

Graph

Object Diagrams

- Definition. A node-labelled graph is a triple $G = (N, E, f)$
- consisting of
 - vertices N ,
 - edges E ,
 - node labelling $f : N \rightarrow X$, where X is some label domain,

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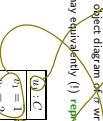
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$$\begin{aligned} \mathcal{G} &= \left\{ g_{m,n} \mid m \in \text{"participants"}, n \in \text{"participants"}, \right. \\ &\quad \left. g_{m,n} = \frac{1}{2} \cdot \text{min}(m, n) \right\}, \\ \mathcal{S}_0 &= \left\{ s_0 \mid s_0 = \frac{1}{2} \cdot \text{min}(m, n), \right. \\ &\quad \left. m, n \in \{1, 2, \dots, 25\} \right\}, \\ \text{Size} &= 125, \\ \text{Participants} &= 25, \\ \text{Participants} \times \text{Participants} &= \{s_{m,n} \mid \\ &\quad m, n \in \{1, 2, \dots, 25\}\}, \\ \mathcal{E} &= \left\{ e_{m,n} \mid \begin{array}{l} m, n \in \{1, 2, \dots, 25\}, \\ (m, n) \in \text{Participants} \times \text{Participants} \end{array} \right\}, \\ f &= \left\{ f_{m,n} \mid \begin{array}{l} m, n \in \{1, 2, \dots, 25\}, \\ (m, n) \in \text{Participants} \times \text{Participants} \end{array} \right\}, \\ \mathcal{S}_m &= \left\{ s_m \mid s_m = \frac{1}{2} \cdot \text{min}(m, n), \right. \\ &\quad \left. n \in \{1, 2, \dots, 25\} \right\}, \\ \mathcal{N} &= \left\{ n_{m,n} \mid m \in \text{"participants"}, n \in \text{"participants"}, \right. \\ &\quad \left. n_{m,n} = \frac{1}{2} \cdot \text{min}(m, n) \right\}, \end{aligned}$$

(N, E, f)

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- Assume: $\mathcal{S} = \{(Int, \cdot), (C, \cdot), (C \rightarrow \{\langle v_1, v_2, r \rangle\})\}$
- Consider $\sigma = \{\langle v_1 \mapsto 1, v_2 \mapsto 2, r \mapsto \langle 2, 1 \rangle \}, q_2 \mapsto \{v_1 \mapsto 3, v_2 \mapsto 4, r \mapsto \emptyset\}\}$
- Then $\bar{G} = (N, E, f)$
 $= (\{v_1, v_2\}, \{\langle v_1, r, v_2 \rangle\}, \{q_1 \mapsto \{v_1 \mapsto 1, v_2 \mapsto 2\}, q_2 \mapsto \{v_1 \mapsto 3, v_2 \mapsto 4\}\})$
is an object diagram of \mathcal{S} wrt. \mathcal{F} and any \mathcal{B} with $\mathcal{B}(Int) = \{1, 2, 3, 4\}$.
- We may equivalently (1) represent G graphically as follows:


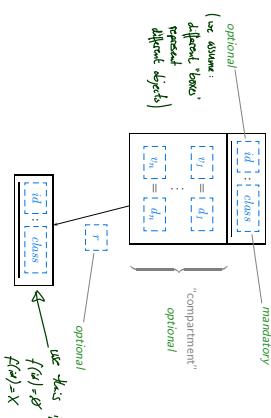
(2) \mathcal{B} ascription

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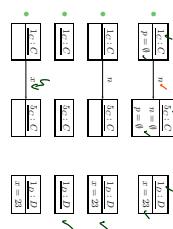
UML Notation for Object Diagrams



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$N \subset \mathcal{D}(\mathcal{G})$ finite, $E \subset N \times \mathbb{N}_{0,1,*}^{\infty} \times N$, $X = \{X\} \subseteq V \rightsquigarrow (\mathcal{D}(\mathcal{P}) \cup \mathcal{D}(\mathcal{G}))$
 $u_1 \in \text{dom}(r) \wedge u_2 \in \sigma(u_1)(r)$, $f(u) \subseteq \sigma(u)$ or $f(u) = \{X\}$

$$\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{\underline{5}_C\}\}, \underline{5}_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}$$



Complete vs. Partial Object Diagram

Definition. Let $G = (N, E, f)$ be an object diagram of system state $\sigma \in \Sigma_{\mathcal{G}}$. We call G **complete wrt.** σ if and only if

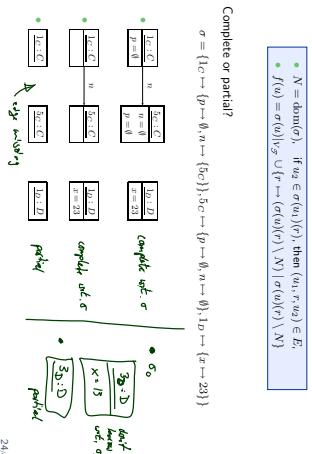
- G consists of all alive objects, i.e. $N = \text{dom}(\sigma)$.
 - G is **complete**, i.e.
 - G comprises all “links” between alive objects, i.e. if $u_0 \in \sigma(u_1)(\tau)$ for some $u_1, u_2 \in \text{dom}(\sigma)$ and $\tau \in V$, then $(u_1, u_2, \tau) \in E$, and
 - each node is labelled with the values of all τ -typed attributes, i.e. for each $u \in \text{dom}(\sigma)$,
$$f(u) \supseteq \sigma(u)(\tau_S \cup \{\sigma(u)(\tau)N \mid \tau \in V : \sigma(u)(\tau)N \neq \emptyset\})$$

where $V, \tau := v : \tau \in V \mid \tau \in \mathcal{T}$.

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Complete vs. Partial Examples

Complete or partial?



Complete/Partial is Relative

- Each finite system state has **exactly one complete** object diagram.
 - A finite system state can have **many partial** object diagrams.
 - Each object diagram G represents a set of system states, namely
$$G^{-1} := \{\sigma \in \mathcal{D} \mid G \text{ is an object diagram of } \sigma\}$$
 - **Observation:** If somebody tells us, that a given (consistent) object diagram G is **complete**, we can uniquely reconstruct the corresponding system state.
 - In other words: G^{-1} is then a singleton.

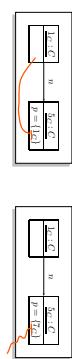
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Corner Cases

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Closed Object Diagrams vs. Dangling References

Find the 10 differences! (Both diagrams shall be completed)



Definition. Let σ be a system state. We say attribute $v \in V_{\sigma, \text{int}}$ has a **dangling reference** in object $u \in \text{dom}(\sigma)$ and if the attribute's value comprises an object which is not alive in σ , i.e. if

$$\sigma(u).v \notin \text{dom}(\sigma).$$

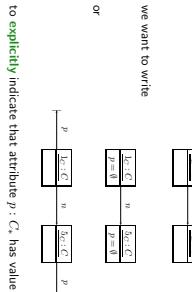
We call σ **closed** if and only if no attribute has a dangling reference in any object alive in σ .

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Special Notation

- $\mathcal{I} = \{\text{Int}\}, \{C\}, \{n, p : C_*\}, \{C \mapsto \{n, p\}\}$.

• Instead of



to explicitly indicate that attribute $p : C_*$ has value \emptyset (also for $p : C_{0,1}$)

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Aftersmath

We slightly deviate from the standard (for reasons):

- In the course, $C_{0,1}$ and C_* -typed attributes **only** have sets as values.



(This is not an object diagram in the sense of our definition because of the requirement on the edges E . Extension is straightforward but tedious.)

- We allow to give the valuation of $C_{0,1}$, or C_* -typed attributes in the values compartment.
- Allows us to indicate that a certain n is not referring to another object.
- Allows us to represent ‘dangling references’, i.e. references to objects which are not alive in the current system state.

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- We introduce a graphical representation of \emptyset values.

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References

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