

Software Design, Modelling and Analysis in UML

Lecture 04: OCL Cont'd, Object Diagrams

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Contents & Goals

Last Lecture:

- OCL Syntax

This Lecture:

- **Educational Objectives:** Capabilities for following tasks/questions.
 - What is an object diagram? What are object diagrams good for?
 - When is an object diagram called partial? What are partial ones good for?
 - When is an object diagram an object diagram (wrt. what)?
 - Is this an object diagram wrt. to that other thing?
 - How are system states and object diagrams related?
 - What does it mean that an OCL expression is satisfiable?
 - When is a set of OCL constraints said to be consistent?
 - Can you think of an object diagram which violates this OCL constraint?

Content:

- OCL Semantics
- Object Diagrams
- Example: Object Diagrams for Documentation
- OCL · consistency · satisfiability

OCL Semantics [OMG, 2006]

The Task

<i>OCL Syntax 1/4: Expressions</i>	
<i>expr ::=</i>	
<i>w</i>	$: \tau(w)$
$ \; expr_1 =_{\tau} expr_2$	$: \tau \times \tau \rightarrow \text{Bool}$
$ \; \text{oclsUndefined}_{\tau}(expr_1)$	$: \tau \rightarrow \text{Bool}$
$ \; \{expr_1, \dots, expr_n\}$	$: \tau \times \dots \times \tau \rightarrow \text{Set}(\tau)$
$ \; \text{isEmpty}(expr_1)$	$: \text{Set}(\tau) \rightarrow \text{Bool}$
$ \; \text{size}(expr_1)$	$: \text{Set}(\tau) \rightarrow \text{Int}$
$ \; \text{allInstances}_{\mathcal{C}}$	$: \text{Set}(\tau_C)$
$ \; v(expr_1)$	$: \tau_C \rightarrow \tau(v)$
$ \; r_1(expr_1)$	$: \tau_C \rightarrow \tau_D$
$ \; r_2(expr_1)$	$: \tau_C \rightarrow \text{Set}(\tau_D)$

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Where, given $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$,

- $W \supseteq \{\text{self}\}$ is a set of typed logical variables, w has type $\tau(w)$
- τ is any type from $\mathcal{T} \cup T_B \cup T_{\mathcal{C}}$
 $\cup \{\text{Set}(\tau_0) \mid \tau_0 \in T_B \cup T_{\mathcal{C}}\}$
- T_B is a set of basic types, in the following we use
 $T_B = \{\text{Bool}, \text{Int}, \text{String}\}$
- $T_{\mathcal{C}} = \{\tau_C \mid C \in \mathcal{C}\}$ is the set of object types,
- $\text{Set}(\tau_0)$ denotes the set-of- τ_0 type for
 $\tau_0 \in T_B \cup T_{\mathcal{C}}$
(sufficient because of "flattening" (cf. standard))
- $v : \tau(v) \in atr(C), \tau(v) \in \mathcal{T}$,
- $r_1 : D_{0,1} \in atr(C)$,
- $r_2 : D_* \in atr(C)$,
- $C, D \in \mathcal{C}$.

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- Given an OCL expression $expr$, a system state $\sigma \in \Sigma_{\mathcal{S}}^{\mathcal{D}}$, and a valuation of logical variables β , define

$$I[\cdot](\cdot, \cdot) : OCLExpressions(\mathcal{S}) \times \Sigma_{\mathcal{S}}^{\mathcal{D}} \times (W \rightarrow I(\mathcal{T} \cup T_B \cup T_{\mathcal{C}})) \rightarrow I(\text{Bool})$$

such that

$$I[expr](\sigma, \beta) \in \{\text{true}, \text{false}, \perp_{\text{Bool}}\}.$$

Basically business as usual...

- (i) Equip each OCL (!) **basic type** with a reasonable **domain**, i.e. define function

$$I \text{ with } \text{dom}(I) = T_B$$

- (ii) Equip each **object type** τ_C with a reasonable **domain**, i.e. define function

$$I \text{ with } \text{dom}(I) = \tau_C$$

(most reasonable: $\mathcal{D}(\mathcal{C})$ determined by structure \mathcal{D} of \mathcal{S}).

- (iii) Equip each **set type** $Set(\tau_0)$ with reasonable **domain**, i.e. define function

$$I \text{ with } \text{dom}(I) = \{Set(\tau_0) \mid \tau_0 \in T_B \cup T_{\mathcal{C}}\}$$

- (iv) Equip each **arithmetical operation** with a reasonable **interpretation**
(that is, with a **function** operating on the corresponding **domains**).

$$I \text{ with } \text{dom}(I) = \{+, -, \leq, \dots\}, \text{ e.g., } I(+) \in I(Int) \times I(Int) \rightarrow I(Int)$$

- (v) **Set operations** similar: I with $\text{dom}(I) = \{\text{isEmpty}, \dots\}$

- (vi) Equip each **expression** with a reasonable **interpretation**, i.e. define function

$$I : Expr \times \Sigma_{\mathcal{S}}^{\mathcal{D}} \times (W \rightarrow I(\mathcal{T} \cup T_B \cup T_{\mathcal{C}})) \rightarrow I(Bool)$$

...except for OCL being a **three-valued logic**, and the “iterate” expression.

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(i) Domains of Basic Types

Recall:

- $T_B = \{Bool, Int, String\}$

We set:

"undefined"

- $I(Bool) := \{true, false\} \cup \{\perp_{Bool}\}$
- $I(Int) := \mathbb{Z} \cup \{\perp_{Int}\}$
- $I(String) := \dots \cup \{\perp_{String}\}$

We may omit index τ of \perp_τ if it is clear from context.

(ii) Domains of Object and (iii) Set Types

- Now we need a structure \mathcal{D} of our signature $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$.
- Recall:** \mathcal{D} assigns an (infinite) domain $\mathcal{D}(C)$ to each class $C \in \mathcal{C}$.

- Let τ_C be an (OCL) **object type** for a class $C \in \mathcal{C}$.

- We set

$$I(\tau_C) := \mathcal{D}(C) \cup \{\perp_{\tau_C}\}$$

↑ disjoint union, i.e. assume
 $\perp_{\tau_C} \notin \mathcal{D}(C)$
 otherwise remove in $\mathcal{D}(C)$

- Let τ be a type from $T_B \cup T_C$.

- We set

$$I(Set(\tau)) := 2^{I(\tau)} \cup \{\perp_{Set(\tau)}\}$$

↓ powerset of $I(\tau)$, i.e. set of
 subsets of $I(\tau)$

Note: in the OCL standard, only **finite** subsets of $I(\tau)$.

But infinity doesn't scare **us**, so we simply allow it.

(iv) Interpretation of Arithmetic Operations

- Literals** map to fixed values:

$$I(\text{true}) := \text{true}, \quad I(\text{false}) := \text{false}, \quad I(0) := 0, \quad I(1) := 1, \dots$$

$$I(\text{OclUndefined}_{\tau}) := \perp_{\tau}$$

↓ equality relation

- Boolean operations** (defined point-wise for $x_1, x_2 \in I(\tau)$):

symbol in OCL syntax

$$I(=_{\tau})(x_1, x_2) := \begin{cases} \text{true} & , \text{ if } x_1 \neq \perp_{\tau} \neq x_2 \text{ and } x_1 = x_2 \\ \text{false} & , \text{ if } x_1 \neq \perp_{\tau} \neq x_2 \text{ and } x_1 \neq x_2 \\ \perp_{Bool} & , \text{ otherwise} \end{cases}$$

- Integer operations** (defined point-wise for $x_1, x_2 \in I(\text{Int})$):

$$I(+)(x_1, x_2) := \begin{cases} x_1 + x_2 & , \text{ if } x_1 \neq \perp \neq x_2 \\ \perp & , \text{ otherwise} \end{cases}$$

Note: There is a **common principle**.

Namely, the **interpretation** of an operation $\omega : \tau_1 \times \dots \times \tau_n \rightarrow \tau$ is a function $I(\omega) : I(\tau_1) \times \dots \times I(\tau_n) \rightarrow I(\tau)$ on corresponding semantical domain(s).

(iv) Interpretation of OclIsUndefined

- The **is-undefined** predicate (defined point-wise for $x \in I(\tau)$):

$$I(\text{oclIsUndefined}_{\tau})(x) := \begin{cases} \text{true} & , \text{ if } x = \perp_{\tau} \\ \text{false} & , \text{ otherwise} \end{cases}$$

(v) Interpretation of Set Operations

Basically the same principle as with arithmetic operations...

Let $\tau \in T_B \cup T_{\mathcal{C}}$.

- Set comprehension** ($x_1, \dots, x_n \in I(\tau)$):

$$I(\{\cdot\}_n^{\tau})(x_1, \dots, x_n) := \{x_1, \dots, x_n\}$$

for all $n \in \mathbb{N}_0$

- Empty-ness check** ($x \in I(\text{Set}(\tau))$):

$$I(\text{isEmpty}^{\tau})(x) := \begin{cases} \text{true} & , \text{ if } x = \emptyset \\ \perp_{\text{Bool}} & , \text{ if } x = \perp_{\text{Set}(\tau)} \\ \text{false} & , \text{ otherwise} \end{cases}$$

- Counting** ($x \in I(\text{Set}(\tau))$):

$$I(\text{size}^{\tau})(x) := |x| \text{ if } x \neq \perp_{\text{Set}(\tau)} \text{ and } \perp_{\text{Int}} \text{ otherwise}$$

(vi) Putting It All Together

<p><i>OCL Syntax 1/4: Expressions</i></p> <pre> expr ::= ... w : $\tau(w)$ expr₁=_{τ}expr₂ ✓ : $\tau \times \tau \rightarrow \text{Bool}$ oclIsUndefined_{τ}(expr₁) : $\tau \rightarrow \text{Bool}$ {expr₁, ..., expr_n} ✓ : $\tau \times \dots \times \tau \rightarrow \text{Set}(\tau)$ isEmpty(expr₁) ✓ : $\text{Set}(\tau) \rightarrow \text{Bool}$ size(expr₁) ✓ : $\text{Set}(\tau) \rightarrow \text{Int}$ allInstances_{C} : $\text{Set}(\tau_C)$ v(expr₁) : $\tau_C \rightarrow \tau(v)$ r₁(expr₁) : $\tau_C \rightarrow \tau_D$ r₂(expr₁) : $\tau_C \rightarrow \text{Set}(\tau_D)$ </pre> <p>Where, given $\mathcal{S} = (\mathcal{T}, \mathcal{C})$,</p> <ul style="list-style-type: none"> • $W \supseteq \{\text{self}\}$ is a set of logical variables, w has • τ is any type from $\mathcal{T} \cup \{\text{Set}(\tau_0) \mid \tau_0 \in T_B\} \cup \{Set(\tau_0) \mid \tau_0 \in T_{\mathcal{C}}\}$ • $T_B = \{\text{Bool}, \text{Int}, \text{String}, \dots\}$ • $T_{\mathcal{C}} = \{\tau_C \mid C \in \mathcal{C}\}$ set of object types. • $Set(\tau_0)$ denotes the set-of-τ_0 type for $\tau_0 \in T_B \cup T_{\mathcal{C}}$ (sufficient because of "flattening" (cf. state diagram)) • $v : \tau(v) \in \text{attr}(C), \tau(v) \in T_C$ • $r_1 : D_{0,1} \in \text{attr}(C), \tau(r_1) \in T_D$ • $r_2 : D_* \in \text{attr}(C), \tau(r_2) \in \text{Set}(\tau_D)$ • $C, D \in \mathcal{C}$. 	<p><i>OCL Syntax 2/4: Constants, Arithmetical Operators</i></p> <p>For example:</p> <pre> expr ::= ... true, false ✓ : Bool expr₁ {and, or, implies} expr₂ ✓ : Bool × Bool → Bool not expr₁ ✓ : Bool → Bool 0, -1, 1, -2, 2, ... ✓ : Int OclUndefined ✓ : τ expr₁ {+, -, ...} expr₂ ✓ : Int × Int → I expr₁ {<, ≤, ...} expr₂ ✓ : Int × Int → I </pre> <p>Generalised notation:</p> <pre> expr ::= ω(expr₁, ..., expr_n) : $\tau_1 \times \dots \times \tau_n \rightarrow \tau$ with $\omega \in \{+, -, \dots\}$ </pre>
<p><i>OCL Syntax 3/4: Iterate</i></p> <pre> expr ::= ... expr₁->iterate(w₁ : τ_1; w₂ : τ_2 = expr₂ expr₃) or, with a little renaming, expr ::= ... expr₁->iterate(iter : τ_1; result : τ_2 = expr₂ expr₃) </pre>	<p><i>OCL Syntax 4/4: Context</i></p> <pre> context ::= context w₁ : $\tau_1, \dots, w_n : \tau_n$ inv : expr where w ∈ W and $\tau_i \in T_{\mathcal{C}}$, $1 \leq i \leq n$, $n \geq 0$. </pre>

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Valuations of Logical Variables

- **Recall:** we have typed logical variables ($w \in W$, $\tau(w)$ is the type of w).

- By β , we denote a valuation of the logical variables, i.e. for each $w \in W$,

$$\beta(w) \in I(\tau(w)).$$

$$\beta : W \longrightarrow \bigcup_{w \in W} I(\tau(w))$$

$$\begin{aligned} \text{e.g. if } w : \tau_C \text{ then} \\ \beta(w) \in I(\tau_C) = D(C) \cup \{\perp\} \end{aligned}$$

(vi) Putting It All Together...

$$\begin{aligned} \text{expr} ::= & w \mid \omega(\text{expr}_1, \dots, \text{expr}_n) \mid \text{allInstances}_C \mid v(\text{expr}_1) \mid r_1(\text{expr}_1) \\ & \mid r_2(\text{expr}_1) \mid \text{expr}_1 \rightarrow \text{iterate}(v_1 : \tau_1 ; v_2 : \tau_2 = \text{expr}_2 \mid \text{expr}_3) \end{aligned}$$

- $I[w](\sigma, \beta) := \beta(\omega)$
- $I[\omega(\text{expr}_1, \dots, \text{expr}_n)](\sigma, \beta) := I(\omega)(I[\text{expr}_1](\sigma, \beta), \dots, I[\text{expr}_n](\sigma, \beta))$
- $I[\text{allInstances}_C](\sigma, \beta) := \text{dom}(\sigma) \cap \mathcal{D}(C)$

Note: in the OCL standard, $\text{dom}(\sigma)$ is assumed to be **finite**.

Again: doesn't scare us.

(vi) Putting It All Together...

$$\begin{aligned} \text{expr} ::= & w \mid \omega(\text{expr}_1, \dots, \text{expr}_n) \mid \text{allInstances}_C \mid v(\text{expr}_1) \mid r_1(\text{expr}_1) \\ & \mid r_2(\text{expr}_1) \mid \text{expr}_1 \rightarrow \text{iterate}(v_1 : \tau_1 ; v_2 : \tau_2 = \text{expr}_2 \mid \text{expr}_3) \end{aligned}$$

Assume $\text{expr}_1 : \tau_C$ for some $C \in \mathcal{C}$. Set $u_1 := I[\text{expr}_1](\sigma, \beta) \in \mathbb{I}(\tau_C) = \mathcal{D}(C) \cup \{\perp\}$

- $I[v(\text{expr}_1)](\sigma, \beta) := \begin{cases} \sigma(u_1)(v) & , \text{ if } u_1 \in \text{dom}(\sigma) \\ \perp & , \text{ otherwise} \end{cases}$
- $I[r_1(\text{expr}_1)](\sigma, \beta) := \begin{cases} u & , \text{ if } u_1 \in \text{dom}(\sigma) \text{ and } \sigma(u_1)(r_1) = \{u\} \\ \perp & , \text{ otherwise} \end{cases}$
- $I[r_2(\text{expr}_1)](\sigma, \beta) := \begin{cases} \sigma(u_1)(r_2) & , \text{ if } u_1 \in \text{dom}(\sigma) \\ \perp & , \text{ otherwise} \end{cases}$

(Recall: σ evaluates r_2 of type C_* to a set)

(vi) Putting It All Together...

$expr ::= w \mid \omega(expr_1, \dots, expr_n) \mid \text{allInstances}_C \mid v(expr_1) \mid r_1(expr_1)$
 $\mid r_2(expr_1) \mid expr_1 \rightarrow \text{iterate}(v_1 : \tau_1 ; v_2 : \tau_2 = expr_2 \mid expr_3)$

- $I[expr_1 \rightarrow \text{iterate}(v_1 : \tau_1 ; v_2 : \tau_2 = expr_2 \mid expr_3)](\sigma, \beta)$
 - assign to hlp the set denoted by $expr_1$
 - assign to v_2 the initial expression
- $\text{modification of } \beta \text{ at } hlp \text{ and } v_2$
 $:= \begin{cases} I[expr_2](\sigma, \beta) & , \text{ if } I[expr_1](\sigma, \beta) = \emptyset \\ \text{iterate}(hlp, v_1, v_2, expr_3, \sigma, \beta') & , \text{ otherwise} \end{cases}$
 - where $\beta' = \beta[hlp \mapsto I[expr_1](\sigma, \beta), v_2 \mapsto I[expr_2](\sigma, \beta)]$ and
- $\text{iterate}(hlp, v_1, v_2, expr_3, \sigma, \beta')$
 $:= \begin{cases} I[expr_3](\sigma, \beta'[v_1 \mapsto x]) & , \text{ if } \beta'(hlp) = \{x\} \\ I[expr_3](\sigma, \beta'') & , \text{ if } \beta'(hlp) = X \dot{\cup} \{x\} \text{ and } X \neq \emptyset \end{cases}$
 - where $\beta'' = \beta'[v_1 \mapsto x, v_2 \mapsto \text{iterate}(hlp, v_1, v_2, expr_3, \sigma, \beta'[hlp \mapsto X])]$

Quiz: Is (our) I a function?

Example

$\sigma = \{1_{TM} \mapsto \{name = "Schnell", age = 27, meetings = \{3_M\}\},$
 $3_M \mapsto \{title = "Secretary", numPart = 2, start = 15-23, duration = 120, participants = \{1_{TM}, 8_{TM}\}, location = \{L_0, L_1\}\},$
 $7_L \mapsto \{name = "Hall", meeting = \{3_M\}\},$
 $8_{TM} \mapsto \{name = "Boss", age = 57, meetings = \{3_M\}\}$

$\beta = \{self \mapsto 1_{TM}\}$

- $I[\text{age}(self)](\sigma, \beta) = \beta(\text{age}) = 7_{TM}$
- $I[\text{age}(self)](\sigma, \beta) = \sigma(1_{TM})(\text{age}) = 27$
- $I[\geq(\text{age}(self), 18)](\sigma, \beta) = I(2) \left(I[\text{age}(self)](\sigma, \beta), I(18) \right) = \geq(27, 18) = \text{true} \in I(\text{Bool})$
- $I[\text{allInstances}_{TM}](\sigma, \beta) = \text{dom}(\sigma) \cap D(TM) = \{1_{TM}, 7_L, 8_{TM}, 3_M\} \cap \{1_{TM}, 2_{TM}, \dots\} = \{1_{TM}, 8_{TM}\}$
- $I[\text{meetings}(x)](\sigma, \{x \mapsto 3_M\}) = \{3_M\}$
- $I[\text{location}(x)](\sigma, \{x \mapsto 3_M\}) = 7_L$
- something will \perp : exercises/tutorials

```

classDiagram
    class TeamMember {
        name : String
        age : Integer
    }
    class Meeting {
        title : String
        numParticipants : Integer
        start : Date
        duration : Time
        move(newStart : Date)
    }
    class Location {
        name : String
    }
    TeamMember "2..*" -- "*" Meeting : participants
    TeamMember "*" -- "*" Location : meetings
    Meeting "*" -- "*" Location : move
    
```

Annotations:

- $1_{TM} \mapsto \{name = "Schnell", age = 27, meetings = \{3_M\}\}$
- $3_M \mapsto \{title = "Secretary", numPart = 2, start = 15-23, duration = 120, participants = \{1_{TM}, 8_{TM}\}, location = \{L_0, L_1\}\}$
- $7_L \mapsto \{name = "Hall", meeting = \{3_M\}\}$
- $8_{TM} \mapsto \{name = "Boss", age = 57, meetings = \{3_M\}\}$
- $1_{TM} \mapsto \{name = "Schnell", age = 27, meetings = \{3_M\}\}$
- $3_M \mapsto \{title = "Secretary", numPart = 2, start = 15-23, duration = 120, participants = \{1_{TM}, 8_{TM}\}, location = \{L_0, L_1\}\}$
- L_0, L_1 (Location instances)

Handwritten notes:

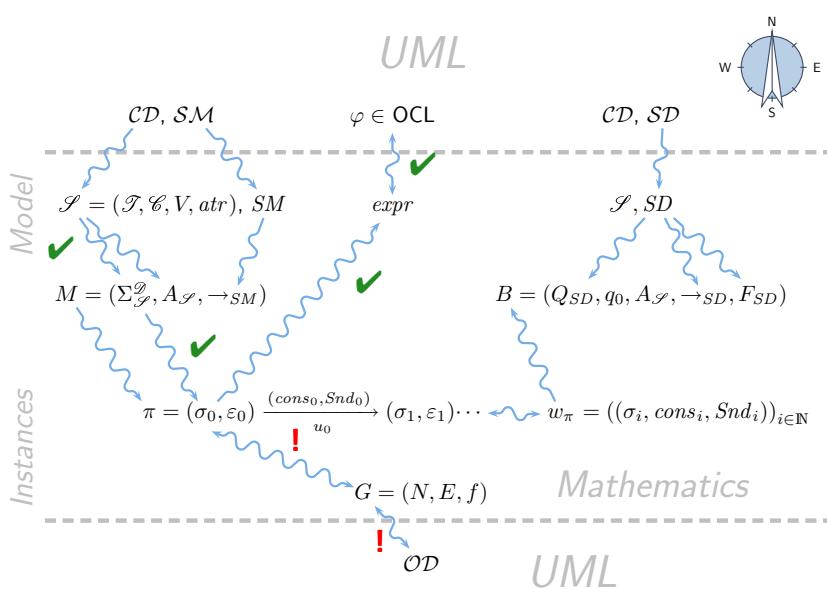
$\text{allInstances}_{TM} \rightarrow \text{iterate}(\text{self: TeamMember}; \text{res: Bool} = \text{true}) \text{ res and } \geq(\text{age}(\text{self}), 18)$

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Where Are We?

You Are Here.



Object Diagrams

Graph

Definition. A node labelled **graph** is a triple

$$G = (N, E, f)$$

consisting of

- **vertices** N ,
- **edges** E ,
- node labeling $f : N \rightarrow X$, where X is some label domain,

Object Diagrams

Definition. Let \mathcal{D} be a structure of signature $\mathcal{S} = (\mathcal{T}, \mathcal{C}, V, atr)$ and $\sigma \in \Sigma_{\mathcal{S}}^{\mathcal{D}}$ a system state.

Then any graph $G = (N, E, f)$ with

- nodes are identities (not necessarily alive), i.e.

$$source \quad attribute \quad N \subset \mathcal{D}(\mathcal{C}) \text{ finite,}$$

$$E \subseteq N \times \{v : \tau \in V \mid \tau \in \{C_{0,1}, C_* \mid C \in \mathcal{C}\}\} \times N,$$

$$\forall (u_1, r, u_2) \in E : u_1 \in \text{dom}(\sigma) \wedge u_2 \in \sigma(u_1)(r),$$

- edges correspond to "links" of objects, i.e.

$$source \quad refers \quad to \quad destination$$

$$source \quad is \quad alive \quad in \quad \sigma$$

$$note: we \quad may \quad have \quad X = \{X\} \dot{\cup} (V \rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$$

$$values \quad of \quad V_{0,1,*} \quad \forall u \in N \cap \text{dom}(\sigma) : f(u) \subseteq \sigma(u)$$

$$attributes \quad in \quad the \quad labelling \quad (maybe \quad \forall u \in N \setminus \text{dom}(\sigma) : f(u) = \{X\})$$

is called object diagram of σ . (redundant with edges)

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$\sigma = \{1_{Th} \mapsto \{name = "Schulze", age = 27, meetings = \{3_M\}\},$
 $3_M \mapsto \{title = "Secretary", numPart = 2, start = 15:23, duration = 120, participants = \{1_{Th}, 8_{Th}\} \cup \{5_{Th}\}, location = \{7_L\}\},$
 $7_L \mapsto \{name = "Herr"\}, meeting = \{3_M\}$
 $8_{Th} \mapsto \{name = "Boss", age = 53, meetings = \{3_M\}\}\}$

(N, E, f)

$N = \{1_{Th}, 3_M, 5_{Th}, 7_L\}$

$E = \{ (3_M, participants, 1_{Th}), (3_M, participants, 5_{Th}) \}$

$f = \{ 1_{Th} \mapsto \{age = 27\}, 3_M \mapsto \{participants = \{1_{Th}, 8_{Th}, 5_{Th}\}, 7_L \mapsto X\} \}$

Graphical Representation of Object Diagrams

$$N \subset \mathcal{D}(\mathcal{C}) \text{ finite}, \quad E \subset N \times V_{0,1,*} \times N, \quad X = \{\mathbf{X}\} \dot{\cup} (V \setminus (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*)))$$

$$u_1 \in \text{dom}(\sigma) \wedge u_2 \in \sigma(u_1)(r), \quad f(u) \subseteq \sigma(u) \text{ or } f(u) = \{\mathbf{X}\}$$

- Assume $\mathcal{S} = (\{Int\}, \{C\}, \{v_1 : Int, v_2 : Int, r : C_*\}, \{C \mapsto \{v_1, v_2, r\}\})$.

- Consider

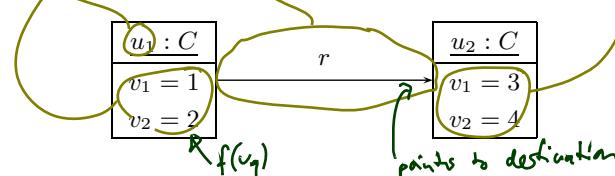
$$\sigma = \{u_1 \mapsto \{v_1 \mapsto 1, v_2 \mapsto 2, r \mapsto \{u_2\}\}, u_2 \mapsto \{v_1 \mapsto 3, v_2 \mapsto 4, r \mapsto \emptyset\}\}$$

- Then $G = (N, E, f)$

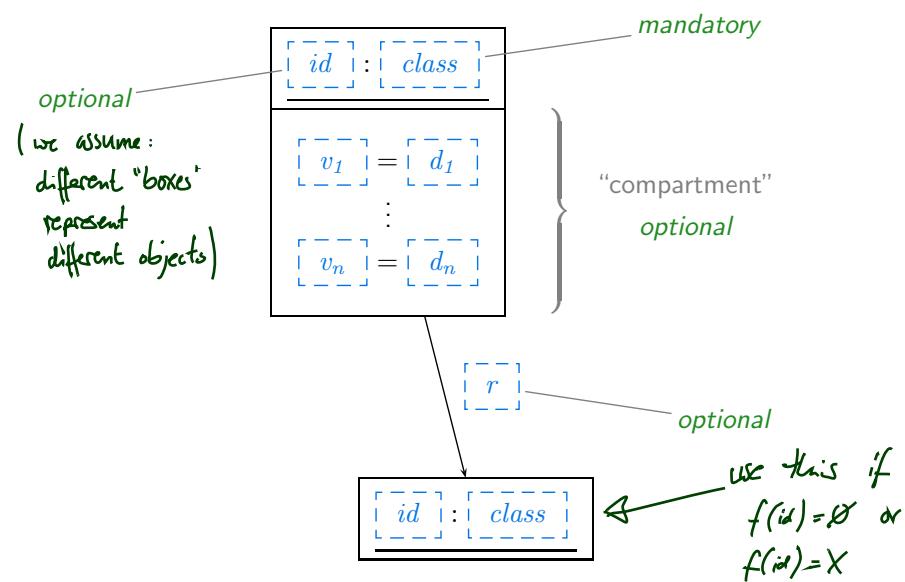
$$= (\{u_1, u_2\}, \{(u_1, r, u_2)\}, \{u_1 \mapsto \{v_1 \mapsto 1, v_2 \mapsto 2\}, u_2 \mapsto \{v_1 \mapsto 3, v_2 \mapsto 4\}\},$$

is an object diagram of σ wrt. \mathcal{S} and any \mathcal{D} with $\mathcal{D}(Int) \supseteq \{1, 2, 3, 4\}$.

- We may equivalently (!) represent G graphically as follows:



UML Notation for Object Diagrams

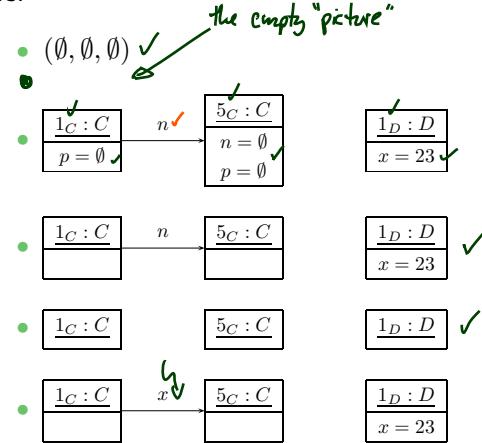


Object Diagrams: More Examples

$$N \subset \mathcal{D}(\mathcal{C}) \text{ finite}, \quad E \subset N \times V_{0,1,*} \times N, \quad X = \{\mathbf{X}\} \dot{\cup} (V \Rightarrow (\mathcal{D}(\mathcal{T}) \cup \mathcal{D}(\mathcal{C}_*))) \\ u_1 \in \text{dom}(\sigma) \wedge u_2 \in \sigma(u_1)(r), \quad f(u) \subseteq \sigma(u) \text{ or } f(u) = \{\mathbf{X}\}$$

$$\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}$$

vs.



Complete vs. Partial Object Diagram

Definition. Let $G = (N, E, f)$ be an object diagram of system state $\sigma \in \Sigma_{\mathcal{G}}$.

We call G **complete** wrt. σ if and only if

- G is **object complete**, i.e.
 - G consists of all alive objects, i.e. $N = \text{dom}(\sigma)$,
- G is **attribute complete**, i.e.
 - G comprises all "links" between alive objects, i.e.
if $u_2 \in \sigma(u_1)(r)$ for some $u_1, u_2 \in \text{dom}(\sigma)$ and $r \in V$,
then $(u_1, r, u_2) \in E$, and
 - each node is labelled with the values of all \mathcal{T} -typed attributes,
i.e. for each $u \in \text{dom}(\sigma)$,

$$f(u) \supseteq \sigma(u)|_{V_{\mathcal{T}}} \cup \{r \mapsto (\sigma(u)(r) \setminus N) \mid r \in V : \sigma(u)(r) \setminus N \neq \emptyset\}$$

where $V_{\mathcal{T}} := \{v : \tau \in V \mid \tau \in \mathcal{T}\}$.

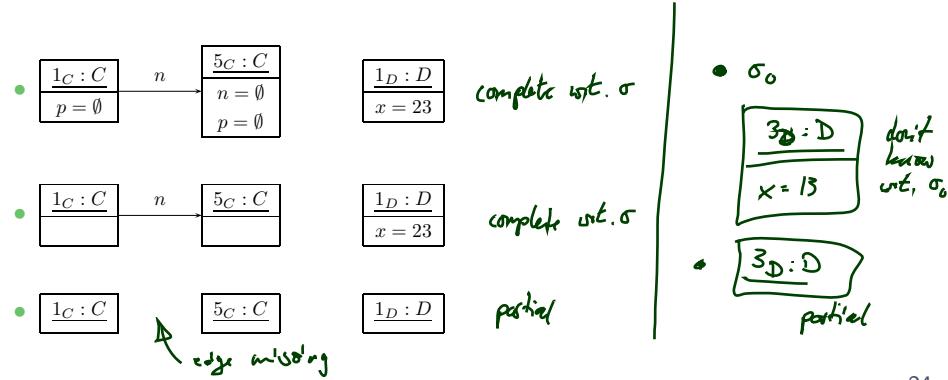
Otherwise we call G **partial**.

Complete vs. Partial Examples

- $N = \text{dom}(\sigma)$, if $u_2 \in \sigma(u_1)(r)$, then $(u_1, r, u_2) \in E$,
- $f(u) = \sigma(u)|_{V_{\mathcal{F}}} \cup \{r \mapsto (\sigma(u)(r) \setminus N) \mid \sigma(u)(r) \setminus N\}$

Complete or partial?

$$\sigma = \{1_C \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}$$



Complete/Partial is Relative

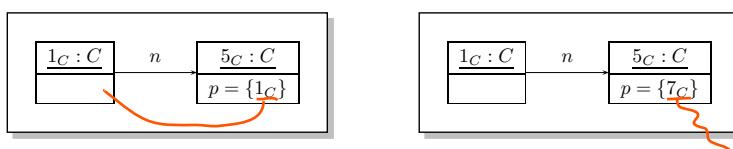
- Claim:
 - Each finite system state has **exactly one complete** object diagram.
 - A finite system state can have **many partial** object diagrams.
- Each object diagram G represents a set of system states, namely

$$G^{-1} := \{\sigma \in \Sigma_{\mathcal{S}}^{\mathcal{D}} \mid G \text{ is an object diagram of } \sigma\}$$
- **Observation:** If somebody **tells us**, that a given (consistent) object diagram G is **complete**, we can uniquely reconstruct the corresponding system state.
In other words: G^{-1} is then a singleton.

Corner Cases

Closed Object Diagrams vs. Dangling References

Find the 10 differences! (Both diagrams shall be complete.)



Definition. Let σ be a system state. We say attribute $v \in V_{0,1,*}$ has a **dangling reference** in object $u \in \text{dom}(\sigma)$ if and only if the attribute's value comprises an object which is not alive in σ , i.e. if

$$\sigma(u)(v) \not\subset \text{dom}(\sigma).$$

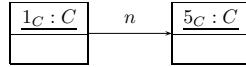
We call σ **closed** if and only if no attribute has a dangling reference in any object alive in σ .

Observation: Let G be the (!) complete object diagram of a **closed** system state σ . Then the nodes in G are labelled with \mathcal{T} -typed attribute/value pairs only.

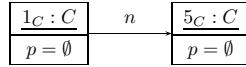
Special Notation

- $\mathcal{S} = (\{Int\}, \{C\}, \{n, p : C_*\}, \{C \mapsto \{n, p\}\})$.

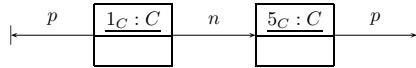
- Instead of



we want to write



or

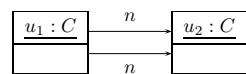


to **explicitly** indicate that attribute $p : C_*$ has value \emptyset (also for $p : C_{0,1}$).

Aftermath

We slightly deviate from the standard (for reasons):

- In the course, $C_{0,1}$ and C_* -typed attributes **only** have **sets as values**.
UML also considers multisets, that is, they can have



(This is not an object diagram in the sense of our definition because of the requirement on the edges E . Extension is straightforward but tedious.)

- We **allow** to give the valuation of $C_{0,1}$ - or C_* -typed attributes in the **values compartment**.
 - Allows us to indicate that a certain r is not referring to another object.
 - Allows us to represent “dangling references”, i.e. references to objects which are not alive in the current system state.
- We introduce a graphical representation of \emptyset values.

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