# Software Design, Modelling and Analysis in UML

Lecture 15: Hierarchical State Machines I State Machines V

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Prof. Dr. Andreas Podelski, Dr. Bernd Westphal

Albert-Ludwigs-Universität Freiburg, Germany

# Notions of Steps: The Step

Note: we call one evolution  $(\sigma, \varepsilon) \xrightarrow{(cons, Snd)} (\sigma', \varepsilon')$  a step. That is: We're going for an interleaving semantics without true parallelism. (We have to extend the concept of "single transition" for hierarchical state machines.) Thus in our setting, a step directly corresponds to one object (namely u) takes a single transition between regular states.

## Contents & Goals

RTC-Rules: Discard, Dispatch, Commence.

### This Lecture:

- Educational Objectives: Capabilities for following tasks/questions.
   What does this State Machine mean' What happens if I nject this event?
   Can you please model the following behaviour.
   What is initial state.
- What does this hierarchical State Machine mean? What may happen if I inject this event?

# What is: AND-State, OR-State, pseudo-state, entry/exit/do, final state, ...

- Content:
   Step, RTC, Divergence
   Putting It All Together
   Rhapsody Demo

- Hierarchical State Machines Syntax

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Step and Run-to-completion Step

Notions of Steps: The Run-to-Completion Step Cont'd

Proposal: Let osal: Let  $\underset{u_0}{\text{det}} \text{ det} \text{ of } \text{ feels of the population of the state of the population o$ 

What is a run-to-completion step...?

Intuition: a maximal sequence of steps, where the first step is a dispatch step and all later steps are commence steps.

 Note: one step corresponds to one transition in the state machine. A run-to-completion step is in general not syntadcally definable — one transition may be taken multiple times during an RTC-step.

Notions of Steps: The Run-to-Completion Step

- be a  $\underbrace{f_{nite}(\underline{\Omega})}_{u_0}$ , non-empty, maximal, consecutive sequence such that  $u_0 = 0$  object  $u_0$  also in  $\sigma_0$ ,  $\sigma_0 = 0$  object  $u_0 = 0$  and  $\sigma_0 = 0$  object  $u_0 = 0$  and  $\sigma_0 = 0$  object  $u_0 = 0$  and  $\sigma_0 = 0$  object  $u_0 = 0$  ob
- ullet there are no receptions by u in between, i.e.  $cons_i \cap \{u\} \times Evs(\mathcal{E}, \mathcal{D}) = \emptyset, i > 1,$
- $u_{n-1}=u$  and u is stable only in  $\sigma_0$  and  $\sigma_n$ , i.e.

Let  $0=k_1< k_2<\cdots< k_N=n$  be the maximal sequence of indices such that  $u_{k_i}=u$  for  $1\leq i\leq N$ . Then we call the sequence  $\sigma_0(u)(stable) = \sigma_n(u)(stable) = 1 \text{ and } \sigma_i(u)(stable) = 0 \text{ for } 0 < i < n,$ 

 $(\sigma_0(u) =) \quad \sigma_{k_1}(u), \sigma_{k_2}(u), \dots, \sigma_{k_N}(u) \quad (= \sigma_{n-1}(u))$ 

 $\left. \left. \left. \left. \right. \right\} \right.$  a (!) run-to-completion computation of u (from (local) configuration  $\sigma_0(u) \right. \right.$ 

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### Divergence

We say, object u can diverge on reception cons from (local) configuration  $\sigma_0(u)$  if and only if there is an infinite, consecutive sequence

$$(\sigma_0, \varepsilon_0) \xrightarrow{(cons_0, Snd_0)} (\sigma_1, \varepsilon_1) \xrightarrow{(cons_1, Snd_1)} \dots$$

such that  $\boldsymbol{u}$  doesn't become stable again.

Note: disappearance of object not considered in the definitions.
 By the current definitions, it's <u>neither</u> divergence <u>nor</u> an RTC-step.

# The Missing Piece: Initial States

Require a (finite) set of object diagrams OD as part of a UML model of the property of the standard set of the standard set

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Recall: a labelled transition system is  $(S, \to, S_0)$ . We have  $\cdot$  S: system configurations  $(\sigma, \varepsilon)$ 

 $\bullet \; \to : \; \mathsf{labelled} \; \; \mathsf{transition} \; \; \mathsf{relation} \; \; (\sigma, \varepsilon) \; \xrightarrow[u]{cons, Snd)} \; (\sigma', \varepsilon').$ 

Wanted: initial states  $S_0$ .

Other Approach: (used by Rhapsody tool) multiplicity of classes.

We can read that as an abbreviation for an object diagram.

Semantics of UML Model — So Far

## The semantics of the UML model

## $\mathcal{M} = (\mathcal{CD}, \mathcal{SM}, \mathcal{OD})$

- \* some classes in  $\mathscr C\mathscr D$  are stereotyped as 'signal' (standard), some signals and attributes are stereotyped as 'external' (non-standard),
- there is a 1-to-1 relation between classes and state machines,
- $\mathscr{O}\mathscr{D}$  is a set of object diagrams over  $\mathscr{C}\mathscr{D}$ .
- is the transition system  $(S, \rightarrow, S_0)$  constructed on the previous slide.

The computations of  $\mathcal M$  are the computations of  $(S, \rightarrow, S_0)$ .

Run-to-Completion Step: Discussion.

- What people may dislike on our definition of RTC-step is that it takes a global and non-compositional view. That is:

  In the projection onto a single object we still see the effect of interaction with other objects.
- Adding classes (or even objects) may change the divergence behaviour of existing ones.
- Compositional would be: the behaviour of a set of objects is determined by the behaviour of each object "in isolation".

Can we give (syntactical) criteria such that any global run-to-completion step is an interleaving of local ones? Our semantics and notion of RTC-step doesn't have this (often desired) property.

(Proof left as exercise...)

Maybe: Strict interfaces. (Poor left as exercise

(A). Refer to private features only via "self".

(Recall that other objects of the same class can modify private attributes.)

(B). Let objects only communicate by events, i.e.
don't let them modify each other's local state via links at all.

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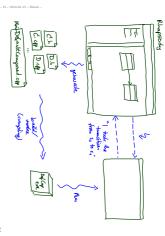
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Putting It All Together

Contemporary UML Modelling Tools

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References

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