# Software Design, Modelling and Analysis in UML

### Lecture 15: Hierarchical State Machines I State Machines V

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## Contents & Goals

#### Last Lecture:

• RTC-Rules: Discard, Dispatch, Commence.

#### This Lecture:

- Educational Objectives: Capabilities for following tasks/questions.
  - What does this State Machine mean? What happens if I inject this event?
  - Can you please model the following behaviour.
  - What is: initial state.
  - What does this hierarchical State Machine mean? What may happen if I inject this event?
  - What is: AND-State, OR-State, pseudo-state, entry/exit/do, final state, ...

#### • Content:

- Step, RTC, Divergence
- Putting It All Together
- Rhapsody Demo
- Hierarchical State Machines Syntax

## Step and Run-to-completion Step

## Notions of Steps: The Step

Note: we call one evolution  $(\sigma, \varepsilon) \xrightarrow[u]{(cons,Snd)}{u} (\sigma', \varepsilon')$  a step. Thus in our setting, a step directly corresponds to one object (namely u) takes a single transition between regular states. (We have to extend the concept of "single transition" for hierarchical state machines.) That is: We're going for an interleaving semantics without true parallelism.

## Notions of Steps: The Run-to-Completion Step

What is a **run-to-completion** step...?

- Intuition: a maximal sequence of steps, where the first step is a dispatch step and all later steps are commence steps.
- Note: one step corresponds to one transition in the state machine.

A run-to-completion step is in general not syntadically definable — one transition may be taken multiple times during an RTC-step.



## Notions of Steps: The Run-to-Completion Step Cont'd



$$cons_i \cap \{u\} \times Evs(\mathscr{E}, \mathscr{D}) = \emptyset, i > 1,$$

•  $u_{n-1} = u$  and u is stable only in  $\sigma_0$  and  $\sigma_n$ , i.e.

$$\sigma_0(u)(stable) = \sigma_n(u)(stable) = 1$$
 and  $\sigma_i(u)(stable) = 0$  for  $0 < i < n$ ,

Let  $0 = k_1 < k_2 < \cdots < k_N = n$  be the maximal sequence of indices such that  $u_{k_i} = u$  for  $1 \le i \le N$ . Then we call the sequence

$$(\sigma_0(u) =) \quad \sigma_{k_1}(u), \sigma_{k_2}(u) \dots, \sigma_{k_N}(u) \quad (= \sigma_{n-1}(u))$$

a (!) run-to-completion computation of u (from (local) configuration  $\sigma_0(u)$ ).

We say, object u can diverge on reception cons from (local) configuration  $\sigma_0(u)$  if and only if there is an infinite, consecutive sequence

$$(\sigma_0, \varepsilon_0) \xrightarrow{(cons_0, Snd_0)} (\sigma_1, \varepsilon_1) \xrightarrow{(cons_1, Snd_1)} \dots$$

such that u doesn't become stable again.

• **Note**: disappearance of object not considered in the definitions. By the current definitions, it's <u>neither</u> divergence <u>nor</u> an RTC-step. What people may **dislike** on our definition of RTC-step is that it takes a **global** and **non-compositional** view. That is:

- In the projection onto a single object we still see the effect of interaction with other objects.
- Adding classes (or even objects) may change the divergence behaviour of existing ones.
- Compositional would be: the behaviour of a set of objects is determined by the behaviour of each object "in isolation".
   Our semantics and notion of RTC-step doesn't have this (often desired) property.

Can we give (syntactical) criteria such that any global run-to-completion step is an interleaving of local ones?

#### Maybe: Strict interfaces.

- (A): Refer to private features only via "self".
  (Recall that other objects of the same class can modify private attributes.)
- (B): Let objects only communicate by events, i.e. don't let them modify each other's local state via links at all.

(Proof left as exercise...)

## Putting It All Together

## The Missing Piece: Initial States

**Recall**: a labelled transition system is  $(S, \rightarrow, S_0)$ . We have

• S: system configurations  $(\sigma, \varepsilon)$ 

• 
$$\rightarrow$$
: labelled transition relation  $(\sigma, \varepsilon) \xrightarrow{(cons,Snd)} (\sigma', \varepsilon')$ .

**Wanted**: initial states  $S_0$ .

# $\begin{array}{l} \textbf{Proposal:}\\ \textbf{Require a (finite) set of object diagrams $\mathcal{OD}$ as part of a UML model}\\ \textbf{class diagrams,}\\ \textbf{induce signature, (CD, SM, OD).}\\ \textbf{induce signature, (SD, SM, OD).}\\ \textbf{induce signature,$

**Other Approach**: (used by Rhapsody tool) multiplicity of classes. We can read that as an abbreviation for an object diagram.

## Semantics of UML Model — So Far

#### The semantics of the UML model

 $\mathcal{M} = (\mathscr{CD}, \mathscr{SM}, \mathscr{OD})$ 

where

- some classes in & D are stereotyped as 'signal' (standard), some signals and attributes are stereotyped as 'external' (non-standard),
- there is a 1-to-1 relation between classes and state machines,
- $\mathscr{OD}$  is a set of object diagrams over  $\mathscr{CD}$ ,

is the transition system  $(S, \rightarrow, S_0)$  constructed on the previous slide.

The computations of  $\mathcal{M}$  are the computations of  $(S, \rightarrow, S_0)$ .

## Contemporary UML Modelling Tools



## References

## References

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