Softwaretechnik / Software-Engineering

Lecture 18: Behavioural Software Modelling

Prof. Dr. Andreas Podelski, Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

Topic Area Architecture & Design: Content

Content

Communicating Finite Automata (CFA)
 concrete and abstract syntax,
 networks of CFA,
 operational semantics.

Transition Sequences

Deadlock, Reachability

VI.TO a Introduction and Vocabulary

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1-a models view (weep)

VI.TI Abdelling (IDEAL)

1-b (implified Close Cobject dagams

1-c (implified tools in pagage (IML)

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Uppaal
 tool demo (simulator),
 e query language,
 CFA model-checking.

Uppaal Architecture

CFA at Work
 drive to configuration, scenarios, invariants
 tool demo (verifier).

Model-driven/-based Software Engineering

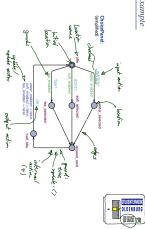
Design Patterns

Communicating Finite Automata presentation follows (Olderog and Dierks, 2008)

Example

Software Modelling

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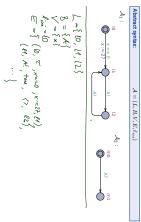


Channel Names and Actions

- To define communicating finite automata, we need the following sets of symbols:
- * A set $(a,b\in)$ Chan of channel names or channels.
- For each channel a ∈ Chan, two visible actions:
 a? and a! denote input and output on the channel (a?, a! ∉ Chan).
- $\, \tau \not\in {\sf Chan}$ represents an internal action, not visible from outside.
- $\bullet \ \ (\alpha,\beta\in)\ Act:=\{a?\mid a\in\mathsf{Chan}\}\cup\{a!\mid a\in\mathsf{Chan}\}\cup\{\tau\}\ \text{ is the set of actions.}$
- $\bullet \;$ For each alphabet B , we define the corresponding action set - An alphabet B is a set of channels, i.e. $B\subseteq \mathsf{Chan}.$
- $B_{?!} := \{a? \mid a \in B\} \cup \{a! \mid a \in B\} \cup \{\tau\}.$

Note: $Chan_{2!} = Act.$

Example



$$\begin{split} & \cdot \; Conf = \{(\vec{t}, \nu) \mid \ell_i \in L_i, \nu : V \to \mathscr{D}(V)\}, \\ & \cdot \; C_{ini} = \langle \vec{t}_{ini}, \nu_{ini} \rangle \text{ with } \nu_{ini}(v) = 0 \text{ for all } v \in V. \end{split}$$

The transition relation consists of transitions of the following two types.

V = U_{i=1}ⁿ V_i.

The operational semantics of the network of CFA $\mathcal{C}(A_1,\dots,A_n)$ is the labelled transition system Definition. Let $\mathcal{A}_i=(L_i,B_i,V_i,E_i,\ell_{im_i,i}), 1\leq i\leq n,$ be communicating finite automata.

 $\mathcal{T}(\mathcal{C}(\mathcal{A}_1,\dots,\mathcal{A}_n)) = (\underbrace{Conf}, \underbrace{\mathsf{Chan}} \cup \{\tau\}, \{\overset{\lambda}{\rightarrow} | \ \lambda \in \mathsf{Chan}} \cup \{\tau\}\}, \underbrace{C_{ini}})$

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Integer Variables and Expressions, Resets

Communicating Finite Automata

Definition. A communicating finite automaton is a structure

 $\mathcal{A} = (L, B, V, E, \ell_{ini})$

* Let $(e,w\in)$ V be a set of ((finite domain) integer) variables. By $(\varphi\in)$ $\Psi(V)$ we denote the set of integer expressions over V using function symbols $<, \leq, \ldots$ and relation symbols $<, \leq, \ldots$

• A modification on $v \in V$ is of the form

By ${\cal R}(V)$ we denote the set of all modifications. $v:=\varphi, \qquad v\in V, \quad \varphi\in \Psi(V).$

• By \vec{r} we denote a finite list $(r_1,\dots,r_n), n\in\mathbb{N}_0$, of modifications $r_i\in R(V)$. \vec{r} is called reset vector (or update vector). \Diamond is the empty list (n=0).

 $\ast\,$ By $R(V)^{\ast}$ we denote the set of all such finite lists of modifications.

• $E \subseteq \{\chi \ge B_{\gamma} \ge 0\}$, $E(Y)^* \searrow f x$ finite pertof directed edges such that $e \in E \subseteq \{\chi \ge B_{\gamma} \le 0\}$, $E(Y)^* \searrow f x$ for $f \in E$ when $(0) \in U \implies \varphi = me$. Edges $\{(x, a) \ne r'\}$ from Location (10° are labelled with an action a, a guard μ) and latter of modifications.

• $\ell_{mi} \in F$ is the initial location.

(ℓ ∈) L is a <u>finite set of locations</u> (or control states),
 B ⊆ Chan,

Helpers: Extended Valuations and Effect of Resets

Operational Semantics of Networks of CFA

- $\bullet \ \nu : V \to \mathscr{D}(V)$ is a valuation of the variables, * A valuation ν of the variables canonically assigns an integer value $\nu(\varphi)$ to each integer expression $\varphi\in\Phi(V)$.
- $\bullet \mid \ = \subseteq (V \to \mathscr{D}(V)) \times \Phi(V) \text{ is the canonical satisfaction relation}$ between valuations and integer expressions from $\Phi(V).$
- Effect of modification $r \in R(V)$ on ν , denoted by $\nu[r]$:

 $\nu[v := \varphi](a) := \begin{cases} \nu(\varphi), & \text{if } a = v, \\ \nu(a), & \text{otherwise} \end{cases}$

• We set $\nu[\{r_1,\ldots,r_n\}]:=\nu[r_1]\ldots[r_n]=\underbrace{((\nu[r_1])[r_2],\ldots)[r_n]}_{\text{That is, modifications are executed sequentially from left to right.}}$

Operational Semantics of Networks of CFA

• there is a τ -edge $(\ell_i, \tau, \varphi, \vec{r}, \ell'_i) \in E_i$ such that • $\nu \models \varphi$, "source valuation satisfies guard"

• $\ell' = \ell' | \ell_i := \ell'_i |$, "automaton i changes location" • $\nu' = \nu | \ell' |$, " ν' is the result of applying ℓ on ν'

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• An internal transition $(\vec{\ell}, \nu) \xrightarrow{\tau} (\vec{\ell}, \nu')$ occurs if there is $i \in \{1, \dots, n\}$ and

there is a reedge $(\ell_1, \tau, \underline{\varphi}, \underline{\xi}', \underline{\xi}') \in E_i$ fuch that $\bullet (D) = \varphi_i$ fourte value a satisfies guard $\underline{z} = \overline{\ell}[\ell_1 := \underline{\xi}']_{i_1}$ any animaton i changes location. ν' is the result of applying \vec{r} on ν''

 $\bullet \ \nu' = (\psi(r_i)(r_i),$ " ν' is the result of applying first r_i and then r_j on ν' . This style of communication is known under the names "rendezvous," synchronous, "blocking" communication (and possibly many others).

Reachability

Transition Sequences

• A transition sequence of $\mathcal{C}(A_1,\dots,A_n)$ is any (in)finite sequence of the form with $\frac{\langle \vec{a}_0,a_0\rangle\xrightarrow{\lambda_1}\langle (\vec{a}_1,a_2)\xrightarrow{\lambda_2}\langle (\vec{a}_1,a_2)\xrightarrow{\lambda_2}\dots}{\langle \vec{a}_n,a_n\rangle}$

 $\bullet \ (\vec{\ell}_0, n_0) = \mathcal{C}_{\mathrm{ini}},$ $\bullet \ \ \text{forall} \ i \in \mathbb{N}, \text{there is} \ \xrightarrow{\lambda_{i+1}} \text{in} \ \mathcal{T}(\mathcal{C}(A_1, \dots, A_n)) \ \text{with} \ (\vec{\ell}_i, \mu_i) \ \xrightarrow{\lambda_{i+1}} \ (\vec{\ell}_{i+1}, \mu_{i+1}),$

• A configuration $(\vec{\ell},\nu)$ is called <u>reachable.</u> (in $C(A_1,\ldots,A_n)$ <u>I from</u> $(\vec{\ell}_0,\nu_0)$ if and only if there is a transition sequence of the form

 $\langle \vec{\ell}_0, \nu_0 \rangle \xrightarrow{\lambda_1} \langle \vec{\ell}_1, \nu_1 \rangle \xrightarrow{\lambda_2} \langle \vec{\ell}_2, \nu_2 \rangle \xrightarrow{\lambda_3} \dots \xrightarrow{\lambda_n} \langle \vec{\ell}_n, \nu_n \rangle = \langle \vec{\ell}_1, \nu \rangle$

 ${}^{\rm th}$ A configuration $\langle \vec{\ell}, \nu \rangle$ is called reachable (without "from") if and only if it is reachable from $\widehat{C_{ini}}.$

* A location $\ell \in L_\ell$ is called reachable if and only if any configuration $(\overline{\ell_\ell}, \underline{\nu})$ with $\ell_i = \ell$ is reachable, i.e. there exist ℓ and ν such that $\ell_i = \ell$ and (ℓ_i, ν) is reachable.

Operational Semantics of Networks of CFA

• An internal transition $(\widehat{l} \underbrace{\widehat{U}}) \xrightarrow{T} (\widehat{l} \underbrace{\widehat{U}})$ occurs if there is $i \in \{1, \dots, n\}$ and

* A synchronisation transition $(\underline{f}_{i,j}) \stackrel{L}{\rightarrow} (\underline{f}_{i,j}) \stackrel{L}{$

 $\langle (\mathcal{D}_{i}, \omega_{0}, \omega_{0}), \times = 0 \rangle$ $\downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \qquad \downarrow$

• A configuration $\underline{\ell(\nu)}$ of $\mathcal{C}(A_1,\dots,A_n)$ is called deadlock if and only if there are no transitions from (ℓ,ν) , i.e. if $-(\exists \lambda \in \Lambda \exists \, (\ell', \nu') \in \mathit{Conf} \bullet (\ell, \nu) \xrightarrow{\Delta} (\ell', \nu')).$ The network $\mathcal{C}(A_1, \dots, A_n)$ is said to have a deadlock if and only if there is a reachable configuration (ℓ, ν) which is a deadlock.

Deadlock

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Uppaal (Larsen et al., 1997; Behrmann et al., 2004)

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Satisfaction of Uppaal Queries by Configurations The satisfaction relation between configurations $\langle \vec{\ell}, \nu \rangle \models F$

Example: Computation Paths vs. Computation Tree

of a network $\mathcal{C}(A_1,\dots,A_n)$ and formulae F of the Uppaal logic is defined inductively as follows:

 $\bullet \ (\vec{\ell},\nu) \models \varphi$

 $\bullet \ \langle \vec{\ell}, \nu \rangle \models \mathtt{not} \ term$ $\bullet \ \langle \vec{\ell}, \nu \rangle \models term_1 \ \mathtt{and} \ term_2$

$\langle \hat{c}_{\nu \nu} \rangle$ is a dendlock out
$i_{\nu} = e$ # $\nu = e$ # $\nu = e$ # $\nu \neq e$ # $\nu \neq e$ # $\nu \neq e$

• $\langle \vec{\ell}, \nu \rangle \models A_i.\ell$ $\bullet \ \langle \vec{\ell}, \nu \rangle \mid = \mathtt{deadlock}$

 $\langle (0,m0,m0), \quad x=0 \rangle$ $\langle (0,m0,m0), \quad x=\frac{27}{\lambda} \rangle$ $\langle (0,m0,m0), \quad x=\frac{27}{\lambda} \rangle$ $\langle (0,m0,m0), \quad x=27 \rangle$ $\langle (0,m0,m1), \quad x=27 \rangle$ $\langle (0,m0,m1), \quad x=27 \rangle$ $\langle (0,m0,m1), \quad x=27 \rangle$

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The Uppaal Query Language

Tool Demo

Consider $N=\mathcal{C}(A_1,\dots,A_n)$ over data variables V. • basic formula:

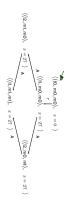
 $adsm::=A_i,t\mid \varphi\mid \text{deadlock}$ where $\ell\in L_i$ is a location and φ an expression over V . • configuration formulae:

existential path formulae: universal path formulae: $term ::= atom \mid not term \mid term_1 and term_2$ e-formula ::= <u>∃0</u> term |]<u>0</u> term

a-formula ::= <u>VQ</u> term | <u>VQ</u> term | term _z> term₂ F ::= e-formula | a-formula

(exists finally)
(exists globally)
(always finally)
(always globally)
(leads to)

Example: Computation Paths & Computation Graph



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Satisfaction of Uppaal Queries by Configurations

• $\langle \vec{\ell_0}, \nu_0 \rangle \models \exists \Diamond \ term$

Example: $\langle \vec{\ell_0}, \nu_0 \rangle \models \exists \Diamond \varphi$

 $\begin{array}{ll} \text{if } \exists \text{path } c \text{ of } N \text{ starting in } \underbrace{(\vec{u}_{i}, u_{i})}_{\text{3 one configuration a staffying } term \text{ is reachable}} \\ \text{``come configuration a staffying } term \text{ is reachable} \\ \end{array}$

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Satisfaction of Uppaal Queries by Configurations

Exists globally: • $\langle \vec{\ell}_0, \nu_0 \rangle \models \exists \Box \textit{term}$

iff $\exists path \xi \text{ of } \mathcal{N} \text{ starting in } \langle \vec{\ell_0}, \nu_0 \rangle$ $\forall i \in \mathbb{N}_0 \bullet \xi^i \mid = term$

"on some computation path, all configurations satisfy term"

Example: $\langle \vec{\ell}_0, \nu_0 \rangle \models \exists \Box \varphi$

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CFA Model-Checking

Satisfaction of Uppaal Queries by Configurations

Example: $(\vec{\ell}_0, \nu_0) \models \varphi_1 \longrightarrow \varphi_2$

"on all paths, from each configuration satisfying $term_1$, a configuration satifying $term_2$ is reachable" (response pattern)

 $\begin{array}{ccc} \text{iff} & \forall \mathsf{path} \ \xi \circ \mathsf{f} \ \mathsf{N} \ \mathsf{starting in} \ (\vec{\ell_0}, \nu_0) \ \forall \ i \in \mathbb{N}_0 \bullet \\ \xi^i \models \mathit{term}_1 \implies \xi^i \models \forall \lozenge \mathit{term}_2 \end{array}$

Definition. Let $\mathcal{N}=\mathcal{C}(A_1,\dots,A_n)$ be a network and F a query. (i) We say N satisfies F, denoted by $N\models F$, if and only if $C_{mi}\models F$.

(ii) The model-checking problem for $\mathcal N$ and F is to $\operatorname{\underline{decide}}$ whether $(\mathcal N,F)\in \models$.

Proposition.

The model-checking problem for communicating finite automata is decidable.

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Satisfaction of Uppaal Queries by Configurations

Always globally:

 $\bullet \ (\vec{\ell_0},\nu_0) \models \forall \Box \ term$ $\mathsf{iff}\,(\vec{\ell}_0,\nu_0)\not\models \exists \Diamond\,\neg term$

"not (some configuration satisfying —term is reachable)" or: "all reachable configurations satisfy term."

 $\bullet \ \langle \vec{\ell_0} \,, \nu_0 \,\rangle \models \forall \Diamond \; term$ $\mathsf{iff}(\vec{t}_0,\nu_0)\not\models\exists\Box\neg term$

hot (on some computation path, all configurations satisfy $\neg term$)" or: "on all computation paths, there is a configuration satisfying term"

Content

Communicating Finite Automata (CFA)
 concrete and abstract syntax,
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Transition SequencesDeadlock, Reachability

Uppaal

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CFA at Work

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Uppaal Architecture

Uppaal Architecture

CFA and Queries at Work

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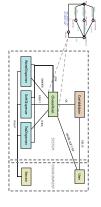
Design Verification: Invariants

STUCEHIENMEXX OLDENBURG ENTER

Design Check: Scenarios Question: Is the following existential LSC satisfied by the model? (Otherwise, the design is definitely broken.)

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Model Architecture — Who Talks What to Whom



Shared variables:
 bool vater_enabled, soft_enabled, tea_enabled;
 int w = 3, s = 3, t = 3;

Note: Our model does not use scopes ("information hiding") for channels.
 That is, "Service" could send "WATER if the modeler wanted to.

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Design Sanity Check: Drive to Configuration

SLOEMEWEX OLDENBURG SESS TO

- Question: Is is (at all) possible to have no water in the vending machine model? (Otherwise, the design is definitely broken.)
- Approach: Check whether a configuration satisfying $\label{eq:w} w = 0$

is reachable, i.e. check whether $N_{\rm VM} \models \frac{\exists \lozenge w = 0.}{}$ for the vending machine model $N_{\rm VM}$.

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STUDENBURG Band to

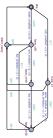
 Question: Is the "tea" button ever enabled?
 (Otherwise, the considered invariant tea_enabled ==> CoinValidator.have_c150

* Approach Check whether a configuration satisfying water_enabled = 1 is reachable. Exactly like we did with w=0 earlier (i.e. check whether $N_{\rm CM}\models \exists \Diamond$ water_enabled = 1).

 $\label{eq:continuity} \begin{array}{l} \text{ce._mable} \Longrightarrow \text{CorNolidatorhave.c150} \\ \text{hods in all reachable configurations, i.e. check whether} \\ N_{NN} \models \forall \square \text{(ce._canabled imply GorNolidatorhave.c150)} \\ \text{for the wending machine model} N_{NA}. \end{array}$

 \circ Question: Is it the case that the "tea" button is only enabled if there is \in 150 in the machine? (Otherwise, the design is broken.)

Design Verification: Another Invariant

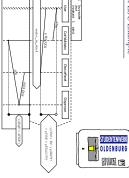


- Approach: Check $\mathcal{N}_{\rm YM} \models \forall\Box$ (CoirValidator.have_c50 or CoirValidator.have_c100 or CoirValidator.have_c150) inply water_enabled.

Question: Is it the case that, if there is money in the machine and water in stock, that the 'water' button is enabled?

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Recall: Universal LSC Example



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Uppaal Architecture

CFA at Work
 drive to configuration, scenarios, invariants
 tool demo (verifier).
 Uppaal Architecture

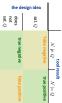
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Uppaal
 tool demo (simulator),
 query language,
 CFA model-checking.

 Deadlock, Reachability Transition Sequences

- Assume that query Q correponds to a requirement on the system under development, and N is our design-idea model.
 Assume that the verification tool states $N \models Q$. What can we conclude from that?

What Can We Conclude From Verification Results?



Tell Them What You've Told Them...

Content

Communicating Finite Automata (CFA)
 concrete and abstract syntax,
 ne tworks of CFA,
 operational semantics.

 Use model-checking e.g., to
 obtain a computation path to a certain configuration (dave-to-configuration),
 check whether as accentrio is possible,
 check whether an invariant is satified.
 firot analyst the desgn further using the <u>diagnost counter-scample</u>). • The Uppaal Query Language can be used to • formalize reachability $(\exists \lozenge \mathit{CF}, \lor \Box \mathit{CF}, \ldots)$ and • leads to $(\mathit{CF}_1 \longrightarrow \mathit{CF}_2)$ properties. Since the model-checking problem of CFA is decidable,
 there are tools which automatically check
 whether a network of CFA satisfies a given query. A network of communicating finite automata
 describes a labelled transition system,
 can be used to model software behaviour.

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References

Medical Control Academy Control Associal angula 2004-1917 Training apart, Adarq Unomph, Cornel Academy Control Associal angula 2004-1917 Training apart, Adarq Unomph, Cornel Academy Control Cont