# Software Design, Modelling and Analysis in UML

Lecture 09: Class Diagrams IV

2012-11-27

Prof. Dr. Andreas Podelski, Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

### The Rest

## Recapitulation: Consider the following association:

- $\langle r: \langle role_1: C_1, \mu_1, P_1, \xi_1, \nu_1, o_1 \rangle, \dots, \langle role_n: C_n, \mu_n, P_n, \xi_n, \nu_n, o_n \rangle \rangle$
- Association name r and role names/types  $role_i/C_i$  induce extended system states  $\lambda$ .
- Multiplicity  $\mu$  is considered in OCL syntax.
- Visibility ξ/Navigability ν: well-typedness.

#### Now the rest:

- ullet Multiplicity  $\mu$ : we propose to view them as constraints
- Properties P<sub>i</sub>: even more typing.
- Ownership o: getting closer to pointers/references.

### Contents & Goals

This Lecture:

Last Lectures:

Started to discuss "associations", the general case.

Associations: The Rest

- Educational Objectives: Capabilities for following tasks/questions.
   Cont'd: Please explain this class diagram with associations.
- When is a class diagram a good class diagram?
   What are purposes of modelling guidelines? (Example?)
   Discuss the style of this class diagram.
- Treat "the rest".
- Where do we put OCL constraints?
   Modelling guidelines, in particular for class diagrams (following [Ambler, 2005])

#### Visibility

Visibility

Not so surprising: Visibility of role-names is treated completely similar to visibility of attributes, namely by typing rules.

Question: given

is the following OCL expression well-typed or not (wrt. visibility):

ξ role

 ${\tt context} \ \ C \ {\tt inv}: self.role.x > 0$ 

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#### Question: given

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Basically same rule as before: (analogously for other multiplicities)

 $\begin{array}{ll} (Assoc_1) & A_*B \vdash expr_1: \tau_C \\ \hline A_*B \vdash rok(expr_1): \tau_D & \xi = +, \text{ or } \xi = - \text{ and } C = B \\ \langle r: \dots \langle rnk: D, \mu, -\xi, -\rangle \dots \langle rnke': C, ---, -\rangle, \dots \rangle \in V \end{array}$ 

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#### Navigability

Navigability is similar to visibility: expressions over non-navigable association ends ( $\nu=\times$ ) are basically type-correct, but forbidden.

#### Question: given



is the following OCL expression well-typed or not (wrt. navigability):

## ${\tt context}\ \ D\ {\tt inv}: self.role.x>0$

## Multiplicities as Constraints

Recall: The multiplicity of an association end is a term of the form:

$$\mu ::= \ast \mid N \mid N..M \mid N..\ast \mid \mu,\mu$$

$$,\mu$$
  $(N, M \in \mathbb{N})$ 

Proposal: View multiplicities (except 0..1, 1) as additional invariants/constraints.

### Navigability

The Rest of the Rest

Recapitulation: Consider the following association:

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• Association name r and role names/types  $role_i/C_i$  induce extended system states  $\lambda$ . • Multiplicity  $\mu$  is considered in OCL syntax.

Navigability is similar to visibility: expressions over non-navigable association ends ( $\nu=\times$ ) are basically type-correct, but forbidden.

#### Question: given



is the following OCL expression well-typed or not (wrt. navigability):

 ${\tt context}\ D\ {\tt inv}: self.role.x>0$ 

So: In general, UML associations are different from pointers/references!

But: Pointers/references can faithfully be modelled by UML associations. " : navigation is possible " ' : navigation is not possible " : navigation is efficient by cartest decide clad "Cofficial" terms by the many communicate this is the defeat The standard says:
- '-': navigation is possible

### Now the rest:

Visibility ξ/Navigability ν: well-typedness.

- Multiplicity \(\mu\): we propose to view them as constraints.
- Properties P<sub>i</sub>: even more typing.
- Ownership o: getting closer to pointers/references.

## Multiplicities as Constraints

Multiplicities as Constraints

 $\mu = N_1..N_2, \ \dots, \ N_{2k-1}..N_{2k}$  where  $N_i \leq N_{i+1}$  for  $1 \leq i \leq 2k, \quad N_1, \dots, N_{2k-1} \in \mathbb{N}, \quad N_{2k} \in \mathbb{N} \cup \{*\}.$ 

Recall: The multiplicity of an association end is a term of the form:

$$\mu ::= * \mid N \mid N..M \mid N..* \mid \mu, \mu \tag{$N, M \in \mathbb{N}$}$$

Proposal: View multiplicities (except 0.1.1) as additional invariants/constraints. Recall: we can normalize each multiplicity  $\mu$  to the form  $\begin{pmatrix} c_1 & 3_1 c_1 c_2 \mu \\ c_3 & c_2 c_3 \mu \end{pmatrix}$  Recall:  $c_1 & c_2 & c_3 & c_3 c_4 \mu \end{pmatrix}$   $\begin{pmatrix} c_1 & c_2 & c_3 & c_3 c_4 \mu \\ c_3 & c_4 & c_3 & c_4 \mu \end{pmatrix}$   $\begin{pmatrix} c_1 & c_2 & c_3 & c_4 \mu \\ c_3 & c_4 & c_4 \mu \end{pmatrix}$   $\begin{pmatrix} c_1 & c_2 & c_3 & c_4 \mu \\ c_3 & c_4 & c_4 \mu \end{pmatrix}$   $\begin{pmatrix} c_1 & c_2 & c_4 \mu \\ c_3 & c_4 \mu \end{pmatrix}$   $\begin{pmatrix} c_1 & c_2 & c_4 \mu \\ c_4 & c_5 \mu \end{pmatrix}$  $N_1..N_2, ..., N_{2k-1}..N_{2k}$ 

 $\underset{\longleftarrow}{\text{where}}\ N_i \leq N_{i+1} \text{ for } 1 \leq i \leq 2k, \quad N_1, \dots, N_{2k-1} \in \mathbb{N}, \quad N_{\underline{2k}} \in \mathbb{N} \cup \{*\}.$ 

## Multiplicities as Constraints

And define  $\mu \widetilde{C}_{0,k}(role) := \text{context} \quad C \text{ inv} : \text{not}(\text{oclkUndefined}(role)) \qquad \qquad \underbrace{F_{k}(ak)}_{F_{k}(ak)}(ak)$  for each  $\mu = 1$ . Note: in n-ary associations with n > 2, there is redundancy.  $\underbrace{C}_{k}(ak) = \underbrace{F_{k}(ak)}_{F_{k}(ak)}(ak)$ for each  $\mu \neq 0.1$ ,  $\mu \neq 1$ , Define  $\mu_{OCL}^{\mathcal{C}}(role) := \text{context } \mathcal{C} \text{ in } v :$  $\mu=N_1...N_2, \ \dots, \ N_{2k-1}...N_{2k}$  where  $N_i\leq N_{i+1}$  for  $1\leq i\leq 2k, \quad N_1,\dots,N_{2k-1}\in\mathbb{N}, \quad N_{2k}\in\mathbb{N}\cup\{*\}.$  $\langle r:\dots,\langle mle':C,\dots,\dots\rangle\in V \text{ or } \\ \langle r:\dots,\langle mle':C,\dots,\dots\rangle\in V, mle\neq mle'.$  $\left(N_1 \leq \underline{vole} - size() \leq N_k\right) \text{ or } \dots \text{ or } \left(N_{2k-1} \leq role - size() \leq N_{2k}\right)$   $\text{omit if } N_{2k} = s$ 

## Why Multiplicities as Constraints?

Why Multiplicities as Constraints? More precise, can't we just use types? (cf. Slide 26)

\*  $\mu=0..1,\ \mu=1$ : many programming language have direct correspondences (the first corresponds to type pointer, the second to type reference) — therefore treated specially.

could be represented by a set data-structure type without fixed bounds — no problem with our approach, we have  $\mu_{\rm OCL}=true$  anyway.

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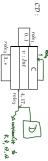
## Multiplicities as Constraints Example

Why Multiplicities as Constraints?

More precise, can't we just use types? (cf. Slide 26)

•  $\mu = 0..1$ ,  $\mu = 1$ :

 $\mu^C_{\mathrm{CL}}(mle) = \mathrm{context} \ C \ \mathrm{inv}:$   $(N_1 \leq mle \rightarrow \mathrm{size}() \leq N_2) \ \ \mathrm{or} \ \dots \ \mathrm{or} \ (N_{2k-1} \leq mle \rightarrow \mathrm{size}() \leq N_{2k})$ 



Inv(CD) =

(owket D inv: \(\psi \int \text{rde}\_{\sigma} \rightarrow \text{P} \int \text{rde}\_{\sigma} \rightarrow \text{P} \int \text{rde}\_{\sigma} \text{contact} \\

\[
\left\{ \text{contact} \text{C inv: 3} \int \text{rde}\_{\sigma} \rightarrow \text{r

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- \*  $\mu=0.3$ : use array of size 4 if model behaviour (or the implementation) adds 5th identity, we'll get a runtime error, and thereby see that the constraint is violated. Principally acceptable, but: checks for array bounds everywhere...?

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- μ = 0..1, μ = 1:
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- could be represented by a set data-structure type without fixed bounds no problem with our approach, we have  $\mu_{\rm OCL}=true$  anyway.
- use array of size 4— if model behaviour (or the implementation) adds 5th identity, we'll get a runtime error, and thereby see that the constraint is violated. Principally acceptable, but: checks for array bounds everywhere...?
- could be represented by an array of size? but free programming languages (data structure libraries allow lover bounds for arrays (other than 0). If we have it identifies and the model behaviour encovers one, this should be a violation of the constraint imposed by the model.

  The implementation which does this removal is wrong. How do we see this...?

Multiplicities Never as Types...?

Well, if the target platform is known and fixed, and the target platform has, for instance,

• range-checked arrays with positions  $0,\ldots,N_r$ 

then we could simply restrict the syntax of multiplicities to set types, -

 $\mu:=1\mid 0..N\mid *$  and don't think about constraints (but use the obvious 1-to-1 mapping to types)...

In general, unfortunately, we don't know.

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#### Properties

Properties

We don't want to cover association **properties** in detail, only some observations (assume binary associations):

Property Intuition

one object has at most one r-link to a current setting single other object

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(so not: lide )

one object may have multiple r-links to have  $\lambda(r)$  yield a single other object an r-link is a sequence of object identi- have  $\lambda(r)$  yield setties (possibly including duplicates) quences

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Property	Intuition	Semantical Effect
unique	one object has at most one $r$ -link to a current setting	current setting
	single other object	
bag	one object may have multiple r-links to have	have $\lambda(r)$ yield
	a single other object	multi-sets
ordered,	an $r$ -link is a sequence of object identi- have $\lambda(r)$ yield se-	have $\lambda(r)$ yield se-
sequence	ties (possibly including duplicates)	quences

bag $\tau_D \rightarrow Bag(\tau_C)$
$\tau_D \rightarrow$

For subsets, redefines, union, etc. see [OMG, 2007a, 127].

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# Multiplicities as Constraints of Class Diagram

Recall/Later: (49 = (CD),...(CD))

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From now on:  $Inv(\mathscr{C}\mathscr{D}) = \{\text{constraints occurring in notes}\} \cup \{\mu^{C}_{\mathsf{OCL}}(role) \mid 1\}$ 

 $\langle r:\dots,\langle role:D,\mu,\_,\_,\_\rangle,\dots,\langle role':C,\_,\_,\_,\_\rangle,\dots\rangle\in V \text{ or }$  $\langle r:\dots,\langle role':C,\_,\_,\_,\_\rangle,\dots,\langle role:D,\mu,\_,\_,\_\rangle,\dots\rangle\in V,$  $role \neq role', \mu \notin \{0..1\}\}.$ 

Ownership

role

Association r is not a "thing on its own" (i.e. provided by  $\lambda$ ), but association end 'role' is owned by C (1). (That is, it's stored inside C object and provided by  $\sigma$ ).

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So: if multiplicity of rule is 0.1 or 1, then the picture above is very close to concepts of pointers/references.

Actually, ownership is seldom seen in UML diagrams. Again: if target platform is clear, one may well live without (cf. [OMG, 2007b, 42] for more details).

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#### Ownership

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Back to the Main Track

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Actually, ownership is seldom seen in UML diagrams. Again: if target platform is clear, one may well live without (cf. [OMG, 2007b, 42] for more details).

# Not clear to me:

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OCL Constraints in (Class) Diagrams

(iii) Particular dedicated places.

(ii) Notes. Numerous options: (i) Additional documents.

Where Shall We Put OCL Constraints?

Recall: on some earlier slides we said, the extension of the signature is **only** to study associations in "full beauty".

For the remainder of the course, we should look for something simpler...

(ii)

role D note D

• We drop  $\lambda$  and go back to our nice  $\sigma$  with  $\sigma(u)(role) \subseteq \mathscr{D}(D)$ .

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• In both cases,  $role \in atr(C)$ .

• Form (i) introduces  $role: C_{0,1}$ , and form (ii) introduces  $role: C_*$  in V. (And we may omit the non-navigability and ownership symbols.) \* from now on, we only use associations of the form  $\begin{array}{c|c}
C & & & \\
C &$ 

Back to the main track:

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## Where Shall We Put OCL Constraints?

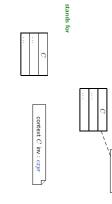
- (i) Additional documents.
- (ii) Notes.
- (iii) Particular dedicated places. (i) Notes:



text can principally be everything, in particular comments and constraints.

Sometimes, content is explicitly classified for clarity:

## OCL in Notes: Conventions



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## Invariants of a Class Diagram

Where Shall We Put OCL Constraints?

(ii) Particular dedicated places in class diagrams: (behav. feature: later)

 $\frac{\{v:\tau\left\{p_1,\dots,p_n\right\}\left\{expr\right\}}{\{\{f(v_1:\tau_1,\dots,v_n:\tau_n):\tau\left\{p_1,\dots,p_n\right\}\left\{pre:expr_1\right\}}$ 

For simplicity, we view the above as an abbreviation for

expr

 $context f pre: expr_1 post: expr_2$ 

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- Let  $\mathcal{CD}$  be a class diagram. As we (now) are able to recognise OCL constraints when we see them, we can define

as the set  $\{\varphi_1,\dots,\varphi_n\}$  of OCL constraints occurring in notes in  $\mathcal{CD}$  — after unfolding all abbreviations (cf. next slides).

Where Shall We Put OCL Constraints?

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 $\begin{array}{l} \{ v: \tau \left\{ p_1, \ldots, p_n \right\} \left\{ expr \right\} \\ \{ f(v_1: \tau_1, \ldots, v_n: \tau_n): \tau \left\{ p_1, \ldots, p_n \right\} \left\{ pre: expr_1 \right. \\ post: expr_2 \} \end{array}$ 

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## Invariants of a Class Diagram

- Let CD be a class diagram.
   As we (now) are able to recognise OCL constraints when we see them, we can define
- as the set  $\{\varphi_1,\dots,\varphi_n\}$  of OCL constraints occurring in notes in  $\mathcal{CD}$  after unfolding all abbreviations (cf. next slides).
- \* As usual:  $Inv(\mathscr{C}\mathscr{D}) := \bigcup_{\mathcal{D} \in \mathscr{C}\mathscr{D}} Inv(\mathcal{D})$ . + implies and form subjective \* Principally clear:  $Inv(\cdot)$  for any kind of diagram. (4 greated)

## Invariant in Class Diagram Example



If  $\mathscr{CD}$  consists of only  $\mathcal{CD}$  with the single class C, then

•  $Inv(\mathscr{CD}) = Inv(\mathcal{CD}) =$ { course & inv: v>3}

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### Pragmatics

Recall: a UML model is an image or pre-image of a software system.

A set of class diagrams  $\mathscr{CD}$  with invariants  $Inv(\mathscr{CD})$  describes the structure of system states. Together with the invariants it can be used to state:

- Pre-image: Dear programmer, please provide an implementation which uses only system states that satisfy  $Inv(\mathscr{C}\mathscr{D}).$
- $\bullet$  Post-image: Dear user/maintainer, in the existing system, only system states which satisfy  $Inv(\mathscr{CD})$  are used.

\* x=4 is not even well-typed in the right context, there cannot be a system state with  $\sigma(u)(x)=4$  because  $\sigma(u)(x)$  is supposed to be in  $\mathcal{D}(T)$  (by definition of system state).  $\ast$  x=4 is well-typed in the left context, a system state satisfying x=4 violates the constraints of the diagram.

(The exact meaning of "use" will become clear when we study behaviour — intuitively: the system states that are reachable from the initial system state(s) by calling methods or firing transitions in state-machines.)

Example: highly abstract model of traffic lights controller.



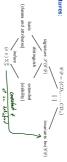
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## Semantics of a Class Diagram

Definition. Let  $\mathscr{C}\mathscr{D}$  be a set of class diagrams. We say, the semantics of  $\mathscr{C}\mathscr{D}$  is the signature it induces and the set of OCL constraints occurring in  $\mathscr{C}\mathscr{D}$ , denoted

 $[\![\mathscr{C}\mathscr{D}]\!] := \langle \mathscr{S}(\mathscr{C}\mathscr{D}), \mathit{Inv}(\mathscr{C}\mathscr{D}) \rangle.$ 

We call a system state  $\sigma \in \Sigma_{\mathscr{S}}^{\mathscr{D}}$  consistent if and only if  $\sigma \models Inv(\mathscr{C}\mathscr{D})$ . Given a structure  $\mathscr{D}$  of  $\mathscr{S}$  (and thus of  $\mathscr{C}\mathscr{D}$ ), the class diagrams describe the system states  $\Sigma_{\mathscr{S}}^{\mathscr{B}}$ . Of those, some satisfy  $hv(\mathscr{C}\mathscr{D})$  and some don't.



A set of class diagrams  $\mathscr{CD}$  with invariants  $\mathit{Inv}(\mathscr{CD})$  describes the structure of system states. Recall: a UML model is an image or pre-image of a software system.

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Pragmatics

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 $\bullet$  Post-image: Dear user/maintainer, in the existing system, only system states which satisfy  $Inv(\mathscr{C}\mathscr{D})$  are used.

• **Pre-image**: Dear programmer, please provide an implementation which uses only system states that satisfy  $Inv(\mathscr{C}\mathscr{D})$ .

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### Constraints vs. Types

Constraints vs. Types Find the 10 differences:

### Find the 10 differences:



 $\mathcal{D}(T) = \{3\}$   $\cup \{n \in \mathbb{N} \mid n > 17\}$ 





- \* x=4 is well-typed in the left context, a system state satisfying x=4 violates the constraints of the diagram.
- \* x=4 is not even well-typed in the right context, there cannot be a system state with  $\sigma(u)(x)=4$  because  $\sigma(u)(x)$  is supposed to be in  $\mathcal{B}(T)$  (by definition of system state).

### Rule-of-thumb:

- If something "feels like" a type (one criterion: has a natural correspondence in the application domain), then make it a type.
   If something is a requirement or restriction of an otherwise useful type, then make it a constraint.

### Design Guidelines for (Class) Diagram (partly following [Ambler, 2005])

Be careful whose advice you buy, but, be patient with those who supply it. Baz Luhrmann/Mary Schmich

# Main and General Modelling Guideline (admittedly: trivial and obvious)

### Be good to your audience.

"Imagine you're given your diagram  ${\mathcal D}$  and asked to conduct task  ${\mathcal T}.$ 

- Can you do T with D?
- (semantics sufficiently clear? all necessary information available? ...)
- Does doing T with D cost you more nerves/time/money/...than it should?" (syntactical well-formedness? readability? intention of deviations from standard syntax clear? reasonable selection of information? Inyout? ...)

#### In other words:

- the things most relevant for  $\mathcal{T}_r$ , do they stand out in  $\mathcal{D}$ ? If p is p and the things less relevant for  $\mathcal{T}_r$  do they disturb in  $\mathcal{D}$ ? If p is p in p is p in p in p?

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# Main and General Quality Criterion (again: trivial and obvious)

Q: When is a (class) diagram a good diagram?

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Examples for purposes and points and rules-of-thumb:

Analysis/Design

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Main and General Quality Criterion (again: trivial and obvious)

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## Examples for purposes and points and rules-of-thumb:

## Analysis/Design

- realizable, no contradictions
   abstract, focused, admitting degrees of freedom for (more detailed) design
   platform independent as far as possible but not (artificially) farer
- Implementation/A - close to target platform  $(C_{0,1} \text{ is easy for Java, } C_* \text{ comes at a cost } \text{— other way round for RDB})$
- Implementation/B
- Documentation complete, executable

Documentation

 complete, executable Implementation/B

Right level of abstraction: "If you've only one diagram to spend, illustrate the
concepts, the architecture, the difficult part!
 The more detailed the documentation, the higher the probability for regression
"outdated/wrong documentation is worse than none"

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General Diagramming Guidelines [Ambler, 2005]

(Note: "Exceptions prove the rule.")

2.1 Readability

Examples for purposes and points and rules-of-thumb:

Analysis/Design

Implementation/A

- close to target platform  $(C_{0,1}$  is easy for Java,  $C_*$  comes at a cost — other way round for RDB)

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 abstract, focused, admitting degrees of freedom for (more detailed) design
 platform independent – as far as possible but not (artificially) farer

 A: If it serves its purpose/makes its point. Q: When is a (class) diagram a good diagram? Main and General Quality Criterion (again: trivial and obvious)

1.–3. Support Readability of Lines







# General Diagramming Guidelines [Ambler, 2005]

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### 2.1 Readability





General Diagramming Guidelines [Ambler, 2005]

(Note: "Exceptions prove the rule.")

### 2.1 Readability

- 1.–3. Support Readability of Lines
- 4. Apply Consistently Sized Symbols
- 9. Minimize the Number of Bubbles

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# General Diagramming Guidelines [Ambler, 2005]

### 2.2 Simplicity

(Note: "Exceptions prove the rule.")

2.1 Readability

1.-3. Support Readability of Lines

10. Include White-Space in Diagrams

 9. Minimize the Number of Bubbles 4. Apply Consistently Sized Symbols

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13. Provide a Notational Legend

General Diagramming Guidelines [Ambler, 2005]

- 14. Show Only What You Have to Show

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#### 2.2 Simplicity

- 14. Show Only What You Have to Show
- 15. Prefer Well-Known Notation over Exotic Notation
- 16. Large vs. Small Diagrams
- 18. Content First, Appearance Second

### 2.3 Naming

20. Set and (23. Consistently) Follow Effective Naming Conventions

# General Diagramming Guidelines [Ambler, 2005]

#### 2.2 Simplicity

- 14. Show Only What You Have to Show
- 15. Prefer Well-Known Notation over Exotic Notation
- 16. Large vs. Small Diagrams
- 18. Content First, Appearance Second

#### 2.3 Naming

- 20. Set and (23. Consistently) Follow Effective Naming Conventions

25. Consider Applying Color to Your Diagram

24. Indicate Unknowns with Question-Marks

26. Apply Color Sparingly

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## Class Diagram Guidelines [Ambler, 2005]

Class Diagram Guidelines [Ambler, 2005]

5.1 General Guidelines

88. Indicate Visibility Only on Design Models (in contrast to analysis models)

5.2 Class Style Guidelines

99. Do Not Model Scaffolding Code [Except for Exceptions]
 ዓታ ነወታ/ያራና

 97. Name Operations with Strong Verbs 96. Prefer Complete Singular Nouns for Class Names

### 5.1 General Guidelines

88. Indicate Visibility Only on Design Models (in contrast to analysis models)

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## Class Diagram Guidelines [Ambler, 2005]

### 5.3 Relationships

Class Diagram Guidelines [Ambler, 2005]

5.2 Class Style Guidelines

103. Never Show Classes with Just Two Compartments

1 T

104. Label Uncommon Class Compartments —

105. Include an Ellipsis (...) at the End of an Incomplete List

107. List Operations/Attributes in Order of Decycasing Visibility

eg. X.U.

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- \* 112. Model Relationships كالمتعمدية . 115. Model a Dependency When the Relationship is Transitory . 117. Always Indicate the Multiplicity (« اعد واحداً الميالية)



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## Class Diagram Guidelines [Ambler, 2005]

### 5.4 Associations

- 127. Indicate Role Names When Multiple Associations Between Two Classes Exist
- 129. Make Associations Bidirectional Only When Collaboration Occurs in Both Directions
- 131. Avoid Indicating Non-Navigability (if hope of of the Careet to be

## Class Diagram Guidelines [Ambler, 2005]

### 5.4 Associations

- 127. Indicate Role Names When Multiple Associations Between Two Classes Exist
- 129. Make Associations Bidirectional Only When Collaboration Occurs in Both Directions
- 131. Avoid Indicating Non-Navigability
- 133. Question Multiplicities Involving Minimums and Maximums

## 5.6 Aggregation and Composition

[...] But trust me on the sunscreen.

Baz Luhrmann/Mary Schmich

Example: Modelling Games

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Task: Game Development

Task: develop a video game. Genre: Racing. Rest: open, i.e.

Degrees of freedom:

simulation vs. arade

platform (SDK or not,
open or proprietary,
hardware capabilities...)

graphics (3D, 2D, ...)

number of players, Al

controller

game experience

Task: Game Development

Task: develop a video game. Genre: Racing. Rest: open, i.e.

<ul> <li>game experience</li> </ul>	controller	<ul> <li>number of players, Al</li> </ul>	<ul> <li>graphics (3D, 2D,)</li> </ul>	open or proprietary, hardware capabilities)	<ul> <li>platform (SDK or not,</li> </ul>	<ul> <li>simulation vs. arcade</li> </ul>	Degrees of freedom:	
minimal: main menu and game	open (later determined by platforn	min. 2, Al open	2D		open	arcade	Exemplary choice: 2D-Tron	



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Modelling Structure: 2D-Tron

In many domains, there are canonical architectures – and adept readers try to see/find/match this!
 For games:

2D-Tron

a arcade

platform open

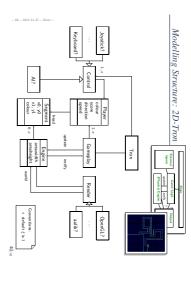
2D

min. 2, Al open

controller open

only game, no mei

Output
Graphics (from ASCII to bitmap: native or via API)
Sound



References

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### References

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