

Softwaretechnik / Software-Engineering

Lecture 16: Program Verification

2019-07-18

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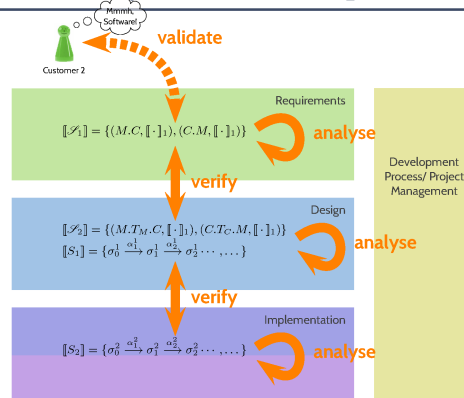
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Topic Area Code Quality Assurance: Content

VL 14	● Introduction and Vocabulary
⋮	● Test case, test suite, test execution.
⋮	● Positive and negative outcomes.
VL 15	● Limits of Software Testing
⋮	● Glass-Box Testing
⋮	● Statement-, branch-, term-coverage.
⋮	● Other Approaches
⋮	● Model-based testing,
VL 16	● Program Verification
⋮	● partial and total correctness,
⋮	● Proof System PD.
⋮	● Runtime verification.
VL 17	● Review
⋮	

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validation—

The process of evaluating a system or component during or at the end of the development process to determine whether it satisfies specified requirements.

Contrast with: **verification**.

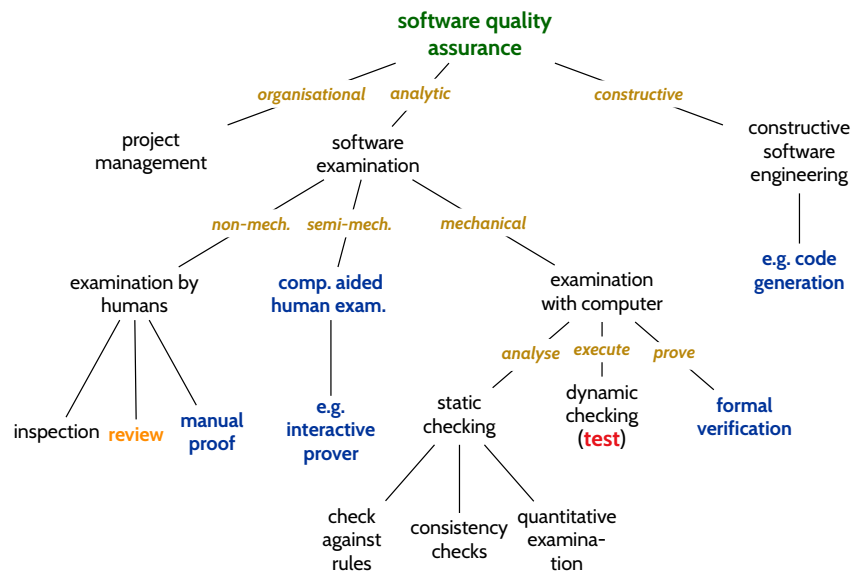
IEEE 610.12 (1990)

verification—

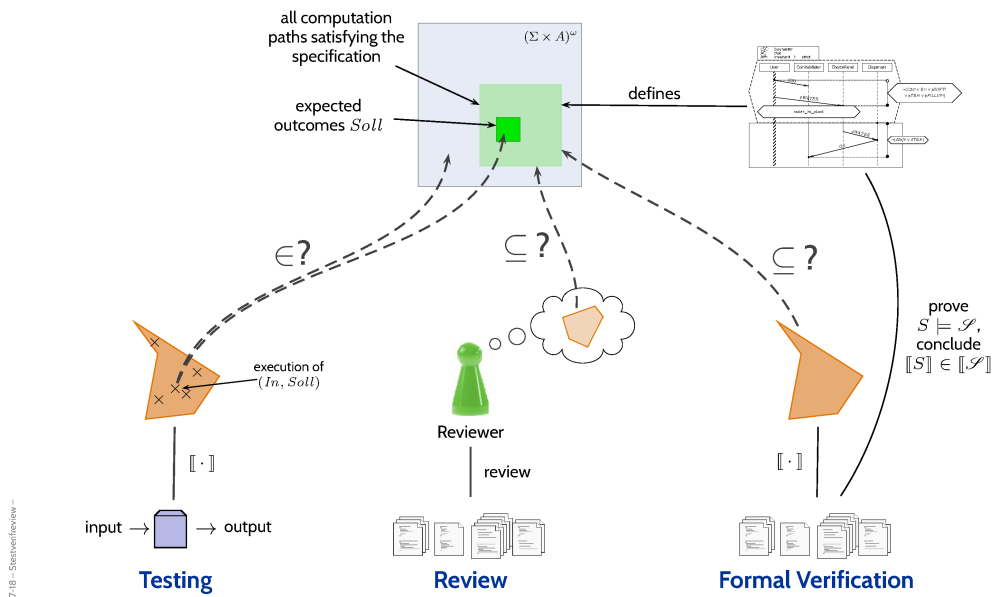
- (1) The process of evaluating a system or component to determine whether the products of a given development phase satisfy the conditions imposed at the start of that phase.
Contrast with: **validation**.
- (2) Formal proof of program correctness.

IEEE 610.12 (1990)

Concepts of Software Quality Assurance



(Ludewig and Lichter, 2013)



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Content

- **Formal Program Verification**
 - **Deterministic Programs**
 - Syntax
 - Semantics
 - Termination, Divergence
 - **Correctness** of deterministic programs
 - partial correctness,
 - total correctness.
 - **Proof System PD**
- **The Verifier for Concurrent C**
 - modular reasoning
 - return values / old values
- **Assertions**

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Sequential, Deterministic While-Programs

Syntax:

$$S := \text{skip} \mid u := t \mid S_1; S_2 \mid \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi} \mid \text{while } B \text{ do } S_1 \text{ od}$$

where $u \in V$ is a **variable**, t is a type-compatible **expression**, B is a Boolean **expression**.

Semantics: (is induced by the following transition relation) — $\sigma : V \rightarrow \mathcal{D}(V)$

- (i) $\langle \text{skip}, \sigma \rangle \rightarrow \langle E, \sigma \rangle$ empty program
- (ii) $\langle u := t, \sigma \rangle \rightarrow \langle E, \sigma[u := \sigma(t)] \rangle$
- (iii) $\frac{\langle S_1, \sigma \rangle \rightarrow \langle S_2, \tau \rangle}{\langle S_1; S, \sigma \rangle \rightarrow \langle S_2; S, \tau \rangle}$
- (iv) $\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_1, \sigma \rangle, \text{ if } \sigma \models B,$
- (v) $\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_2, \sigma \rangle, \text{ if } \sigma \not\models B,$
- (vi) $\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle S; \text{while } B \text{ do } S \text{ od}, \sigma \rangle, \text{ if } \sigma \models B,$
- (vii) $\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle E, \sigma \rangle, \text{ if } \sigma \not\models B,$

E denotes the **empty program**; define $E; S \equiv S; E \equiv S$.

Note: the first component of $\langle S, \sigma \rangle$ is a program (**structural operational semantics (SOS)**).

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Example

(i) $\langle \text{skip}, \sigma \rangle \rightarrow \langle E, \sigma \rangle$	$E; S \equiv S; E \equiv S$
(ii) $\langle u := t, \sigma \rangle \rightarrow \langle E, \sigma[u := \sigma(t)] \rangle$	
(iii) $\frac{\langle S_1, \sigma \rangle \rightarrow \langle S_2, \tau \rangle}{\langle S_1; S, \sigma \rangle \rightarrow \langle S_2; S, \tau \rangle}$	
(iv) $\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_1, \sigma \rangle, \text{ if } \sigma \models B,$	
(v) $\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_2, \sigma \rangle, \text{ if } \sigma \not\models B,$	
(vi) $\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle S; \text{while } B \text{ do } S \text{ od}, \sigma \rangle, \text{ if } \sigma \models B,$	
(vii) $\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle E, \sigma \rangle, \text{ if } \sigma \not\models B,$	

Consider **program**

$$S \equiv \underbrace{a[0] := 1}_{\sigma} ; \underbrace{a[1] := 0}_t ; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}$$

and a **state** σ with $\sigma \models x = 0$.

$$\langle S, \sigma \rangle \xrightarrow{(ii), (iii)} \langle a[1] := 0; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \underbrace{\sigma[a[0] := 1]}_{Gi} \rangle$$

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Example

(i) $\langle \text{skip}, \sigma \rangle \rightarrow \langle E, \sigma \rangle$	$E; S \equiv S; E \equiv S$
(ii) $\langle u := t, \sigma \rangle \rightarrow \langle E, \sigma[u := \sigma(t)] \rangle$	
(iii) $\frac{\langle S_1, \sigma \rangle \rightarrow \langle S_2, \tau \rangle}{\langle S_1; S, \sigma \rangle \rightarrow \langle S_2; S, \tau \rangle}$	
(iv) $\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_1, \sigma \rangle, \text{ if } \sigma \models B,$	
(v) $\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_2, \sigma \rangle, \text{ if } \sigma \not\models B,$	
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(vii) $\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle E, \sigma \rangle, \text{ if } \sigma \not\models B,$	

Consider **program**

$S \equiv a[0] := 1; a[1] := 0; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}$

and a **state** σ with $\sigma \models x = 0$.

$$\begin{aligned} \langle S, \sigma \rangle &\xrightarrow{(ii), (iii)} \langle a[1] := 0; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma[a[0] := 1] \rangle \\ &\xrightarrow{(ii), (iii)} \langle \underbrace{\text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}}_{\mathfrak{B}}, \sigma' \rangle \end{aligned}$$

where $\sigma' = (\sigma[a[0] := 1])[a[1] := 0]$.

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Example

(i) $\langle \text{skip}, \sigma \rangle \rightarrow \langle E, \sigma \rangle$	$E; S \equiv S; E \equiv S$
(ii) $\langle u := t, \sigma \rangle \rightarrow \langle E, \sigma[u := \sigma(t)] \rangle$	
(iii) $\frac{\langle S_1, \sigma \rangle \rightarrow \langle S_2, \tau \rangle}{\langle S_1; S, \sigma \rangle \rightarrow \langle S_2; S, \tau \rangle}$	
(iv) $\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_1, \sigma \rangle, \text{ if } \sigma \models B,$	
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(vii) $\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle E, \sigma \rangle, \text{ if } \sigma \not\models B,$	

Consider **program**

$S \equiv a[0] := 1; a[1] := 0; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}$

and a **state** σ with $\sigma \models x = 0$.

$$\begin{aligned} \langle S, \sigma \rangle &\xrightarrow{(ii), (iii)} \langle a[1] := 0; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma[a[0] := 1] \rangle \\ &\xrightarrow{(ii), (iii)} \langle \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma' \rangle \\ &\xrightarrow{(vi)} \langle x := x + 1; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma' \rangle \\ &\xrightarrow{(ii), (iii)} \langle \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma'[x := 1] \rangle \\ &\xrightarrow{(vii)} \langle E, \sigma'[x := 1] \rangle \end{aligned}$$

where $\sigma' = \sigma[a[0] := 1][a[1] := 0]$.

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Another Example

(i)	$\langle \text{skip}, \sigma \rangle \rightarrow \langle E, \sigma \rangle$	$E; S \equiv S; E \equiv S$
(ii)	$\langle u := t, \sigma \rangle \rightarrow \langle E, \sigma[u := \sigma(t)] \rangle$	
(iii)	$\frac{\langle S_1, \sigma \rangle \rightarrow \langle S_2, \tau \rangle}{\langle S_1; S, \sigma \rangle \rightarrow \langle S_2; S, \tau \rangle}$	
(iv)	$\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_1, \sigma \rangle, \text{ if } \sigma \models B,$	
(v)	$\langle \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, \sigma \rangle \rightarrow \langle S_2, \sigma \rangle, \text{ if } \sigma \not\models B,$	
(vi)	$\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle S; \text{while } B \text{ do } S \text{ od}, \sigma \rangle, \text{ if } \sigma \models B,$	
(vii)	$\langle \text{while } B \text{ do } S \text{ od}, \sigma \rangle \rightarrow \langle E, \sigma \rangle, \text{ if } \sigma \not\models B,$	

Consider **program**

$$S_1 \equiv y := x; y := (x - 1) \cdot x + y$$

and a **state** σ with $\sigma \models x = 3$.

$$\begin{aligned} \langle S_1, \sigma \rangle &\xrightarrow{(ii), (iii)} \langle y := (x - 1) \cdot x + y, \{x \mapsto 3, y \mapsto 3\} \rangle \\ &\xrightarrow{(ii)} \langle E, \{x \mapsto 3, y \mapsto 9\} \rangle \end{aligned}$$

Consider **program** $S_3 \equiv y := x; y := (x - 1) \cdot x + y; \text{ while } 1 \text{ do skip od}.$

$$\begin{aligned} \langle S_3, \sigma \rangle &\xrightarrow{(ii), (iii)} \langle y := (x - 1) \cdot x + y; \text{ while } 1 \text{ do skip od}, \{x \mapsto 3, y \mapsto 3\} \rangle \\ &\xrightarrow{(ii), (iii)} \langle \text{while } 1 \text{ do skip od}, \{x \mapsto 3, y \mapsto 9\} \rangle \\ &\xrightarrow{(vi)} \langle \text{skip}; \text{while } 1 \text{ do skip od}, \{x \mapsto 3, y \mapsto 9\} \rangle \\ &\xrightarrow{(i), (iii)} \langle \text{while } 1 \text{ do skip od}, \{x \mapsto 3, y \mapsto 9\} \rangle \\ &\xrightarrow{(vi)} \dots \end{aligned}$$

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Computations of Deterministic Programs

Definition. Let S be a deterministic program.

(i) A **transition sequence** of S (starting in σ) is a finite or infinite sequence

$$\langle S, \sigma \rangle = \langle S_0, \sigma_0 \rangle \rightarrow \langle S_1, \sigma_1 \rangle \rightarrow \dots$$

(that is, $\langle S_i, \sigma_i \rangle$ and $\langle S_{i+1}, \sigma_{i+1} \rangle$ are in transition relation for all i).

(ii) A **computation (path)** of S (starting in σ) is a **maximal** transition sequence of S (starting in σ), i.e. infinite or not extendible.

(iii) A computation of S is said to

a) **terminate** in τ if and only if it is finite and ends with $\langle E, \tau \rangle$,

b) **diverge** if and only if it is infinite.

S can diverge from σ if and only if a diverging computation starts in σ .

(iv) We use $\rightarrow^*$ to denote the transitive, reflexive closure of $\rightarrow$.

Lemma. For each deterministic program S and each state σ , there is exactly one computation of S which starts in σ .

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Definition.

Let S be a deterministic program.

- (i) The **semantics of partial correctness** is the function

$$\mathcal{M}[[S]] : \Sigma \rightarrow 2^\Sigma$$

with $\mathcal{M}[[S]](\sigma) = \{\tau \mid \langle S, \sigma \rangle \rightarrow^* \langle E, \tau \rangle\}$.

- (ii) The **semantics of total correctness** is the function

$$\mathcal{M}_{tot}[[S]] : \Sigma \rightarrow 2^\Sigma \cup \{\infty\}$$

with $\mathcal{M}_{tot}[[S]](\sigma) = \mathcal{M}[[S]](\sigma) \cup \{\infty \mid S \text{ can diverge from } \sigma\}$.

∞ is an error state representing **divergence**.

Note: $\mathcal{M}_{tot}[[S]](\sigma)$ has exactly one element, $\mathcal{M}[[S]](\sigma)$ at most one.

Example: $\mathcal{M}[[S_1]](\sigma) = \mathcal{M}_{tot}[[S_1]](\sigma) = \{\tau \mid \tau(x) = \sigma(x) \wedge \tau(y) = \sigma(x)^2\}, \quad \sigma \in \Sigma.$

(Recall: $S_1 \equiv y := x; y := (x - 1) \cdot x + y$)

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Correctness of While-Programs

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Correctness of Deterministic Programs

Definition.

Let S be a program over variables V , and p and q Boolean expressions over V .

(i) The correctness formula

$$\{p\} S \{q\}$$

("Hoare triple")

holds in the sense of partial correctness,

denoted by $\models \{p\} S \{q\}$, if and only if $\{\sigma \mid \sigma \models p\}$

$$\mathcal{M}[S](\llbracket p \rrbracket) \subseteq \llbracket q \rrbracket.$$

$$\leftarrow \{\tau \mid \tau \models q\}$$

We say S is partially correct wrt. p and q .

(ii) A correctness formula

$$\{p\} S \{q\}$$

holds in the sense of total correctness,

denoted by $\models_{tot} \{p\} S \{q\}$, if and only if $\nexists \infty$

$$\mathcal{M}_{tot}[S](\llbracket p \rrbracket) \subseteq \llbracket q \rrbracket.$$

We say S is totally correct wrt. p and q .



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Example: Computing squares (of numbers $0, \dots, 27$)

- **Pre-condition:** $p \equiv 0 \leq x \leq 27$,
- **Post-condition:** $q \equiv y = x^2$.

Program S_1 :

```
1 int y = x;
2 y = (x - 1) * x + y;
```

$$\models \{p\} S_1 \{q\} \quad \checkmark$$

$$\models_{tot} \{p\} S_1 \{q\} \quad \checkmark$$

Program S_2 :

```
1 int y = x;
2 int z; // uninitialised
3 y = ((x - 1) * x + y) + z;
```

$$\not\models \{p\} S_2 \{q\} \quad \times$$

$$\not\models_{tot} \{p\} S_2 \{q\} \quad \times$$

Program S_3 :

```
1 int y = x;
2 y = (x - 1) * x + y;
3 while (1);
```

$$\models \{p\} S_3 \{q\} \quad \checkmark$$

$$\not\models_{tot} \{p\} S_3 \{q\} \quad \times$$

Program S_4 :

```
1 int x = read_input();
2 int y = x + (x - 1) * x;
```

$$\models \{p\} S_4 \{q\}$$

$$\models_{tot} \{p\} S_4 \{q\}$$

S_5 :

```
S2;
while (1);
```

$\models \{p\} S_5 \{q\} \quad \checkmark$
 $\not\models_{tot} \{p\} S_5 \{q\} \quad \times$

math.	if-then
$\mathbb{Z}$	(X)
$\checkmark$	(X)

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Example: Correctness

- By the example, we have shown

$$\models \{x = 0\} S \{x = 1\}$$

and

$$\models_{tot} \{x = 0\} S \{x = 1\}.$$

(because we only assumed $\sigma \models x = 0$ for the example, which is exactly the precondition.)

Example

```
10 (skip,  $\sigma$ )  $\rightarrow$  ( $E$ ,  $\sigma$ )
11 ( $x := t$ ,  $\sigma$ )  $\rightarrow$  ( $E$ ,  $\sigma[x := \sigma(t)]$ )
12 ( $S_1; S_2$ ,  $\sigma$ )  $\rightarrow$  ( $E$ ,  $\sigma$ )  $\rightarrow$  ( $S_2$ ,  $\sigma$ )
13 ( $S_1; S_2$ ,  $\sigma$ )  $\rightarrow$  ( $S_2$ ,  $\sigma$ )
14 (if  $B$  then  $S_1$  else  $S_2$ ,  $\sigma$ )  $\rightarrow$  ( $S_1$ ,  $\sigma$ ) if  $\sigma \models B$ 
15 (if  $B$  then  $S_1$  else  $S_2$ ,  $\sigma$ )  $\rightarrow$  ( $S_2$ ,  $\sigma$ ) if  $\sigma \not\models B$ 
16 (while  $B$  do  $S$  od,  $\sigma$ )  $\rightarrow$  ( $S$ , while  $B$  do  $S$  od,  $\sigma$ ) if  $\sigma \models B$ 
17 (while  $B$  do  $S$  od,  $\sigma$ )  $\rightarrow$  ( $E$ ,  $\sigma$ ) if  $\sigma \not\models B$ 
```

Consider program

$S \equiv a[0] := 1; a[1] := 0; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}$

and a state σ with $\sigma \models x = 0$.

$(S, \sigma) \xrightarrow{(i1), (i11)} (a[1] := 0; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma[a[0] := 1])$
 $\xrightarrow{(i2), (i11)} (\text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma')$
 $\xrightarrow{(i11)} (x := x + 1; \text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma')$
 $\xrightarrow{(i1), (i11)} (\text{while } a[x] \neq 0 \text{ do } x := x + 1 \text{ od}, \sigma'[x := 1])$
 $\xrightarrow{(i11)} (E, \sigma'[x := 1])$

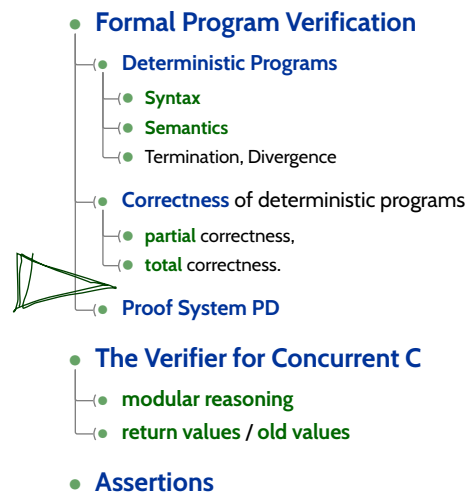
where $\sigma' = \sigma[a[0] := 1][a[1] := 0]$.

- We have also shown (= proved (!)):

$$\models \{x = 0\} S \{x = 1 \wedge a[x] = 0\}.$$

- The correctness formula $\{x = 2\} S \{\text{true}\}$ does not hold for S .
(For example, if $\sigma \models a[i] \neq 0$ for all $i > 2$.)
- In the sense of **partial correctness**, $\{x = 2 \wedge \forall i \geq 2 \bullet a[i] = 1\} S \{\text{false}\}$ also holds.

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Proof-System PD

Axiom 1: Skip-Statement

$$\{p\} \text{ skip } \{p\}$$

Axiom 2: Assignment

$$\{p[u := t]\} u := t \{p\}$$

Rule 3: Sequential Composition

$$\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$$

Rule 4: Conditional Statement

$$\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$$

Rule 5: While-Loop

$$\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$$

Rule 6: Consequence

$$\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$$

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Axiom 1: Skip-Statement

$$\{p\} \text{ skip } \{p\}$$

Axiom 2: Assignment

$$\{p[u := t]\} u := t \{p\}$$

Rule 3: Sequential Composition

$$\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$$

Rule 4: Conditional Statement

$$\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$$

Rule 5: While-Loop

$$\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$$

Rule 6: Consequence

$$\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$$

Theorem. PD is correct (“sound”) and (relative) complete for partial correctness of deterministic programs, i.e. $\vdash_{PD} \{p\} S \{q\}$ if and only if $\models \{p\} S \{q\}$.

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Example Proof

$$DIV \equiv \overbrace{a := 0; b := x; \text{while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od}}^{=:S_0^D} \quad \overbrace{b \geq y}^{=:B^D} \quad \overbrace{b := b - y; a := a + 1 \text{ od}}^{=:S_1^D} \quad (2)$$

(The first (textually represented) program that has been formally verified (Hoare, 1969). (3) ✓

We can prove $\models \{x \geq 0 \wedge y \geq 0\} DIV \{a \cdot y + b = x \wedge b < y\}$

by showing $\vdash_{PD} \underbrace{\{x \geq 0 \wedge y \geq 0\}}_{=:p^D} DIV \underbrace{\{a \cdot y + b = x \wedge b < y\}}_{=:q^D}$, i.e., derivability in PD:

$$\frac{\frac{(1) \quad \{p^D\} S_0^D \{P\}, \quad \frac{\frac{(2) \quad \{P \wedge (B^D)\} S_1^D \{P\}}{P \rightarrow P, \{P\} \text{ while } B^D \text{ do } S_1^D \text{ od } \{P \wedge \neg(B^D)\}}, \quad \frac{(3) \quad P \wedge \neg(B^D) \rightarrow q^D}{P \wedge \neg(B^D) \rightarrow q^D}}{\{P\} \text{ while } B^D \text{ do } S_1^D \text{ od } \{q^D\}} \quad (R5) \quad (R6)}{\{p^D\} S_0^D; \text{ while } B^D \text{ do } S_1^D \text{ od } \{q^D\}} \quad (R3)$$

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(A1) $\{p\} \text{ skip } \{p\}$	(R3) $\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$	(R5) $\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$
(A2) $\{p[u := t]\} u := t \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$	(R6) $\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$

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Example Proof

$$DIV \equiv \overbrace{a := 0; b := x; \text{while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od}}^{=:S_0^D} \quad \overbrace{b \geq y}^{=:B^D} \quad \overbrace{b := b - y; a := a + 1 \text{ od}}^{=:S_1^D}$$

(The first (textually represented) program that has been formally verified (Hoare, 1969).

We can prove $\models \{x \geq 0 \wedge y \geq 0\} DIV \{a \cdot y + b = x \wedge b < y\}$

by showing $\vdash_{PD} \underbrace{\{x \geq 0 \wedge y \geq 0\}}_{=:p^D} DIV \underbrace{\{a \cdot y + b = x \wedge b < y\}}_{=:q^D}$, i.e., derivability in PD:

$$\frac{\frac{(1) \quad \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\}, \quad \frac{\frac{(2) \quad \{P \wedge (b \geq y)\} b := b - y; a := a + 1 \{P\}}{\{P\} \text{ while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od } \{P \wedge \neg(b \geq y)\}}, \quad \frac{(3) \quad P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y}{P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y}}{\{x \geq 0 \wedge y \geq 0\} a := 0; b := x; \text{ while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od } \{a \cdot y + b = x \wedge b < y\}} \quad (R5) \quad (R6) \quad (R3)$$

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(A1) $\{p\} \text{ skip } \{p\}$	(R3) $\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$	(R5) $\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$
(A2) $\{p[u := t]\} u := t \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$	(R6) $\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$

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$$\begin{array}{c}
 \text{(1)} \quad \frac{}{\{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\},} \quad \frac{\frac{}{P \rightarrow P,} \quad \frac{\frac{}{\{P \wedge (b \geq y)\} b := b - y; a := a + 1 \{P\}} \quad \text{(R5)} \quad \frac{}{P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y} \quad \text{(3)}}{\{P\} \text{ while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od } \{P \wedge \neg(b \geq y)\},} \quad \text{(R6)} \\
 \hline
 \{x \geq 0 \wedge y \geq 0\} a := 0; b := x; \text{ while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od } \{a \cdot y + b = x \wedge b < y\} \quad \text{(R3)}
 \end{array}$$

In the following, we show

- (1) $\vdash_{PD} \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\},$
- (2) $\vdash_{PD} \{P \wedge b \geq y\} b := b - y; a := a + 1 \{P\},$
- (3) $\models P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y.$

As **loop invariant**, we choose (**creative act!**):

$$P \equiv a \cdot y + b = x \wedge b \geq 0$$

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Proof of (1)

$$\begin{array}{ll}
 \text{(A1)} \quad \{p\} \text{ skip } \{p\} & \text{(R4)} \quad \frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}} \\
 \text{(A2)} \quad \{p[u := t]\} u := t \{p\} & \text{(R5)} \quad \frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}} \\
 \text{(R3)} \quad \frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}} & \text{(R6)} \quad \frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}
 \end{array}$$

- (1) claims:

$$\vdash_{PD} \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\}$$

where $P \equiv a \cdot y + b = x \wedge b \geq 0.$

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Proof of (1)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
(A2) $\{p[u := t]\} u := t \{p\}$	(R5) $\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$
(R3) $\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$	(R6) $\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$

- (1) claims:

$$\vdash_{PD} \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\}$$

$$\text{where } P \equiv a \cdot y + b = x \wedge b \geq 0.$$

- $\vdash_{PD} \{0 \cdot y + x = x \wedge x \geq 0\} a := 0 \{a \cdot y + x = x \wedge x \geq 0\}$ by (A2),

$$\underbrace{\{a := 0\}}_{\mathcal{P} \llbracket a := 0 \rrbracket} \quad \underbrace{\{a \cdot y + x = x \wedge x \geq 0\}}_{\mathcal{P}}$$

Proof of (1)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
(A2) $\{p[u := t]\} u := t \{p\}$	(R5) $\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$
(R3) $\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$	(R6) $\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$

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Proof of (1)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
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- $\vdash_{PD} \{0 \cdot y + x = x \wedge x \geq 0\} a := 0 \{a \cdot y + x = x \wedge x \geq 0\}$ by (A2),

- $\vdash_{PD} \{a \cdot y + x = x \wedge x \geq 0\} b := x \underbrace{\{a \cdot y + b = x \wedge b \geq 0\}}_{\equiv P}$ by (A2),

- thus, $\vdash_{PD} \{0 \cdot y + x = x \wedge x \geq 0\} a := 0; b := x \{P\}$ by (R3),

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Proof of (1)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
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- (1) claims:

$$\vdash_{PD} \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\}$$

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- $\vdash_{PD} \{0 \cdot y + x = x \wedge x \geq 0\} a := 0 \{a \cdot y + x = x \wedge x \geq 0\}$ by (A2),

- $\vdash_{PD} \{a \cdot y + x = x \wedge x \geq 0\} b := x \underbrace{\{a \cdot y + b = x \wedge b \geq 0\}}_{\equiv P}$ by (A2),

- thus, $\vdash_{PD} \{0 \cdot y + x = x \wedge x \geq 0\} a := 0; b := x \{P\}$ by (R3),

- using $x \geq 0 \wedge y \geq 0 \rightarrow 0 \cdot y + x = x \wedge x \geq 0$ and $P \rightarrow P$, we obtain

$$\vdash_{PD} \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\}$$

by (R6).

□

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Substitution

The rule 'Assignment' uses (syntactical) **substitution**: $\{p[u := t]\} u := t \{p\}$

(In formula p , replace all (free) occurrences of (program or logical) variable u by term t .)

Defined as usual, only **indexed** and **bound** variables need to be treated specially:

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Defined as usual, only **indexed** and **bound** variables need to be treated specially:

Expressions:

- plain variable x : $x[u := t] \equiv \begin{cases} t & , \text{ if } x = u \\ x & , \text{ otherwise} \end{cases}$
- constant c :
 $c[u := t] \equiv c$.
- constant op , terms s_i :
 $op(s_1, \dots, s_n)[u := t] \equiv op(s_1[u := t], \dots, s_n[u := t])$.
- conditional expression:
 $(B ? s_1 : s_2)[u := t] \equiv (B[u := t] ? s_1[u := t] : s_2[u := t])$

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- conditional expression:
 $(B ? s_1 : s_2)[u := t] \equiv (B[u := t] ? s_1[u := t] : s_2[u := t])$

Formulae:

- boolean expression $p \equiv s$:
 $p[u := t] \equiv s[u := t]$
- negation:
 $(\neg q)[u := t] \equiv \neg(q[u := t])$
- conjunction etc.:
 $(q \wedge r)[u := t] \equiv q[u := t] \wedge r[u := t]$

Substitution

The rule ‘**Assignment**’ uses (syntactical) **substitution**: $\{p[u := t]\} u := t \{p\}$

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 $(\neg q)[u := t] \equiv \neg(q[u := t])$
- conjunction etc.:
 $(q \wedge r)[u := t] \equiv q[u := t] \wedge r[u := t]$
- **quantifier**:
 $(\forall x : q)[u := t] \equiv \forall y : q[x := y][u := t]$
 y fresh (not in q, t, u), same type as x .

Substitution

The rule 'Assignment' uses (syntactical) **substitution**: $\{p[u := t]\} u := t \{p\}$

(In formula p , replace all (free) occurrences of (program or logical) variable u by term t .)

Defined as usual, only **indexed** and **bound** variables need to be treated specially:

Expressions:

- plain variable x : $x[u := t] \equiv \begin{cases} t & , \text{ if } x = u \\ x & , \text{ otherwise} \end{cases}$
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 $c[u := t] \equiv c$.
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Formulae:

- **boolean expression** $p \equiv s$:
 $p[u := t] \equiv s[u := t]$
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 $(\neg q)[u := t] \equiv \neg(q[u := t])$
- **conjunction etc.**:
 $(q \wedge r)[u := t]$
 $\equiv q[u := t] \wedge r[u := t]$
- **quantifier**:
 $(\forall x : \tau) q[u := t] \equiv \forall y : \tau. q[x := y][u := t]$
 y fresh (not in q, t, u), same type as x .

- indexed variable**, u plain or $u \equiv b[t_1, \dots, t_m]$ and $a \neq b$:

$$(a[s_1, \dots, s_n])[u := t] \equiv a[s_1[u := t], \dots, s_n[u := t]]$$
- indexed variable**, $u \equiv a[t_1, \dots, t_m]$:

$$(a[s_1, \dots, s_n])[u := t] \equiv (\bigwedge_{i=1}^n s_i[u := t] = t_i ? t : a[s_1[u := t], \dots, s_n[u := t]])$$

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Example Proof Cont'd

$$\begin{array}{c}
\text{(2)} \\
\frac{}{\frac{}{\text{(1)} \quad \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\}, \quad \{P \wedge (b \geq y)\} b := b - y; a := a + 1 \text{ od } \{P \wedge \neg(b \geq y)\}, \quad P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y} \{P \wedge (b \geq y)\} b := b - y; a := a + 1 \text{ od } \{P \wedge \neg(b \geq y)\}, \quad P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y} \text{(R5)} \quad \text{(3)} \\
\frac{}{\{x \geq 0 \wedge y \geq 0\} a := 0; b := x; \text{ while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od } \{a \cdot y + b = x \wedge b < y\}} \text{(R3)}
\end{array}$$

In the following, we show

- $$\begin{aligned} \text{(1)} \quad & \vdash_{PD} \{x \geq 0 \wedge y \geq 0\} a := 0; b := x \{P\}, \\ \text{(2)} \quad & \vdash_{PD} \{P \wedge b \geq y\} b := b - y; a := a + 1 \{P\}, \\ \text{(3)} \quad & \models P \wedge \neg(b \geq y) \rightarrow a \cdot y + b = x \wedge b < y. \end{aligned}$$

As **loop invariant**, we choose (**creative act!**):

$$P \equiv a \cdot y + b = x \wedge b \geq 0$$

$$\begin{array}{lll}
\text{(A1)} \{p\} \text{ skip } \{p\} & \text{(R3)} \frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}} & \text{(R5)} \frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}} \\
\text{(A2)} \{p[u := t]\} u := t \{p\} & \text{(R4)} \frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}} & \text{(R6)} \frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}
\end{array}$$

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Proof of (2)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
(A2) $\{p[u := t]\} u := t \{p\}$	(R5) $\frac{\{p \wedge B\} S \{p\}}{\{p\} \text{ while } B \text{ do } S \text{ od } \{p \wedge \neg B\}}$
(R3) $\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$	(R6) $\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$

- (2) claims:

$$\vdash_{PD} \{P \wedge b \geq y\} b := b - y; a := a + 1 \{P\}$$

where $P \equiv a \cdot y + b = x \wedge b \geq 0$.

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Proof of (2)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
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- (2) claims:

$$\vdash_{PD} \{P \wedge b \geq y\} b := b - y; a := a + 1 \{P\}$$

where $P \equiv a \cdot y + b = x \wedge b \geq 0$.

- $\vdash_{PD} \{(a+1) \cdot y + (b-y) = x \wedge (b-y) \geq 0\} b := b - y \{(a+1) \cdot y + b = x \wedge b \geq 0\}$
by (A2),

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Proof of (2)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
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• $\vdash_{PD} \{(a+1) \cdot y + b = x \wedge b \geq 0\} a := a + 1 \underbrace{\{a \cdot y + b = x \wedge b \geq 0\}}_{\equiv P} \text{ by (A2),}$

Proof of (2)

(A1) $\{p\} \text{ skip } \{p\}$	(R4) $\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
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(R3) $\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$	(R6) $\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$

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by (A2),

• $\vdash_{PD} \{(a+1) \cdot y + b = x \wedge b \geq 0\} a := a + 1 \underbrace{\{a \cdot y + b = x \wedge b \geq 0\}}_{\equiv P} \text{ by (A2),}$

• $\vdash_{PD} \{(a+1) \cdot y + (b-y) = x \wedge (b-y) \geq 0\} b := b - y; a := a + 1 \{P\} \text{ by (R3),}$

Once Again

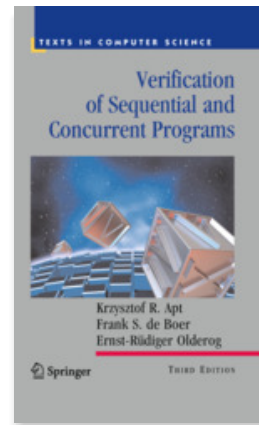
- $P \equiv a \cdot y + b = x \wedge b \geq 0$
 $\{x \geq 0 \wedge y \geq 0\}$
 $\{0 \cdot y + x = x \wedge x \geq 0\}$
- $a := 0;$
 $\{a \cdot y + x = x \wedge x \geq 0\}$
- $b := x;$
 $\{a \cdot y + b = x \wedge b \geq 0\}$
 $\{P\}$
- **while** $b \geq y$ **do**
 $\{P \wedge b \geq y\}$
 $\{(a+1) \cdot y + (b-y) = x \wedge (b-y) \geq 0\}$
- $b := b - y;$
 $\{(a+1) \cdot y + b = x \wedge b \geq 0\}$
- $a := a + 1$
 $\{a \cdot y + b = x \wedge b \geq 0\}$
 $\{P\}$
- **od**
 $\{P \wedge \neg(b \geq y)\}$
 $\{a \cdot y + b = x \wedge b < y\}$

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(A1)	$\{p\} \text{ skip } \{p\}$
(A2)	$\{p[u := t]\} u := t \{p\}$
(R3)	$\frac{\{p\} S_1 \{r\}, \{r\} S_2 \{q\}}{\{p\} S_1; S_2 \{q\}}$
(R4)	$\frac{\{p \wedge B\} S_1 \{q\}, \{p \wedge \neg B\} S_2 \{q\}}{\{p\} \text{ if } B \text{ then } S_1 \text{ else } S_2 \text{ fi } \{q\}}$
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(R6)	$\frac{p \rightarrow p_1, \{p_1\} S \{q_1\}, q_1 \rightarrow q}{\{p\} S \{q\}}$

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Literature Recommendation



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- **Formal Program Verification**
 - **Deterministic Programs**
 - Syntax
 - Semantics
 - Termination, Divergence
 - **Correctness** of deterministic programs
 - partial correctness,
 - total correctness.
 - **Proof System PD**
- **The Verifier for Concurrent C**
 - modular reasoning
 - return values / old values
- **Assertions**

The Verifier for Concurrent C

- The **Verifier for Concurrent C** (VCC) basically implements Hoare-style reasoning.
- **Special syntax:**
 - `#include <vcc.h>`
 - `_(requires p)` — **pre-condition**, *p* is (basically) a C expression
 - `_(ensures q)` — **post-condition**, *q* is (basically) a C expression
 - `_(invariant expr)` — **loop invariant**, *expr* is (basically) a C expression
 - `_(assert p)` — **intermediate invariant**, *p* is (basically) a C expression
 - `_(writes &v)` — VCC considers **concurrent** C programs; we need to declare for each procedure which global variables it is allowed to write to (also checked by VCC)
- **Special expressions:**
 - `\thread_local(&v)` — no other thread writes to variable *v* (in pre-conditions)
 - `\old(v)` — the value of *v* when procedure was called (useful for post-conditions)
 - `\result` — return value of procedure (useful for post-conditions)

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VCC Syntax Example

```

1  #include <vcc.h>
2
3  int a, b;
4
5  void div( int x, int y )
6  _(requires x >= 0 && y >= 0)
7  _(ensures a * y + b == x && b < y)
8  _(writes &a)
9  _(writes &b)
10 {
11     a = 0;
12     b = x;
13     while (b >= y)
14     _(invariant a * y + b == x && b >= 0)
15     {
16         b = b - y;
17         a = a + 1;
18     }
19 }

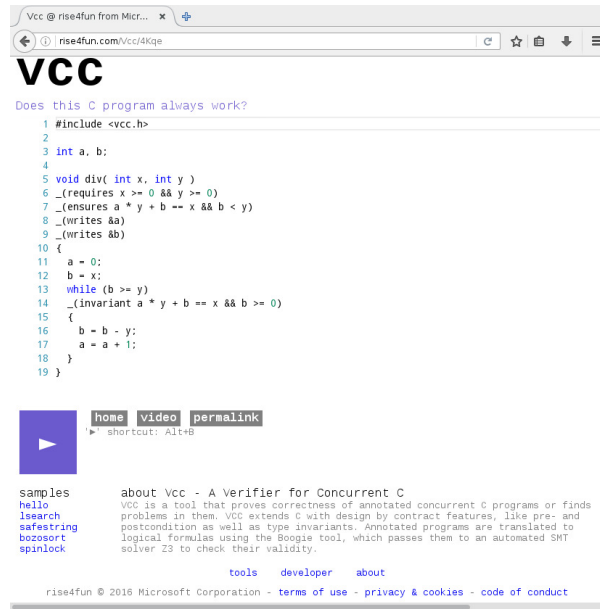
```

$$DIV \equiv a := 0; b := x; \text{ while } b \geq y \text{ do } b := b - y; a := a + 1 \text{ od}$$

$$\{x \geq 0 \wedge y \geq 0\} DIV \{x \geq 0 \wedge y \geq 0\}$$

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Example program *DIV*: <http://rise4fun.com/Vcc/4Kqe>

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Interpretation of Results

- VCC result: **"verification succeeded"**

- VCC result: **"verification failed"**

- Other case: **"timeout"** etc.

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 - under its interpretation of the C-standard, under its platform assumptions (32-bit), etc. —
 - claims that there is a proof for $\models \{p\} \text{ DIV } \{q\}$.

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- Other case: “**timeout**” etc. — completely **inconclusive** outcome.

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 - and many more.

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 - In many cases, we need to provide **loop invariants** manually.
- VCC also supports:
 - **concurrency**:
different threads may write to shared global variables; VCC can check whether concurrent access to shared variables is properly managed;
 - **data structure invariants**:
we may declare invariants that have to hold for, e.g., records (e.g. the length field l is always equal to the length of the string field str); those invariants may **temporarily** be violated when updating the data structure.
 - and much more.

Modular Reasoning

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We can add another rule for calls of functions $f : F$ (simplest case: only global variables):

$$(R7) \frac{\{p\} F \{q\}}{\{p\} f() \{q\}}$$

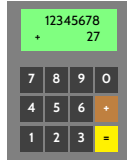
"If we have $\vdash \{p\} F \{q\}$ for the **implementation** of function f ,
then if f is **called** in a state satisfying p , the state after return of f will satisfy q ."

p is called **pre-condition** and q is called **post-condition** of f .

Example: if we have

- $\{true\} \text{read_number} \{0 \leq result < 10^8\}$
- $\{0 \leq x \wedge 0 \leq y\} \text{add} \{(old(x) + old(y) < 10^8 \wedge result = old(x) + old(y)) \vee result < 0\}$
- $\{true\} \text{display} \{(0 \leq old(sum) < 10^8 \implies "old(sum)") \wedge (old(sum) < 0 \implies "-E-")\}$

we may be able to prove our pocket calculator correct.



```
int main() {
    while (true) {
        int x = read_number();
        int y = read_number();
        int sum = add(x, y);
        display(sum);
    }
}
```

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Return Values and Old Values

- For **modular reasoning**, it's often useful to refer in the post-condition to
 - the **return value** as *result*,
 - the **values** of variable x **at calling time** as $old(x)$.

- Can be defined using **auxiliary variables**:

- Transform function

$$T f() \{ \dots; \text{return } expr; \}$$

(over variables $V = \{v_1, \dots, v_n\}$; where $result, v_i^{old} \notin V$) into

$$T f() \{$$

$$v_1^{old} := v_1; \dots; v_n^{old} := v_n;$$

$$\dots;$$

$$result := expr;$$

$$\text{return } result;$$

$$\}$$

over $V' = V \cup \{v^{old} \mid v \in V\} \cup \{result\}$.

- Then $old(x)$ is just an abbreviation for x^{old} .

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Assertions

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Assertions

- Extend the **syntax** of **deterministic programs** by

$$S := \dots \mid \text{assert}(B)$$

- and the **semantics** by rule

$$\langle \text{assert}(B), \sigma \rangle \rightarrow \langle E, \sigma \rangle \text{ if } \sigma \models B.$$

(If the asserted boolean expression B does not hold in state σ , the empty program is not reached; otherwise the assertion remains in the first component: **abnormal** program termination).

Extend PD by axiom:

$$(A7) \{p\} \text{assert}(p) \{p\}$$

- That is, if p holds **before** the assertion, then we can **continue** with the derivation in PD.
If p does not hold, we “**get stuck**” (and cannot complete the derivation).
- So we **cannot** derive $\{true\} x := 0; \text{assert}(x = 27) \{true\}$ in PD.

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Formal Verification:

- **Program verification** is **another approach** to software quality assurance.
- **Proof System PD** can be used
 - to **prove**
 - that a given program is
 - **correct** wrt. its specification.

This approach considers **all inputs** inside the specification!

- Tools like **VCC** implement this approach.

References

References

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