# Formal Methods for Java Lecture 3: Operational Semantics (Part 2)

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# Operational Semantics for Java

#### Idea: define transition system for Java

#### Definition (Transition System)

A transition system (TS) is a structure  $TS = (Q, Act, \rightarrow)$ , where

- Q is a set of states,
- Act a set of actions,
- $\rightarrow \subseteq Q \times Act \times Q$  the transition relation.
- Q reflects the current dynamic state (heap and local variables).
- Act is the executed code.
- Idea from: D. v. Oheimb, T. Nipkow, Machine-checking the Java specification: Proving type-safety, 1999

The state of a Java program gives valuations local and global (heap) variables.

- Q = Heap imes Local
- *Heap* = *Address* → *Class* × seq *Value*
- Local = Identifier  $\rightarrow$  Value
- Value =  $\mathbb{Z}$ , Address  $\subseteq \mathbb{Z}$

A state is denoted as (heap, lcl), where heap : Heap and lcl : Local.

An action of a Java Program is either

- the evaluation of an expression e to a value v, denoted as  $e \triangleright v$ , or
- a Java statement, or
- a Java code block.

Note that expressions with side-effects can modify the current state

## Rules for Java Expressions

axiom for evaluating local variables:

$$(heap, lcl) \xrightarrow{x \triangleright lcl(x)} (heap, lcl)$$

axiom for evaluating constants:

$$(heap, lcl) \xrightarrow{c \triangleright c} (heap, lcl)$$

rule for field access:

 $\frac{(heap, lcl) \xrightarrow{e \triangleright v} (heap', lcl')}{(heap, lcl) \xrightarrow{e.fld \triangleright heap'(v)(idx)} (heap', lcl')},$ where *idx* is the index of the field *fld* in the object *heap'(v)* 

## Rules for Assignment Expressions

rule for assignment to local:

$$\frac{(\textit{heap},\textit{lcl}) \xrightarrow{e \triangleright v} (\textit{heap}',\textit{lcl}')}{(\textit{heap},\textit{lcl}) \xrightarrow{x=e \triangleright v} (\textit{heap}',\textit{lcl}' \oplus \{x \mapsto v\})}$$

rule for assignment to field:

$$\begin{array}{c} (\textit{heap}_1,\textit{lcl}_1) \xrightarrow{e_1 \triangleright v_1} (\textit{heap}_2,\textit{lcl}_2) \\ (\textit{heap}_2,\textit{lcl}_2) \xrightarrow{e_2 \triangleright v_2} (\textit{heap}_3,\textit{lcl}_3) \\ \hline (\textit{heap}_1,\textit{lcl}_1) \xrightarrow{e_1.\textit{fld} = e_2 \triangleright v_2} (\textit{heap}_4,\textit{lcl}_3) \end{array},$$

where  $heap_4 = heap_3 \oplus \{(v_1, id_x) \mapsto v_2\}$  and  $id_x$  is the index of the field *fld* in the object at  $heap_3(v_1)$ .

expression statement (assignment or method call):

$$\frac{(heap, lcl) \xrightarrow{e \triangleright v} (heap', lcl')}{(heap, lcl) \xrightarrow{e} (heap', lcl')}$$

sequence of statements:

$$\frac{(heap_1, lcl_1) \xrightarrow{s_1} (heap_2, lcl_2) \quad (heap_2, lcl_2) \xrightarrow{s_2} (heap_3, lcl_3)}{(heap_1, lcl_1) \xrightarrow{s_1 s_2} (heap_3, lcl_3)}$$

## Rules for Java Statements

if statement:

$$\frac{(heap_1, lcl_1) \xrightarrow{e \triangleright v} (heap_2, lcl_2) \quad (heap_2, lcl_2) \xrightarrow{s_1} (heap_3, lcl_3)}{(heap_1, lcl_1) \xrightarrow{if(e) s_1 elses_2} (heap_3, lcl_3)}, \text{where } v \neq 0$$

$$\frac{(heap_1, lcl_1) \xrightarrow{e \triangleright v} (heap_2, lcl_2) \quad (heap_2, lcl_2) \xrightarrow{s_2} (heap_3, lcl_3)}{(heap_1, lcl_1) \xrightarrow{if(e) s_1 elses_2} (heap_3, lcl_3)}, \text{where } v = 0$$

while statement:

$$\frac{(heap_1, lcl_1) \xrightarrow{if(e) \{s \text{ while}(e) s\}} (heap_2, lcl_2)}{(heap_1, lcl_1) \xrightarrow{while(e) s} (heap_2, lcl_2)}$$

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## Rule for Java Method Call

$$\begin{array}{c} (heap_{1}, lcl_{1}) \xrightarrow{e \triangleright v} (heap_{2}, lcl_{2}) \\ (heap_{2}, lcl_{2}) \xrightarrow{e_{1} \triangleright v_{1}} (heap_{3}, lcl_{3}) \\ \vdots \\ (heap_{n+1}, lcl_{n+1}) \xrightarrow{e_{n} \triangleright v_{n}} (heap_{n+2}, lcl_{n+2}) \\ (heap_{n+2}, mlcl) \xrightarrow{body} (heap_{n+3}, mlcl') \\ \hline (heap_{1}, lcl_{1}) \xrightarrow{e.m(e_{1}, \dots, e_{n}) \triangleright mlcl'(\backslash result)} (heap_{n+3}, lcl_{n+2}) \end{array},$$

where *body* is the body of the method *m* in the object  $heap_{n+2}(v)$ , and  $mlcl = \{this \mapsto v, param_1 \mapsto v_1, \dots, param_n \mapsto v_n\}$  where  $param_1, \dots, param_n$  are the names of the parameters of *m* 

The value  $\$  result is written by the return statement using the rule

$$\frac{(heap_1, lcl_1) \xrightarrow{e \triangleright v} (heap_2, lcl_2)}{(heap_1, lcl_1) \xrightarrow{return e} (heap_2, lcl_2 \oplus \{ \backslash result \mapsto v \})}$$

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## Example: Method Call

```
public class C
public int factorial(int n) {
    if (n == 0)
        return 1;
    else
        return n * this.factorial(n-1);
}
```

Start state: (h, I), where I(this) is an object of class C

We show

$$(h, l) \xrightarrow{this.factorial(0) \triangleright 1} (h, l)$$

## Example: Method Call

Let 
$$ml = \{this \mapsto l(this), n \mapsto 0\}$$
. Then,  

$$\frac{(h, ml) \xrightarrow{n \ge 0} (h, ml)}{(h, ml) \xrightarrow{0 \ge 0} (h, ml)} \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, ml) \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, ml) \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, ml) \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, ml) \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, ml) \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, ml) \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, l) \xrightarrow{(h, ml) \xrightarrow{1 \ge 1} (h, ml)} (h, l) \xrightarrow{(h, ml) \xrightarrow{1 \le 1} (h, ml)} (h, l) \xrightarrow{(h, ml) \xrightarrow{1 \le 1} (h, ml)} (h, l) \xrightarrow{(h, ml) \xrightarrow{1 \le 1} (h, ml)} (h, l) \xrightarrow{(h, ml) \xrightarrow{1 \le 1} (h, ml)} (h, l) \xrightarrow{(h, ml) \xrightarrow{1 \le 1} (h, ml)} (h, l) \xrightarrow{(h, ml) \xrightarrow{1 \le 1} (h, ml)} (h, l)} (h, l)$$

## Example: Method Call (general proof)

We can even show by induction that for  $ml(n) \ge 0$ 

$$(h, ml) \xrightarrow{\text{if } (n==0) \dots} (h, ml \oplus \{ \setminus result \mapsto (ml(n)! \mod 2^{32}) \})$$

Proof by induction over ml(n). Base case ml(n) = 0 was already shown. Assume n > 0. Induction hypothesis: if ml'(n) = ml(n) - 1, then

$$(h, ml') \xrightarrow{if (n==0) \dots} (h, ml' \oplus \{ \backslash result \mapsto ((ml(n) - 1)! \mod 2^{32}) \})$$
 (IH)

We first show that

$$(h, ml) \xrightarrow{this.factorial(n-1) \triangleright (ml(n)-1)! \mod 2^{32}} (h, ml)$$

Proof tree:

$$\frac{(h,ml) \xrightarrow{h \gg ml(this)} (h,ml)}{(h,ml) \xrightarrow{(h,ml) \xrightarrow{n \ge ml(n)} (h,ml)} (h,ml)} (H)}$$
$$\frac{(h,ml) \xrightarrow{(h,ml) \xrightarrow{1 \ge 1} (h,ml)} (H)}{(h,ml) \xrightarrow{(his.factorial(n-1) \ge (ml(n)-1)! \mod 2^{32}} (h,ml)} (H)$$

## Example: Method Call (general proof, cont.)

Now we can prove the return statement correct.

$$\frac{(h, ml) \xrightarrow{n \triangleright ml(n)} (h, ml) \quad (*)}{(h, ml) \xrightarrow{n*this.factorial(n-1) \triangleright (ml(n)! \mod 2^{32})} (h, ml)}$$
$$(h, ml) \xrightarrow{return \ n*this.factorial(n-1);} (h, ml \oplus \{\backslash result \mapsto (ml(n)! \mod 2^{32}\}) \ (**)$$

Finally, prove the whole method body.

$$\frac{(h,ml) \xrightarrow{n \triangleright ml(n)} (h,ml) (h,ml) \xrightarrow{0 \triangleright 0} (h,ml)}{(h,ml) \xrightarrow{n==0 \triangleright 0} (h,ml)} (**)$$

$$(h,ml) \xrightarrow{if (n==0) \dots} (h,ml \oplus \{ \setminus result \mapsto 1 \})$$

Creating an Object is always combined with the call of a constructor:

$$\begin{array}{l} heap_{1} = heap \cup \{na \mapsto (Type, \langle 0, \dots, 0 \rangle) \\ \hline (heap_{1}, lcl) \xrightarrow{na. < \texttt{init} > (e_{1}, \dots, e_{n}) \triangleright v} (heap', lcl') \\ \hline (heap, lcl) \xrightarrow{\texttt{new } Type(e_{1}, \dots, e_{n}) \triangleright na} (heap', lcl') \end{array}, \text{ where } na \notin \texttt{dom } heap$$

Here <init> stands for the internal name of the constructor.

## Exceptions and Control Flow

To handle exceptions a few changes are necessary:

- We extend the state by a flow component:
  - Q = Flow imes Heap imes Local
- Flow ::= Norm|Ret|Exc((Address))

We use the identifiers  $flow \in Flow$ ,  $heap \in Heap$  and  $lcl \in Local$  in the rules. Also  $q \in Q$  stands for an arbitrary state.

The following axioms state that in an abnormal state statements are not executed:

(flow, heap, lcl)  $\xrightarrow{e \triangleright v}$  (flow, heap, lcl), where flow  $\neq$  Norm

(flow, heap, lcl)  $\xrightarrow{s}$  (flow, heap, lcl), where flow  $\neq$  Norm

## Expressions With Exceptions

The previously defined rules are valid only if the left-hand-state is not an exception state.

$$\frac{(Norm, heap, lcl) \xrightarrow{e_1 \triangleright v_1} q \quad q \xrightarrow{e_2 \triangleright v_2} q'}{(Norm, heap, lcl) \xrightarrow{e_1 \ast e_2 \triangleright (v_1 \cdot v_2) \mod 2^{32}} q'}$$
$$\frac{(Norm, heap, lcl) \xrightarrow{st_1} q \quad q \xrightarrow{st_2} q'}{(Norm, heap, lcl) \xrightarrow{st_1; st_2} q'}$$
$$\frac{(Norm, heap, lcl) \xrightarrow{e \triangleright v} q \quad q \xrightarrow{s_1} q'}{(Norm, heap, lcl) \xrightarrow{if(e) s_1 elses_2} q'}, \text{ where } v \neq 0$$

Note that exceptions are propagated using the axiom from the last slide.  $(flow, heap, lcl) \xrightarrow{e \triangleright v} (flow, heap, lcl), \text{ where } flow \neq Norm$ 

## Throwing Exceptions

$$\frac{(Norm, heap, lcl) \xrightarrow{e \triangleright v} (Norm, heap', lcl')}{(Norm, heap, lcl) \xrightarrow{\text{throw } e;} (Exc(v), heap', lcl')}$$

What happens if in a field access the object is null?

$$(Norm, heap, lcl) \xrightarrow{e \triangleright 0} q'$$

$$q' \xrightarrow{\text{throw new NullPointerException}()} q''$$

$$(Norm, heap, lcl) \xrightarrow{e.fld \triangleright v} q''$$
, where v is some arbitrary value

#### Complete Rules for throw

$$\frac{(Norm, heap, lcl) \xrightarrow{e \triangleright v} (Norm, heap', lcl')}{(Norm, heap, lcl) \xrightarrow{\text{throw } e_i} (Exc(v), heap', lcl')}, \text{ where } v \neq 0$$

$$\frac{(Norm, heap, lcl) \xrightarrow{e \triangleright 0} q'}{(Norm, heap, lcl) \xrightarrow{e \triangleright 0} q''}$$

$$\frac{q' \xrightarrow{\text{throw new NullPointerException}()}{(Norm, heap, lcl) \xrightarrow{\text{throw } e_i} q''}$$

 $\frac{(Norm, heap, lcl) \xrightarrow{e \triangleright v} (flow', heap', lcl')}{(Norm, heap, lcl) \xrightarrow{\text{throw } e;} (flow', heap', lcl')}, \text{ where } flow' \neq Norm$ 

## Catching Exceptions

#### Catching an exception:

$$\begin{array}{l} (Norm, heap, lcl) \xrightarrow{s_1} (Exc(v), heap', lcl') \\ (Norm, heap', lcl' \cup \{ex \mapsto v\}) \xrightarrow{s_2} q'' \\ \hline (Norm, heap, lcl) \xrightarrow{\operatorname{try} s_1 \operatorname{catch}(Type \ ex)s_2} q'' \end{array}, \text{ where } v \text{ is an instance of } Type \\ \end{array}$$

No exception caught:

$$\frac{(Norm, h, l) \xrightarrow{s_1} (flow', h', l')}{(Norm, h, l) \xrightarrow{\text{try } s_1 \text{catch}(Type \ ex) s_2} (flow', h', l')}, \begin{array}{c} \text{where flow is not} \\ Exc(v) & \text{or } v & \text{is} \\ \text{not an instance of} \\ Type \end{array}$$

whore flow' is not

Return statement stores the value and signals the Ret in flow component:

$$\frac{(\textit{Norm}, \textit{heap}, \textit{lcl}) \xrightarrow{e \triangleright v} (\textit{Norm}, \textit{heap'}, \textit{lcl'})}{(\textit{Norm}, \textit{heap}, \textit{lcl}) \xrightarrow{return e} (\textit{Ret}, \textit{heap'}, \textit{lcl'} \oplus \{ \backslash \textit{result} \mapsto v \})}$$

But evaluating *e* can also throw exception:

$$\frac{(Norm, heap, lcl) \xrightarrow{e \triangleright \vee} (flow, heap', lcl')}{(Norm, heap, lcl) \xrightarrow{return e} (flow, heap', lcl')}, \text{ where } flow \neq Norm$$

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# Method Call (Normal Case)

$$(Norm, h_{1}, l_{1}) \xrightarrow{e \triangleright v} q_{2}$$

$$q_{2} \xrightarrow{e_{1} \triangleright v_{1}} q_{3}$$

$$\vdots$$

$$q_{n+1} \xrightarrow{e_{n} \triangleright v_{n}} (f_{n+2}, h_{n+2}, l_{n+2})$$

$$(f_{n+2}, h_{n+2}, ml) \xrightarrow{body} (Ret, h_{n+3}, ml')$$

$$(Norm, h_{1}, l_{1}) \xrightarrow{e.m(e_{1}, \dots, e_{n}) \triangleright ml'(\backslash result)} (Norm, heap_{n+3}, l_{n+2}),$$
The param\_{1}, ..., param\_{n} are the names of the parameters and body is

where  $param_1, \ldots, param_n$  are the names of the parameters and *body* is the body of the method *m* in the object  $heap_{n+2}(v)$ , and  $ml = \{this \mapsto v, param_1 \mapsto v_1, \ldots, param_n \mapsto v_n\}$ 

## Method Call With Exception

$$\begin{array}{c} (Norm, h_{1}, l_{1}) \xrightarrow{e \triangleright v} q_{2} \\ q_{2} \xrightarrow{e_{1} \triangleright v_{1}} q_{3} \\ \vdots \\ q_{n+1} \xrightarrow{e_{n} \triangleright v_{n}} (f_{n+2}, h_{n+2}, l_{n+2}) \\ (f_{n+2}, h_{n+2}, ml) \xrightarrow{body} (Exc(v_{e}), h_{n+3}, ml') \\ \hline (Norm, h_{1}, l_{1}) \xrightarrow{e.m(e_{1}, \dots, e_{n}) \triangleright ml'(\backslash result)} (Exc(v_{e}), heap_{n+3}, l_{n+2}) \end{array},$$
where  $param_{1}, \dots, param_{n}$  are the names of the parameters and  $body$  is the body of the method  $m$  in the object  $heap_{n+2}(v)$ , and
 $ml = \{this \mapsto v, param_{1} \mapsto v_{1}, \dots, param_{n} \mapsto v_{n}\}$