Software Design, Modelling and Analysis in UML

Lecture 02: Semantical Model

2013-10-23

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Contents & Goals

Last Lecture:

- Motivation: model-based development of things (houses, software) to cope with complexity, detect errors early
- Model-based (or -driven) Software Engineering
- UML Mode of the Lecture: Blueprint.

This Lecture:

- **Educational Objectives:** Capabilities for these tasks/questions:
  - Why is UML of the form it is?
  - Shall one feel bad if not using all diagrams during software development?
  - What is a signature, an object, a system state, etc.?
    What's the purpose of signature, object, etc. in the course?
  - How do Basic Object System Signatures relate to UML class diagrams?
- **Content:**
  - Brief history of UML
  - Course map revisited
  - Basic Object System Signature, Structure, and System State

Why (of all things) UML?

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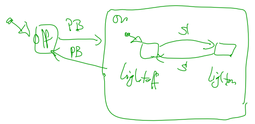
- Note: being a **modelling** languages doesn't mean being graphical (or: being a visual formalism [Harel]).
- For instance, [Kastens and Büning, 2008] also name:
  - Sets, Relations, Functions
  - Terms and Algebras
  - Propositional and Predicate Logic
  - Graphs
  - XML Schema, Entity Relation Diagrams, UML Class Diagrams
  - Finite Automata, Petri Nets, UML State Machines
- **Pro**: visual formalisms are found appealing and easier to **grasp**.
  Yet they are not necessarily easier to **write**!
- **Beware**: you may meet people who dislike visual formalisms just for being graphical — maybe because it is easier to "trick" people with a meaningless picture than with a meaningless formula.

  More serious: it's maybe easier to misunderstand a picture than a formula.

A Brief History of UML

- Boxes/lines and finite automata are used to visualise software **for ages**.
- **1970's**, **Software Crisis**™
  — Idea: learn from engineering disciplines to handle growing complexity.
  Languages: **Flowcharts, Nassi-Shneiderman, Entity-Relation Diagrams**
- Mid **1980**'s: **Statecharts** [Harel, 1987], **StateMate**™ [Harel et al., 1990]



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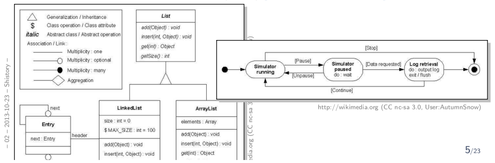
- Early **1990's**, advent of **Object-Oriented**-Analysis/Design/Programming
  — Inflation of notations and methods, most prominent:
  - **Object-Modeling Technique** (OMT) [Rumbaugh et al., 1990]



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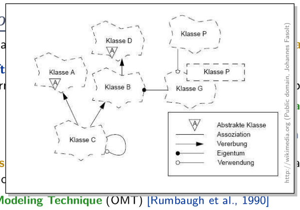
  - **Booch Method and Notation** [Booch, 1993]



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  - **Booch Method and Notation** [Booch, 1993]
  - **Object-Oriented Software Engineering** (OOSE) [Jacobson et al., 1992]

  Each "persuasion" selling books, tools, seminars...
- Late **1990's**: joint effort **UML 0.x, 1.x**
  Standards published by **Object Management Group** (OMG), "*international, open membership, not-for-profit* **computer industry** *consortium*".
- Since **2005**: **UML 2.x**

UML Overview *[OMG, 2007b, 684]*

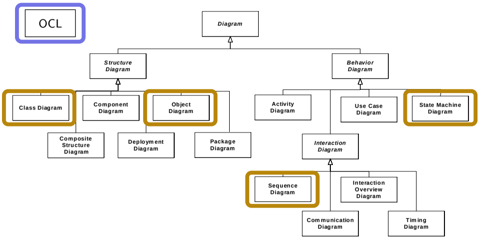


Figure A.5 - The taxonomy of structure and behavior diagram

[Dobing and Parsons, 2006]

Common Expectations on UML

- Easily writeable, readable even by customers
- Powerful enough to bridge the gap between idea and implementation
- Means to tame complexity by separation of concerns ("views")
- Unambiguous
- Standardised, exchangeable between modelling tools
- UML standard says how to develop software
- Using UML leads to better software
- ...

We will see...

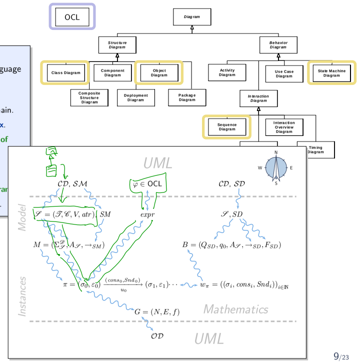
Seriously: After the course, you should have an own opinion on each of these claims.
In how far/in what sense does it hold? Why? Why not? How can it be achieved?
Which ones are really only hopes and expectations? ...?

Course Map Revisited

The Plan

Recall:

- **Overall aim**: a formal language for software blueprints.
- **Approach**:
  (i) Common semantical domain.
  (ii) UML fragments as **syntax**.
  (iii) Abstract **representation of diagrams**.
  (iv) **Informal semantics**: UML standard
  (v) **assign meaning to diagrar**
  (vi) Define, e.g., **consistency**.


OCL
Diagram
Structure Diagram
Behavior Diagram
Class Diagram
Component Diagram
Object Diagram
Activity Diagram
Use Case Diagram
State Machine Diagram
Composite Structure Diagram
Deployment Diagram
Package Diagram
Interaction Diagram
Sequence Diagram
Interaction Overview Diagram
Timing Diagram
UML
N
W
E
S
$\mathcal{CD}, \mathcal{SM}$
$\varphi \in$ OCL
$\mathcal{CD}, \mathcal{SD}$
Model
$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr), SM$
$expr$
$\mathscr{S}, SD$
$M = (\Sigma_{\mathscr{S}}^{\mathscr{D}}, A_{\mathscr{S}}, \to_{SM})$
$B = (Q_{SD}, q_0, A_{\mathscr{S}}, \to_{SD}, F_{SD})$
Instances
$\pi = (\sigma_0, \varepsilon_0) \xrightarrow[u_0]{(cons_0, Snd_0)} (\sigma_1, \varepsilon_1) \cdots$
$w_\pi = ((\sigma_i, cons_i, Snd_i))_{i \in \mathbb{N}}$
$G = (N, E, f)$
Mathematics
$\mathcal{OD}$
UML

UML: Semantic Areas

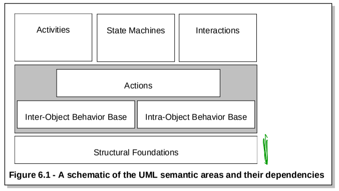


Figure 6.1 - A schematic of the UML semantic areas and their dependencies

[OMG, 2007b, 11]

Common Semantical Domain

Basic Object System Signature

Definition. A (Basic) Object System Signature is a quadruple

$$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$$

where

- $\mathscr{T}$ is a set of (basic) types,
- $\mathscr{C}$ is a finite set of classes,
- V is a finite set of typed attributes, i.e., each $v \in V$ has type
  - $\tau \in \mathscr{T}$ or
  - $C_{0,1}$ or C_*, where $C \in \mathscr{C}$

  (written $v : \tau$ or $v : C_{0,1}$ or $v : C_*$),
- $atr : \mathscr{C} \to \underbrace{2^V}$ maps each class to its set of attributes.

for each class $D \in \mathscr{C}$ there are two different types:

$D_{0,1}$ or: $D_\triangle$ or: $\triangle D$

D_* $D_{(i)}$ $\boxed{D}$

in other words:

$typeof : V \to \mathscr{T} \cup \{D_{0,1}, D_* \mid D \in \mathscr{C}\}$

total function

powerset of V

Note: Inspired by OCL 2.0 standard [OMG, 2006], Annex A.

Basic Object System Signature Example

$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$ where

- (basic) types $\mathscr{T}$ and classes $\mathscr{C}$, (both finite),
- typed attributes V, τ from $\mathscr{T}$ or $C_{0,1}$ or C_*, $C \in \mathscr{C}$,
- $atr : \mathscr{C} \to 2^V$ mapping classes to attributes.

Example:

basic types classes attributes attribute x has type Int atr $atr(C) = \{p, n\}$ $atr(D) = \{x\}$

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \underbrace{\{x : Int}, p : C_{0,1}, n : C_*\}, \{\underbrace{C \mapsto \{p, n\}}, \underbrace{D \mapsto \{x\}}\})$$

mapsto

Basic Object System Signature Another Example

$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$ where

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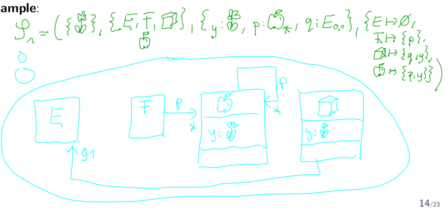
Example:



Basic Object System Structure

Definition. A Basic Object System Structure of

$$\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$$

is a domain function $\mathscr{D}$ which assigns to each type a domain, i.e.

- $\tau \in \mathscr{T}$ is mapped to $\mathscr{D}(\tau)$,
- $C \in \mathscr{C}$ is mapped to an infinite set $\mathscr{D}(C)$ of (object) identities.

  Note: Object identities only have the "=" operation;
  object identities of different classes are disjoint, i.e.
  $\forall\, C, D \in \mathscr{C} : C \neq D \to \mathscr{D}(C) \cap \mathscr{D}(D) = \emptyset$.
- C_* **and** $C_{0,1}$ for $C \in \mathscr{C}$ are mapped to $2^{\mathscr{D}(C)}$.

We use $\mathscr{D}(\mathscr{C})$ to denote $\bigcup_{C \in \mathscr{C}} \mathscr{D}(C)$; analogously $\mathscr{D}(\mathscr{C}_*)$.

Note: We identify objects and object identities, because both uniquely determine each other (cf. OCL 2.0 standard).

Basic Object System Structure Example

Wanted: a structure for signature

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

Recall: by definition, seek a $\mathscr{D}$ which maps

- $\tau \in \mathscr{T}$ to **some** $\mathscr{D}(\tau)$,
- $c \in \mathscr{C}$ to **some** identities $\mathscr{D}(C)$ (infinite, disjoint for different classes),
- C_* and $C_{0,1}$ for $C \in \mathscr{C}$ to $\mathscr{D}(C_{0,1}) = \mathscr{D}(C_*) = 2^{\mathscr{D}(C)}$.

$$\begin{aligned}
\mathscr{D}(Int) &= \mathbb{Z} \\
\mathscr{D}(C) &= \mathbb{N}^+ \times \{C\} = \{1_C, 2_C, 3_C, ...\} \\
\mathscr{D}(D) &= \mathbb{N}^+ \times \{D\} = \{1_D, 2_D, 3_D, ...\} \\
\mathscr{D}(C_{0,1}) = \mathscr{D}(C_*) &= 2^{\mathbb{N}^+ \times \{C\}} \\
\mathscr{D}(D_{0,1}) = \mathscr{D}(D_*) &= 2^{\mathscr{D}(D)}
\end{aligned}$$

alternative choice:

$$\begin{aligned}
&\mathscr{D}_2(Int) = \{-127, ..., 127\} \\
&\mathscr{D}_2(C) = \{1, 3, 5, ...\} \\
&\mathscr{D}_2(D) = \{2, 4, 6, ...\} \\
&2^{\mathscr{D}_2(C)} \\
&2^{\mathscr{D}_2(D)}
\end{aligned}$$

System State

Definition. Let $\mathscr{D}$ be a structure of $\mathscr{S} = (\mathscr{T}, \mathscr{C}, V, atr)$.
A system state of $\mathscr{S}$ wrt. $\mathscr{D}$ is a **type-consistent** mapping

$$\sigma : \overbrace{\mathscr{D}(\mathscr{C})}^{\text{all object identifiers}} \overset{\text{partial function}}{\nrightarrow} \overbrace{(V \nrightarrow (\mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*)))}^{\text{partial function from } V \text{ to types' domains}}.$$

That is, for each $u \in \mathscr{D}(C)$, $C \in \mathscr{C}$, if $u \in \mathrm{dom}(\sigma)$

- $\mathrm{dom}(\sigma(u)) = atr(C)$
- $\sigma(u)(v) \in \mathscr{D}(\tau)$ if $v : \tau, \tau \in \mathscr{T}$
- $\sigma(u)(v) \in \mathscr{D}(D_*)$ if $v : D_{0,1}$ or $v : D_*$ with $D \in \mathscr{C}$

We call $u \in \mathscr{D}(\mathscr{C})$ alive in σ if and only if $u \in \mathrm{dom}(\sigma)$.

We use $\Sigma_{\mathscr{S}}^{\mathscr{D}}$ to denote the set of all system states of $\mathscr{S}$ wrt. $\mathscr{D}$.

System State Example

Signature, Structure:

$$\mathscr{S}_0 = (\{Int\}, \{C, D\}, \{x : Int, p : C_{0,1}, n : C_*\}, \{C \mapsto \{p, n\}, D \mapsto \{x\}\})$$

$$\mathscr{D}(Int) = \mathbb{Z}, \quad \mathscr{D}(C) = \{1_C, 2_C, 3_C, ...\}, \quad \mathscr{D}(D) = \{1_D, 2_D, 3_D, ...\}$$

Wanted: $\sigma : \mathscr{D}(\mathscr{C}) \nrightarrow (V \nrightarrow (\mathscr{D}(\mathscr{T}) \cup \mathscr{D}(\mathscr{C}_*)))$ such that

- $\mathrm{dom}(\sigma(u)) = atr(C)$,
- $\sigma(u)(v) \in \mathscr{D}(\tau)$ if $v : \tau, \tau \in \mathscr{T}$,
- $\sigma(u)(v) \in \mathscr{D}(C_*)$ if $v : D_*$ with $D \in \mathscr{C}$.

- $\sigma_1 = \emptyset$ ← empty function
- $\sigma_2 = \{ 1_C \mapsto \{p \mapsto \{1_C\}, n \mapsto \{5_C, 6_C\}\}, 27_D \mapsto \{x \mapsto 3\} \}$

one way to read out:

- object 1_C has a p-link to 1_C (i.e. to itself)
- object 1_C refers to objects $5_C, 6_C$ via link n

Wrt. $\mathscr{D}_2$:

- $\sigma_3 = \{ 5 \mapsto \{p \mapsto \{17\}, n \mapsto \emptyset \}$

System State Example

Signature, Structure:

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- $\sigma(u)(v) \in \mathscr{D}(C_*)$ if $v : D_*$ with $D \in \mathscr{C}$.

- **Concrete, explicit**:

  $$\sigma = \{\boxed{1_C} \mapsto \{p \mapsto \emptyset, n \mapsto \{5_C\}\}, 5_C \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, 1_D \mapsto \{x \mapsto 23\}\}.$$

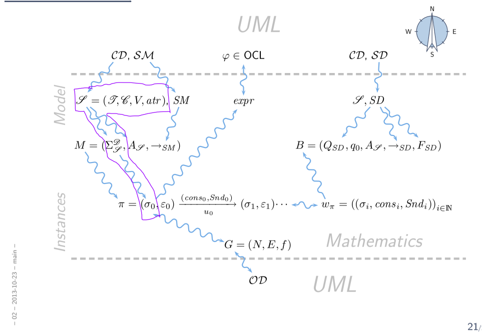
- **Alternative**: symbolic system state

  $$\sigma = \{c_1 \mapsto \{p \mapsto \emptyset, n \mapsto \{c_2\}\}, c_2 \mapsto \{p \mapsto \emptyset, n \mapsto \emptyset\}, d \mapsto \{x \mapsto 23\}\}$$

  assuming $c_1 \neq c_2 \in \mathscr{D}(C)$, $d \in \mathscr{D}(D)$, $c_1 \neq c_2$.

You Are Here.

Course Map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