

- Rule r_4 is subsumed by r_3 .
- Rule r_3 is not subsumed by r_4 .
- Useless rules "do not hurt" as such.

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 Yet useless rules should be removed to make the table more readable, yielding an easier usable specification.

Requirements on Requirements Specification Documents Useless The representation and form of a requirements specification should be: easily understandable, easily maintainable not unnecessarily complicated -all affected people should be able to creating and maintaining the requirements specification should be easy and should not understand the requirements specification, need unnecessary effort, precise the requirements specification should not introduce new unclarities or rooms for easily usable storage of and access to the requirements specification should not need significant effort. interpretation (\rightarrow testable, objective), Note: Once again, it's about compromises. • Rule r • A very precise objective requirements specification may not be easily understandable by every affected person. • Rule r_i \rightarrow provide redundant explanations. It is not trivial to have both, low maintenance effort and low access effort. → value low access effort higher, a requirements specification document is much more often read than changed or written (and most changes require reading beforehand). 15/42

- Useless rules "do not hurt" as such.
- Yet useless rules should be removed to make the table more readable, yielding an **easier usable** specification.

Determinism

Definition. [*Determinism*] A decision table *T* is called **deterministic** if and only if the premises of all rules are pairwise disjoint, i.e. if

$$\forall r_1 \neq r_2 \in T \bullet \models \neg (\mathcal{F}_{pre}(r_1) \land \mathcal{F}_{pre}(r_2)).$$

Otherwise, T is called **non-deterministic**.

• And again: determinism is decidable; reduces to SAT.

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Determinism: Example

T: roo	m ventilation	r_1	r_2	r_3
b	button pressed?	×	\times	_
off	ventilation off?	×		*
on	ventilation on?	—	\times	*
go	start ventilation	×	_	_
stop	stop ventilation	-	×	-

• Is T deterministic? Yes.

· Fre(in) n Fre (r2)

Determinism: Another Example

			\bigcirc	\square	
T_{abstr}	: room ventilation	1	(r_1)	$ r_2 $	r_3
b	button pressed?	Í	Х	×	—
go	start ventilation	T	×	-	-
stop	stop ventilation		/	$\times/$	-
			∇	∇	

• Is T_{abstr} determistic? No. $b \mapsto + pre$

By the way...

- Is non-determinism a bad thing in general?
 - Just the opposite: non-determinism is a very, very powerful modelling tool.
 - Read table T_{abstr} as:
 - the button may switch the ventilation on under certain conditions (which I will specify later), and
 - the button may switch the ventilation off under certain conditions (which I will specify later).

We in particular state that we do not (under any condition) want to see *on* and *off* executed together, and that we do not (under any condition) see *go* or *stop* without button pressed.

• On the other hand: non-determinism may not be intended by the customer.

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Domain Modelling for Decision Tables

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Domain Modelling

Example:

T: roc	T: room ventilation			r_3
b	button pressed?	×	\times	-
off	ventilation off?	×	Ι	*
on	ventilation on?	-	×	*
go	start ventilation	×	-	-
stop	stop ventilation	-	×	

- If *on* and *off* model opposite output values of one and the same sensor for "room ventilation on/off", then $\sigma \models on \land off$ and $\sigma \models \neg on \land \neg off$ never happen in reality for any observation σ .
- Decision table *T* is incomplete for exactly these cases. (*T* "does not know" that *on* and *off* can be opposites in the real-world).
- We should be able to "tell" T that on and off are opposites (if they are). Then T would be relative complete (relative to the domain knowledge that on/off are opposites).

Bottom-line:

- Conditions and actions are **abstract entities** without inherent connection to the **real world**.
- When modelling real-world aspects by conditions and actions,
- we may also want to represent relations between actions/conditions in the real-world $(\rightarrow \text{ domain model (Bjørner, 2006)}).$

Conflict Axioms for Domain Modelling

• A conflict axiom over conditions C is a propositional formula φ_{confl} over C.

Intuition: a conflict axiom characterises all those cases, i.e. all those combinations of condition values which 'cannot happen' — according to our understanding of the domain.

• Note: the decision table semantics remains unchanged!

Example:

• Let $\varphi_{confl} = (on \land off) \lor (\neg on \land \neg off).$

"on models an opposite of off, neither can both be satisfied nor both non-satisfied at a time"

Notation:

T: roo	m ventilation	r_1	r_2	r_3		
b	button pressed?	×	×	-		
off	ventilation off?	×	-	*		
on	ventilation on?		×	*		
go	start ventilation	×	-	-		
stop	stop ventilation		×	١		
$\neg [(on \land off) \lor (\neg on \land \neg off)]$						

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Relative Completeness

Definition. [Completeness wrt. Conflict Axiom] A decision table T is called **complete wrt. conflict axiom** φ_{confl} if and only if the disjunction of all rules' premises and the conflict axiom is a tautology, i.e. if

$$=\varphi_{confl} \vee \bigvee_{r \in T} \mathcal{F}_{pre}(r)$$

- Intuition: a relative complete decision table explicitly cares for all cases which 'may happen'.
- Note: with $\varphi_{confl} = false$, we obtain the previous definitions as a special case. Fits intuition: $\varphi_{confl} = false$ means we don't exclude any states from consideration.

Example

T: room ventilation			r_2	r_3	
b	button pressed?	×	×	-	
off	ventilation off?	×		*	
on	ventilation on?	-	×	*	
go	start ventilation	×	-	-	
stop	stop ventilation	-	×	-	
$\neg [(\mathit{on} \land \mathit{off}) \lor (\neg \mathit{on} \land \neg \mathit{off})]$					

- *T* is complete wrt. its conflict axiom.
- Pitfall: if on and off are outputs of two different, independent sensors, then σ ⊨ on ∧ off is possible in reality (e.g. due to sensor failures).
 Decision table T does not tell us what to do in that case!

Pitfalls in Domain Modelling (Wikipedia, 2015)

"Airbus A320-200 overran runway at Warsaw Okecie Intl. Airport on 14 Sep. 1993."

- To stop a plane after touchdown, there are spoilers and thrust-reverse systems.
- Enabling one of those while in the air, can have fatal consequences.
- Design decision: the software should block activation of spoilers or thrust-revers while in the air.
- Simplified decision table of **blocking** procedure:

	T		r_1	r_2	r_3	else
	splq	spoilers requested	×	×	-	
	thra	thrust-reverse requested	-	-	×	
abe	lgsw	at least 6.3 tons weight on each landing gear strut	×	*	×	
fabe ((spd)	wheels turning faster than 133 km/h	*	×	*	
	spl	enable spoilers	×	×	-	-
	thr	enable thrust-reverse	-	-	×	-

Idea: if conditions lgsw and spd not satisfied, then aircraft is in the air.

14 Sep. 1993:

- wind conditions not as announced from tower, tail- and crosswinds,
- anti-crosswind manoeuvre puts too little weight on landing gear
- wheels didn't turn fast due to hydroplaning.





Definition. [Vacuity wrt. Conflict Axiom] A rule $r \in T$ is called vacuous wrt. conflict axiom φ_{confl} if and only if the premise of r implies the conflict axiom, i.e. if $\models \mathcal{F}_{pre}(r) \rightarrow \varphi_{confl}$.

Intuition: a vacuous rule would only be enabled in states which 'cannot happen'.

Example:

T: roc	om ventilation	r_1	r_2	r_3	r_4		
b	button pressed?	×	×	-	×		
off	ventilation off?	×	-	*	×		
on	ventilation on?	-	×	*	×		
go	start ventilation	×	-	-	-		
stop	stop ventilation	-	×	-	×		
$\neg [(on \land off) \lor (\neg on \land \neg off)]$							

- Vacuity wrt. φ_{confl} : Like uselessness, vacuity doesn't hurt as such but
 - May hint on inconsistencies on customer's side. (Misunderstandings with conflict axiom?)
 - Makes using the table less easy! (Due to more rules.)
 - Implementing vacuous rules is a waste of effort!

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Conflicting Actions

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Conflicting Actions

Definition. [Conflict Relation] A conflict relation on actions A is a transitive and symmetric relation $\xi \subseteq (A \times A)$.

Definition. [Consistency] Let r be a rule of decision table T over C and A.

(i) Rule *r* is called **consistent with conflict relation** \notin if and only if there are no conflicting actions in its effect, i.e. if

$$= \mathcal{F}_{eff}(r) \to \bigwedge_{(a_1, a_2) \in \pounds} \neg (a_1 \land a_2).$$

(ii) *T* is called **consistent** with \notin iff all rules $r \in T$ are consistent with \notin .

• Again: consistency is decidable; reduces to SAT.

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Example: Conflicting Actions

T: room ventilation			r_2	r_3				
b	button pressed?	×	×	-				
off	ventilation off?	×	1	*				
on	ventilation on?	- (×	*				
go	start ventilation	XX	-	-				
stop	stop ventilation	X×l	×	-				
$\neg [(on \land off) \lor (\neg on \land \neg off)]$								
				1				
		\ \		0				

• Let \notin be the transitive, symmetric closure of $\{(stop, go)\}$.

"actions stop and go are not supposed to be executed at the same time"

- Then rule r_1 is inconsistent with $\frac{1}{2}$.
- A decision table with inconsistent rules may do harm in operation!
- Detecting an inconsistency only late during a project can incur significant cost!
- Inconsistencies in particular in (multiple) decision tables, created and edited by multiple people, as well as in requirements in general — are not always as obvious as in the toy examples given here! (would be too easy...)
- And is even less obvious with the collecting semantics (\rightarrow in a minute).

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Collecting Semantics

 Let T be a decision table over C and A and σ be a model of an observation of C and A. Then

$$\mathcal{F}_{coll}(T) := \bigwedge_{a \in A} \left(a \leftrightarrow \bigvee_{r \in T, r(a) = \times} \mathcal{F}_{pre}(r) \right)$$

is called the collecting semantics of T.

• We say, σ is allowed by T in the collecting semantics if and only if $\sigma \models \mathcal{F}_{coll}(T)$. That is, if exactly all actions of all enabled rules are planned/executed.

Example:

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T: room ventilation		r_1	r_2	r_3	r_{41}	
b	button pressed?	×	×	-	×	
off	ventilation off?	×	-	*	*	
on	ventilation on?	-	×	*	*	
go	start ventilation	×	-	-		D start
stop	stop ventilation	-	×	-	-	
blnk	blink button	-	-	1	×L	5 blin
	$\neg [(on \land off) \lor (\neg on \land \neg$]				

• "Whenever the button is pressed, let it blink (in addition to go/stop action."

Definition. [Consistency in the Collecting Semantics]

Decision table T is called <u>consistent with conflict relation</u> $\frac{1}{2}$ in the <u>collecting semantics</u> (under conflict axiom φ_{confl}) if and only if there are no conflicting actions in the effect of jointly enabled transitions, i.e. if

 $\models \mathcal{F}_{coll}(T) \land \neg \varphi_{confl} \to \bigwedge_{(a_1, a_2) \in \sharp} \neg (a_1 \land a_2).$

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Discussion

"Es ist aussichtslos, den Klienten mit formalen Darstellungen zu kommen; [...]" ("It is futile to approach clients with formal representations") (Ludewig and Lichter, 2013)



- ... of course it is the vast majority of customers is not trained in formal methods.
- A formalisation is (first of all) for developers analysts have to translate for customers.
- A formalisation is the description of the analyst's understanding, in a most precise form. Precise/objective: whoever reads it whenever to whomever, the meaning will not change.

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Formalisation Validation

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- 1 domain experts tell system scenario S (maybe keep back, whether allowed / forbidden),
- @ FM expert translates system scenario to valuation σ ,
- 3 FM expert evaluates DT on σ ,
- ④ FM expert translates outcome to "allowed / forbidden by DT",
- (5) compare expected outcome and real outcome.

Formalisation Validation

Two broad directions:







- \odot domain experts tell system scenario S (maybe keep back, whether allowed / forbidden),
- ⁽²⁾ FM expert translates system scenario to valuation σ ,
- $\ensuremath{\mathfrak{I}}$ $\ensuremath{\mathfrak{S}}$ FM expert evaluates DT on σ ,
- ④ FM expert translates outcome to "allowed / forbidden by DT",
- $\ensuremath{\,^{\odot}}$ compare expected outcome and real outcome.

• **Recommendation**: (Course's Manifesto?)

- use formal methods for the most important/intricate requirements (formalising all requirements is in most cases not possible),
- use the most appropriate formalism for a given task,
- use formalisms that you know (really) well.

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References

References

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