Software Design, Modelling and Analysis in UML

Lecture 19: Live Sequence Charts III

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Contents & Goals

- This Lecture:
- Educational Objectives: Capabilities for following tasks/questions.
 What does this LSC mean?
 Are this UML model's sate machines consistent with the interactions?
 Please provide a UML model which is consistent with this LSC.
 What is: activation, hot/cold condition, pre-chart, etc.?

- LSC abstract syntax.
 LSC formal semantics.

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UML

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Mathematics

Course Map

- Last Lecture:

 Symbolic Blichi Automata (TBA) and its (accepted) language.

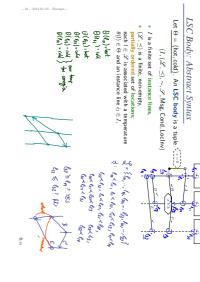
 Words of a model.

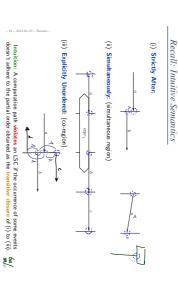
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Let $\Theta = \{\text{hot, cold}\}$. An **LSC body** is a tuple $\{\underbrace{v=0}_{v=0}\}$ LSC Body: Abstract Syntax I is a finite set of instance lines, $(I,(\mathcal{L},\preceq),\sim,\mathcal{S},\mathsf{Msg},\mathsf{Cond},\mathsf{Lodnv})$ 1. 10. 1. 10. 10. 10. 10. 11. $T=\{i_1,i_2,i_3\}$

Live Sequence Charts Abstract Syntax

Example





Let $\Theta = \{\text{hot, cold}\}$. An **LSC body** is a tuple $\{\underbrace{v=0}_{v=0}\}$

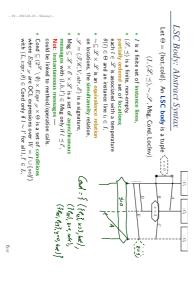
 $(I,(\mathcal{L},\preceq),\sim,\mathcal{S},\mathsf{Msg},\mathsf{Cond},\mathsf{LocInv})$

• (\mathscr{L}, \preceq) is a finite, non-empty, partially ordered set of locations; each $l \in \mathscr{L}$ is associated with a temperature $\theta(l) \in \Theta$ and an instance line $i_l \in I$,

I is a finite set of instance lines,

• $\sim\subseteq\mathcal{L}\times\mathcal{L}$ is an equivalence relation on locations, the simultaneity relation,

LSC Body: Abstract Syntax



LSC Body: Abstract Syntax

Let $\Theta = \{\text{hot, cold}\}$. An LSC body is a tuple $\{\frac{n-n}{n-n}\}$

 $(I,(\mathcal{L},\preceq),\sim,\mathcal{S},\mathsf{Msg},\mathsf{Cond},\mathsf{LocInv})$

• (\mathscr{L},\preceq) is a finite, non-empty, partially ordered set of locations; each $l\in\mathscr{L}$ is associated with a temperature $\theta(l)\in\Theta$ and an instance line $i_l\in I$.

 $\log : \{ (a_n, A, c_n),$

I is a finite set of instance lines,

• Msg $\subseteq \mathcal{Z} \times \mathcal{E} \times \mathcal{Z}$ is a set of asynchronous messages with $(l,b,l') \in \mathsf{Msg}$ only if $l \not \prec l'$.

Not: instantaneous messages — could be linked to method/operation calls.

• $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr, \mathcal{E})$ is a signature,

 $(c_0, 3, c_{n'}), (c_2, 0, c_{n'}), (c_3, 0, c_{n'}), (c_2, 0, c_{n'}), (c_n, \varepsilon, c_n)$

 $\sim\subseteq\mathcal{L}\times\mathcal{L}$ is an equivalence relation on locations, the simultaneity relation,

LSC Body: Abstract Syntax Let $\Theta = \{ \text{hot, cold} \}$. An LSC body is a tuple $\langle \neg \neg \neg \rangle$ and $\langle \neg \neg \neg \rangle$ a finite set of instance lines, $\langle \mathscr{L}, \preceq \rangle$ is a finite non-empty.

Partially ordered set of locations, each $l \in \mathscr{L}$ is associated with a temperature $\langle \mathscr{L}, \preceq \rangle$ is an equivalence relation on locations, the simultaneity relation.

 $a(t)\in\Theta$ and an instance line $t\in I$. $a=c_0(t)$ an equivalence relation on locations, the simultaneity relation, $a=c_0(t)$ ($a=c_0(t)$, $a=c_0(t)$) is a signature. As $a=c_0(t)$, $a=c_0(t)$, $a=c_0(t)$ is a set of asynchronous messages with $(a,b,t')\in Mog$ only $a=c_0(t)$. Not: instantaneous messages—could be infeet to method/operation calls. $a=c_0(t)$ ($a=c_0(t)$) $a=c_0(t)$ ($a=c_0(t)$) $a=c_0(t)$ and $a=c_0(t)$ $a=c_0(t)$ $a=c_0(t)$ $a=c_0(t)$ $a=c_0(t)$ with $a=c_0(t)$ $a=c_0(t)$ a

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 $\bullet \ \, \mathsf{LocInv} \subseteq \mathscr{L} \times \{ \diamond, \bullet \} \times \mathit{Expr}_{\mathscr{S}} \times \Theta \times \mathscr{L} \times \{ \diamond, \bullet \} \\ \mathsf{is a set of local invariants},$

Well-Formedness

Note: if messages in a chart are cyclic, then there doesn't exist a partial order (so such charts don't even have an abstract syntax). Bondedness/no floating conditions: (could be relaxed a little if we wanted to) then there is a location l' equivalent to l, i.e. $l \sim l'$, which is the location of an instance head, i.e. l' is minimal wrt. △, or $\exists (l_1,b,l_2) \in \mathsf{Msg} : l \in \{l_1,l_2\}.$

TBA-based Semantics of LSCs

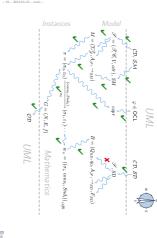
- Given an LSC ${\cal L}$ with body $(I,(\mathcal{L},\preceq),\sim,\mathcal{S},\mathsf{Msg},\mathsf{Cond},\mathsf{LocInv}),$

* construct a TBA \mathcal{B}_L , and * define $\mathcal{L}(L)$ in terms of $\mathcal{L}(\mathcal{B}_L)$. in particular taking activation condition and activation mode into construct.

• Then $\mathcal{M} \models L$ (universal) if and only if $\mathcal{L}(\mathcal{M}) \subseteq \mathcal{L}(L)$.

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Course Map



Formal LSC Semantics: It's in the Cuts!

Definition. Let $(I,(\mathscr{L},\preceq),\sim,\mathscr{S},\operatorname{Msg.}\mathsf{Cond},\operatorname{Locliny})$ be an LSC body. A non-empty set $\emptyset \neq C \subseteq \mathscr{L}$ is called a cut of the LSC body iff it is closed under simultaneity, i.e. it is downward closed, i.e. $\forall l,l':l'\in C\land l\preceq l'\implies l\in C,$

Otherwise, C is called **cold**, denoted by $\theta(C) = \operatorname{cold}$. $\exists l \in C : \theta(l) = \text{hot } \land \nexists l' \in C : l \prec l'$ A cut C is called **hot**, denoted by $\theta(C)=$ hot, if and only if at least one of its maximal elements is hot, i.e. if

it comprises at least one location per instance line, i.e.

 $\forall\,i\in I\;\exists\,l\in C:i_l=i.$

 $\forall l,l':l'\in C\wedge l\sim l'\implies l\in C, \text{ and }$

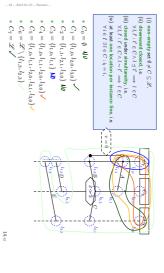
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Live Sequence Charts Semantics

Examples: Cut or Not Cut? Hot/Cold?

A Successor Relation on Cuts



The partial order of (\mathcal{L},\preceq) and the simultaneity relation " \sim " induce a direct successor relation on cuts of $\mathcal L$ as follows: Definition. Let $C,C'\subseteq\mathscr{L}$ bet cuts of an LSC body with locations (\mathscr{L}_{-C}) and messages Mg. (\mathscr{L}_{-C}) and messages successor of C via fired-set F, denoted by C'=F C' is fand only if * $C'\setminus C=F,$ * for each message reception in F, the corresponding sending is already in C,

locations in F, that lie on the same instance line, are pairwise

 $\forall (l,E,l') \in \mathsf{Msg}: l' \in F \implies l \in C \text{, and}$

 $\forall \, l,l' \in F : l \neq l' \wedge i_l = i_{l'} \implies l \not \preceq l' \wedge l' \not \preceq l$

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Idea: Accept Timed Words by Advancing the Cut

• Let $w=(\sigma_0,cons_0,Snd_0),(\sigma_1,cons_1,Snd_1),(\sigma_2,cons_2,Snd_2),\dots$ be a word of a UML model and β a valuation of $I\cup\{self\}.$

$$\begin{split} \text{(i)} \ F \neq \emptyset, \quad \text{(ii)} \ C' \backslash C = F, \\ \text{(ii)} \ \forall (l, E, l') \in \operatorname{Msg}: l' \in F \implies l \in C, \text{and} \\ \text{(iv)} \ \forall l, l' \in F: l \neq l' \land i_l = i_l \implies l \not\preceq l' \land l' \not\preceq l \end{split}$$
Successor Cut Examples

an LSC body $(I,(\mathcal{L},\preceq),\sim,\mathcal{S},\mathrm{Msg},\mathrm{Cond},\mathrm{LocInv})$ is supposed to accept w if and only if there exists a sequence Intuitively (and for now disregarding cold conditions),

 $C_0 \leadsto_{F_1} C_1 \leadsto_{F_2} C_2 \cdots \leadsto_{F_n} C_n$

and indices $0 = i_0 < i_1 < \cdots < i_n$ such that for all $0 \le j < n$,

• for all $i_n < k$, $(\sigma_k, cons_{i_j}, Snd_{i_j})$, β satisfies the hold condition of C_n . C_n is cold, • for all $i_j \le k < i_{j+1}$, $(\sigma_k, cons_k, Snd_k)$, β satisfies the hold condition of C_j , • $(\sigma_{i_j}, cons_{i_j}, Snd_{i_j}), \beta$ • attisfies the transition condition of F_j , $\checkmark v=0$

Properties of the Fired-set

 $C \leadsto_F C'$ if and only if $F \neq \emptyset$, $\begin{array}{ll} \circ & C' \setminus C = F, \\ \circ & \forall (l, E, l') \in \mathsf{Msg}: l' \in F \implies l \in C, \text{ and} \\ \circ & \forall l, l' \in F: l \neq l' \land i_l = i_{l'} \implies l \not\succeq l' \land l' \not\succeq l \end{array}$

- Note: F is closed under simultaneity.
- Note: locations in F are direct ≤-successors of locations in C, i.e.

 $\forall\,l'\in F\;\exists\,l\in C:l\prec l'\wedge \nexists l''\in C:l'\prec l''\prec l$

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Examples: Semantics

Language of LSC Body

The language of the body

 $(I,(\mathscr{L},\preceq),\sim,\mathscr{S},\mathsf{Msg},\mathsf{Cond},\mathsf{LocInv})$

of LSC ${\cal L}$ is the language of the TBA

 $\mathcal{B}_L = (Eapr_{\mathcal{B}}(X), X, Q, q_{ini}, \rightarrow, Q_F)$

$$\operatorname{Sapr}_{\mathcal{B}}(X) = \operatorname{Expr}_{\mathscr{S}}(\mathscr{S}, X)$$

- $\bullet \ Expr_{\mathcal{B}}(X) = Expr_{\mathscr{S}}(\mathscr{S},X)$
- * Q is the set of cuts of (\mathscr{L},\preceq) , q_{ini} is the instance heads cut, * $F=\{C\in Q\mid \theta(C)=\operatorname{cold}\}$ is the set of cold cuts of (\mathscr{L},\preceq) , * \longrightarrow as defined in the following, consisting of
- progress transitions (q, ψ, q') corresponding to $q \leadsto_F q'$, and loops (q, ψ, q),
- legal exits (q, ψ, ℒ).

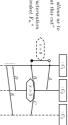
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Language of LSC Body: Intuition

$$\begin{split} \mathcal{B}_L &= (Expr_B(X), X, Q, q_{ini}, \rightarrow, Q_F) \text{ with} \\ & \bullet \ Expr_B(X) = Expr_{\mathscr{S}}(\mathscr{S}, X) \end{split}$$

- Q is the set of cuts of (\mathcal{L}, \preceq) , q_{ini} is the instance heads cut,
- $F = \{C \in Q \mid \theta(C) = \operatorname{cold}\}$ is the set of cold cuts,

- loops (q,ψ,q) . progress transitions (q,ψ,q') corresponding to $q\leadsto_F q'$, and legal exits (q,ψ,\mathscr{L}) .



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Some Helper Functions

Message-expressions of a location:

 $\mathcal{E}(l) := \{E_{i_l,i_{l'}}^l \mid (l,E,l') \in \mathsf{Msg}\} \cup \{E_{i_l,i_l}^l \mid (l',E,l) \in \mathsf{Msg}\},$

 $\mathcal{E}(\{l_1,\ldots,l_n\}) := \mathcal{E}(l_1) \cup \cdots \cup \mathcal{E}(l_n).$

 $\bigvee \emptyset := \mathit{true}_i \bigvee \{E_{1_{i_1,i_{12}}}^1, \dots F_{k_{k_{k_1,i_{k_2}}}}^2, \dots\} := \bigvee_{1 \leq j < k} E_{i_{i_1i_1i_2}}^j \vee \bigvee_{k \leq j} F_{j_{i_1,i_{i_2}}}^2$

- How long may we legally stay at a cut q?
- Intuition: those $(\sigma_i, cons_i, Snd_i)$ are allowed to fire the self-loop (q, ψ, q) where
- cons_i ∪ Snd_i comprises only irrelevant messages:
 weak mode:
- no message from a direct successor cut is in, e strict mode:
 no message occurring in the LSC is in,
- And nothing else.
- Formally: Let F := F₁ ∪···∪F_n be the union of the firedsets of q.

 $\mathcal{E}(\ell) = \left\{ \frac{g_{i,i}}{w_{i+1}}, \frac{g_{i+1}}{w_{i}} \right\}$

 $\psi := \neg (\bigvee \mathscr{E}(F))$ $=_{\mathsf{true}} \ \mathscr{E}(F))$

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Step I: Only Messages

Progress

- When do we move from q to q'?
- Intuition: those $(\sigma_i, cons_i, Snd_i)$ fire the progress transition (q, ψ, q') for which there exists a firedset F such that $q \sim_F q'$ and
- e $cons_i \cup Snd_i$ comprises exactly the messages that distinguish F from other friedests of q (weak mode), and in addition no message occurring in the LSC is in $cons_i \cup Snd_i$ (strict mode).

Progress

- When do we move from q to q'?
- Intuition: those $(\sigma_1, cons_1, Snd_1)$ fire the progress transition (q, ψ, q) for which there exists a findset F such that $q \leadsto_F q$ and F are F and F and F and F are F are F and F are F and F are F and F are F and F are F are F and F are F are F and F are F and F are F are F and F are F and F are F are F are F are F and F are F and F are F and F are F are F are F are
- cons. U Snd, comprises exactly the messages that distinguish F from other firedests of q (weak mode), and in addition no message occurring in the LSC is in cons. U Snd, (strict mode).
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- Formally: Let $F_1 F_1, \dots, F_n$ be the firedests of q and let $q \leadsto_F q'$ (unique). $\psi := \bigwedge \mathcal{E}(F) \land \lnot(\bigvee (\mathcal{E}(F_1) \cup \dots \cup \mathcal{E}(F_n)) \setminus \mathcal{E}(F))$,

Step II: Conditions and Local Invariants

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Even More Helper Functions

Loops with Conditions

• How long may we legally stay at a cut q?

Intuition: those $(\sigma_i, cons_i, Snd_i)$ are allowed to fire the self-loop (q, ψ, q) where

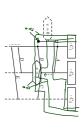
 $cons_t \cup Snd_t$ comprises only irrelevant messages: • weak mode:

Constraints relevant when moving from q to cut q':

 $\psi_{\theta}(q,q') = \{\psi \mid \exists \, L \subseteq \mathscr{L} \mid (L,\psi,\theta) \in \mathsf{Cond} \land L \cap (q' \setminus q) \neq \emptyset \}$

 $\cup \{\psi \mid \exists \, l \in q' \setminus q, l' \in \mathcal{L} \mid (l, \bullet, expr, \theta, l') \in \mathsf{LocInv} \vee (l', expr, \theta, \bullet, l) \in \mathsf{LocInv} \}$ $\backslash \ \{\psi \mid \exists \ l \in q' \setminus q, l' \in \mathscr{L} \mid (l, \diamond, expr, \theta, l') \in \mathsf{LocInv} \ \lor (l', expr, \theta, \diamond, l) \in \mathsf{LocInv} \}$

 $\psi(q,q')=\psi_{\mathrm{hot}}(q,q')\cup\psi_{\mathrm{cold}}(q,q')$



• Formally: Let $F:=F_1\cup\cdots\cup F_n$ be the union of the firedsets of q.

 $\bullet \ \psi := \neg (\bigvee \mathscr{E}(F)) \wedge \bigwedge \mathscr{V}(\mathbf{f})$

And nothing else.

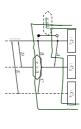
no message from a direct successor cut is in, e strict mode:
no message occurring in the LSC is in,
or; Sattics that local injuniment retiract at g

Some More Helper Functions

Constraints relevant at cut q:

 $\psi_{\theta}(q) = \{\psi \mid \exists \, l \in q, l' \not\in q \mid (l, \psi, \theta, l') \in \mathsf{LocInv} \lor (l', \psi, \theta, l) \in \mathsf{LocInv}\},$ $\psi(q) = \psi_{\text{hot}}(q) \cup \psi_{\text{cold}}(q)$

 $\bigwedge \emptyset := \mathit{false}; \quad \bigwedge \{ \psi_1, \dots, \psi_n \} := \bigwedge_{1 \leq i \leq n} \psi_i$



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Progress with Conditions

- When do we move from q to q'?
- Intuition: those $(\sigma_i, cons_i, Snd_i)$ fire the progress transition (q, ψ, q') for which there exists a firedset F such that $q \leadsto_F q'$ and
- e cons, U Sind, comprises exactly the messages that distinguish F from other firedesis of q (weak mode), and in addition no message occurring in the LSC is in cons, U Sind, (strict mode), and (and dish in the constant of t
- $$\begin{split} & \quad \textbf{Formally:} \quad \text{Let } F, F_1, \dots, F_n \\ & \quad \text{be the firedests of } q \text{ and let } q \leadsto_F q' \text{ (unique)} \\ & \quad \text{$\psi := \bigwedge \mathcal{S}(F) \land \neg(\bigvee (\mathcal{S}(F_1) \cup \dots \cup \mathcal{S}(F_n)) \setminus \mathcal{S}(F)) \land \bigwedge \mathcal{W}(q_{g,q'})$} \end{split}$$

Step III: Cold Conditions and Cold Local Invariants

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Legal Exits

- ullet When do we take a legal exit from q?
- Intuition: those $(\sigma_i, cons_i, Snd_i)$ fire the legal exit transition (q, ψ, \mathcal{L})
- for which there exists a firedset F and some q' such that $q \leadsto_F q'$ and

- cons. USM, comprises eactly the messages that distinguish F from other firedests of q (weak mode), and in addition no message occurring in the LSC is in cons. USM, (strict mode) and
 at least one cold condition or local invariant relevant when moving to q' is violated, or
- \bullet for which there is no matching fired set and at least one cold local invariant relevant at q is violated.
- Formally: Let F₁,..., F_n be the firedsets of q with q →_{Fi} q'_i. $\bullet \ \psi := \bigvee_{i=1}^n \bigwedge \mathscr{E}(F_i) \land \neg (\bigvee (\mathscr{E}(F_1) \cup \dots \cup \mathscr{E}(F_n)) \setminus \mathscr{E}(F_i)) \land \bigvee \psi_{\mathrm{odd}}(q,q_i) }$ $\bigvee_{i=1}^n \bigvee \mathscr{E}(F_i) \land \bigvee \psi_{\mathrm{odd}}(q,q_i) }$

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Model Consistency wrt. Interaction

 \bullet We assume that the set of interactions $\mathcal I$ is partitioned into two (possibly empty) sets of universal and existential interactions, i.e.

 $\mathscr{I}=\mathscr{I}_{\forall} \;\dot{\cup}\; \mathscr{I}_{\exists}.$

Back to UML: Interactions

is called consistent (more precise: the constructive description of behaviour is consistent with the reflective one) if and only if

 $\mathcal{M} = (\mathcal{CD}, \mathcal{SM}, \mathcal{OD}, \mathcal{I})$

Definition. A model

 $\forall\,\mathcal{I}\in\mathscr{I}_V:\mathcal{L}(\mathcal{M})\subseteq\mathcal{L}(\mathcal{I})$

 $\forall \mathcal{I} \in \mathscr{I}_\exists : \mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{I}) \neq \emptyset.$

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Finally: The LSC Semantics

- A full LSC L consist of
- a body $(I,(\mathcal{L},\preceq),\sim,\mathcal{S},\mathsf{Msg},\mathsf{Cond},\mathsf{LocInv}),$
- * an activation condition (here: event) ac $=E_{i_1,i_2}^r, E\in \mathscr{E}, i_1, i_2\in I$, * an activation mode, either initial or invariant, * a chart mode, either existential (cold) or universal (hot).

A set W of words over $\mathscr S$ and $\mathscr D$ satisfies L, denoted $W\models L$, iff L

- universal (= hot), initial, and
- $\forall w \in W \ \forall \beta: I \to \mathrm{dom}(\sigma(w^0)) \bullet w \ \text{activates} \ L \implies w \in \mathcal{L}_\beta(\mathcal{B}_L).$ existential (= cold). initial, and
- $\begin{aligned} & \exists w \in W \ \exists \beta : I \mathsf{dom}(\sigma(w^0)) \bullet w \ \mathsf{activates} \ I \cdot w \in \mathcal{L}_{\delta}(\mathcal{B}_L), \\ & \mathsf{universal} \ (= \mathsf{loo}), \mathsf{invariant}, \ \mathsf{and} \end{aligned} \qquad \int_{\mathcal{C}} \mathcal{A}_{\delta}(\mathcal{B}_L) \cdot \mathsf{dom}(\mathcal{C}_{\delta}(\mathcal{B}_L)) \cdot \mathsf{dom}(\mathcal$
- $\exists\, w\in W\ \exists k\in\mathbb{N}_0\ \exists\beta:I\rightarrow \mathrm{dom}(\sigma(w^k))\bullet w/k\ \mathrm{activates}\ L\wedge w/k\in\mathcal{L}_\beta(\mathcal{B}_L).$

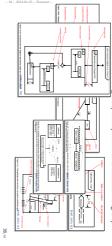
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Interactions as Reflective Description

- A UML model $\mathcal{M}=(\mathscr{CD},\mathscr{SM},\mathscr{OD},\mathscr{S})$ has a set of interactions \mathscr{I} . In UML, reflective (temporal) descriptions are subsumed by interactions.
- An interaction $\mathcal{I} \in \mathscr{I}$ can be (OMG claim: equivalently) diagrammed as
- sequence diagram, timing diagram, or
- communication diagram (formerly known as collaboration diagram).
- And Contract Total

Interactions as Reflective Description

- In UML, reflective (temporal) descriptions are subsumed by interactions. A UML model $\mathcal{M}=(\mathscr{CG},\mathscr{SM},\mathscr{GG},\mathscr{F})$ has a set of interactions \mathscr{I} . An interaction $\mathcal{I}\in\mathscr{I}$ can be (OMG claim: equivalently) diagrammed as
- sequence diagram, communication diagram (formerly known as collaboration diagram). timing diagram, or



Side Note: Protocol Statemachines

Same direction: call orders on operations

- "for each C instance, method $f(\tt)$ shall only be called after $g(\tt)$ but before $h(\tt)$ "

Can be formalised with protocol state machines.

The Concept of History, and Other Pseudo-States

Why Sequence Diagrams?

Thus: Live Sequence Charts

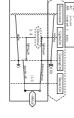
SDs of UML 2.x address some issues, yet the standard exhibits unclarities and eyen contradictions (Harel and Maoz. 2007, Störde, 2003)
 For the lecture, we consider Live Sequence Charts (LSCs)
 [Damm and Harel, 2001, Klose, 2005, Harel and Marelly, 2003] who have a common fragment with UML 2.x SDs [Harel and Maoz., 2007]

Modelling guideline: stick to that fragment.

Sequence Diagrams of UML 1.x

Most severe drawbacks of these formalisms:

- no means to express forbidden scenarios



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Most Prominent: Sequence Diagrams — with long history:

• Message Sequence Charts, standardized by the ITU in different versions, often accused to lack a formal semantics.

- unclear interpretation: example scenario or invariant?
- unclear activation:
 what triggers the requirement?
- unclear progress requirement: must all messages be observed? conditions merely comments

History and Deep History: By Example

8₅ E/ ⊞ $R_{\rm s}/R_{\rm d}/R_{\rm d}/R_{\rm$ \$2 C/ **(E)** What happens on... R_d? R_s? A, B, C, D, R_d? A, B, C, D, E, R,? A, B, C, S, R_s? A, B, S, R_d?

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Note: not so sure about naming and symbols, e.g., I'd guessed it was just the other way round... Junction and Choice Choice: ("dynamic conditional branch") Junction ("static conditional branch"): × 42/57

Entry and Exit Point, Submachine State, Terminate

- Hierarchical states can be "folded" for readability. (but: this can also hinder readability.)
- ullet Can even be taken from a different state-machine for re-use. $\begin{tabular}{c} S:s \end{tabular}$

Entry and Exit Point, Submachine State, Terminate

- Hierarchical states can be "folded" for readability.
 (but: this can also hinder readability.)
- ullet Can even be taken from a different state-machine for re-use. $\begin{tabular}{c} S:s \end{tabular}$
- $\bigcirc \otimes$ Provide connection points for finer integration into the current level, than just via initial state.

Semantically a bit tricky: First the exit action of the exiting state,

- then the actions of the transition,
 then the entry actions of the entered state,
- then action of the transition from the entry point to an internal state,
 and then that internal state's entry action.

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Junction and Choice

Junction and Choice

Junction ("static conditional branch"):

good: abbreviation
 unfolds to so many similar transitions with different guards,
 the unfolded transitions are then checked for enabledness
 at best, start with trigger, branch into conditions, then apply actions

- Junction ("static conditional branch"):
- good: abbreviation
 unfolds to so many similar transitions with different guards, the unfolded transitions are then checked for enabledness
- at best, start with trigger, branch into conditions, then apply actions
- Choice: ("dynamic conditional branch")



Note: not so sure about naming and symbols, e.g., I'd guessed it was just the other way round...

Choice: ("dynamic conditional branch")

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evil: may get stuck

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Note: not so sure about naming and symbols, e.g., I'd guessed it was just the other way round...

maybe even better: avoid

enters the transition without knowing whether there's an enabled path
 at best, use "else" and convince yourself that it cannot get stuck

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Entry and Exit Point, Submachine State, Terminate

- Hierarchical states can be "folded" for readability.
 (but: this can also hinder readability.)
- ullet Can even be taken from a different state-machine for re-use. $\begin{tabular}{c} S:s \end{tabular}$
- Entry/exit points $\bigcirc \otimes$ • Provide connection points for finer integration into the current level, than just via initial state.
- Semantically a bit tricky:
- First the exit action of the exiting state,

- then the actions of the transition,
 then the entry actions of the entered state,
 then action of the transition from the entry point to an internal state,
- and then that internal state's entry action.

Terminate Pseudo-State
 When a terminate pseudo-state is reached, the object taking the transition is immediately killed.



Deferred Events in State-Machines

Deferred Events: Idea

For ages, UML state machines comprises the feature of deferred events.

The idea is as follows:

Consider the following state machine:



- Assume we're stable in s₁, and F is ready in the ether.
- In the framework of the course, F is discarded.
 But we may find it a pity to discard the poor event and may want to remember it for later processing, e.g. in s₂, in other words, defer it.

General options to satisfy such needs:

- Provide a pattern how to "program" this (use self-loops and helper attributes).
- Turn it into an original language concept.

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- Turn it into an original language concept. (← OMG's choice)

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Deferred Events: Syntax and Semantics

Syntactically,
 Each state has (in addition to the name) a set of deferred events.
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- Default: the empty set.
- The semantics is a bit intricate, something like

- if an event E is dispatched,
 and there is no transition enabled to consume E,
 and E is in the deferred set of the current state configuration,
 and E is in the deferred events space" of the object, (e.g., into the ether (= extend e) or into the local state of the object (= extend a))
- and turn attention to the next event.

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What about non-Active Objects?

What about non-Active Objects?

- We're still working under the assumption that all classes in the class diagram (and thus all objects) are active.
- That is, each object has its own thread of control and is (if stable) at any time ready to process an event from the ether.

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- and turn attention to the next event.

Not so obvious:

- Is there a priority between deferred and regular events?

Is the order of deferred events preserved?

[Fecher and Schönborn, 2007], e.g., claim to provide semantics for the complete Hierarchical State Machine language, including deferred events.

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Active and Passive Objects [Harel and Gery, 1997]

Active and Passive Objects: Nomenclature

[Harel and Gery, 1997] propose the following (orthogonal!) notions:

- A class (and thus the instances of this class) is either active or passive as declared in the class diagram.
- An active object has (in the operating system sense) an own thread: an own program counter, an own stack, etc.
 A passive object doesn't.

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So we have to address questions like:

Can we send events to a non-active object?
 And if so, when are these events processed?

But the world doesn't consist of only active objects.

 That is, each object has its own thread of control and is (if stable) at any time ready to process an event from the ether. We're still working under the assumption that all classes in the class diagram (and thus all objects) are active.

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- A passive object doesn't.
- A class is either reactive or non-reactive.
- A reactive class has a (non-trivial) state machine.
- A non-reactive one hasn't.

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Passive and Reactive

- So why don't we understand passive/reactive?
- Assume passive objects u_1 and u_2 , and active object u_i and that there are events in the ether for all three.

Which of them (can) start a run-to-completion step...?

Do run-to-completion steps still interleave...?

Reasonable Approaches:

- Avoid for instance, by
- require that reactive implies active for model well-formedness.
 requiring for model well-formedness that events are never sent to instances of non-reactive classes.
- Explain here: (following [Harel and Gery, 1997])
- Delegate all dispatching of events to the active objects.

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Which combinations do we understand?

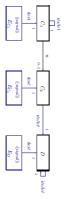
A non-reactive one hasn't.

active passive

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Passive Reactive Classes

- Firstly, establish that each object u knows, via (implicit) link #sAct, the active object u_{act} which is responsible for dispatching events to u.
- If u is an instance of an active class, then u_a = u.



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Sending an event:

- Establish that of each signal we have a version E_C with an association $dest: C_{0,1}, C \in \mathscr{C}$.
- Then n!E in $u_1:C_1$ becomes: Create an instance u_c of E_{C_2} and set u_c 's dest to $u_d:=\sigma(u_1)(n)$.
- Send to $u_a := \sigma(\sigma(u_1)(n))(itsAct)$ i.e., $\varepsilon' = \varepsilon \oplus (u_a, u_e)$.

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- Send to $u_a:=\sigma(\sigma(u_1)(n))(itsAct)$. u_d may in particular discard event. i.e., $\varepsilon'=\varepsilon\oplus(u_a,u_e)$.

• Then u_a asks $\sigma(u_e)(dest) = u_d$ to process u_e — and waits until completion of corresponding RTC.

Dispatching an event:

- ullet Say u_e is ready in the ether for u_a Observation: the ether only has events for active objects.

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And What About Methods?

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Behavioural Features

And What About Methods?

In the current setting, the (local) state of objects is only modified by actions of transitions, which we abstract to transformers.

Semantics:

- The implementation of a behavioural feature can be provided by:
- An operation.

 $.., \tau_{1,n_1}) : \tau_1 P_1$

In UML, the former is called behavioural feature

and can (roughly) be

UML follows an approach to separate
 the interface declaration from

the implementation.

In C++ lingo: distinguish declaration and definition of method.

In general, there are also methods.

• a call interface $f(au_{1_1},\ldots, au_{n_1}): au_1$

Note: The signal list can be seen as redundant (can be looked up in the state machine) of the class. But: certainly useful for documentation (or sanity check). a signal name E

The class' state-machine ("triggered operation").

Behavioural Features

Semantics:

- The implementation of a behavioural feature can be provided by:
- An operation.
- In our setting, we simply assume a transformer like T_f . It is then, e.g. clear how to admit method calls as actions on transitions: function composition of transformers (clear but tedious: non-termination). In a setting with Java as action language: operation is a method body.
- The class' state-machine ("triggered operation").

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And What About Methods?

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- In general, there are also methods.

- UML follows an approach to separate
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In C++ lingo: distinguish declaration and definition of method.

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Behavioural Features

8	n	'n	ı
signal) E	$_{2}F(\tau_{2,1},,\tau_{2,n_{2}}):\tau_{2}P_{2}$	$_{1} f(\eta_{,1},, \eta_{,n_{1}}) : \tau_{1} P_{1}$	

- The implementation of a behavioural feature can be provided by:
- An operation.
- In a setting with Java as action language: operation is a method body. In our setting, we simply assume a transformer like T_l . It is then, e.g. clear how to admit method calls as actions on transitions: function composition of transformers (clear but tedious: non-termination).
- The class' state-machine ("triggered operation").

- Calling P with no parameters for a stable instance of C creates an auditiny event P and disparches it (opposing the ether).
 Transition actions may fill in the return value.
 On completion of the RTC step the call returns.
 For a non-stable instance, the caller blooks until stability is reached again.

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Behavioural Features: Visibility and Properties



- Extend typing rules to sequences of actions such that a well-typed action sequence only calls visible methods.

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Behavioural Features: Visibility and Properties



Visibility:

- Extend typing rules to sequences of actions such that a well-typed action sequence only calls visible methods.
- Useful properties:
- concurrency
 concurrent is thread safe
 guarded some mechanism ensures/should ensure mutual exclusion
 sequential is not thread safe, users have to ensure mutual exclusion
- isQuery doesn't modify the state space (thus thread safe)
- For simplicity, we leave the notion of steps untouched, we construct our semantics around state machines.
 Yet we could explain pre/post in OCL (if we wanted to).